



**TELEDYNE LECROY**  
Everywhereyoulook™

# **USB Power Delivery Exerciser Manual**

Manual Version 1.85

**For USB Protocol Suite Software Version 8.50 and above**

**December 2020**

## **Document Disclaimer**

The information contained in this document has been carefully checked and is believed to be reliable. However, no responsibility can be assumed for inaccuracies that may not have been detected.

Teledyne LeCroy reserves the right to revise the information presented in this document without notice or penalty.

## **Trademarks and Servicemarks**

*CATC Trace, Voyager M310C, Voyager M310P, Voyager M4x, Voyager ReadyLink, USB Protocol Suite, and BusEngine* are trademarks of Teledyne LeCroy.

All other trademarks are property of their respective companies.

## **Copyright**

Copyright © 2020, Teledyne LeCroy, Inc. All Rights Reserved.

This document may be printed and reproduced without additional permission, but all copies should contain this copyright notice.

## Contents

1	INTRODUCTION .....	15
2	Packet Templates .....	18
2.1	PD_ControlMessage .....	18
2.1.1	Revision 2.0 .....	18
2.1.2	Revision 3.0 .....	18
2.2	PD_GoodCrcMessage .....	18
2.3	PD_GotoMinMessage .....	18
2.4	PD_AcceptMessage .....	18
2.5	PD_RejectMessage .....	18
2.6	PD_PingMessage .....	19
2.7	PD_PsRdyMessage .....	19
2.8	PD_GetSourceCapMessage .....	19
2.9	PD_GetSinkCapMessage .....	19
2.10	PD_DataRoleSwapMessage .....	19
2.11	PD_PowerRoleSwapMessage .....	19
2.12	PD_VConnSwapMessage .....	19
2.13	PD_WaitMessage .....	19
2.14	PD_SoftResetMessage .....	19
2.15	PD_DataResetMessage .....	19
2.16	PD_DataResetCompleteMessage .....	20
2.17	PD_NotSupportedMsg .....	20
2.18	PD_GetSourceCapExtendedMsg .....	20
2.19	PD_GetStatusMsg .....	20
2.20	PD_FRSwapMsg .....	20
2.21	Pd_GetPPSStatusMsg .....	20
2.22	Pd_GetCountryCodesMsg .....	20
2.23	Pd_GetSinkCapExtendedMsg .....	20
2.24	PD_SourceCapabilitiesMessage .....	20
2.24.1	PD_PowerDataObjectFixedSupply_Source .....	21
2.24.2	PD_PDOFixedSupplyNotVSafe5V_Source .....	21
2.24.3	PD_PowerDataObjectVariableSupply_Source .....	21

2.24.4	PD_PowerDataObjectBatterySupply_Source .....	22
2.24.5	Pd_PowerDataObjectPPS.....	22
2.25	PD_SinkCapabilitiesMessage .....	22
2.25.1	PD_PowerDataObjectFixedSupply_Sink .....	22
2.25.2	PD_PowerDataObjectVariableSupply_Sink .....	23
2.25.3	PD_PowerDataObjectBatterySupply_Sink.....	23
2.26	PD_RequestPacket.....	23
2.26.1	PD_RequestDataObject_Fixed_Variable_NoGiveBack .....	23
2.26.2	PD_RequestDataObject_Fixed_Variable_GiveBack.....	24
2.26.3	PD_RequestDataObject_Battery_NoGiveBack .....	24
2.26.4	PD_RequestDataObject_Battery_GiveBack.....	24
2.26.5	Pd_ProgrammableRDO .....	24
2.27	PD_BISTCarrierModeMessage.....	25
2.28	PD_BISTTestDataMessage .....	25
2.29	PD_BISTSharedCapacityTestModeEntry .....	25
2.30	PD_BISTSharedCapacityTestModeExit .....	25
2.31	PD_BatteryStatusMsg.....	26
2.31.1	Pd_BatteryStatusDataObject .....	26
2.32	PD_AlertMsg .....	26
2.32.1	Pd_AlertDataObject .....	26
2.33	Pd_GetCountryInfoMsg.....	27
2.33.1	Pd_GetCountryInfoDO .....	27
2.34	PD_EnterUSB_Message .....	27
2.34.1	PD_EnterUSBDataObject .....	27
2.35	PD_VDM_Unstructured_Header .....	27
2.36	PD_VDM_Structured_Header .....	28
2.37	PD_VDM_Discover_Identity_Message.....	29
2.38	PD_VDM_Discover_Identity_Response .....	29
2.38.1	PD_VDM_Discover_Identity_ID_Header_VDO.....	29
2.38.1.1	Revision 2.0 .....	29
2.38.1.2	Revision 3.0 .....	29
2.38.2	PD_VDM_Discover_Identity_Cert_Stat_VDO.....	30

2.38.3	PD_VDM_Discover_Identity_Product_VDO .....	30
2.38.4	PD_VDM_Discover_Identity_Cable_VDO.....	30
2.38.5	PD_VDM_DiscoverIdentity_UFP1_VDO .....	30
2.38.6	PD_VDM_DiscoverIdentity_UFP2_VDO .....	31
2.38.7	PD_VDM_DiscoverIdentity_DFP_VDO.....	31
2.38.8	PD_DiscoverIdPassiveCableVdo.....	31
2.38.9	Pd_DiscoverIdActiveCableVdo_1.....	32
2.38.10	Pd_DiscoverIdActiveCableVdo_2 .....	32
2.38.11	PD_VDM_Discover_Identity_Alternate_Mode_Adapter_VDO .....	32
2.38.11.1	Revision 2.0 .....	33
2.38.11.2	Revision 3.0 .....	33
2.38.12	Pd_DiscoverIdVConnPoweredDeviceVdo .....	33
2.39	PD_VDM_Discover_Svids_Message .....	33
2.40	PD_VDM_Discover_Svids_Response.....	34
2.40.1	Discover_SVIDs_Responder_VDO.....	34
2.41	PD_VDM_Discover_Modes_Message .....	34
2.42	PD_VDM_Discover_Modes_Response.....	34
2.42.1	PD_VDO.....	34
2.42.2	PD_VDM_DisplayPort_DiscoverMode_Vdo .....	35
2.43	PD_VDM_Enter_Mode_Message.....	35
2.44	PD_VDM_Enter_Mode_Response.....	35
2.45	PD_VDM_Exit_Mode_Message.....	35
2.46	PD_VDM_Exit_Mode_Response .....	35
2.47	PD_VDM_Attention_Message.....	36
2.48	PD_VDM_DisplayPort_UpdateStatus_Message .....	36
2.48.1	PD_VDM_DisplayPort_Status_VDO .....	36
2.49	PD_VDM_DisplayPort_UpdateStatus_Response .....	36
2.50	PD_VDM_DisplayPort_Configure_Message.....	37
2.50.1	PD_VDM_DisplayPort_Configure_VDO .....	37
2.51	PD_VDM_DisplayPort_Configure_Response .....	37
2.52	PD_ExtMsgHeaders .....	37
2.53	PD_SourceCapExtendedMsg .....	37

2.53.1	Pd_SourceCapExtDataBlock.....	38
2.54	PD_StatusMsg.....	38
2.54.1	Pd_StatusDataBlock.....	39
2.55	Pd_StatusMsg_Cable .....	39
2.55.1	Pd_StatusDataBlock_Cable .....	39
2.56	PD_GetBatteryCapMsg.....	40
2.56.1	Pd_GetBatteryCapDataBlock .....	40
2.57	PD_GetBatteryStatusMsg .....	40
2.57.1	Pd_GetBatteryStatusDataBlock .....	40
2.58	PD_BatteryCapabilitiesMsg .....	40
2.58.1	Pd_BatteryCapDataBlock.....	40
2.59	PD_GetManufacturerInfoMsg .....	41
2.59.1	Pd_GetManufacturerInfoDataBlock .....	41
2.60	PD_ManufacturerInfoMsg .....	41
2.60.1	Pd_ManufacturerInfoDataBlock .....	41
2.61	PD_SecurityRequestMsg .....	41
2.61.1	PD_SRQDB_GetDigests .....	42
2.61.2	PD_SRQDB_GetCertificate .....	42
2.61.3	PD_SRQDB_Challenge.....	42
2.62	PD_SecurityResponseMsg .....	42
2.62.1	PD_SRQDB_Digests.....	43
2.62.1.1	PD_Security_Digest.....	43
2.62.2	PD_SRQDB_Certificate .....	43
2.62.3	PD_SRQDB_ChallengeAuth .....	43
2.62.4	PD_SRQDB_Error .....	44
2.63	Pd_PPSStatusMsg .....	44
2.63.1	Pd_PPSStatusDataBlock .....	44
2.64	Pd_CountryInfoMsg .....	44
2.64.1	Pd_CountryInfoDataBlock .....	44
2.65	Pd_CountryCodesMsg .....	45
2.65.1	Pd_CountryCodesDataBlock .....	45
2.65.1.1	CountryCode .....	45

2.66	Pd_SinkCapExtendedMsg .....	45
2.66.1	Pd_SinkCapExtDataBlock .....	45
3	Type-C Commands .....	47
3.1	PD_SetResistorRp .....	47
3.2	PD_SetResistorRd .....	47
3.3	PD_SetResistorRa .....	48
3.4	PD_SetVBusCap10MicroFarad .....	48
3.5	PD_SetVBusCap1MicroFarad .....	49
3.6	PD_SetVBus .....	49
3.7	PD_WaitForVBus .....	50
3.8	PD_SetVConn .....	50
3.9	PD_SetLoadOnVBus .....	51
3.10	PD_SetResistor100K .....	51
3.11	PD_SetResistor95_3K .....	52
3.12	PD_SetResistor264K .....	52
3.13	PD_SetBCSourceMode .....	53
3.14	PD_SetCapacitor400pF .....	53
3.15	PD_SetCC1Capacitor390pF .....	54
3.16	PD_ReportSafeStateStatus .....	54
3.17	PD_SetVbusToCCWithResistor53_2K .....	55
3.18	PD_AllowVbusWithoutCCTerm .....	55
3.19	PD_TerminateCCLines .....	56
3.20	PD_WaitForUUTPinState .....	56
3.21	PD_SetStartDRPSetting .....	57
3.22	PD_StartDRP .....	58
3.23	PD_SetStartSourceSetting .....	58
3.24	PD_StartSource .....	59
3.25	PD_SetStartSinkSetting .....	59
3.26	PD_StartSink .....	60
4	Basic Commands .....	62
4.1	PD_SendPacket .....	62
4.2	PD_SendPacket_Cable .....	63

4.3	Pd_SendErroneousChunks .....	64
4.4	PD_SendCorruptedPacket.....	65
4.5	PD_ReceivePacket.....	67
4.6	PD_SendSoftReset.....	69
4.7	PD_SendHardReset .....	70
4.8	PD_SendCableReset .....	70
4.9	PD_DelayNoAutoResponse .....	70
4.10	PD_Delay.....	71
4.11	PD_SetRoles.....	71
4.12	PD_Set.....	71
4.13	IfMatched/ElseMatched.....	75
4.14	PD_Loop.....	77
4.15	PD_TimerLoop .....	77
4.16	PD_Stop .....	78
4.17	PD_Disconnect.....	78
4.18	PD_StartUSBExerciser.....	79
4.19	PD_RunUSB3TermDetection .....	79
4.20	PD_ResumeUSB2Exerciser .....	79
4.21	PD_ReportUSB3TermStatus .....	80
4.22	PD_IncreaseMsgId .....	80
4.23	PD_DecreaseMsgId.....	80
4.24	PD_IncreaseMsgId_Cable .....	81
4.25	PD_DecreaseMsgId_Cable.....	81
4.26	PD_SendExternalTriggerOut.....	82
5	Transaction Engine™ .....	83
5.1	High Level Commands.....	83
5.1.1	PD_SetWorkingRevision .....	83
5.1.2	PD_SetNegotiationSetting_Source .....	83
5.1.3	PD_AddSourceCap .....	84
5.1.4	PD_ResetSourceCaps .....	85
5.1.5	PD_NegotiatePower_Source .....	85
5.1.6	PD_SetNegotiationSetting_Sink.....	86

5.1.7	PD_AddSinkCap.....	87
5.1.8	PD_ResetSinkCaps.....	87
5.1.9	PD_NegotiatePower_Sink.....	88
5.1.10	PD_WaitForNegotiatePower .....	88
5.1.11	PD_NegotiatePower.....	89
5.1.12	PD_SetSwapPowerRoleSetting .....	90
5.1.13	PD_SwapPowerRole.....	91
5.1.14	PD_WaitForSwapPowerRole.....	91
5.1.15	Pd_SetFRSwapNewSnkSetting .....	92
5.1.16	Pd_SetFRSwapNewSrcSetting .....	93
5.1.17	PD_FastRoleSwap .....	93
5.1.18	PD_WaitForFRSwapSignal.....	94
5.1.19	Pd_GetPPSStatus .....	94
5.1.20	Pd_SetGetPPSStatusSetting .....	95
5.1.21	Pd_SetPPSStatusDataBlock .....	95
5.1.22	Pd_ResetPPSStatusDataBlock .....	96
5.1.23	Pd_WaitForGetPPSStatus .....	96
5.1.24	Pd_SetPPSNegotiationSetting_Sink .....	97
5.1.25	Pd_StartPPSNegotiatePower_Sink .....	98
5.1.26	Pd_NextPPSNegotiatePower_Sink.....	98
5.1.27	PD_SetDataResetSetting.....	99
5.1.28	PD_SendDataReset .....	99
5.1.29	PD_WaitForDataReset .....	100
5.1.30	PD_SetSwapDataRoleSetting .....	100
5.1.31	PD_SwapDataRole .....	101
5.1.32	PD_WaitForSwapDataRole .....	102
5.1.33	PD_SetSwapVConnSetting .....	102
5.1.34	PD_SwapVConn.....	103
5.1.35	PD_WaitForSwapVConn .....	104
5.1.36	PD_SetGotoMinSetting.....	104
5.1.37	PD_GotoMin .....	105
5.1.38	PD_WaitForGotoMin .....	105

5.1.39	PD_SetGetSourceCapSetting .....	106
5.1.40	PD_GetSourceCapabilities .....	107
5.1.41	PD_WaitForGetSourceCapabilities .....	107
5.1.42	PD_SetGetSinkCapSetting.....	108
5.1.43	PD_GetSinkCapabilities.....	108
5.1.44	PD_WaitForGetSinkCapabilities.....	109
5.1.45	PD_SendBISTCarrierMode .....	110
5.1.46	PD_SendBISTTestData.....	110
5.1.47	PD_GetSourceCapExtended.....	111
5.1.48	PD_SetGetSrcCapExtSetting .....	111
5.1.49	PD_WaitForGetSrcCapExtended.....	112
5.1.50	PD_SetSrcCapExtDataBlock .....	113
5.1.51	PD_ResetSrcCapExtDataBlock .....	113
5.1.52	PD_GetStatus .....	113
5.1.53	PD_SetGetStatusSetting .....	114
5.1.54	PD_WaitForGetStatus .....	115
5.1.55	PD_SetStatusDataBlock .....	115
5.1.56	PD_ResetStatusDataBlock.....	116
5.1.57	PD_GetBatteryStatus .....	116
5.1.58	PD_SetGetBatteryStatusDataBlock.....	116
5.1.59	PD_SetGetBatteryStatusSetting.....	117
5.1.60	PD_WaitForGetBatteryStatus .....	117
5.1.61	PD_SetBatteryStatusDO.....	118
5.1.62	PD_ResetBatteryStatusDO.....	118
5.1.63	PD_Alert .....	119
5.1.64	PD_SetAlertDO.....	119
5.1.65	PD_SetAlertSetting .....	120
5.1.66	PD_WaitForAlert.....	120
5.1.67	PD_GetBatteryCap .....	121
5.1.68	PD_SetGetBatteryCapDataBlock.....	121
5.1.69	PD_SetGetBatteryCapSetting .....	122
5.1.70	PD_WaitForGetBatteryCap .....	122

5.1.71	PD_SetBatteryCapDataBlock .....	123
5.1.72	PD_ResetBatteryCapDataBlock .....	123
5.1.73	PD_GetManufacturerInfo .....	124
5.1.74	PD_SetGetManufacturerInfoDataBlock.....	124
5.1.75	PD_SetGetManufacturerInfoSetting.....	125
5.1.76	PD_WaitForGetManufacturerInfo .....	125
5.1.77	PD_SetManufacturerInfoDataBlock .....	126
5.1.78	PD_SetSecurityRequestSetting .....	126
5.1.79	PD_SecurityRequest.....	127
5.1.80	PD_SetSecurityRequestDataBlock .....	127
5.1.81	PD_WaitForSecurityRequest.....	128
5.1.82	PD_SetSecurityResponseDataBlock.....	128
5.1.83	Pd_SetGetCountryInfoSetting .....	129
5.1.84	Pd_SetCountryInfoDataBlock .....	129
5.1.85	Pd_ResetCountryInfoDataBlock.....	130
5.1.86	Pd_SetGetCountryInfoDO .....	130
5.1.87	Pd_GetCountryInfo .....	130
5.1.88	Pd_WaitForGetCountryInfo .....	131
5.1.89	Pd_SetGetCountryCodesSetting .....	132
5.1.90	Pd_SetCountryCodesDataBlock .....	132
5.1.91	Pd_ResetCountryCodesDataBlock .....	133
5.1.92	Pd_GetCountryCodes.....	133
5.1.93	Pd_WaitForGetCountryCodes.....	134
5.1.94	PD_EnterUSB.....	134
5.1.95	PD_WaitForEnterUSB.....	135
5.1.96	PD_SetEnterUSBSetting .....	135
5.1.97	PD_SetEnterUSBD0 .....	136
5.1.98	PD_ResetEnterUSBD0 .....	136
5.1.99	Pd_SetGetSnkCapExtSetting .....	137
5.1.100	Pd_SetSnkCapExtDataBlock .....	137
5.1.101	Pd_ResetSnkCapExtDataBlock .....	138
5.1.102	Pd_GetSinkCapExtended.....	138

5.1.103	Pd_WaitForGetSnkCapExtended.....	138
5.1.104	PD_SetDiscoverIdentitySetting .....	139
5.1.105	PD_AddDiscoverIdentityVDO .....	140
5.1.106	PD_ResetDiscoverIdentityVDO .....	140
5.1.107	PD_DiscoverIdentity.....	141
5.1.108	PD_WaitForDiscoverIdentity.....	141
5.1.109	PD_SetDiscoverSVIDSetting .....	142
5.1.110	PD_AddSvid .....	142
5.1.111	PD_ResetSvids .....	143
5.1.112	PD_DiscoverSvids .....	143
5.1.113	PD_WaitForDiscoverSvids .....	144
5.1.114	PD_SetDiscoverModeSetting .....	144
5.1.115	PD_AddMode .....	145
5.1.116	PD_AddModeVDO.....	145
5.1.117	PD_ResetModes .....	146
5.1.118	PD_DiscoverModes .....	146
5.1.119	PD_WaitForDiscoverModes .....	147
5.1.120	PD_SetEnterModeSetting .....	147
5.1.121	PD_EnterMode .....	148
5.1.122	PD_EnterModeVdo .....	149
5.1.123	PD_WaitForEnterMode.....	149
5.1.124	PD_SetExitModeSetting .....	150
5.1.125	PD_ExitMode.....	150
5.1.126	PD_WaitForExitMode.....	151
5.1.127	PD_Attention.....	152
5.1.128	PD_AttentionVdo .....	152
5.1.129	PD_SetDiscoveryProcessSetting.....	153
5.1.130	PD_PerformDiscoveryProcess .....	154
5.1.131	PD_SetDisplayPortSetting .....	154
5.1.132	PD_DisplayPort_UpdateStatus.....	155
5.1.133	PD_DisplayPort_Configure.....	156
5.1.134	PD_WaitForDisplayPortStatus.....	156

5.1.135	PD_WaitForDisplayPortConfigure.....	157
5.1.136	PD_SetDiscoverIdentitySetting_Cable .....	157
5.1.137	PD_WaitForDiscoverIdentity_Cable.....	158
5.1.138	PD_AddDiscoverIdentityVDO_Cable.....	159
5.1.139	PD_ResetDiscoverIdentityVDO_Cable .....	159
5.1.140	PD_SetDiscoverSVIDSetting_Cable .....	160
5.1.141	PD_WaitForDiscoverSvids_Cable .....	160
5.1.142	PD_AddSvid_Cable .....	161
5.1.143	PD_ResetSvids_Cable .....	161
5.1.144	PD_SetDiscoverModeSetting_Cable .....	162
5.1.145	PD_WaitForDiscoverModes_Cable .....	163
5.1.146	PD_AddModeVDO_Cable.....	163
5.1.147	PD_AddMode_Cable .....	164
5.1.148	PD_ResetModes_Cable .....	164
5.1.149	PD_SetEnterModeSetting_Cable .....	165
5.1.150	PD_WaitForEnterMode_Cable.....	166
5.1.151	PD_SetExitModeSetting_Cable .....	166
5.1.152	PD_WaitForExitMode_Cable.....	167
5.1.153	PD_SetManufacturerInfoDataBlock_Cable.....	167
5.1.154	PD_SetGetManufacturerInfoSetting_Cable .....	168
5.1.155	PD_WaitForGetManufacturerInfo_Cable .....	168
5.1.156	PD_SetSecurityResponseDataBlock_Cable .....	169
5.1.157	PD_SetSecurityRequestSetting_Cable .....	170
5.1.158	PD_WaitForSecurityRequest_Cable.....	170
5.1.159	Pd_SetGetStatusSetting_Cable .....	171
5.1.160	PD_SetStatusDataBlock_Cable.....	171
5.1.161	Pd_ResetStatusDataBlock_Cable .....	172
5.1.162	Pd_WaitForGetStatus_Cable.....	172
5.1.163	PD_SetEnterUSBSetting_Cable .....	173
5.1.164	PD_WaitForEnterUSB_Cable.....	173
5.1.165	Pd_SetHardResetSetting .....	174
5.1.166	Pd_WaitForHardReset.....	174

5.2	Auto Responses Capability.....	175
5.2.1	PD_DelayAutoResponse .....	175
5.2.2	PD_PauseAutoResponse.....	175

# 1 INTRODUCTION

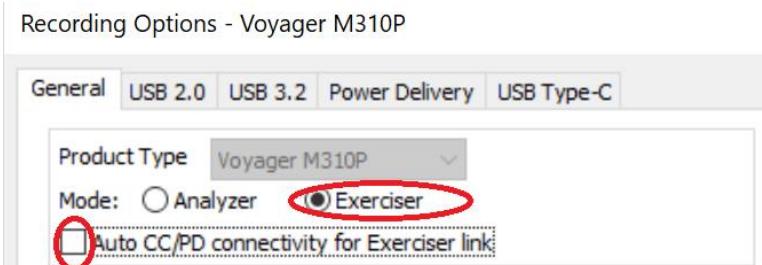
Integrated in Teledyne LeCroy's Voyager M310C test platform, the Power Delivery exerciser supports traffic generation, including both provider and consumer device emulation. The Power Delivery exerciser continues to evolve with each software release. Be sure to check for updated software and firmware before getting started with the Exerciser.

## 1.1 Scope of the Document

The document is intended as an extension to Voyager Exerciser language. It addresses only the new elements specific to PD Exerciser on top of the language described in "**Voyager Exerciser Language Manual**" (accessible through Menu -> Help -> Other Manuals).

## 1.2 Getting Started:

- The port that labeled as "Exerciser" should be used to connect DUT to the PD Exerciser. This port is same as left Analyzer port in Voyager M310C, but in other platforms "Exerciser" port is independent port.
  - The PD exerciser also requires specific cable orientation (Red LED when connected wrong side-up). Voyager M310P platform is capable to work in every orientation.
- 
- To enable the PD Trainer/Exerciser, set working mode to "Exerciser" in general page of "Recording options" and make sure "Auto CC/PD connectivity" is unchecked.



- If need to source more than 5V need to uncheck "Allow Vbus > 5V" in "Power delivery tab of "Recording Options". See important note below:



**Note** – *Allow VBUS > 5v* is a safety feature which prevents sourcing above 5V. When enabled, this mode will allow Voltage levels to be delivered to the DUT which may exceed their current carrying capabilities. While the Voyager system is designed to tolerate

higher current, these higher voltages may inadvertently cause damage to devices/cables under test.

- To set *devices port name*, use the General Tab under "Recording Options" to add "alias labels" for your DUTs.

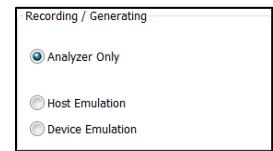


These labels will appear in the trace capture.

PD	Packet	DUT	SOP	SNK	PD Msg	Msg Type	DR	PR	Msg ID	Obj Cnt	Idle	Time Stamp		
	5	"DUT"			PD Msg	GoodCRC	UFP	SNK	0	0	263.030 us	7.900 668 406		
PD	Packet	Exerciser	SOP	SRC	PD Msg	Msg Type	DR	PR	Msg ID	Obj Cnt	Fixed	Max Cur	Voltage	Dual Role
	6	"M310C"			Source Cap	Source Cap	DFP	SRC	0	1		0.90 A	4.50 V	0

The Alias name is primarily for use in analyzer mode and requires that device names are added before recording traffic. The device naming can also be used in Exerciser mode; however message frames from the Voyager M310C will be always be labeled "M310C".

- Within the USB 3.1 tab – "Recording/Generating" option - leave in 'Analyzer Only' mode unless you also want to run 3.1 traffic.
- Use the example PD Exerciser scripts to begin testing:



C:\Users\Public\Documents\LeCroy\USB Protocol Suite\Examples\Power Delivery Exerciser

Example Script	Behavior
<b>Source Power Negotiate VDM.updg</b>	Voyager as Source negotiates default Provider 900mA@4.5V then sends Discover-Id. Using Basic Commands.
<b>High Level Negotiate with dynamic change cap.updg</b>	Voyager as Source negotiates default Provider 1A@5V then broadcasts lower PDO 900mA@4.5V and re-negotiates. Using High Level Commands.
<b>Discover Cable.updg</b>	Voyager as Source programmatically turns on VCONN and performs Discovery Process for cable. Using High Level Commands.
<b>Sink Power Negotiate.updg</b>	Voyager as Sink Waits to receive Source cap then negotiates as Sink - 900mA@5V. Using Basic Commands.
<b>Apple VGA multiple Adaptor.updg</b>	Voyager as Source enables VCONN and Sends Discover Id; Discover Mode for Apple SVID (0x05AC); Enter Mode (PD_DISPLAY_PORT_SVID) then Exit Mode; turns off VCONN. Using Basic Commands.
<b>High Level Device Discovery.updg</b>	Voyager as Source sends Discover Id; Discover SVIDs; Discover Modes for Display Port SVID (0xFF01); Enter Mode (0xFF01); Exit Mode (0xFF01); Discover Modes for Apple SVID (0x05AC); Enter Mode(0x5AC mode 1); Exit Mode(0x5AC mode 1); Enter Mode(0x5AC mode 2); Exit Mode(0x5AC mode 2); Using High Level Commands.
<b>NegotiationSample_WithSwapPowerRole.updg</b>	Voyager as Source sends SwapPowerRole; and negotiates as a Sink after power role swap. 1.5A@5V. Using High Level Commands.
<b>Sink Auto Response.updg</b>	Voyager as Sink will response to all incoming PD messages within 100s. Using Auto Response Command.

- To Run Sample Script – Connect Cable to Exerciser port; Click *Record*, wait a few seconds and Click *Run*. The PD Exerciser uses the sequence below at the beginning of each example script to simulate a re-connect event.

```
call PD_Disconnect()
call PD_SetResistorRp( PD_ON, CC_RP_CUR_1_5, CC_LINE_1 )
call PD_SetVBus( PD_ON )
```

**Note-** it's also possible to execute the example scripts before the cable is connected to M310C then performing "hot-plug" (It's possible some issues may be seen with some devices not responding to exerciser in this case).

**Note** – some latency may be observed when activating/downloading PD exerciser scripts (Run button) This will be improved in a future release.

### Important Licensing Note:

- Operating the PD Exerciser beta requires that the USB Power Delivery Exerciser option is enabled on the M310C base unit:

USB Power Delivery - Type C	Yes	USB Power Delivery Analysis - Type-C
USB Power Delivery - Exerciser	Yes	USB Power Delivery Exerciser

## 2 Packet Templates

Following Packet Templates can be used in Basic or High-Level commands as data containers. All of these messages inherited from `PD_Packet` packet template except those which are used as containers for Data Objects.

### 2.1 PD\_ControlMessage

Available fields for `PD_ControlMessage` packet template are:

#### 2.1.1 Revision 2.0

Field Name	Field Size in bits	Description
<code>MessageType</code>	4b	Default: 0
<code>Reserved1</code>	1b	Default: 0
<code>PortDataRole_Reserved2</code>	1b	Default: 0
<code>SpecificationRevision</code>	2b	Default: PD_SPEC_REVISION_2 (Rev2.0)
<code>PortPowerRole_CablePlug</code>	1b	Default: 0
<code>MessageId</code>	3b	Default: 0
<code>NumberOfDataObjects</code>	3b	Default: 0
<code>Reserved2</code>	1b	Default: 0

#### 2.1.2 Revision 3.0

Field Name	Field Size in bits	Description
<code>MessageType</code>	5b	Default: 0
<code>PortDataRole_Reserved2</code>	1b	Default: 0
<code>SpecificationRevision</code>	2b	Default: PD_SPEC_REVISION_3 (Rev3.0)
<code>PortPowerRole_CablePlug</code>	1b	Default: 0
<code>MessageId</code>	3b	Default: 0
<code>NumberOfDataObjects</code>	3b	Default: 0
<code>Extended</code>	1b	Default: 0

### 2.2 PD\_GoodCrcMessage

`PD_GoodCrcMessage` packet template has same fields as `PD_ControlMessage` but default value for `MessageType` is `PD_MESSAGE_TYPE_GOODCRC`.

### 2.3 PD\_GotoMinMessage

`PD_GotoMinMessage` packet template has same fields as `PD_ControlMessage` but default value for `MessageType` is `PD_MESSAGE_TYPE_GOTO_MIN`.

### 2.4 PD\_AcceptMessage

`PD_AcceptMessage` packet template has same fields as `PD_ControlMessage` but default value for `MessageType` is `PD_MESSAGE_TYPE_ACCEPT`.

### 2.5 PD\_RejectMessage

`PD_RejectMessage` packet template has same fields as `PD_ControlMessage` but default value for `MessageType` is `PD_MESSAGE_TYPE_REJECT`.

## 2.6 PD\_PingMessage

PD\_PingMessage packet template has same fields as [PD\\_ControlMessage](#) but default value for MessageType is PD\_MESSAGE\_TYPE\_PING.

## 2.7 PD\_PsRdyMessage

PD\_PsRdyMessage packet template has same fields as [PD\\_ControlMessage](#) but default value for MessageType is PD\_MESSAGE\_TYPE\_PS\_RDY.

## 2.8 PD\_GetSourceCapMessage

PD\_GetSourceCapMessage packet template has same fields as [PD\\_ControlMessage](#) but default value for MessageType is PD\_MESSAGE\_TYPE\_GET\_SOURCE\_CAP.

## 2.9 PD\_GetSinkCapMessage

PD\_GetSinkCapMessage packet template has same fields as [PD\\_ControlMessage](#) but default value for MessageType is PD\_MESSAGE\_TYPE\_GET\_SINK\_CAP.

## 2.10 PD\_DataRoleSwapMessage

PD\_DataRoleSwapMessage packet template has same fields as [PD\\_ControlMessage](#) but default value for MessageType is PD\_MESSAGE\_TYPE\_DR\_SWAP.

## 2.11 PD\_PowerRoleSwapMessage

PD\_PowerRoleSwapMessage packet template has same fields as [PD\\_ControlMessage](#) but default value for MessageType is PD\_MESSAGE\_TYPE\_PR\_SWAP.

## 2.12 PD\_VConnSwapMessage

PD\_VConnSwapMessage packet template has same fields as [PD\\_ControlMessage](#) but default value for MessageType is PD\_MESSAGE\_TYPE\_VCONN\_SWAP.

## 2.13 PD\_WaitMessage

PD\_WaitMessage packet template has same fields as [PD\\_ControlMessage](#) but default value for MessageType is PD\_MESSAGE\_TYPE\_WAIT.

## 2.14 PD\_SoftResetMessage

PD\_SoftResetMessage packet template has same fields as [PD\\_ControlMessage](#) but default value for MessageType is PD\_MESSAGE\_TYPE\_SOFT\_RESET.

## 2.15 PD\_DataResetMessage

PD\_DataResetMessage packet template has same fields as [PD\\_ControlMessage](#) but default value for MessageType is PD\_MESSAGE\_TYPE\_DATA\_RESET. Only applicable to Power Delivery Rev3.0.

## 2.16 PD\_DataResetCompleteMessage

PD\_DataResetCompleteMessage packet template has same fields as [PD\\_ControlMessage](#) but default value for MessageType is PD\_MESSAGE\_TYPE\_DATA\_RESET\_COMPLETE. Only applicable to Power Delivery Rev3.0.

## 2.17 PD\_NotSupportedMsg

PD\_NotSupportedMsg packet template has same fields as [PD\\_ControlMessage](#) but default value for MessageType is PD\_MESSAGE\_TYPE\_NOT\_SUPPORTED. Only applicable to Power Delivery Rev3.0.

## 2.18 PD\_GetSourceCapExtendedMsg

PD\_GetSourceCapExtendedMsg packet template has same fields as [PD\\_ControlMessage](#) but default value for MessageType is PD\_MESSAGE\_TYPE\_GET\_SRC\_CAP\_EXT. Only applicable to Power Delivery Rev3.0.

## 2.19 PD\_GetStatusMsg

PD\_GetStatusMsg packet template has same fields as [PD\\_ControlMessage](#) but default value for MessageType is PD\_MESSAGE\_TYPE\_GET\_STATUS. Only applicable to Power Delivery Rev3.0.

## 2.20 PD\_FRSwapMsg

PD\_FRSwapMsg packet template has same fields as [PD\\_ControlMessage](#) but default value for MessageType is PD\_MESSAGE\_TYPE\_FR\_SWAP. Only applicable to Power Delivery Rev3.0.

## 2.21 Pd\_GetPPSStatusMsg

Pd\_GetPPSStatusMsg packet template has same fields as [PD\\_ControlMessage](#) but default value for MessageType is PD\_MESSAGE\_TYPE\_GET\_PPS\_STATUS. Only applicable to Power Delivery Rev3.0.

## 2.22 Pd\_GetCountryCodesMsg

Pd\_GetCountryCodesMsg packet template has same fields as [PD\\_ControlMessage](#) but default value for MessageType is PD\_MESSAGE\_TYPE\_GET\_COUNTRY\_CODES. Only applicable to Power Delivery Rev3.0.

## 2.23 Pd\_GetSinkCapExtendedMsg

Pd\_GetSinkCapExtendedMsg packet template has same fields as [PD\\_ControlMessage](#) but default value for MessageType is PD\_MESSAGE\_TYPE\_GET\_SNK\_CAP\_EXT. Only applicable to Power Delivery Rev3.0.

## 2.24 PD\_SourceCapabilitiesMessage

PD\_SourceCapabilitiesMessage packet template contains all the fields of [PD\\_ControlMessage](#) but default value for MessageType is 1(PD\_MESSAGE\_TYPE\_SOURCE\_CAP -

`PD_DATA_MESSAGE_TYPE_OFFSET`). Following are additional data fields for `PD_SourceCapabilitiesMessage` packet template:

Field Name	Description
<code>SourceCapabilitiesData</code>	This field can contain one or more(up-to 7 according to PD Spec) PDO packet variables. PDO types which can assign to this field are: <code>PD_PowerDataObjectFixedSupply_Source</code> , <code>PD_PDOFixedSupplyNotVSafe5V_Source</code> , <code>PD_PowerDataObjectVariableSupply_Source</code> , <code>PD_PowerDataObjectBatterySupply_Source</code> , <code>Pd_PowerDataObjectPPS</code> When using the <a href="#">Transaction Engine™</a> functions: the <code>PD_AddSourceCap</code> function can be used to add desired Source PDOs to PD Exerciser.

### 2.24.1 PD\_PowerDataObjectFixedSupply\_Source

Can be used as `SourceCapabilitiesData` for `PD_SourceCapabilitiesMessage`. Available fields for this packet template are:

Field Name	Field Size in bits	Description
<code>MaxCurrent_10mAUnits</code>	10b	Default: 100
<code>Voltage_50mVUnits</code>	10b	Default: 100
<code>PeakCurrent</code>	2b	Default: 0
<code>Reserved</code>	Rev.3.0: 2b Rev.2.0: 3b	Default: 0
<code>UnchunkedExtMsgSupported</code>	1b	Default: 0 Rev3.0 only
<code>DataRoleSwap</code>	1b	Default: 0
<code>UsbCommunicationsCapable</code>	1b	Default: 0
<code>UnconstrainedPower</code>	1b	Default: 1
<code>UsbSuspendSupported</code>	1b	Default: 0
<code>DualRolePower</code>	1b	Default: 0
<code>PowerDataType</code>	2b	Default: 0

### 2.24.2 PD\_PDOFixedSupplyNotVSafe5V\_Source

Can be used as `SourceCapabilitiesData` for `PD_SourceCapabilitiesMessage`. Available fields for this packet template are:

Field Name	Field Size in bits	Description
<code>MaxCurrent_10mAUnits</code>	10b	Default: 0
<code>Voltage_50mVUnits</code>	10b	Default: 0
<code>PeakCurrent</code>	2b	Default: 0
<code>Reserved</code>	8b	Default: 0
<code>PowerDataType</code>	2b	Default: 0

### 2.24.3 PD\_PowerDataObjectVariableSupply\_Source

Can be used as `SourceCapabilitiesData` for `PD_SourceCapabilitiesMessage`. Available fields for this packet template are:

Field Name	Field Size in bits	Description
<code>MaxCurrent_10mAUnits</code>	10b	Default: 0
<code>MinVoltage_50mVUnits</code>	10b	Default: 0
<code>MaxVoltage_50mVUnits</code>	10b	Default: 0
<code>PowerDataType</code>	2b	Default: 2

## 2.24.4 PD\_PowerDataObjectBatterySupply\_Source

Can be used as `SourceCapabilitiesData` for `PD_SourceCapabilitiesMessage`. Available fields for this packet template are:

Field Name	Field Size in bits	Description
<code>MaxAllowablePower_250mWUnits</code>	10b	Default: 0
<code>MinVoltage_50mVUnits</code>	10b	Default: 0
<code>MaxVoltage_50mVUnits</code>	10b	Default: 0
<code>PowerDataType</code>	2b	Default: 1

## 2.24.5 Pd\_PowerDataObjectPPS

Can be used as `SourceCapabilitiesData` for `PD_SourceCapabilitiesMessage`. Available fields for this packet template are:

Field Name	Field Size in bits	Description
<code>MaxCurrent_50mAUnits</code>	7b	Default: 0
<code>PPS_Rsvd_1</code>	1b	Default: 0
<code>MinVoltage_100mVUnits</code>	8b	Default: 0
<code>PPS_Rsvd_2</code>	1b	Default: 0
<code>MaxVoltage_100mVUnits</code>	8b	Default: 0
<code>PPS_Rsvd_3</code>	2b	Default: 0
<code>PPSPowerLimited</code>	1b	Default: 0
<code>APDOType</code>	2b	Default: 0
<code>PowerDataType</code>	2b	Default: 3

## 2.25 PD\_SinkCapabilitiesMessage

`PD_SinkCapabilitiesMessage` packet template contains all the fields of `PD_ControlMessage` but default value for `MessageType` is 4(`PD_MESSAGE_TYPE_SINK_CAP` - `PD_DATA_MESSAGE_TYPE_OFFSET`).

Following are additional data fields for `PD_SinkCapabilitiesMessage` packet template:

Field Name	Description
<code>SinkCapabilitiesData</code>	This field can contain one or more(up-to 7 according to PD Spec) PDO packet variables. PDO types which can assign to this field are: <code>PD_PowerDataObjectFixedSupply_Sink</code> , <code>PD_PowerDataObjectVariableSupply_Sink</code> , <code>PD_PowerDataObjectBatterySupply_Sink</code> , <code>Pd_PowerDataObjectPPS</code> (same fields as <code>Pd_PowerDataObjectPPS</code> )  When using the <b>Transaction Engine™</b> functions: the <code>PD_AddSinkCap</code> function can be used to add desired Sink PDOs to the PD Exerciser.

## 2.25.1 PD\_PowerDataObjectFixedSupply\_Sink

Can be used as `sinkCapabilitiesData` for `PD_SinkCapabilitiesMessage`. Available fields for this packet template are:

Field Name	Field Size in bits	Description
<code>OperationalCurrent_10mAUnits</code>	10b	Default: 100
<code>Voltage_50mVUnits</code>	10b	Default: 100
<code>Reserved</code>	Rev.3.0: 3b Rev.2.0: 5b	Default: 0

FRswapTypeCCurrent	2b	Default: 0 Rev3.0 only
DataRoleSwap	1b	Default: 0
UsbCommunicationsCapable	1b	Default: 0
UnconstrainedPower	1b	Default: 1
HigherCapability	1b	Default: 0
DualRolePower	1b	Default: 0
PowerDataType	2b	Default: 0

## 2.25.2 PD\_PowerDataObjectVariableSupply\_Sink

Can be used as `SinkCapabilitiesData` for [PD\\_SinkCapabilitiesMessage](#). Available fields for this packet template are:

Field Name	Field Size in bits	Description
OperationalCurrent_10mAUnits	10b	Default: 0
MinVoltage_50mVUnits	10b	Default: 0
MaxVoltage_50mVUnits	10b	Default: 0
PowerDataType	2b	Default: 2

## 2.25.3 PD\_PowerDataObjectBatterySupply\_Sink

Can be used as `SinkCapabilitiesData` for [PD\\_SinkCapabilitiesMessage](#). Available fields for this packet template are:

Field Name	Field Size in bits	Description
OperationalPower_250mWUnits	10b	Default: 0
MinVoltage_50mVUnits	10b	Default: 0
MaxVoltage_50mVUnits	10b	Default: 0
PowerDataType	2b	Default: 1

## 2.26 PD\_RequestPacket

`PD_RequestPacket` packet template contains all the fields of [PD\\_ControlMessage](#) but default value for `MessageType` is  $2 \times (\text{PD_MESSAGE_TYPE_REQUEST} - \text{PD_DATA_MESSAGE_TYPE_OFFSET})$  and default value for `NumberOfDataObjects` field is 1. Following are additional data fields for `PD_RequestPacket` packet template:

Field Name	Description
<code>Data</code>	This field can contain only one RDO packet variables. RDO types which can assign to this field are: <code>PD_RequestDataObject_Fixed_Variable_NoGiveBack</code> , <code>PD_RequestDataObject_Fixed_Variable_GiveBack</code> , <code>PD_RequestDataObject_Battery_NoGiveBack</code> , <code>PD_RequestDataObject_Battery_GiveBack</code> , <code>Pd_ProgrammableRDO</code>  When using the <a href="#">Transaction Engine™</a> functions: the <code>PD_SetNegotiationSetting_Sink</code> function can be used to add Request RDOs to the PD Exerciser.

### 2.26.1 PD\_RequestDataObject\_Fixed\_Variable\_NoGiveBack

Can be used as `data` for [PD\\_RequestPacket](#). Available fields for this packet template are:

Field Name	Field Size in bits	Description
------------	--------------------	-------------

<a href="#">MaxOperatingCurrent_10mAUnits</a>	10b	Default: 0
<a href="#">OperatingCurrent_10mAUnits</a>	10b	Default: 0
<a href="#">Rsvd1</a>	Rev.3.0: 3b Rev.2.0: 4b	Default: 0
<a href="#">UnchunkedExtMsgSupported</a>	1b	Default: 0 Rev3.0 only
<a href="#">NoUsbSuspend</a>	1b	Default: 0
<a href="#">UsbCommunicationsCapable</a>	1b	Default: 0
<a href="#">CapabilityMismatch</a>	1b	Default: 0
<a href="#">GiveBackFlag</a>	1b	Default: 0
<a href="#">ObjectPosition</a>	3b	Default: 1
<a href="#">Rsvd2</a>	1b	Default: 0

## 2.26.2 PD\_RequestDataObject\_Fixed\_Variable\_GiveBack

Can be used as `data` for [PD\\_RequestPacket](#). This packet template has same fields as [PD\\_RequestDataObject\\_Fixed\\_Variable\\_NoGiveBack](#) packet template, but default value for `GiveBackFlag` field is 1.

## 2.26.3 PD\_RequestDataObject\_Battery\_NoGiveBack

Can be used as `data` for [PD\\_RequestPacket](#). Available fields for this packet template are:

Field Name	Field Size in bits	Description
<a href="#">MaxOperatingPower_250mWUnits</a>	10b	Default: 0
<a href="#">OperatingPower_250mWUnits</a>	10b	Default: 0
<a href="#">Rsvd1</a>	Rev.3.0: 3b Rev.2.0: 4b	Default: 0
<a href="#">UnchunkedExtMsgSupported</a>	1b	Default: 0 Rev3.0 only
<a href="#">NoUsbSuspend</a>	1b	Default: 0
<a href="#">UsbCommunicationsCapable</a>	1b	Default: 0
<a href="#">CapabilityMismatch</a>	1b	Default: 0
<a href="#">GiveBackFlag</a>	1b	Default: 0
<a href="#">ObjectPosition</a>	3b	Default: 1
<a href="#">Rsvd2</a>	1b	Default: 0

## 2.26.4 PD\_RequestDataObject\_Battery\_GiveBack

Can be used as `data` for [PD\\_RequestPacket](#). This packet template has same fields as [PD\\_RequestDataObject\\_Battery\\_NoGiveBack](#) packet template, but default value for `GiveBackFlag` field is 1.

## 2.26.5 Pd\_ProgrammableRDO

Can be used as `data` for [PD\\_RequestPacket](#). Available fields for this packet template are:

Field Name	Field Size in bits	Description
<a href="#">OperatingCurrent_50mAUnits</a>	7b	Default: 0
<a href="#">PRDO_Rsvd_1</a>	2b	Default: 0
<a href="#">OutputVoltage_20mVUnits</a>	11b	Default: 0
<a href="#">Rsvd1</a>	Rev.3.0: 3b Rev.2.0: 4b	Default: 0
<a href="#">UnchunkedExtMsgSupported</a>	1b	Default: 0 Rev3.0 only

NoUsbSuspend	1b	Default: 0
UsbCommunicationsCapable	1b	Default: 0
CapabilityMismatch	1b	Default: 0
GiveBackFlag	1b	Default: 0
ObjectPosition	3b	Default: 1
Rsvd2	1b	Default: 0

## 2.27 PD\_BISTCarrierModeMessage

PD\_BISTCarrierModeMessage packet template contains all the fields of PD\_ControlMessage but default value for MessageType is 3(PD\_MESSAGE\_TYPE\_BIST - PD\_DATA\_MESSAGE\_TYPE\_OFFSET) and default value for NumberOfDataObjects field is 1. Following are additional data fields for PD\_BISTCarrierModeMessage packet template:

Field Name	Field Size in bits	Description
Reserved	28b	Default: 0
BISTRequestType	4b	Default: BIST_REQUEST_CARRIER_MODE

## 2.28 PD\_BISTTestDataMessage

PD\_BISTTestDataMessage packet template contains all the fields of PD\_ControlMessage but default value for MessageType is 3(PD\_MESSAGE\_TYPE\_BIST - PD\_DATA\_MESSAGE\_TYPE\_OFFSET) and default value for NumberOfDataObjects field is 7. Following are additional data fields for PD\_BISTTestDataMessage packet template:

Field Name	Field Size in bits	Description
Reserved	28b	Default: 0
BISTRequestType	4b	Default: BIST_REQUEST_TEST_DATA
TestData	192b(max) Should be multiple of 32b	Default: {AA AA AA AA AA AA AA AA}

## 2.29 PD\_BISTSharedCapacityTestModeEntry

PD\_BISTSharedCapacityTestModeEntry packet template contains all the fields of PD\_ControlMessage but default value for MessageType is 3(PD\_MESSAGE\_TYPE\_BIST - PD\_DATA\_MESSAGE\_TYPE\_OFFSET) and default value for NumberOfDataObjects field is 1. Following are additional data fields for PD\_BISTSharedCapacityTestModeEntry packet template:

Field Name	Field Size in bits	Description
Reserved	28b	Default: 0
BISTRequestType	4b	Default: BIST_REQUEST_SHARED_TEST_MODE_ENTRY

## 2.30 PD\_BISTSharedCapacityTestModeExit

PD\_BISTSharedCapacityTestModeExit packet template contains all the fields of PD\_ControlMessage but default value for MessageType is 3(PD\_MESSAGE\_TYPE\_BIST - PD\_DATA\_MESSAGE\_TYPE\_OFFSET) and default value for NumberOfDataObjects field is 1. Following are additional data fields for PD\_BISTSharedCapacityTestModeExit packet template:

Field Name	Field Size in bits	Description
Reserved	28b	Default: 0
BISTRequestType	4b	Default: BIST_REQUEST_SHARED_TEST_MODE_EXIT

## 2.31 PD\_BatteryStatusMsg

Applicable to PD Rev3.0 only. `PD_BatteryStatusMsg` packet template contains all the fields of `PD_ControlMessage` but default value for `MessageType` is 5 (`PD_MESSAGE_TYPE_BATTERY_STATUS - PD_DATA_MESSAGE_TYPE_OFFSET`) and default value for `NumberOfDataObjects` field is 1. Following are additional data fields for `PD_BatteryStatusMsg` packet template:

### 2.31.1 Pd\_BatteryStatusDataObject

When using the `Transaction Engine™` functions: the `PD_SetBatteryStatusDO` can be used to add `Pd_BatteryStatusDataObject` to the PD Exerciser.

Field Name	Field Size in bits	Description
Reserved_1	8b	Default: 0x00
InvalidBatteryReference	1b	Default: 0x00
BatteryIsPresent	1b	Default: 0x00
BatteryChargingStatus	2b	Default: 0x00
Reserved_2	4b	Default: 0x00
BatteryPC	16b	Default: 0xFFFF

## 2.32 PD\_AlertMsg

Applicable to PD Rev3.0 only. `PD_AlertMsg` packet template contains all the fields of `PD_ControlMessage` but default value for `MessageType` is 6 (`PD_MESSAGE_TYPE_ALERT - PD_DATA_MESSAGE_TYPE_OFFSET`) and default value for `NumberOfDataObjects` field is 1. Following are additional data fields for `PD_AlertMsg` packet template:

### 2.32.1 Pd\_AlertDataObject

When using the `Transaction Engine™` functions: the `PD_SetAlertDO` function can be used to add `Pd_AlertDataObject` to PD Exerciser.

Field Name	Field Size in bits	Description
Reserved_1	16b	Default:0x00
HotSwappableBatteries	4b	Default:0x00
FixedBatteries	4b	Default:0x00
Reserved_2	1b	Default:0x00
BatteryStatusChange	1b	Default:0x00
OverCurProtection	1b	Default:0x00
OverTempProtection	1b	Default:0x00
OperatingConditionChange	1b	Default:0x00
SourceInputChange	1b	Default:0x00
OverVoltageProtection	1b	Default:0x00
Reserved_3	1b	Default:0x00

## 2.33 Pd\_GetCountryInfoMsg

Applicable to PD Rev3.0 only. `Pd_GetCountryInfoMsg` packet template contains all the fields of `PD_ControlMessage` but default value for `MessageType` is 7 (`PD_MESSAGE_TYPE_GET_COUNTRY_INFO - PD_DATA_MESSAGE_TYPE_OFFSET`) and default value for `NumberOfDataObjects` field is 1.

Following are additional data fields for `Pd_GetCountryInfoMsg` packet template:

### 2.33.1 Pd\_GetCountryInfoDO

When using the `Transaction Engine™` functions: the `Pd_SetGetCountryInfoDO` function can be used to add `Pd_GetCountryInfoDO` to the PD Exerciser.

Field Name	Field Size in bits	Description
<code>GetCountryInfoDO_Rsvd_1</code>	16b	Default:0x00
<code>Alpha2CountryCode2ndChar</code>	8b	Default:0x00
<code>Alpha2CountryCode1stChar</code>	8b	Default:0x00

## 2.34 PD\_EnterUSB\_Message

Applicable to PD Rev3.0 only. `Pd_EnterUSBMsg` packet template contains all the fields of `PD_ControlMessage` but default value for `MessageType` is 8 (`PD_MESSAGE_TYPE_ENTER_USB - PD_DATA_MESSAGE_TYPE_OFFSET`) and default value for `NumberOfDataObjects` field is 1. Following are additional data fields for `Pd_EnterUSBMsg` packet template:

### 2.34.1 PD\_EnterUSBDataObject

When using the `Transaction Engine™` functions: the `PD_SetEnterUSBDO` function can be used to add `Pd_EnterUSBDataObject` to the PD Exerciser.

Field Name	Field Size in bits	Description
<code>Reserved_1</code>	13b	Default: 0x00
<code>HostPresent</code>	1b	Default: PD_FALSE
<code>TBTSupport</code>	1b	Default: PD_FALSE
<code>DPSupport</code>	1b	Default: PD_FALSE
<code>PCIeSupport</code>	1b	Default: PD_FALSE
<code>CableCurrent</code>	2b	Default: PD_CABLECURRENT_VBUS_NOT_SUPP
<code>CableType</code>	2b	Default: PD_CABLETYPE_PASSIVE
<code>CableSpeed</code>	3b	Default: PD_CABLESPEED_USB2_NO_SSP
<code>Reserved_2</code>	1b	Default: 0x00
<code>USB3DRD</code>	1b	Default: PD_FALSE
<code>USB4DRD</code>	1b	Default: PD_FALSE
<code>Reserved_3</code>	1b	Default: 0x00
<code>USBMode</code>	3b	Default: PD_USBMODE_USB2
<code>Reserved_4</code>	1b	Default: 0x00

## 2.35 PD\_VDM\_Unstructured\_Header

Can be used as Header for Unstructured VDM messages. `PD_VDM_Unstructured_Header` packet template contains all the fields of `PD_ControlMessage` but default value for

MessageType is 0x0F( $\text{PD\_MESSAGE\_TYPE\_VDM} - \text{PD\_DATA\_MESSAGE\_TYPE\_OFFSET}$ ) and default value for NumberOfDataObjects field is 1. Following are additional data fields for PD\_VDM\_Unstructured\_Header packet template:

Field Name	Field Size in bits	Description
VDMCustom	15b	Default: 0x00
VDMType	1b	Default: PD_VDM_TYPE_UNSTRUCTURED_VDM
VDMSVID	16b	Default: 0x00

Following is an example which demonstrates how to send an Unstructured VDM containing two VDOs:

```

:
:
# Define VD01 fields
packet VD01Type
{
    Field1 : 2 = 0x03
    Field2 : 10 = 0xffff
    Field3 : 20 = 0xffffffff
}
local $vdo1_var = VD01Type

# Create an unstructured VDM packet with two VDOs
local $unstructured_vdm = Pd_VDM_Unstructured_Header
{
    # Number of VDOs + 1
    NumberOfDataObjects = 0x03

    # Vendor SVID
    VDMSVID = 0xABCD

    # Optional Packet variable
    VDO1 : 32 = $vdo1_var

    # Optional value
    VDO2 : 32 = 0x11111111
}

# Send VDM packet with default settings
local $SendSettings = PD_SendPacketSettings
call PD_SendPacket($unstructured_vdm, $SendSettings)

# To receive probable response packet
local $ReceiveSettings = PD_ReceivePacketSettings
call PD_ReceivePacket($ReceiveSettings)
:
:
```

## 2.36 PD\_VDM\_Structured\_Header

Can be used as Header for all Structured VDM messages. PD\_VDM\_Structured\_Header packet template contains all the fields of PD\_ControlMessage but default value for MessageType is 0x0F( $\text{PD\_MESSAGE\_TYPE\_VDM} - \text{PD\_DATA\_MESSAGE\_TYPE\_OFFSET}$ ) and default value for NumberOfDataObjects field is 1. Following are additional data fields for PD\_VDM\_Structured\_Header packet template:

Field Name	Field Size in bits	Description
VDMCommand	5b	Default: PD_VDM_COMMAND_RESERVED_0
VDMReserved1	1b	Default: 0x00
VDMCommandType	2b	Default: PD_VDM_COMMAND_TYPE_REQ
VDMObjectPosition	3b	Default: 0x00
VDMReserved2	2b	Default: 0x00
VDMStructuredVdmVersion	2b	Default: PD_VDM_STRUCTURED_VERSION_2 (Rev 3.0) Default: PD_VDM_STRUCTURED_VERSION_1 (Rev 2.0)
VDMType	1b	Default: PD_VDM_TYPE_STRUCTURED_VDM
VDMSVID	16b	Default: 0x00

## 2.37 PD\_VDM\_Discover\_Identity\_Message

PD\_VDM\_Discover\_Identity\_Message packet template contains all the fields of [PD\\_VDM\\_Structured\\_Header](#) but default value for `VDMCommand` field is `PD_VDM_COMMAND_DISCOVER_IDENTITY` and default value for `VDMSSVID` field is `PD_VDM_SID`.

## 2.38 PD\_VDM\_Discover\_Identity\_Response

PD\_VDM\_Discover\_Identity\_Response packet template contains all the fields of [PD\\_VDM\\_Discover\\_Identity\\_Message](#) but default value for `VDMCommandType` field is `PD_VDM_COMMAND_TYPE_RESPONDER_ACK`. Following are additional data fields for PD\_VDM\_Discover\_Identity\_Response packet template:

Field Name	Description
VDOs	This field can contain up-to 6 VDOs, but should contain at least 3 VDOs (according to PD Spec). VDO types which can assign to this field are: <code>PD_VDM_Discover_Identity_ID_Header_VDO</code> , <code>PD_VDM_Discover_Identity_Cert_Stat_VDO</code> , <code>PD_VDM_Discover_Identity_Product_VDO</code> , <code>PD_VDM_Discover_Identity_Cable_VDO</code> (Rev 2.0 only), <code>PD_DiscoverId_DFP_VDO</code> (Rev 3.0 only), <code>PD_DiscoverId_UFP_1_VDO</code> (Rev 3.0 only), <code>PD_DiscoverId_UFP_2_VDO</code> (Rev 3.0 only), <code>PD_DiscoverId_PassiveCableVdo</code> (Rev 3.0 only), <code>Pd_DiscoverId_ActiveCableVdo_1</code> (Rev 3.0 only), <code>Pd_DiscoverId_ActiveCableVdo_2</code> (Rev 3.0 only), <code>PD_VDM_Discover_Identity_Alternate_Mode_Adapter_VDO</code> , <code>Pd_DiscoverId_VConnPoweredDeviceVdo</code> (Rev 3.0 only)  When using the <a href="#">Transaction Engine™</a> functions: the <code>PD_AddDiscoverIdentityVDO</code> function can be used to add DiscoverIdentity VDOs to the PD Exerciser.

### 2.38.1 PD\_VDM\_Discover\_Identity\_ID\_Header\_VDO

Can be used as `VDOs` for [PD\\_VDM\\_Discover\\_Identity\\_Response](#) packet template. Available fields of this packet template are varies from Revision 2.0 to higher revisions:

#### 2.38.1.1 Revision 2.0

Field Name	Field Size in bits	Description
<code>IDHeaderVDO_USBVendorID</code>	16b	Default: 0x05FF (LeCroy ID)
<code>IDHeaderVDO_Reserved</code>	10b	Default: 0x00
<code>IDHeaderVDO_ModalOperationSupported</code>	1b	Default: 0x00
<code>IDHeaderVDO_ProductType</code>	3b	Default: <code>PD_VDM_ID_HEADER_VDO_PRODUCT_TYPE_UNDEFINED</code>
<code>IDHeaderVDO_DataCapableAsUSBDevice</code>	1b	Default: 0x00
<code>IDHeaderVDO_DataCapableAsUSBHost</code>	1b	Default: 0x00

#### 2.38.1.2 Revision 3.0

Field Name	Field Size in bits	Description
<code>USBVendorID</code>	16b	Default: 0x05FF (LeCroy ID)
<code>Reserved</code>	5b	Default: 0x00
<code>Connector_Type</code>	2b	Default: <code>PD_CABLE_CONNECTOR_TYPE_TYPEC_RECEPACLES</code>

<a href="#">ProductType_DFP</a>	3b	Default: PD_PRODUCT_TYPE_UNDEFINED
<a href="#">ModalOperationSupported</a>	1b	Default: 0x00
<a href="#">ProductType_UFP_Cable</a>	3b	Default: PD_PRODUCT_TYPE_UNDEFINED
<a href="#">DataCapableAsUSBDevice</a>	1b	Default: 0x00
<a href="#">DataCapableAsUSBHost</a>	1b	Default: 0x00

### 2.38.2 PD\_VDM\_Discover\_Identity\_Cert\_Stat\_VDO

Can be used as [VDOs](#) for [PD\\_VDM\\_Discover\\_Identity\\_Response](#) packet template. Available fields of this packet template are:

Field Name	Field Size in bits	Description
<a href="#">CertStatVDO_XID</a>	32b	Default: 0x00

### 2.38.3 PD\_VDM\_Discover\_Identity\_Product\_VDO

Can be used as [VDOs](#) for [PD\\_VDM\\_Discover\\_Identity\\_Response](#) packet template. Available fields of this packet template are:

Field Name	Field Size in bits	Description
<a href="#">ProductVDO_BCDDevice</a>	16b	Default: 0x00
<a href="#">ProductVDO_USBProductId</a>	16b	Default: 0x00

### 2.38.4 PD\_VDM\_Discover\_Identity\_Cable\_VDO

Applicable to PD Rev 2.0 only. Can be used as [VDOs](#) for [PD\\_VDM\\_Discover\\_Identity\\_Response](#) packet template. Available fields of this packet template are:

Field Name	Field Size in bits	Description
<a href="#">CableVDO_USBSuperSpeedSignalingSupport</a>	3b	Default: PD_CABLE_USB31_GEN1_SIGNALING
<a href="#">CableVDO_SOPDPrimeControllerPresent</a>	1b	Default: 0x00 should be 0x00 in case of passive cable
<a href="#">CableVDO_VBusThroughCable</a>	1b	Default: 0x00
<a href="#">CableVDO_VBusCurrentHandlingCapability</a>	2b	Default: PD_CABLE_CUR_HANDLING_CAP_3A
<a href="#">CableVDO_SSRX2DirectionalitySupport</a>	1b	Default: 0x00
<a href="#">CableVDO_SSRX1DirectionalitySupport</a>	1b	Default: 0x00
<a href="#">CableVDO_SSTX2DirectionalitySupport</a>	1b	Default: 0x00
<a href="#">CableVDO_SSTX1DirectionalitySupport</a>	1b	Default: 0x00
<a href="#">CableVDO_CableTerminationType</a>	2b	Default: 0x00
<a href="#">CableVDO_CableLatency</a>	4b	Default: PD_CABLE_LATENCY_MAX_10ns
<a href="#">CableVDO_Rsvd_2</a>	1b	Default: 0x00
<a href="#">CableVDO_TypeCPlugToTypeA_B_C_Captive</a>	2b	Default: PD_CABLE_TYPEC_TO_TYPEC
<a href="#">CableVDO_Reserved</a>	4b	Default: 0x00
<a href="#">CableVDO_FirmwareVersion</a>	4b	Default: 0x00
<a href="#">CableVDO_HardwareVersion</a>	4b	Default: 0x00

### 2.38.5 PD\_VDM\_DiscoverIdentity\_UFP1\_VDO

Applicable to Rev 3.0 only. Can be used as [VDOs](#) for [PD\\_VDM\\_Discover\\_Identity\\_Response](#) packet template. Available fields of this packet template are:

Field Name	Field Size in bits	Description
<a href="#">USBHighestSpeed</a>	3b	Default: PD_USB_HIGHEST_SPEED_USB20_ONLY

<a href="#">AlternateModes</a>	3b	Default: PD_SUPP_ALTERNATE_MODE
<a href="#">Reserved_1</a>	18b	Default: 0x00
<a href="#">DeviceCapability</a>	4b	Default: PD_DEV_CAP_USB20
<a href="#">Reserved_2</a>	1b	Default: 0x00
<a href="#">UFPVDOVersion</a>	3b	Default: PD_UFP_VDO_VERSION_1_0

## 2.38.6 PD\_VDM\_DiscoverIdentity\_UFP2\_VDO

Applicable to Rev 3.0 only. Can be used as [VDOS](#) for [PD\\_VDM\\_Discover\\_Identity\\_Response](#) packet template. Available fields of this packet template are:

Field Name	Field Size in bits	Description
<a href="#">USB3MaxPower</a>	7b	Default: 0x00
<a href="#">USB3MinPower</a>	7b	Default: 0x00
<a href="#">Reserved_1</a>	2b	Default: 0x00
<a href="#">USB4MaxPower</a>	7b	Default: 0x00
<a href="#">USB4MinPower</a>	7b	Default: 0x00
<a href="#">Reserved_2</a>	2b	Default: 0x00

## 2.38.7 PD\_VDM\_DiscoverIdentity\_DFP\_VDO

Applicable to Rev 3.0 only. Can be used as [VDOS](#) for [PD\\_VDM\\_Discover\\_Identity\\_Response](#) packet template. Available fields of this packet template are:

Field Name	Field Size in bits	Description
<a href="#">PortNumber</a>	5b	Default: 0x00
<a href="#">Reserved_1</a>	19b	Default: 0x00
<a href="#">HostCapability</a>	3b	Default: PD_HOST_CAP_USB20
<a href="#">Reserved_2</a>	2b	Default: 0x00
<a href="#">DFPVDOVersion</a>	3b	Default: PD_DFP_VDO_VERSION_1_0

## 2.38.8 PD\_DiscoverIdPassiveCableVdo

Applicable to Rev 3.0 only. Can be used as [VDOS](#) for [PD\\_VDM\\_Discover\\_Identity\\_Response](#) packet template. Available fields of this packet template are:

Field Name	Field Size in bits	Description
<a href="#">USBHighestSpeed</a>	3b	Default: PD_USB_HIGHEST_SPEED_USB32_GEN1
<a href="#">Reserved_1</a>	2b	Default: 0x00
<a href="#">VBusCurHandlingCap</a>	2b	Default: PD_CABLE_CUR_HANDLING_CAP_3A
<a href="#">Reserved_2</a>	2b	Default: 0x00
<a href="#">MaxVBusVoltage</a>	2b	Default: PD_CABLE_MAX_VBUS_20V
<a href="#">CableTerminationType</a>	2b	Default: PD_CABLE_VCONN_NOT_REQUIRED
<a href="#">CableLatency</a>	4b	Default: PD_CABLE_LATENCY_MAX_10ns
<a href="#">Reserved_3</a>	1b	Default: 0x00
<a href="#">TypeCtoTypeC_Captive</a>	2b	Default: PD_CABLE_TYPEC_TO_TYPEC
<a href="#">Reserved_4</a>	1b	Default: 0x00
<a href="#">Version</a>	3b	Default: PD_CABLE_PASSIVE_VDO_VERSION_1

FirmwareVersion	4b	Default: 0x00
HardwareVersion	4b	Default: 0x00

### 2.38.9 Pd\_DiscoverIdActiveCableVdo\_1

Applicable to Rev3.0 only. Can be used as VDOS for [PD\\_VDM\\_Discover\\_Identity\\_Response](#) packet template. Available fields of this packet template are:

Field Name	Field Size in bits	Description
USBHighestSpeed	3b	Default: PD_USB_HIGHEST_SPEED_USB32_GEN1
SOPDoublePrimeController	1b	Default: 0x00
VBusThrough	1b	Default: 0x01
VBusCurHandlingCap	2b	Default: PD_CABLE_CUR_HANDLING_CAP_3A
SBUType	1b	Default: PD_CABLE_PASSIVE_SBU
SBUSupported	1b	Default: PD_FALSE
MaxVBusVoltage	2b	Default: PD_CABLE_MAX_VBUS_20V
CableTerminationType	2b	Default: PD_CABLE_TERM_ACTIVE_ACTIVE
CableLatency	4b	Default: PD_CABLE_LATENCY_MAX_10ns
Reserved_2	1b	Default: 0x00
ConnectorType	2b	Default: PD_CABLE_TYPEC_TO_TYPEC
Reserved_3	1b	Default: 0x00
Version	3b	Default: PD_CABLE_ACTIVE_VDO_VERSION_1_3
FirmwareVersion	4b	Default: 0x00
HardwareVersion	4b	Default: 0x00

### 2.38.10 Pd\_DiscoverIdActiveCableVdo\_2

Applicable to Rev3.0 only. Can be used as VDOS for [PD\\_VDM\\_Discover\\_Identity\\_Response](#) packet template. Available fields of this packet template are:

Field Name	Field Size in bits	Description
USBGen	1b	Default: PD_CABLE_ACTIVE_USB_GEN1
Reserved_1	1b	Default: 0x00
OpticallyIsolatedActCbl	1b	Default: PD_FALSE
USBLanesSupported	1b	Default: PD_CABLE_ACTIVE_SS_ONE_LANE
USB32Supported	1b	Default: PD_FALSE
USB2Supported	1b	Default: PD_FALSE
USB2HubHopsConsumed	2b	Default: 0x00
USB4Supported	1b	Default: PD_FALSE
ActiveElement	1b	Default: PD_CABLE_ACTIVE_REDRIIVER
PhysicalConnection	1b	Default: PD_CABLE_ACTIVE_PHYSICAL_CONN_COPPER
U3ToU0TransMode	1b	Default: PD_CABLE_ACTIVE_U3_TO_U0_DIRECT
U3CLdPower	3b	Default: PD_CABLE_ACTIVE_U3POWER_GR_THAN_10mW
Reserved_3	1b	Default: 0x00
ShutdownTemperature	8b	Default: 0x00
MaxOperatingTemperature	8b	Default: 0x00

### 2.38.11 PD\_VDM\_Discover\_Identity\_Alternate\_Mode\_Adapter\_VDO

Can be used as VDOS for [PD\\_VDM\\_Discover\\_Identity\\_Response](#) packet template. Available fields of this packet template are varies from Revision 2.0 to higher revisions:

### 2.38.11.1 Revision 2.0

Field Name	Field Size in bits	Description
AMDVDO_USBSuperSpeedSignalingSupport	3b	Default: 0x01
AMDVDO_VBusRequired	1b	Default: 0x00
AMDVDO_VConnRequired	1b	Default: 0x00
AMDVDO_VConnPower	3b	Default: 0x00
AMDVDO_SSRX2DirectionalitySupport	1b	Default: 0x00
AMDVDO_SSRX1DirectionalitySupport	1b	Default: 0x00
AMDVDO_SSTX2DirectionalitySupport	1b	Default: 0x00
AMDVDO_SSTX1DirectionalitySupport	1b	Default: 0x00
AMDVDO_Reserved	12b	Default: 0x00
AMDVDO_FirmwareVersion	4b	Default: 0x00
AMDVDO_HardwareVersion	4b	Default: 0x00

### 2.38.11.2 Revision 3.0

Field Name	Field Size in bits	Description
USBHighestSpeed	3b	Default: PD_AMA_USB_HIGHEST_SPEED_USB20_ONLY
VBusRequired	1b	Default: 0x00
VConnRequired	1b	Default: 0x00
VConnPower	3b	Default: PD_AMA_VCONN_POWER_1
Reserved	13b	Default: 0x00
Version	3b	Default: PD_AMA_VDO_VERSION_1
FirmwareVersion	4b	Default: 0x00
HardwareVersion	4b	Default: 0x00

## 2.38.12 Pd\_DiscoverIdVConnPoweredDeviceVdo

Applicable to Rev3.0 only. Can be used as VDOS for [PD\\_VDM\\_Discover\\_Identity\\_Response](#) packet template. Available fields of this packet template are:

Field Name	Field Size in bits	Description
ChargeThroughSupport	1b	Default: 0x00
GroundImpedance_1mOUnits	6b	Default: 0x00
VBUSImpedance_2mOUnits	6b	Default: 0x00
VPD_Rsvd_1	1b	Default: 0x00
ChargeThroughCurrentSupport	1b	Default: PD_VPD_CHARGE_THROUGH_CURRENT_SUPP_3A
MaxVbusVoltage	2b	Default: PD_VPD_MAX_VBUS_20V
VPD_Rsvd_2	4b	Default: 0x00
VDOVersion	3b	Default: PD_VPD_VDO_VERSION_1
FirmwareVersion	4b	Default: 0x00
HWVersion	4b	Default: 0x00

## 2.39 PD\_VDM\_Discover\_Svids\_Message

[PD\\_VDM\\_Discover\\_Svids\\_Message](#) packet template contains all the fields of [PD\\_VDM\\_Structured\\_Header](#) but default value for [VDMCommand](#) field is [PD\\_VDM\\_COMMAND\\_DISCOVER\\_SVIDS](#) and default value for [VDMSSID](#) field is [PD\\_VDM\\_SID](#).

## 2.40 PD\_VDM\_Discover\_Svids\_Response

PD\_VDM\_Discover\_Svids\_Response packet template contains all the fields of [PD\\_VDM\\_Discover\\_Svids\\_Message](#) but default value for VDMCommandType field is PD\_VDM\_COMMAND\_TYPE\_RESPONDER\_ACK. Following are additional data fields for PD\_VDM\_Discover\_Svids\_Response packet template:

Field Name	Description
DiscoverSVIDsResponderVDOs	Contains one or more VDOs. The only VDO type which can assign to this field is: Discover_SVIDs_Responder_VDO When using the <a href="#">Transaction Engine™</a> functions: the <a href="#">PD_AddSvid</a> function can be used to add SVID VDOs to the PD Exerciser.

### 2.40.1 Discover\_SVIDs\_Responder\_VDO

Can be used as DiscoverSVIDsResponderVDOs for [PD\\_VDM\\_Discover\\_Svids\\_Response](#) packet template. Available fields of this packet template are:

Field Name	Field Size in bits	Description
SVID1	16b	Default: 0x00
SVID2	16b	Default: 0x00

## 2.41 PD\_VDM\_Discover\_Modes\_Message

PD\_VDM\_Discover\_Modes\_Message packet template contains all the fields of [PD\\_VDM\\_Structured\\_Header](#) but default value for VDMCommand field is PD\_VDM\_COMMAND\_DISCOVER\_MODES and default value for VDMSSID field is PD\_VDM\_SID.

## 2.42 PD\_VDM\_Discover\_Modes\_Response

PD\_VDM\_Discover\_Modes\_Response packet template contains all the fields of [PD\\_VDM\\_Discover\\_Modes\\_Message](#) but default value for VDMCommandType field is PD\_VDM\_COMMAND\_TYPE\_RESPONDER\_ACK. Following are additional data fields for PD\_VDM\_Discover\_Modes\_Response packet template:

Field Name	Description
DiscoverModes	This field should contain one or more VDOs(modes). Each Mode can be a PD_VDO packet variable which has 32bits data length. When using the <a href="#">Transaction Engine™</a> functions: the <a href="#">PD_AddMode</a> or <a href="#">PD_AddModeVDO</a> functions can be used to add desired Modes to the PD Exerciser.

### 2.42.1 PD\_VDO

Can be used as DiscoverModes for [PD\\_VDM\\_Discover\\_Modes\\_Response](#) packet template or as VDO for [PD\\_VDM\\_Enter\\_Mode\\_Message](#) and [PD\\_VDM\\_Attention\\_Message](#) packet templates. Available fields of this packet template are:

Field Name	Field Size in bits	Description
Data	32b	Default: 0x00

## 2.42.2 PD\_VDM\_DisplayPort\_DiscoverMode\_Vdo

In response to a Discover Mode Command, the VDO assigned to the `DiscoverModes` field can be in type of `PD_VDM_DisplayPort_DiscoverMode_Vdo` packet template, if the requested `VDMVID` is `PD_DISPLAY_PORT_SVID(0xFF01)`. Available data fields for `PD_VDM_DisplayPort_DiscoverMode_Vdo` packet template are:

Field Name	Fields Size in bits	Description
<code>PortCapability</code>	2b	Default: <code>PD_DISPLAYPORT_UFPD_CAPABLE</code>
<code>Signaling</code>	4b	Default: 0x01
<code>ReceptacleIndication</code>	1b	Default: 0x00
<code>Usb2SignalingNotUsed</code>	1b	Default: 0x01
<code>DFPDPinAssignmentSupported</code>	8b	Default: 0x00
<code>UFPDPinAssignmentSupported</code>	8b	Default: 0x00
<code>Reserved_DMV</code>	8b	Default: 0x00

## 2.43 PD\_VDM\_Enter\_Mode\_Message

`PD_VDM_Enter_Mode_Message` packet template contains all the fields of `PD_VDM_Structured_Header` but default value for `VDMCommand` field is `PD_VDM_COMMAND_ENTER_MODE` and default value for `VDMVID` field is `PD_VDM_SID`. Following are additional data fields for `PD_VDM_Enter_Mode_Message` packet template:

Field Name	Description
<code>VDO</code>	This field may contain one VDO. The VDO can be a <code>PD_VDO</code> packet variable which has 32bits data length.  When using the <b>Transaction Engine™</b> functions: the <code>PD_EnterModeVdo</code> function can be used to add an EnterMode VDO to PD Exerciser. This function will actually send an EnterMode command using this VDO towards the peer device/cable plug.

## 2.44 PD\_VDM\_Enter\_Mode\_Response

`PD_VDM_Enter_Mode_Response` packet template contains all the fields of `PD_VDM_Structured_Header` but default value for `VDMCommand` field is `PD_VDM_COMMAND_ENTER_MODE` and default value for `VDMVID` field is `PD_VDM_SID` and default value for `VDMCommandType` field is `PD_VDM_COMMAND_TYPE_RESPONDER_ACK`.

## 2.45 PD\_VDM\_Exit\_Mode\_Message

`PD_VDM_Exit_Mode_Message` packet template contains all the fields of `PD_VDM_Structured_Header` but default value for `VDMCommand` field is `PD_VDM_COMMAND_EXIT_MODE` and default value for `VDMVID` field is `PD_VDM_SID`.

## 2.46 PD\_VDM\_Exit\_Mode\_Response

`PD_VDM_Exit_Mode_Response` packet template contains all the fields of `PD_VDM_Exit_Mode_Message` but default value for `VDMCommandType` field is `PD_VDM_COMMAND_TYPE_RESPONDER_ACK`.

## 2.47 PD\_VDM\_Attention\_Message

PD\_VDM\_Attention\_Message packet template contains all the fields of [PD\\_VDM\\_Structured\\_Header](#) but default value for `VDMCommand` field is `PD_VDM_COMMAND_ATTENTION` and default value for `VDMSSVID` field is `PD_VDM_SID`. Following are additional data fields for PD\_VDM\_Attention\_Message packet template:

Field Name	Description
<code>VDO</code>	This field may contain one VDO. The VDO can be a <a href="#">PD_VDO</a> packet variable which has 32bits data length.  When using the <a href="#">Transaction Engine™</a> functions: the <a href="#">PD_AttentionVdo</a> function can be used to add an Attention VDO to the PD Exerciser. This function will actually send an Attention command using this VDO towards the peer device/cable plug.

## 2.48 PD\_VDM\_DisplayPort\_UpdateStatus\_Message

PD\_VDM\_DisplayPort\_UpdateStatus\_Message packet template contains all the fields of [PD\\_VDM\\_Structured\\_Header](#) but default value for `NumberofDataobjects` field is 2 and default value for `VDMCommand` field is `PD_VDM_COMMAND_DISPLAYPORT_STATUS_UPDATE` and default value for `VDMSSVID` field is `PD_DISPLAY_PORT_SVID`. Following are additional data fields for PD\_VDM\_DisplayPort\_UpdateStatus\_Message packet template:

Field Name	Description
<code>StatusVdo</code>	Contains only one VDO in type of <a href="#">PD_VDM_DisplayPort_Status_VDO</a> packet template.  When using the <a href="#">Transaction Engine™</a> functions: the <a href="#">PD_SetDisplayPortSetting</a> can be used to add a DisplayPort UpdateStatus VDO to the PD Exerciser.

### 2.48.1 PD\_VDM\_DisplayPort\_Status\_VDO

Can be used as `StatusVdo` for [PD\\_VDM\\_DisplayPort\\_UpdateStatus\\_Message](#) and [PD\\_VDM\\_DisplayPort\\_UpdateStatus\\_Response](#) packet templates. Following are available data fields for this packet template:

Field Name	Field Size in bits	Description
<code>DFPD_UFPD_Connected</code>	2b	Default: PD_DISPLAYPORT_DISCONNECTED
<code>PowerLow</code>	1b	Default: 0x00
<code>AdaptorEnabled</code>	1b	Default: 0x00
<code>MultiFunctionPreferred</code>	1b	Default: 0x00
<code>UsbConfigurationRequest</code>	1b	Default: 0x00
<code>ExitDisplayModeRequest</code>	1b	Default: 0x00
<code>HPD_State</code>	1b	Default: 0x00
<code>IRQ_HPD</code>	1b	Default: 0x00
<code>Reserved_DPS_1</code>	23b	Default: 0x00

## 2.49 PD\_VDM\_DisplayPort\_UpdateStatus\_Response

PD\_VDM\_DisplayPort\_UpdateStatus\_Response packet template contains all the fields of [PD\\_VDM\\_DisplayPort\\_UpdateStatus\\_Message](#) but default value for `VDMCommandType` field is `PD_VDM_COMMAND_TYPE_RESPONDER_ACK`.

## 2.50 PD\_VDM\_DisplayPort\_Configure\_Message

`PD_VDM_DisplayPort_Configure_Message` packet template contains all the fields of `PD_VDM_Structured_Header` but default value for `NumberOfDataObjects` field is 2 and default value for `VDMCommand` field is `PD_VDM_COMMAND_DISPLAYPORT_CONFIGURE` and default value for `VDM_SVID` field is `PD_DISPLAY_PORT_SVID`. Following are additional data fields for this packet template:

Field Name	Description
<code>ConfigureVdo</code>	Contains only one VDO in type of <code>PD_VDM_DisplayPort_Configure_VDO</code> packet template. When using the <code>Transaction Engine™</code> functions: the <code>PD_SetDisplayPortSetting</code> can be used to add a DisplayPort Configure VDO to the PD Exerciser.

### 2.50.1 PD\_VDM\_DisplayPort\_Configure\_VDO

Can be used as `ConfigureVdo` for `PD_VDM_DisplayPort_Configure_Message` packet template.  
Available data fields for this packet template are:

Field Name	Field Size in bits	Description
<code>SelectConfiguration</code>	2b	Default: <code>PD_DISPLAYPORT_CONFIGURATION_USB</code>
<code>Signaling</code>	4b	Default: 0x00
<code>Reserved_DPC_1</code>	2b	Default: 0x00
<code>UFPU_PinAssignment</code>	8b	Default: 0x00
<code>Reserved_DPC_2</code>	16b	Default: 0x00

## 2.51 PD\_VDM\_DisplayPort\_Configure\_Response

`PD_VDM_DisplayPort_Configure_Response` packet template contains all the fields of `PD_VDM_Structured_Header` but default value for `VDMCommand` field is `PD_VDM_COMMAND_DISPLAYPORT_CONFIGURE` and default value for `VDM_SVID` field is `PD_DISPLAY_PORT_SVID` and default value for `VDMCommandType` is `PD_VDM_COMMAND_TYPE_RESPONDER_ACK`.

## 2.52 PD\_ExtMsgHeaders

Applicable to Rev3.0 only. `PD_ExtMsgHeaders` packet template contains all the fields of `PD_ControlMessage` but the default value of `Extended` field is 1. Following are the additional fields for this packet template:

Field Name	Field Size in bits	Description
<code>DataSize</code>	9b	Default: 0x00
<code>Reserved</code>	1b	Default: 0x00
<code>RequestChunk</code>	1b	Default: 0x00
<code>ChunkNumber</code>	4b	Default: 0x00
<code>Chunked</code>	1b	Default: 0x00

## 2.53 PD\_SourceCapExtendedMsg

Applicable to Rev3.0 only. `PD_SourceCapExtendedMsg` packet template contains all the fields of `PD_ExtMsgHeaders` but the default value of `MessageType` field is 1

(`PD_MESSAGE_TYPE_SRC_CAP_EXT` – `PD_EXT_MESSAGE_TYPE_OFFSET`) and the default value of `dataSize` field is `PD_SCEDB_DATA_SIZE`. Following are the additional fields for this packet template:

### 2.53.1 Pd\_SourceCapExtDataBlock

When using the `Transaction Engine™` functions: the `PD_SetSrcCapExtDataBlock` function can be used to add `Pd_SourceCapExtDataBlock` to the PD Exerciser.

Field Name	Field Size in bits	Description
<code>VendorId</code>	16b	Default: 0x00
<code>ProductId</code>	16b	Default: 0x00
<code>Xid</code>	32b	Default: 0x00
<code>FirmwareVersion</code>	8b	Default: 0x00
<code>HardwareVersion</code>	8b	Default: 0x00
<code>LoadStep</code>	2b	Default: 0x00
<code>IOC</code>	1b	Default: 0x00
<code>Reserved_1</code>	5b	Default: 0x00
<code>HoldupTime</code>	8b	Default: 0x00
<code>LPSCompliant</code>	1b	Default: 0x00
<code>PS1Compliant</code>	1b	Default: 0x00
<code>PS2Compliant</code>	1b	Default: 0x00
<code>Reserved_2</code>	5b	Default: 0x00
<code>LowTouchCurEPS</code>	1b	Default: 0x00
<code>GroundPinSupport</code>	1b	Default: 0x00
<code>GrndPinForProtectiveEarth</code>	1b	Default: 0x00
<code>Reserved_3</code>	5b	Default: 0x00
<code>PeakCur1_PercentOverload</code>	5b	Default: 0x00
<code>PeakCur1_OverloadPeriod</code>	6b	Default: 0x00
<code>PeakCur1_DutyCycle</code>	4b	Default: 0x00
<code>PeakCur1_VBusVoltageDroop</code>	1b	Default: 0x00
<code>PeakCur2_PercentOverload</code>	5b	Default: 0x00
<code>PeakCur2_OverloadPeriod</code>	6b	Default: 0x00
<code>PeakCur2_DutyCycle</code>	4b	Default: 0x00
<code>PeakCur2_VBusVoltageDroop</code>	1b	Default: 0x00
<code>PeakCur3_PercentOverload</code>	5b	Default: 0x00
<code>PeakCur3_OverloadPeriod</code>	6b	Default: 0x00
<code>PeakCur3_DutyCycle</code>	4b	Default: 0x00
<code>PeakCur3_VBusVoltageDroop</code>	1b	Default: 0x00
<code>TouchTemp</code>	8b	Default: 0x00
<code>ExternalSupplyIsPresent</code>	1b	Default: 0x00
<code>ExternalSupplyCondition</code>	1b	Default: 0x00
<code>InternalBatteryIsPresent</code>	1b	Default: 0x00
<code>Reserved_4</code>	5b	Default: 0x00
<code>NumberOfFixedBatteries</code>	4b	Default: 0x00
<code>NumberOfHotSwappableBatteries</code>	4b	Default: 0x00
<code>SourcePDP</code>	7b	Default: 0x00
<code>Reserved_5</code>	1b	Default: 0x00

### 2.54 PD\_StatusMsg

Applicable to PD Rev3.0 only. `PD_StatusMsg` packet template contains all the fields of `PD_ExtMsgHeaders` but the default value of `MessageType` field is 2 (`PD_MESSAGE_TYPE_STATUS` –

`PD_EXT_MESSAGE_TYPE_OFFSET`) and the default value of `DataSize` field is `PD_SOP_SDB_DATA_SIZE`. Following are the additional fields for this packet template:

### 2.54.1 Pd\_StatusDataBlock

When using the [Transaction Engine™](#) functions: the `PD_SetStatusDataBlock` function can be used to add `Pd_StatusDataBlock` to PD Exerciser.

Field Name	Field Size in bits	Description
<code>InternalTemp</code>	8b	Default: 0x00
<code>PresentInput_Rsvd_1</code>	1b	Default: 0x00
<code>ExternalPowerIsPresent</code>	1b	Default: 0x00
<code>ExternalPower_AC_DC</code>	1b	Default: 0x00
<code>InternalPowerBattery</code>	1b	Default: 0x00
<code>InternalPowerNonBattery</code>	1b	Default: 0x00
<code>PresentInput_Rsvd_1_2</code>	3b	Default: 0x00
<code>FixedBattery</code>	4b	Default: 0x00
<code>HotSwappableBattery</code>	4b	Default: 0x00
<code>EventFlags_Rsvd_1</code>	1b	Default: 0x00
<code>OverCurProtectionEvent</code>	1b	Default: 0x00
<code>OverTempProtectionEvent</code>	1b	Default: 0x00
<code>OverVoltProtection</code>	1b	Default: 0x00
<code>OperatingModeFlag</code>	1b	Default: 0x00
<code>EventFlags_Rsvd_2</code>	3b	Default: 0x00
<code>TempStatus_Rsvd_1</code>	1b	Default: 0x00
<code>TemperatureStatus</code>	2b	Default: <code>PD_TEMP_STATUS_NORMAL</code>
<code>TempStatus_Rsvd_2</code>	5b	Default: 0x00
<code>PowerStatus_Rsvd_1</code>	1b	Default: 0x00
<code>PowLimited_CableCurrent</code>	1b	Default: <code>PD_FALSE</code>
<code>PowLimited_InsuffPower</code>	1b	Default: <code>PD_FALSE</code>
<code>PowLimited_InsuffExtPower</code>	1b	Default: <code>PD_FALSE</code>
<code>PowLimited_EventFlagsSet</code>	1b	Default: <code>PD_FALSE</code>
<code>PowLimited_Temperature</code>	1b	Default: <code>PD_FALSE</code>
<code>PowerStatus_Rsvd_2</code>	2b	Default: 0x00

### 2.55 Pd\_StatusMsg\_Cable

Applicable to PD Rev3.0 only. `Pd_StatusMsg_Cable` packet template contains all the fields of `PD_ExtMsgHeaders` but the default value of `MessageType` field is `2`(`PD_MESSAGE_TYPE_STATUS - PD_EXT_MESSAGE_TYPE_OFFSET`) and the default value of `DataSize` field is `PD_SOPP_SDB_DATA_SIZE`. Following are the additional fields for this packet template:

### 2.55.1 Pd\_StatusDataBlock\_Cable

When using the [Transaction Engine™](#) functions: the `PD_SetStatusDataBlock_Cable` function can be used to add `Pd_StatusDataBlock_Cable` to the PD Exerciser.

Field Name	Field Size in bits	Description
<code>InternalTemp</code>	8b	Default: 0x00
<code>ThermalShutdown</code>	1b	Default: <code>PD_FALSE</code>
<code>Rsvd</code>	7b	Default: 0x00

## 2.56 PD\_GetBatteryCapMsg

Applicable to PD Rev3.0 only. `PD_GetBatteryCapMsg` packet template contains all the fields of `PD_ExtMsgHeaders` but the default value of `MessageType` field is 3 (`PD_MESSAGE_TYPE_GET_BATTERY_CAP - PD_EXT_MESSAGE_TYPE_OFFSET`) and the default value of `DataSize` field is `PD_GBCDB_DATA_SIZE`. Following are the additional fields for this packet template:

### 2.56.1 Pd\_GetBatteryCapDataBlock

When using the **Transaction Engine™** functions: the `PD_SetGetBatteryCapDataBlock` function can be used to add `Pd_GetBatteryCapDataBlock` to the PD Exerciser.

Field Name	Field Size in bits	Description
<code>BatteryCapRef</code>	8b	Default: 0x00

## 2.57 PD\_GetBatteryStatusMsg

Applicable to PD Rev3.0 only. `PD_GetBatteryStatusMsg` packet template contains all the fields of `PD_ExtMsgHeaders` but the default value of `MessageType` field is 4 (`PD_MESSAGE_TYPE_GET_BATTERY_STATUS - PD_EXT_MESSAGE_TYPE_OFFSET`) and the default value of `DataSize` field is `PD_GBSDB_DATA_SIZE`. Following are the additional fields for this packet template:

### 2.57.1 Pd\_GetBatteryStatusDataBlock

When using the **Transaction Engine™** functions: the `PD_SetGetBatteryStatusDataBlock` function can be used to add `Pd_GetBatteryStatusDataBlock` to the PD Exerciser.

Field Name	Field Size in bits	Description
<code>BatteryStatusRef</code>	8b	Default: 0x00

## 2.58 PD\_BatteryCapabilitiesMsg

Applicable to PD Rev3.0 only. `PD_BatteryCapabilitiesMsg` packet template contains all the fields of `PD_ExtMsgHeaders` but the default value of `MessageType` field is 5 (`PD_MESSAGE_TYPE_BATTERY_CAP - PD_EXT_MESSAGE_TYPE_OFFSET`) and the default value of `DataSize` field is `PD_BCDB_DATA_SIZE`. Following are the additional fields for this packet template:

### 2.58.1 Pd\_BatteryCapDataBlock

When using the **Transaction Engine™** functions: the `PD_SetBatteryCapDataBlock` function can be used to add `Pd_BatteryCapDataBlock` to the PD Exerciser.

Field Name	Field Size in bits	Description
<code>VendorId</code>	16b	Default: 0x00
<code>ProductId</code>	16b	Default: 0x00
<code>DesignCap_100mWHUnits</code>	16b	Default: 0x00
<code>LastFullChargeCap_100mWHUnits</code>	16b	Default: 0x00
<code>InvalidBatteryRef</code>	1b	Default: 0x00

BCDB_Rsvd_1	7b	Default: 0x00
-------------	----	---------------

## 2.59 PD\_GetManufacturerInfoMsg

Applicable to PD Rev3.0 only. `PD_GetManufacturerInfoMsg` packet template contains all the fields of `PD_ExtMsgHeaders` but the default value of `MessageType` field is 6 (`PD_MESSAGE_TYPE_GET_MANUFACTURER_INFO - PD_EXT_MESSAGE_TYPE_OFFSET`) and the default value of `DataSize` field is `PD_GMIDB_DATA_SIZE`. Following are the additional fields for this packet template:

### 2.59.1 Pd\_GetManufacturerInfoDataBlock

When using the `Transaction Engine™` functions: the `PD_SetGetManufacturerInfoDataBlock` function can be used to add `Pd_GetManufacturerInfoDataBlock` to the PD Exerciser.

Field Name	Field Size in bits	Description
<code>Target</code>	8b	Default: <code>PD_MANINFO_TARGET_PORT_CABLE</code>
<code>ManufacturerInfoRef</code>	8b	Default: 0x00

## 2.60 PD\_ManufacturerInfoMsg

Applicable to PD Rev3.0 only. `PD_ManufacturerInfoMsg` packet template contains all the fields of `PD_ExtMsgHeaders` but the default value of `MessageType` field is 7 (`PD_MESSAGE_TYPE_MANUFACTURER_INFO - PD_EXT_MESSAGE_TYPE_OFFSET`) and the default value of `DataSize` field is `PD_MIDB_DATA_SIZE`. Following are the additional fields for this packet template:

### 2.60.1 Pd\_ManufacturerInfoDataBlock

When using the `Transaction Engine™` functions: the `PD_SetManufacturerInfoDataBlock` and `PD_SetManufacturerInfoDataBlock_Cable` functions can be used to add `Pd_ManufacturerInfoDataBlock` to the PD Exerciser.

Field Name	Field Size in bits	Description
<code>VendorId</code>	16b	Default: 0x00
<code>ProductId</code>	16b	Default: 0x00
<code>ManufacturerString</code>	Undefined(max is 176b)	Default: null Can be initialized using a byte stream

## 2.61 PD\_SecurityRequestMsg

Applicable to PD Rev3.0 only. `PD_SecurityRequestMsg` packet template contains all the fields of `PD_ExtMsgHeaders` but the default value of `MessageType` field is 8 (`PD_MESSAGE_TYPE_SECURITY_REQUEST - PD_EXT_MESSAGE_TYPE_OFFSET`) and the default value for `DataSize` field is `PD_SRQDB_DATA_SIZE`. Following are the additional fields for this packet template:

Field Name	Description
<code>SecurityRequestDB</code>	Can contain only one Security Request Data Block. Available SRDB types are: <code>PD_SRQDB_GetDigests</code> , <code>PD_SRQDB_GetCertificate</code> , <code>PD_SRQDB_Challenge</code>

	When using the <b>Transaction Engine™</b> functions: the <b>PD_SetSecurityRequestDataBlock</b> function can be used to add Security Request Data Blocks to the PD Exerciser.
--	--

### 2.61.1 PD\_SRQDB\_GetDigests

Can be used as `SecurityRequestDB` for **PD\_SecurityRequestMsg** packet template. Available data fields for this packet template are:

Field Name	Field Size in bits	Description
<a href="#">AuthProtocolVersion</a>	8b	Default: PD_AUTH_PROT_VER_1
<a href="#">AuthMessageType</a>	8b	Default: PD_AUTH_TYPE_GET_DIGESTS
<a href="#">AuthParam1</a>	8b	Default: 0x00
<a href="#">AuthParam2</a>	8b	Default: 0x00

### 2.61.2 PD\_SRQDB\_GetCertificate

Can be used as `SecurityRequestDB` for **PD\_SecurityRequestMsg** packet template. Available data fields for this packet template are:

Field Name	Field Size in bits	Description
<a href="#">AuthProtocolVersion</a>	8b	Default: PD_AUTH_PROT_VER_1
<a href="#">AuthMessageType</a>	8b	Default: PD_AUTH_TYPE_GET_CERTIFICATE
<a href="#">AuthParam1</a>	8b	Default: 0x00
<a href="#">AuthParam2</a>	8b	Default: 0x00
<a href="#">Offset</a>	16b	Default: 0x00
<a href="#">Length</a>	16b	Default: 0x00

### 2.61.3 PD\_SRQDB\_Challenge

Can be used as `SecurityRequestDB` for **PD\_SecurityRequestMsg** packet template. Available data fields for this packet template are:

Field Name	Field Size in bits	Description
<a href="#">AuthProtocolVersion</a>	8b	Default: PD_AUTH_PROT_VER_1
<a href="#">AuthMessageType</a>	8b	Default: PD_AUTH_TYPE_GET_CHALLENGE
<a href="#">AuthParam1</a>	8b	Default: 0x00
<a href="#">AuthParam2</a>	8b	Default: 0x00
<a href="#">Nonce</a>	256b	Default: { 00 00 00 00 }

## 2.62 PD\_SecurityResponseMsg

Applicable to PD Rev3.0 only. `PD_SecurityResponseMsg` packet template contains all the fields of **PD\_ExtMsgHeaders** but the default value of `MessageType` field is 9 (`PD_MESSAGE_TYPE_SECURITY_RESPONSE - PD_EXT_MESSAGE_TYPE_OFFSET`) and the default value for `DataSize` field is `PD_SRQDB_DATA_SIZE`. Following are the additional fields for this packet template:

Field Name	Description
<a href="#">SecurityResponseDB</a>	Can contain only one Security Response Data Block. Available SRPDB types are: <code>PD_SRQDB_Digests</code> , <code>PD_SRQDB_Certificate</code> , <code>PD_SRQDB_ChallengeAuth</code> ,

	<b>PD_SRPDB_Error</b> When using the <a href="#">Transaction Engine™</a> functions: the <a href="#">PD_SetSecurityResponseDataBlock</a> function can be used to add Security Response Data Blocks to the PD Exerciser.
--	---

### 2.62.1 PD\_SRPDB\_Digests

Can be used as `SecurityResponseDB` for [PD\\_SecurityResponseMsg](#) packet template. Available data fields for this packet template are:

Field Name	Field Size in bits	Description
<a href="#">AuthProtocolVersion</a>	8b	Default: PD_AUTH_PROT_VER_1
<a href="#">AuthMessageType</a>	8b	Default: PD_AUTH_TYPE_DIGESTS
<a href="#">AuthParam1</a>	8b	Default: 0x01
<a href="#">AuthParam2</a>	8b	Default: 0x00
<a href="#">DigestArray</a>	2048b(max)	Max len is 256 bytes, each digest is 32 bytes. Packet variables of <a href="#">PD_Security_Digest</a> type, can be assigned to this field.

#### 2.62.1.1 PD\_Security\_Digest

Can be used as `DigestArray` for [PD\\_SRPDB\\_Digests](#) packet template. Available fields of this packet template are:

Field Name	Field Size in bits	Description
<a href="#">Digest</a>	256b	Default: 0x00

### 2.62.2 PD\_SRPDB\_Certificate

Can be used as `SecurityResponseDB` for [PD\\_SecurityResponseMsg](#) packet template. Available data fields for this packet template are:

Field Name	Field Size in bits	Description
<a href="#">AuthProtocolVersion</a>	8b	Default: PD_AUTH_PROT_VER_1
<a href="#">AuthMessageType</a>	8b	Default: PD_AUTH_TYPE_CERTIFICATE
<a href="#">AuthParam1</a>	8b	Default: 0x00
<a href="#">AuthParam2</a>	8b	Default: 0x00
<a href="#">Certificate</a>	undefined	Default: null Can be initialized using a byte stream.

### 2.62.3 PD\_SRPDB\_ChallengeAuth

Can be used as `SecurityResponseDB` for [PD\\_SecurityResponseMsg](#) packet template. Available data fields for this packet template are:

Field Name	Field Size in bits	Description
<a href="#">AuthProtocolVersion</a>	8b	Default: PD_AUTH_PROT_VER_1
<a href="#">AuthMessageType</a>	8b	Default: PD_AUTH_TYPE_CHALLENGE_AUTH
<a href="#">AuthParam1</a>	8b	Default: 0x00
<a href="#">AuthParam2</a>	8b	Default: 0x00
<a href="#">MinProtVer</a>	8b	Default: 0x00
<a href="#">MaxProtVer</a>	8b	Default: 0x00
<a href="#">Capabilities</a>	8b	Default: 0x01
<a href="#">Rsvd</a>	8b	Default: 0x00

<a href="#">CertChainHash</a>	256b	Default: { 00 00 00 00 }
<a href="#">Salt</a>	256b	Default: { 00 00 00 00 }
<a href="#">ContextHash</a>	256b	Default: { 00 00 00 00 }
<a href="#">Signature</a>	256b	Default: { 00 00 00 00 }

## 2.62.4 PD\_SRPDB\_Error

Can be used as `SecurityResponseDB` for [PD\\_SecurityResponseMsg](#) packet template. Available data fields for this packet template are:

Field Name	Field Size in bits	Description
<a href="#">AuthProtocolVersion</a>	8b	Default: PD_AUTH_PROT_VER_1
<a href="#">AuthMessageType</a>	8b	Default: PD_AUTH_TYPE_ERROR
<a href="#">AuthParam1</a>	8b	Default: 0x00
<a href="#">AuthParam2</a>	8b	Default: 0x00

## 2.63 Pd\_PPSStatusMsg

Applicable to PD Rev3.0 only. [Pd\\_PPSStatusMsg](#) packet template contains all the fields of [PD\\_ExtMsgHeaders](#) but the default value of `MessageType` field is 12 (`PD_MESSAGE_TYPE_PPS_STATUS - PD_EXT_MESSAGE_TYPE_OFFSET`) and the default value of `DataSize` field is `PD_PPSSDB_DATA_SIZE`. Following are the additional fields for this packet template:

### 2.63.1 Pd\_PPSStatusDataBlock

When using the [Transaction Engine™](#) functions: the [Pd\\_SetPPSStatusDataBlock](#) function can be used to add `Pd_PPSStatusDataBlock` to the PD Exerciser.

Field Name	Field Size in bits	Description
<a href="#">OutputVoltage_20mVUnits</a>	16b	Default: 0xFFFF
<a href="#">OutputCurrent_50mAUnits</a>	8b	Default: 0xFF
<a href="#">PPSSDB_Rsvd_1</a>	1b	Default: 0x00
<a href="#">PresentTemperatureFlag</a>	2b	Default: 0x01
<a href="#">OperatingModeFlag</a>	1b	Default: 0x00
<a href="#">PPSSDB_Rsvd_2</a>	4b	Default: 0x00

## 2.64 Pd\_CountryInfoMsg

Applicable to PD Rev3.0 only. [Pd\\_CountryInfoMsg](#) packet template contains all the fields of [PD\\_ExtMsgHeaders](#) but the default value of `MessageType` field is 13 (`PD_MESSAGE_TYPE_COUNTRY_INFO - PD_EXT_MESSAGE_TYPE_OFFSET`) and the default value of `DataSize` field is `PD_CIDB_DATA_SIZE`. Following are the additional fields for this packet template:

### 2.64.1 Pd\_CountryInfoDataBlock

When using the [Transaction Engine™](#) functions: the [Pd\\_SetCountryInfoDataBlock](#) function can be used to add `Pd_CountryInfoDataBlock` to the PD Exerciser.

Field Name	Field Size in bits	Description
<a href="#">Alpha2CountryCode1stChar</a>	8b	Default: 0x00
<a href="#">Alpha2CountryCode2ndChar</a>	8b	Default: 0x00

CIDB_Rsvd_1	16b	Default: 0x00
CountrySpecificData	2048b max	Default: null Byte stream data. Max length is 256Bytes.

## 2.65 Pd\_CountryCodesMsg

Applicable to PD Rev3.0 only. `Pd_CountryCodesMsg` packet template contains all the fields of `PD_ExtMsgHeaders` but the default value of `MessageType` field is 14 (`PD_MESSAGE_TYPE_COUNTRY_CODES - PD_EXT_MESSAGE_TYPE_OFFSET`) and the default value of  `dataSize`  field is `PD_CCDB_DATA_SIZE`. Following are the additional fields for this packet template:

### 2.65.1 Pd\_CountryCodesDataBlock

When using the `Transaction Engine™` functions: the `Pd_SetCountryCodesDataBlock` function can be used to add `Pd_CountryCodesDataBlock` to the PD Exerciser.

Field Name	Field Size in bits	Description
NumberOfCountryCodes	16	Default: 0x01
Alpha2CountryCode1stChar	8b	Default: 0x00
Alpha2CountryCode2ndChar	8b	Default: 0x00
CountryCodes	2048b max	Default: 0x00 Should be multiple of 16bits. Max Len is 256Bytes. Each CountryCode is 2Bytes. Each CountryCode can be assigned using the <code>CountryCode</code> packet variable.

#### 2.65.1.1 CountryCode

Can be used as `CountryCodes` for `Pd_CountryCodesDataBlock` of `Pd_CountryCodesMsg` message. Following are available fields of `CountryCode` packet templates:

Field Name	Field Size in bits	Description
Alpha2CountryCode1stChar	8b	Default: 0x00
Alpha2CountryCode2ndChar	8b	Default: 0x00

## 2.66 Pd\_SinkCapExtendedMsg

Applicable to PD Rev3.0 only. `Pd_SinkCapExtendedMsg` packet template contains all the fields of `PD_ExtMsgHeaders` but the default value of `MessageType` field is 15 (`PD_MESSAGE_TYPE_SNK_CAP_EXT - PD_EXT_MESSAGE_TYPE_OFFSET`) and the default value of  `dataSize`  field is `PD_SKEDB_DATA_SIZE`. Following are the additional fields for this packet template:

### 2.66.1 Pd\_SinkCapExtDataBlock

When using the `Transaction Engine™` functions: the `Pd_SetSinkCapExtDataBlock` function can be used to add `Pd_SinkCapExtDataBlock` to the PD Exerciser.

Field Name	Field Size in bits	Description
VendorId	16b	Default: 0x00
ProductId	16b	Default: 0x00

<a href="#">XId</a>	32b	Default: 0x00
<a href="#">FirmwareVersion</a>	8b	Default: 0x00
<a href="#">HardwareVersion</a>	8b	Default: 0x00
<a href="#">SKEDBVersion</a>	8b	Default: PD_SKEDB_VERSION_1
<a href="#">LoadStep</a>	2b	Default: PD_SKEDB_LOADSTEP_150mA_PER_us
<a href="#">LoadStep_Rsvd</a>	6b	Default: 0x00
<a href="#">OverLoad_10PercentUnits</a>	5b	Default: 0x00
<a href="#">OverloadPeriod_20mSUnits</a>	6b	Default: 0x00
<a href="#">DutyCycle_5PercentUnits</a>	4b	Default: 0x00
<a href="#">TolerateVBusDroop</a>	1b	Default: 0x00
<a href="#">RequiresLPSSource</a>	1b	Default: 0x00
<a href="#">RequiresPS1Source</a>	1b	Default: 0x00
<a href="#">RequiresPS2Source</a>	1b	Default: 0x00
<a href="#">Compliance_Rsvd</a>	5b	Default: 0x00
<a href="#">TouchTemp</a>	8b	Default: PD_SKEDB_TOUCHTEMP_DEFAULT
<a href="#">NumberOfFixedBatteries</a>	4b	Default: 0x00
<a href="#">NumberOfHotSwappableSlots</a>	4b	Default: 0x00
<a href="#">PPSChargingSupported</a>	1b	Default: 0x00
<a href="#">VBusPowered</a>	1b	Default: 0x01
<a href="#">MainsPowered</a>	1b	Default: 0x00
<a href="#">BatteryPowered</a>	1b	Default: 0x00
<a href="#">BatteryEssentiallyUnlimited</a>	1b	Default: 0x00
<a href="#">SinkModes_Rsvd</a>	3b	Default: 0x00
<a href="#">SinkMinPDP</a>	7b	Default: 0x00
<a href="#">SinkMinPDP_Rsvd</a>	1b	Default: 0x00
<a href="#">SinkOperationalPDP</a>	7b	Default: 0x00
<a href="#">SinkOperationalPDP_Rsvd</a>	1b	Default: 0x00
<a href="#">SinkMaxPDP</a>	7b	Default: 0x00
<a href="#">SinkMaxPDP_Rsvd</a>	1b	Default: 0x00

### 3 Type-C Commands

In addition to Power Delivery commands, PD Exerciser also provides a command set to manage USB Type-C connection . It includes some low level commands for manipulating voltages, capacitors and resistors as well as some high level commands that let you have SINK, SINKAS, SOURCE and DRP state machines, described in Type-C specification, with the facilities to customize different behaviors and characteristics. Note that at the present, Type-C state machines are just followed when related commands are running. In other words, Type-C state machines are not followed in parallel to other Power Delivery commands execution.

#### 3.1 PD\_SetResistorRp

Sets resistor Rp On/Off.

##### Format

```
Call PD_SetResistorRp( state, current, line )
```

##### Parameters

###### state

Possible values:

```
PD_ON  
PD_OFF
```

###### current

Possible values:

```
CC_RP_CUR_DEFAULT  
CC_RP_CUR_1_5  
CC_RP_CUR_3_0
```

###### line

Possible values:

```
CC_LINE_1  
CC_LINE_2  
CC_LINE_ALL
```

##### Result

None

##### Examples

```
Call PD_SetResistorRP( PD_ON, CC_RP_CUR_1_5, CC_LINE_2 )
```

#### 3.2 PD\_SetResistorRd

Sets resistor Rd On/Off.

##### Format

```
Call PD_SetResistorRd( state, line )
```

## Parameters

**state**

Possible values:

PD\_ON  
PD\_OFF

**line**

Possible values:

CC\_LINE\_1  
CC\_LINE\_2  
CC\_LINE\_ALL

## Result

None

## Examples

```
Call PD_SetResistorRd( PD_ON, CC_LINE_1 )
```

## 3.3 PD\_SetResistorRa

Sets resistor Ra On/Off.

### Format

```
Call PD_SetResistorRa( state, line )
```

## Parameters

**state**

Possible values:

PD\_ON  
PD\_OFF

**line**

Possible values:

CC\_LINE\_1  
CC\_LINE\_2  
CC\_LINE\_ALL

## Result

None

## Examples

```
Call PD_SetResistorRa( PD_ON, CC_LINE_2 )
```

## 3.4 PD\_SetVBusCap10MicroFarad

Sets the VBus Capacitor(10 Micro Farad) On/Off.

### Format

```
Call PD_SetVBusCap10MicroFarad( state )
```

## Parameters

### state

Possible values:

PD\_ON  
PD\_OFF

## Result

None

## Examples

```
Call PD_SetVBusCap10MicroFarad( PD_ON )
```

## 3.5 PD\_SetVBusCap1MicroFarad

Sets the VBus Capacitor(1 Micro Farad) On/Off.

### Format

```
Call PD_SetVBusCap1MicroFarad( state )
```

## Parameters

### state

Possible values:

PD\_ON  
PD\_OFF

## Result

None

## Examples

```
Call PD_SetVBusCap1MicroFarad( PD_ON )
```

## 3.6 PD\_SetVBus

Sets VBus On/Off.

### Format

```
Call PD_SetVBus( state, voltage_milli_volt )
```

## Parameters

### state

Possible values:

PD\_ON  
PD\_OFF

### voltage\_milli\_volt

The voltage which applied on VBus. `voltage_mili_volt` cannot be greater than 20500 mV. In order to apply voltages greater than 5V, the corresponding check box should be set in recording options.

### Result

None

### Examples

```
call PD_SetVBus( PD_ON, 5000 )
```

## 3.7 PD\_WaitForVBus

Compares VBus voltage with the desired value within a specific time.

### Format

```
call PD_WaitForVBus( voltage_mv, wait_timeout_us, compare_operator )
```

### Parameters

#### voltage\_mv

The desired VBus voltage value(in milli-volt) to be compared with the VBus voltage value.

#### wait\_timeout\_us

The function will monitor the VBus voltage within this time-out(in micro seconds). If VBus voltage reaches to the desired value during this time-out then the function returns `PD_RESULT_OK` otherwise it returns `PD_RESULT_FAILED` with sub-result set to `PD_SUBRESULT_TIMEOUT_OCCURRED`.

#### compare\_operator

Indicates the desired comparator.

Possible values:

```
PD_COMPARE_EQUAL  
PD_COMPARE_GREATER  
PD_COMPARE_LESS
```

### Result

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

Result Values
<code>PD_RESULT_OK</code>
<code>PD_RESULT_FAILED</code>
<code>PD_SUBRESULT_TIMEOUT_OCCURRED</code>

### Examples

```
call PD_WaitForVBus(VBUS_VOLTAGE_V5_SAFE_MIN, 1000000, PD_COMPARE_GREATER)
```

## 3.8 PD\_SetVConn

Sets VConn On/Off.

### **Format**

```
Call PD_SetVConn( state, cc_line, voltage_mili_volt )
```

### **Parameters**

#### **state**

Possible values:

```
PD_ON  
PD_OFF
```

#### **cc\_line**

Possible values:

```
CC_LINE_AUTO  
CC_LINE_1  
CC_LINE_2
```

#### **voltage\_mili\_volt**

Indicates the desired VConn voltage in mV.

### **Result**

None

### **Examples**

```
Call PD_SetVConn( PD_ON, CC_LINE_2, 3000 )
```

## **3.9 PD\_SetLoadOnVBus**

Enables/Disables load on VBus.

### **Format**

```
Call PD_SetLoadOnVBus( state )
```

### **Parameters**

#### **state**

Possible values:

```
PD_ON  
PD_OFF
```

### **Result**

None

### **Examples**

```
Call PD_SetLoadOnVBus( PD_ON )
```

## **3.10 PD\_SetResistor100K**

Sets the Resistor100K on the specified CC line.

### **Format**

```
Call PD_SetResistor100K( state, cc_line )
```

## Parameters

### state

Possible values:

PD\_ON  
PD\_OFF

### cc\_line

Possible values:

CC\_LINE\_ALL  
CC\_LINE\_1  
CC\_LINE\_2

## Result

None

## Examples

```
Call PD_SetResistor100K( PD_ON, CC_LINE_1 )
```

## 3.11 PD\_SetResistor95\_3K

Sets the Resistor95.3K on the specified CC line.

## Format

```
Call PD_SetResistor95_3K( state, cc_line )
```

## Parameters

### state

Possible values:

PD\_ON  
PD\_OFF

### cc\_line

Possible values:

CC\_LINE\_ALL  
CC\_LINE\_1  
CC\_LINE\_2

## Result

None

## Examples

```
Call PD_SetResistor95_3K( PD_ON, CC_LINE_1 )
```

## 3.12 PD\_SetResistor264K

Sets the Resistor264K on the specified CC line.

## Format

```
Call PD_SetResistor264K( state, cc_line )
```

## Parameters

### state

Possible values:

PD\_ON  
PD\_OFF

### cc\_line

Possible values:

CC\_LINE\_ALL  
CC\_LINE\_1  
CC\_LINE\_2

## Result

None

## Examples

```
Call PD_SetResistor264K( PD_ON, CC_LINE_1 )
```

## 3.13 PD\_SetBCSourceMode

Enables/Disables Battery Charger Source Mode.

## Format

```
Call PD_SetBCSourceMode( state )
```

## Parameters

### state

Possible values:

PD\_ON  
PD\_OFF

## Result

None

## Examples

```
Call PD_SetBCSourceMode( PD_ON )
```

## 3.14 PD\_SetCapacitor400pF

Sets the Capacitor400pF on the specified CC line.

## Format

```
Call PD_SetCapacitor400pF( state, cc_line )
```

## Parameters

### state

Possible values:

PD\_ON  
PD\_OFF

#### cc\_line

Possible values:

CC\_LINE\_ALL  
CC\_LINE\_1  
CC\_LINE\_2

#### Result

None

#### Examples

```
call PD_SetCapacitor400pF( PD_ON, CC_LINE_1 )
```

## 3.15 PD\_SetCC1Capacitor390pF

Enables/Disables the Capacitor 390pF on CC1.

#### Format

```
call PD_SetCC1Capacitor390pF( state )
```

#### Parameters

##### state

Possible values:

PD\_ON  
PD\_OFF

#### Result

None

#### Examples

```
call PD_SetCC1Capacitor390pF( PD_ON )
```

## 3.16 PD\_ReportSafeStateStatus

Enables/Disables USB Safe States report on the specified lines.

#### Format

```
call PD_ReportSafeStateStatus( lines )
```

#### Parameters

##### lines

Possible values:

DP\_LINE\_1  
DP\_LINE\_2  
DM\_LINE\_1  
DM\_LINE\_2  
RX\_LINE\_1  
RX\_LINE\_2  
TX\_LINE\_1  
TX\_LINE\_2

```
SBU_LINE_1  
SBU_LINE_2
```

## Result

None

## Examples

```
#Enables USB_Safe States report on DP_LINE_2, DM_LINE_2, SBU_LTNE_1, SBU_LTNE_2  
#lines and disables the report on all other lines.  
call PD_ReportSafeStateStatus(DP_LINE_2 | DM_LINE_2 | SBU_LINE_1 | SBU_LINE_2)
```

## 3.17 PD\_SetVbusToCCWithResistor53\_2K

Puts VBus voltage on specified CC line using the 53.2K resistor

### Format

```
Call PD_SetVbusToCCWithResistor53_2K( state, cc_line )
```

### Parameters

**state**

Possible values:

```
PD_ON  
PD_OFF
```

**cc\_line**

Possible values:

```
CC_LINE_ALL  
CC_LINE_1  
CC_LINE_2
```

## Result

None

## Examples

```
Call PD_SetVbusToCCWithResistor53_2K( PD_ON, CC_LINE_1 )
```

## 3.18 PD\_AllowVbusWithoutCCTerm

Allows/Prevents to turn on VBus without any CC terminations.

### Format

```
Call PD_AllowVbusWithoutCCTerm( state )
```

### Parameters

**state**

Possible values:

```
PD_ON  
PD_OFF
```

## Result

None

### Examples

```
call PD_AllowbuswithoutCCTerm( PD_ON )
```

## 3.19 PD\_TerminateCCLines

Terminates CC lines with the specified resistors.

### Format

```
call PD_TerminateCCLines( CC1_Resistor, CC2_Resistor )
```

### Parameters

#### CC1\_Resistor

Possible values:

```
CC_OPEN  
CC_RP  
CC_RP_1_5  
CC_RP_3_0  
CC_RD  
CC_RA
```

#### CC2\_Resistor

Possible values:

```
CC_OPEN  
CC_RP  
CC_RP_1_5  
CC_RP_3_0  
CC_RD  
CC_RA
```

### Result

None

### Examples

```
call PD_TerminateCCLines( CC_RP_1_5, CC_OPEN )
```

## 3.20 PD\_WaitForUUTPinState

Waits until either a time-out being occurred or a specific UUT pin state being detected for a specific duration of time.

### Format

```
call PD_WaitForUUTPinState( pin_state, state_duration, pin_selector, timeout )
```

### Parameters

#### pin\_state

The specific UUT pin state to check.

Possible values:

```
CC_PIN_STATE_NONE  
CC_PIN_STATE_SRC_OPEN
```

CC\_PIN\_STATE\_SRC\_RD  
 CC\_PIN\_STATE\_SRC\_RA  
 CC\_PIN\_STATE\_SNK\_OPEN  
 CC\_PIN\_STATE\_SNK\_RP

#### **state\_duration**

Time duration(in micro seconds) to check the presentation of the UUT specified pin state.

#### **pin\_selector**

Indicates the CC line(s)

CC\_PIN\_SELECTOR\_NEITHER  
 CC\_PIN\_SELECTOR\_EITHER  
 CC\_PIN\_SELECTOR\_BOTH  
 CC\_PIN\_SELECTOR\_ONLY\_ONE  
 CC\_PIN\_SELECTOR\_ONE\_OTHER  
 CC\_PIN\_SELECTOR\_CC1  
 CC\_PIN\_SELECTOR\_CC2

#### **timeout**

If the time-out(in micro seconds) occurs function will return.

### **Result**

None

### **Examples**

```
Call PD_WaitForUUTPinState(CC_PIN_STATE_SRC_RD, 50000, CC_PIN_SELECTOR_CC2, 200000)
```

## **3.21 PD\_SetStartDRPSetting**

It is used to customize behavior and characteristics of the Exerciser when acts as a DRP device. Settings will be applied to [PD\\_StartDRP](#) function.

#### **Format**

```
Call PD_SetStartDRPSetting( PD_Start_DRP_Settings $settings )
```

#### **Parameters**

##### **\$settings**

Parameter type is [PD\\_Start\\_DRP\\_Settings](#). This type contains following data fields:

Field Name	Default Values	Description
Timeout	PD_DEFAULT_TIMEOUT_INFINITE	Indicates the timeout in micro second for connecting as a SINK or SOURCE. Should be greater than 5000us.
WithRa	PD_FALSE	Indicates whether to provide Ra on one of CC lines or not.
WithAccessory	PD_FALSE	If set to PD_TRUE, the command checks whether the UUT transitions to the AudioAccessory state or not.
AdvertizedCurrent	CC_RP_CUR_1_5	Indicates advertised current level on Rp.
WithVConn	PD_FALSE	Indicates whether to turn on the VConn or not.
VConnVoltage_mV	VCONN_VOLTAGE_DEFAULT	Indicates the VConn voltage level when start sourcing.
AccessoryStateDuration	1000000 (us)	Time duration to check whether the UUT is in AudioAccessory state or not.
StartWithSNK	PD_FALSE	If is set to PD_TRUE, DRP state machine starts from Unattached.SNK state instead of Unattached.SRC state.

WithTrySRC	PD_FALSE	If is set to PD_TRUE, Exerciser supports Try.SRC state machine.
WithTrySNK	PD_FALSE	If is set to PD_TRUE, Exerciser supports Try.SNK state machine.

## Result

None

## Examples

```
$startdrp_setting = PD_Start_DRP_Settings
{
    WithTrySRC = PD_TRUE
}
Call PD_SetStartDRPSetting( $startdrp_setting )
```

## 3.22 PD\_StartDRP

It starts DRP state machine for connecting to a Type-C device. The command quits if timeouts or Exerciser transitions to Attached.Src or Attached.SNK. Usually is being called after [PD\\_SetStartDRPSetting](#) function.

### Format

Call PD\_StartDRP()

### Parameters

None

## Result

User can evaluate the command results(including sub-results) using IfMatched/ElseMatched command.

Result Values
PD_RESULT_OK
PD_RESULT_FAILED

## Examples

Call PD\_StartDRP()

## 3.23 PD\_SetStartSourceSetting

It is used to customize behavior and characteristics of the Exerciser when acts as a SOURCE device. Settings will be applied to [PD\\_StartSource](#) command.

### Format

Call PD\_SetStartSourceSetting( PD\_Start\_Source\_Settings \$settings )

### Parameters

\$settings

Parameter type is PD\_Start\_Source\_Settings. Available fields for this type are:

Field Names	Default Values	Description
Timeout	PD_DEFAULT_TIMEOUT_INFINITE	Indicates the timeout (micro seconds) for connecting as SOURCE.

		Should be greater than 5000us.
WithRa	PD_FALSE	Indicates whether to provide Ra on one of CC lines or not.
WithAccessory	PD_FALSE	If set to PD_TRUE, the command checks whether the UUT transitions to the AudioAccessory state or not.
AdvertizedCurrent	CC_RP_CUR_1_5	Indicates advertised current level on Rp.
WithVConn	PD_FALSE	Indicates whether to turn on VConn or not.
VConnVoltage_mV	VCONN_VOLTAGE_DEFAULT	Indicates the VConn voltage level when start sourcing.
AccessoryStateDuration	1000000 (us)	Time duration to check whether the UUT is in AudioAccessory state or not.

## Result

None

## Examples

```
$startsrc_setting = PD_Start_Source_Settings
{
    WithRa = PD_TRUE
}
Call PD_SetStartSourceSetting( $startsrc_setting )
```

## 3.24 PD\_StartSource

It starts SOURCE state machine for connecting to a Type-C device. The command is terminated if timeout occurs or the Exerciser transitions to Attached.SRC state. Usually is being called after [PD\\_SetStartSourceSetting](#) function.

### Format

```
Call PD_StartSource()
```

### Parameters

None

## Result

User can evaluate the command results(including sub-results) using IfMatched/ElseMatched command.

Result Values
PD_RESULT_OK
PD_RESULT_FAILED

## Examples

```
Call PD_StartSource()
```

## 3.25 PD\_SetStartSinkSetting

It is used to customize behavior and characteristics of the Exerciser when acts as a SINK device. Settings will be applied to [PD\\_StartSink](#) command.

### Format

```
Call PD_SetStartSinkSetting( PD_Start_Sink_Settings $settings )
```

## Parameters

`$settings`

Parameter type is `PD_Start_Sink_Settings`. Available fields of this type are:

Field Name	Default Values	Description
<code>Timeout</code>	<code>PD_DEFAULT_TIMEOUT_INFINITE</code>	Indicates the timeout (micro second) for connecting as a SINK. Should be greater than 5000us.
<code>WithRa</code>	<code>PD_FALSE</code>	Indicates whether to provide Ra on one of CC lines or not.
<code>WithAccessory</code>	<code>PD_FALSE</code>	Indicates whether to support SINKAS state machine or not.
<code>AdvertizedCurrent</code>	<code>CC_RP_CUR_1_5</code>	When <code>WithAccessory</code> setting is <code>PD_TRUE</code> : indicates advertised current level on Rp.
<code>StartWithSNK</code>	<code>PD_TRUE</code>	Applies when <code>WithAccessory</code> setting is <code>PD_TRUE</code> . If is set to <code>PD_FALSE</code> , SINKAS state machine starts from Unattached.Accessory state instead of Unattached.SNK state.
<code>AccessoryStateDuration</code>	<code>1000000 us</code>	When <code>WithAccessory</code> setting is <code>PD_TRUE</code> : indicates the time that Execiser stays in Powered.Accessory or Audio.Accessory states.
<code>PoweredAccessoryExitState</code>	<code>PD_TYPE_C_STATE_NONE</code>	When <code>WithAccessory</code> setting is <code>PD_TRUE</code> : indicates the exit state from Powered.Accessory state.

## Result

None

## Examples

```
$startsnk_setting = PD_Start_Sink_Settings
{
    WithAccessory = PD_TRUE
}
Call PD_SetStartSinkSetting( $startsnk_setting )
```

## 3.26 PD\_StartSink

It starts SINK or SINKAS state machine for connecting to a Type-C device. The command is terminated if timeout occurs or Exerciser transitions to Attached.SNK. When Exerciser acts as SINKAS, with no exit state for Powered.Accessory state, that state will be the last state and command is terminated after specified time for this state duration. Usually is being called after the `PD_SetStartSinkSetting` function.

### Format

```
Call PD_StartSink()
```

### Parameters

None

### Result

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

Result Values
<code>PD_RESULT_OK</code>

`PD_RESULT_FAILED`

## Examples

Call `PD_StartSink()`

## 4 Basic Commands

### 4.1 PD\_SendPacket

Sends the data payload towards the device. You can customize its behavior using provided settings.

#### Format

```
Call PD_SendPacket(PD_Packet $send_packet, PD_SendPacketSettings $settings)
```

#### Parameters

**\$send\_packet**

Defines the payload. Refer to [Packet Templates](#) for available packet templates.

**\$settings**

Settings for sending packet. It should be inherited from `PD_SendPacketSettings` template.

Table below shows `PD_SendPacketSettings` structure in detail:

Field Name	Possible/Default Values	Description
OrderedSetType	PD_ORDERED_SET_TYPE_SOP(default) PD_ORDERED_SET_TYPE_SOP_PRIME PD_ORDERED_SET_TYPE_SOP_DOUBLE_PRIME PD_ORDERED_SET_TYPE_HARDRESET PD_ORDERED_SET_TYPE_CABLERESET	Defines Ordered set type.
WaitForGoodCrc	PD_TRUE(default) PD_FALSE	If the command should wait for peer GoodCrc message.
ResetOnError	PD_TRUE(default) PD_FALSE	Send Soft Reset if relative GoodCrc has not been received, in case of sending SoftReset failure, HardReset will be sent.
RetryCount	PD_DEFAULT_RETRY_COUNT_REV_2(default.Rev2.0) PD_DEFAULT_RETRY_COUNT_REV_3(default.Rev3.0)	Indicates the Retry Count.
RetryDelayTime	0(default)	Delay time between two consecutive retries.
AutoMessageId	PD_TRUE(default) PD_FALSE	To increase MessageId automatically.

#### Result

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

Value	Description
PD_RESULT_OK	Command succeeded
PD_RESULT_FAILED	Command failed
PD_SUBRESULT_NO_GOODCRC	Subresult - No GoodCRC received for sent packet
PD_SUBRESULT_HARDRESET	Subresult - HardReset occurred.
PD_SUBRESULT_SOFTRESET	Subresult - SoftReset occurred.

#### Examples

```
#send a discover identity command
#####
$send_setting = PD_SendPacketSettings
{
    # could be PD_ORDERED_SET_TYPE_SOP_PRIME for cables
    OrderedSetType = PD_ORDERED_SET_TYPE_SOP
}
```

```

$discover_identity = PD_VDM_Discover_Identity_Message
Call PD_SendPacket( $discover_identity, $send_setting )

# Send Request message
#####
$request_data = PD_RequestDataObject_Fixed_Variable_NoGiveBack
{
    MaxOperatingCurrent_10mAUnits = 90
    OperatingCurrent_10mAUnits = 90
}
$request_packet = PD_RequestPacket
{
    Data = $request_data
}
#calling PD_SendPacket() command using default settings
$send_packet_settings = PD_SendPacketSettings
Call PD_SendPacket($request_packet, $send_packet_settings)

```

## 4.2 PD\_SendPacket\_Cable

Sends a packet as a Marked Cable towards the device.

### Format

```

Call PD_SendPacket_Cable( PD_Packet $send_packet,
                           PD_SendPacketSettings_Cable $settings )

```

### Parameters

**\$send\_packet**

Defines the payload. Refer to [Packet Templates](#) for available packet templates.

**\$settings**

Settings for sending packet. It should be derived from `PD_SendPacketSettings_Cable` template.

`PD_SendPacketSettings_Cable` is derived from `PD_SendPacketSettings` template. Default values for some fields is changed as below:

```

OrderedSetType = PD_ORDERED_SET_TYPE_SOP_PRIME
ResetOnErrors = PD_FALSE
RetryCount = 0

```

### Result

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

List of possible result values:

Value	Description
<code>PD_RESULT_OK</code>	Command succeeded
<code>PD_RESULT_FAILED</code>	Command failed
<code>PD_SUBRESULT_NO_GOODCRC</code>	Subresult - No GoodCRC received for sent packet

### Examples

```

#send a discover identity response
#####
$send_setting = PD_SendPacketSettings_Cable

$header_vdo = PD_VDM_Discover_Identity_ID_Header_VDO
$stat_vdo = PD_VDM_Discover_Identity_Cert_Stat_VDO
$product_vdo = PD_VDM_Discover_Identity_Product_VDO
$cable_vdo = PD_VDM_Discover_Identity_Cable_VDO

$discover_identity_response = PD_VDM_Discover_Identity_Response
{
    VDOS = $header_vdo + $stat_vdo + $product_vdo + $cable_vdo

```

```

    }
call PD_SendPacket_Cable( $discover_identity_response, $send_setting )

```

## 4.3 Pd\_SendErroneousChunks

Applicable to PD Rev 3.0 only. Sends packet chunks towards the UUT and has the ability to skip sending some packet chunks. User may set the `$PdGlobalSettings.UnchunkedSupport` (refer to [PD\\_Set](#)) setting to `PD_FALSE` before calling this function.

### Format

```
Pd_SendErroneousChunks( Pd_Packet $SentPacket, PD_SendErrChunksSettings  
$SendErrChunksSettings )
```

### Parameters

`$send_packet`

Defines the payload. Refer to [Packet Templates](#) for available packet templates.

`$SendErrChunksSettings`

It should be inherited from `PD_SendErrChunksSettings` template. It includes all the fields of `PD_SendPacketSettings` (refer to [PD\\_SendPacket](#)) packet template but the default value for `RetryCount` field is `PD_DEFAULT_RETRY_COUNT_REV_3`. Following are additional fields of `PD_SendErrChunksSettings` packet template:

Field Name	Default Values	Description
<code>SkipSendChunkIndex</code>	<code>PD_INVALID_VALUE</code>	Indicates from which chunk number the function should stop sending chunks.

### Result

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

Value	Description
<code>PD_RESULT_OK</code>	Command succeeded
<code>PD_RESULT_FAILED</code>	Command failed
<code>PD_SUBRESULT_NO_GOODCRC</code>	Subresult - No GoodCRC received for sent packet
<code>PD_SUBRESULT_HARDRESET</code>	Subresult - HardReset occurred.
<code>PD_SUBRESULT_SOFTRESET</code>	Subresult - SoftReset occurred.

### Examples

```

Packet TempExtendedPacket : Pd_Packet
{
    : Pd_MessageHeader
    : Pd_ExtendedMsgHeader
    : Pd_GenericPacket

    Extended = 1
}

Main
{
    :
    :
    :

    Pd_Set $PdGlobalSettings.UnchunkedSupport = PD_FALSE

    local $ErrChunkSettings = PD_SendErrChunksSettings
    {
        SkipSendChunkIndex = 4
    }

    local $SentPacket = TempExtendedPacket

```

```

{
    MessageType = _00011111
    DataSize    = 260
    Data = { 00 01 02 03 }
}
call Pd_SendErroneousChunks($SentPacket, $ErrChunkSettings)
:
:
}

```

## 4.4 PD\_SendCorruptedPacket

Sends a packet towards the Unit Under Test which is corrupted intentionally.

### Format

```
Call PD_SendCorruptedPacket( PD_Packet $send_payload,
                            PD_SendCorruptedPacketSettings $send_settings )
```

### Parameters

#### \$send\_payload

The payload to be sent. Refer to [Packet Templates](#) for available packet templates.

#### \$send\_settings

Settings for sending the corrupted payload. Setting type is `PD_SendCorruptedPacketSettings`:

Field Name	Possible/Default Values	Description
<code>PreambleBitLen</code>	0x40(default)	Indicates the length of Preamble in bit.
<code>NoPreamble</code>	PD_TRUE PD_FALSE(default)	Indicates whether to insert the Preamble or not.
<code>OrderedsetType</code>	PD_ORDERED_SET_TYPE_SOP(default), PD_ORDERED_SET_TYPE_SOP_PRIME, PD_ORDERED_SET_TYPE_SOP_DOUBLE_PRIME, PD_ORDERED_SET_TYPE_SOP_PRIME_DEBUG, PD_ORDERED_SET_TYPE_SOP_DOUBLE_PRIME_DEBUG, PD_ORDERED_SET_TYPE_HARDRESET, PD_ORDERED_SET_TYPE_CABLERESET, PD_ORDERED_SET_TYPE_INVALID	Indicates the ordered-set type.
<code>CorruptedOrderedset</code>	PD_TRUE PD_FALSE(default)	If <code>OrderedsetType</code> field is <code>PD_ORDERED_SET_TYPE_INVALID</code> then content of this field will be replaced with ordered-set in the sent packet.
<code>NoCrc</code>	PD_TRUE PD_FALSE(default)	Indicates whether to insert Crc in the packet or not.
<code>CorruptCrc4b</code>	PD_TRUE PD_FALSE(default)	Indicates whether to corrupt Crc before 5-bit encoding or not.
<code>CorruptCrc5b</code>	PD_TRUE PD_FALSE(default)	Indicates whether to corrupt Crc after 5-bit encoding or not.
<code>CorruptCrc4bBitOffset</code>	0x00(default)	Indicates the bit offset (starting from 0) of 4-bit encoded Crc data to be corrupted. This field will be processed if <code>CorruptCrc4b</code> is <code>PD_TRUE</code> .
<code>CorruptCrc4bBitLen</code>	0x00(default)	Indicates the length of corrupted Crc value which will be injected into Crc before 4-bit encoding. Will be processed if <code>CorruptCrc4b</code> is <code>PD_TRUE</code> .
<code>CorruptCrc5bBitOffset</code>	0x00(default)	Indicates the bit offset (starting from 0) of 5-bit encoded Crc data to be corrupted. This

		field will be processed if <code>CorruptCrc5b</code> is <code>PD_TRUE</code> .
<code>CorruptCrc5bBitLen</code>	0x00(default)	Indicates the length of corrupted Crc value which will be injected into Crc after 5-bit encoding. Will be processed if <code>CorruptCrc5b</code> is <code>PD_TRUE</code> .
<code>CorruptCrc4bValue</code>	0x00(default)	Byte stream. Indicates the value to be replaced with Crc before 4-bit encoding value from <code>CorruptCrc4bBitOffset</code> with length of <code>CorruptCrc4bBitLen</code> . Will be processed if <code>CorruptCrc4b</code> is <code>PD_TRUE</code> .
<code>CorruptCrc5bValue</code>	0x00(default)	Byte stream. Indicates the value to be replaced with Crc after 5-bit encoding value from <code>CorruptCrc5bBitOffset</code> with length of <code>CorruptCrc5bBitLen</code> . Will be processed if <code>CorruptCrc5b</code> is <code>PD_TRUE</code> .
<code>CorruptPayload4b</code>	<code>PD_TRUE</code> <code>PD_FALSE</code> (default)	Indicates whether to corrupt Payload before 5-bit encoding or not.
<code>CorruptPayload5b</code>	<code>PD_TRUE</code> <code>PD_FALSE</code> (default)	Indicates whether to corrupt Payload after 5-bit encoding or not.
<code>CorruptPayload4bBitOffset</code>	0x00(default)	Indicates the bit offset of Payload (before 5-bit encoding) to get as the first data bit being corrupted (e.g. bit offset <code>0x08</code> means: get the Payload data corrupted starting from offset <code>0x08</code> ). This field will be processed if <code>CorruptPayload4b</code> is <code>PD_TRUE</code> .
<code>CorruptPaylaod4bBitLen</code>	0x00(default)	Indicates the bit length of Payload (before 5-bit encoding) to get corrupted.(e.g. bit length <code>0x03</code> means: corrupt Payload( before 5-bit encoding) starting from <code>CorruptPayload4bBitOffset</code> and length of <code>0x03</code> bits). This field will be processed if <code>CorruptPayload4b</code> is <code>PD_TRUE</code> .
<code>CorruptPaylaod4bValue</code>	0x00(default)	Byte stream. Defines the value to be replaced with the Payload (before 5-bit encoding) data. The offset and length of replacing data should be defined using <code>CorruptPayload4bBitOffset</code> and <code>CorruptPaylaod4bBitLen</code> fields. This field will be processed if <code>CorruptPayload4b</code> field is <code>PD_TRUE</code> .
<code>CorruptPyload5bBitOffset</code>	0x00(default)	Indicates the bit offset of Payload (after 5-bit encoding) to get as the first data bit being corrupted (e.g. bit offset <code>0x08</code> means: get the Payload data corrupted starting from offset <code>0x08</code> ). This field will be processed if <code>CorruptPayload5b</code> field is <code>PD_TRUE</code> .
<code>CorruptPyload5bBitLen</code>	0x00(default)	Indicates the bit length of Payload (after 5-bit encoding) to get corrupted.(e.g. bit length <code>0x03</code> means: corrupt Payload( after 5-bit encoding) starting from <code>CorruptPyload5bBitOffset</code> and length of <code>0x03</code> bits).This field will be processed if <code>CorruptPayload5b</code> field is <code>PD_TRUE</code> .
<code>CorruptPyload5bValue</code>	0x00(default)	Byte stream. Defines the value to be replaced with the Payload (after 5-bit encoding) data. The offset and length of replacing data should be defined using <code>CorruptPyload5bBitOffset</code> and <code>CorruptPyload5bBitLen</code> fields. Will be processed if <code>CorruptPayload5b</code> field is <code>PD_TRUE</code> .

NoEop	PD_TRUE PD_FALSE(default)	Indicates whether to insert EOP in the packet or not.
CorruptEop	PD_TRUE PD_FALSE(default)	Indicates whether to corrupt EOP in the packet or not
CorruptedEopSymbol	0x00(default)	Corrupted EOP symbol to be replaced with EOP in the packet. This field will be processed if CorruptEop field is PD_TRUE.
OperationType	PD_CORRUPT_OPERATION_TYPE_CUSTOM_VALUE(default) PD_CORRUPT_OPERATION_TYPE_FLIP_ALL_BITS PD_CORRUPT_OPERATION_TYPE_INCREMENT_MSG_ID	Defines the operation type which will be applied. Only one operation type can be chosen at a time.  Default operation which is PD_CORRUPT_OPERATION_TYPE_CUSTOM_VALUE will be replacing data from the specified offset for specified length.  PD_CORRUPT_OPERATION_TYPE_FLIP_ALL_BITS will be flipping all the bits in between the specified offset to the specified length.  PD_CORRUPT_OPERATION_TYPE_INCREMENT_MSG_ID will be incrementing MsgID of the \$send_message

## Result

None

### Examples

```
$GetSinkCapsPacket = PD_GetSinkCapMessage
{
    PortPowerRole_CablePlug = 1
}
$corrupted_send_settings = PD_SendCorruptedPacketSettings
{
    CorruptCrc4b = PD_TRUE
}
call PD_SendCorruptedPacket($GetSinkCapsPacket, $corrupted_send_settings)
```

## 4.5 PD\_ReceivePacket

Receives a packet from device. You can specify the packet type using its settings.

### Format

```
Call PD_ReceivePacket( PD_ReceivePacketSettings $receive_Settings )
```

### Parameters

\$receive\_Settings

Settings for receiving packet. The structure type should be PD\_ReceivePacketSettings.

Table below shows this structure in detail:

Field Name	Possible/Default Values	Description
OrderedSetType	PD_ORDERED_SET_TYPE_SOP(default) PD_ORDERED_SET_TYPE_SOP_PRIME PD_ORDERED_SET_TYPE_SOP_DOUBLE_PRIME PD_ORDERED_SET_TYPE_HARDRESET PD_ORDERED_SET_TYPE_CABLERESET	Ordered set type for receiving message.
PacketType	PD_MESSAGE_TYPE_ANY(default) PD_MESSAGE_TYPE_GOODCRC	Message type to receive.

	PD_MESSAGE_TYPE_GOTO_MIN PD_MESSAGE_TYPE_ACCEPT PD_MESSAGE_TYPE_REJECT PD_MESSAGE_TYPE_PING PD_MESSAGE_TYPE_PS_RDY PD_MESSAGE_TYPE_GET_SOURCE_CAP PD_MESSAGE_TYPE_GET_SINK_CAP PD_MESSAGE_TYPE_DR_SWAP PD_MESSAGE_TYPE_PR_SWAP PD_MESSAGE_TYPE_VCONN_SWAP PD_MESSAGE_TYPE_WAIT PD_MESSAGE_TYPE_SOFT_RESET PD_MESSAGE_TYPE_HARD_RESET PD_MESSAGE_TYPE_CABLE_RESET PD_MESSAGE_TYPE_NOT_SUPPORTED PD_MESSAGE_TYPE_GET_SRC_CAP_EXT PD_MESSAGE_TYPE_GET_STATUS PD_MESSAGE_TYPE_FR_SWAP PD_MESSAGE_TYPE_GET_PPS_STATUS PD_MESSAGE_TYPE_GET_COUNTRY_CODES PD_MESSAGE_TYPE_GET_SNK_CAP_EXT PD_MESSAGE_TYPE_SOURCE_CAP PD_MESSAGE_TYPE_REQUEST PD_MESSAGE_TYPE_BIST PD_MESSAGE_TYPE_SINK_CAP PD_MESSAGE_TYPE_BATTERY_STATUS PD_MESSAGE_TYPE_ALERT PD_MESSAGE_TYPE_GET_COUNTRY_INFO PD_MESSAGE_TYPE_VDM PD_MESSAGE_TYPE_SRC_CAP_EXT PD_MESSAGE_TYPE_STATUS PD_MESSAGE_TYPE_GET_BATTERY_CAP PD_MESSAGE_TYPE_GET_BATTERY_STATUS PD_MESSAGE_TYPE_BATTERY_CAP PD_MESSAGE_TYPE_GET_MANUFACTURER_INFO PD_MESSAGE_TYPE_MANUFACTURER_INFO PD_MESSAGE_TYPE_SECURITY_REQUEST PD_MESSAGE_TYPE_SECURITY_RESPONSE PD_MESSAGE_TYPE_PPS_STATUS PD_MESSAGE_TYPE_COUNTRY_INFO PD_MESSAGE_TYPE_COUNTRY_CODES PD_MESSAGE_TYPE_SNK_CAP_EXT	
VdmCommand	PD_VDM_COMMAND_ANY(default) PD_VDM_COMMAND_DISCOVER_IDENTITY PD_VDM_COMMAND_DISCOVER_SVIDS PD_VDM_COMMAND_DISCOVER_MODES PD_VDM_COMMAND_ENTER_MODE PD_VDM_COMMAND_EXIT_MODE PD_VDM_COMMAND_DISPLAYPORT_STATUS_UPDATE PD_VDM_COMMAND_DISPLAYPORT_CONFIGURE PD_VDM_COMMAND_ATTENTION	VDM command.
VdmCommandType	PD_VDM_COMMAND_TYPE_INITIATOR(default) PD_VDM_COMMAND_TYPE_RESPONDER_ACK PD_VDM_COMMAND_TYPE_RESPONDER_NAK PD_VDM_COMMAND_TYPE_RESPONDER_BUSY PD_VDM_COMMAND_TYPE_ANY	VDM command type.
AutoGoodCrc	PD_TRUE(default) PD_FALSE	Send GoodCrc on receiving a message, automatically.
DelayBeforeGoodCrc	0(default) Or other user defined value.	Delay before sending GoodCrc message.
WaitTimeOut	PD_DEFAULT_TIMEOUT_SENDER_RESPONSE(default) PD_DEFAULT_TIMEOUT_INFINITE Or other user defined value.	Receive timeout(micro second).
DiscardPrevReceived	PD_TRUE PD_FALSE(default)	Discards any (unprocessed) packet received before calling PD_ReceivePacket function.
ReturnOnUnexpectedPkt	PD_TRUE PD_FALSE(default)	If set to PD_TRUE, cause PD_ReceivePacket() function to return on receiving unexpected packet.
NoSoftResetResponse	PD_TRUE PD_FALSE(default)	If set to PD_TRUE, the PD_ReceivePacket() function will not respond to any received Soft_Resets.
NoHardResetResponse	PD_TRUE PD_FALSE(default)	If set to PD_TRUE, the PD_ReceivePacket() function will not respond to any received Hard_Resets.

## Result

User can evaluate the command results(including sub-results) using IfMatched/ElseMatched command.

List of result values:

Result Value	Description
PD_RESULT_OK	Command succeeded
PD_RESULT_FAILED	Command failed
PD_SUBRESULT_RECEIVE_TIMEOUT	Subresult - No packet received within specified time
PD_SUBRESULT_UNEXPECTED_MSG RECEIVED	Subresult - Unexpected packet received
PD_SUBRESULT_HARDRESET	Subresult - HardReset received
PD_SUBRESULT_SOFTRESET	Subresult - SoftReset received

## Examples

```
#Receive source caps
#####
# Wait to receive source capability. GoodCRC is sent automatically.
$recv_settings = PD_ReceivePacketSettings
{
    WaitTimeOut = PD_DEFAULT_TIMEOUT_INFINITE
    PacketType = PD_MESSAGE_TYPE_SOURCE_CAP
}
call PD_ReceivePacket($recv_settings)

#Receive VDM message
#####
$receive_settings = PD_ReceivePacketSettings
{
    PacketType = PD_MESSAGE_TYPE_VDM
}
call PD_ReceivePacket( $receive_settings )
```

## 4.6 PD\_SendSoftReset

Sends Soft Reset and performs the reset according to the selected Ordered-Set Type.

### Format

```
call PD_SendSoftReset( orderedset_type )
```

### Parameters

orderedset\_type

Possible values:

```
PD_ORDERED_SET_TYPE_SOP
PD_ORDERED_SET_TYPE_SOP_PRIME
PD_ORDERED_SET_TYPE_SOP_DOUBLE_PRIME
```

## Result

User can evaluate the command results(including sub-results) using IfMatched/ElseMatched command.

If sending SoftReset succeeded the result is PD\_RESULT\_OK. In case of failure it may lead to Power Negotiation.

## Examples

```
call PD_SendSoftReset( PD_ORDERED_SET_TYPE_SOP )
```

## 4.7 PD\_SendHardReset

Sends Hard Reset and performs the reset.

### Format

```
Call PD_SendHardReset()
```

### Parameters

None

### Result

None

### Examples

```
Call PD_SendHardReset()
```

## 4.8 PD\_SendCableReset

Sends Cable Reset and resets all the cable related states in protocol layer.

### Format

```
Call PD_SendCableReset()
```

### Parameters

None

### Result

None

### Examples

```
Call PD_SendCableReset()
```

## 4.9 PD\_DelayNoAutoResponse

Delays Exerciser execution for specified time.

### Format

```
Call PD_DelayNoAutoResponse( Micro_Sec )
```

### Parameters

#### Micro\_Sec

Delay in micro seconds.

### Result

None

### Examples

```
#calling PD_DelayNoAutoResponse  
Call PD_DelayNoAutoResponse(15000)
```

## 4.10 PD\_Delay

Delays Exerciser execution for specified time.

### Format

```
Call PD_Delay( delay_value )
```

### Parameters

**delay\_value**

Delay in micro seconds.

### Result

None

### Examples

```
#calling PD_Delay  
Call PD_Delay(15000)
```

## 4.11 PD\_SetRoles

Sets data role and power role of Exerciser.

### Format

```
Call PD_SetRoles( DataRole, PowerRole )
```

### Parameters

**DataRole**

Possible values:

PD\_PORT\_DATA\_ROLE\_UFP  
PD\_PORT\_DATA\_ROLE\_DFP

**PowerRole**

Possible values:

PD\_PORT\_POWER\_ROLE\_SINK  
PD\_PORT\_POWER\_ROLE\_SOURCE

### Examples

```
Call PD_SetRoles( PD_PORT_DATA_ROLE_DFP, PD_PORT_POWER_ROLE_SOURCE )
```

## 4.12 PD\_Set

Using this command you can change necessary settings or variables inside the Exerciser.

### Format

```
PD_Set $PdGlobalSettings.<field_name> = <value>  
PD_Set $PdTimers.<field_name> = <value>
```

### Parameters

List of \$PdGlobalSettings fields:

Field Name	Possible/Default Values	Description
PortDataRole	PD_PORT_DATA_ROLE_DFP PD_PORT_DATA_ROLE_UFP(default)	Defines port data role.
PortPowerRole	PD_PORT_POWER_ROLE_SINK(defau lt) PD_PORT_POWER_ROLE_SOURCE	Defines port power role.
CheckMessageId	PD_FALSE(Default) PD_TRUE	Enables/Disables received packet message id verification.
SpecificationRevision	PD_SPEC_REVISION_1 PD_SPEC_REVISION_2(Default) PD_SPEC_REVISION_3 Or any user defined value.	Changes the SpecificationRevision of all messages sent by the Exerciser.  <b>Note 1 (Rev.3.0 or higher, all messages except non-SOP messages which are sent by PD Exerciser to a cable plug):</b> This setting will be applied only if the AutoSpecRev setting of <a href="#">PD_SetNegotiationSetting_Source</a> (PD Exerciser operating as Source) or <a href="#">PD_SetNegotiationSetting_Sink</a> (PD Exerciser operating as Sink) has been set to PD_FALSE.  <b>Note 2:</b> To set the Specification Revision of GoodCrc messages which are sent by PD Exerciser, refer to <i>AutoGoodCRCSpecRev</i> and <i>GoodCRCSpecRev</i> global settings.
EnableCableEmulator	PD_FALSE(default) PD_TRUE	Enables/Disables SOP Cable Emulator engine in Exerciser. If enabled, the Exerciser simulates a SOP Prime Marked Cable as well as source or sink PD Device. <i>It should be set only once in the target Exerciser Script.</i>
EnableCableDPrimeEmulator	PD_FALSE (default) PD_TRUE	Enables/Disables SOP Double Prime Cable Emulator engine in Exerciser. If enabled, the Exerciser simulates a SOP Double Prime Marked Cable as well as source or sink PD Device. <i>It should be set only once in the target Exerciser Script.</i>
EnableDeviceEmulator	PD_FALSE, PD_TRUE(default)	If disabled, Device Emulator AutoResponse will be disabled (in case of Exerciser acting as a Sink or Source device).
NegotiateAfterReset	PD_FALSE, PD_TRUE (default)	If set to PD_TRUE, then the Exerciser will run Negotiation after receiving/sending SoftReset or HardReset.
VConnPassThrough	PD_FALSE(default), PD_TRUE	Indicates whether the Exerciser is connected to the DUT using a VConn Pass Through cable or not.
PDWorkingRevision	PD_SPEC_REVISION_2(default) PD_SPEC_REVISION_3	Sets the Power Delivery working revision. <i>It should be set only once in the target Exerciser Script.</i> Its recommended to change this setting using <a href="#">PD_SetWorkingRevision</a> high-level function.
UnchunkedSupport	PD_FALSE, PD_TRUE (default)	Indicates whether to support sending unchunked messages or not.
StructuredVDMVersion	PD_INVALID_VALUE(default) Or any user defined value.	Indicates the VDM version of structured VDM messages. If the value is PD_INVALID_VALUE then the Exerciser assigns the proper value for structured VDM version according to current operational Power Delivery Revision.
VConnThroughConnectCCLine	CC_LINE_1 (default) CC_LINE_2	Indicates the desired CC line which makes the PD Exerciser to try to establish the Type-C connection on this CC line. This setting is

		only applicable when the cable is a VConnPassThrough cable.
FRSwapSupport	PD_TRUE (default) PD_FALSE	Applies only if the run-time working revision is Rev.3.0 or higher. Indicates whether the Fast Role Swap is supported by Pd Exerciser engine or not.
AutoGoodCRCSpecRev	PD_TRUE (default) PD_FALSE	If set to PD_TRUE, proper Specification Revision will be set in each GoodCRC message sent to peer port (SOP or non-SOP) depending on the run-time working revision and whether the PD Exerciser is operating as Cable Emulator or not. Otherwise the value of \$PdGlobalSettings.GoodCRCSpecRev will be used.
GoodCRCSpecRev	PD_SPEC_REVISION_1 (default) PD_SPEC_REVISION_2 PD_SPEC_REVISION_3	If \$PdGlobalSettings.AutoGoodCRCSpecRev is PD_FALSE, then this value will be used as Specification revision of all GoodCRC messages sent by PD Exerciser.
InitiateAMS	PD_TRUE (default) PD_FALSE	Applies If the run-time working revision is Rev.3.0 or higher. If set to PD_TRUE, then the PD Exerciser will always check for SinkTxNG and SinkTxOk values, regarding to its current role as Source or Sink, before starting an AMS.
SpecificationRevisionToCable	PD_SPEC_REVISION_1 PD_SPEC_REVISION_2 PD_SPEC_REVISION_3 (default)	Applies if the run-time working revision is Rev.3.0 or higher. If AutoSpecRevCable setting of <b>PD_SetDiscoverIdentitySetting</b> has been set to PD_FALSE, then this value will be used as Specification Revision of all non-SOP messages which are sent by PD Exerciser to cable plug.
DisableVBusOn	PD_TRUE PD_FALSE (default)	If set to PD_TRUE, then PD Exerciser will not turn the VBus on.
CheckBatteryRef	PD_TRUE (default) PD_FALSE	Applies if the run-time working revision is Rev.3.0 or higher. If set to PD_TRUE, then PD Exerciser will check the Battery Reference received by Get_Battery_Status, Alert, Get_Battery_Cap and Manufacturer_info messages with the number of batteries defined by PD Exerciser (using the <b>PD_SetSrcCapExtDataBlock</b> command) and replies with a proper message.
CheckCountryCode	PD_TRUE (default) PD_FALSE	Applies if the run-time working revision is Rev.3.0 or higher. If set to PD_TRUE, then PD Exerciser will check the Country Codes received by Get_Country_info message with the available country codes which has been added using the <b>Pd_SetCountryCodesDataBlock</b> function and replies with a proper message.  <b>Note:</b> PD Exerciser checks the received country codes with only the first 15 country codes which has been added by <b>Pd_SetCountryCodesDataBlock</b> function.
ChangeHWSettingDelay	5000(default)	Indicates how much delay (in micro seconds) is needed to apply after changing any Hardware Setting (e.g. changing Rp/Rd/Ra resistors or inserting/removing a capacitor etc.).

SetVbusDelay	20000(default)	Indicates how much delay (in micro seconds) is needed to apply after changing the VBus state.
--------------	----------------	---

List of \$PdTimers fields(for detailed description refer to Power Delivery Specification):

Field Name	Description
tTypeCSinkWaitCap	Default: 620000 us
tTypeCSendSourceCap	Default: 150000 us
tPSTransition	Default: 550000 us
tPSSourceOff	Default: 920000 us
tPSSourceOn	Default: 480000 us
tSrcTransition	Default: 25000 us
tDiscoverIdentity	Default: 45000 us
tSafe0V	Default: 650000 us
tSafe5V	Default: 275000 us
tPSHardResetMin	Default: 25000 us
tPSHardResetMax	Default: 35000 us
tPSHardReset	Default: 30000 us
tSrcRecoverMin	Default: 660000 us
tSrcRecoverMax	Default: 1000000 us
tSrcRecover	Default: 1000000 us
tReceive	Default: 1100 us
tVCONNstable	Default: 50000 us
tVCONNSourceOff	Default: 25000 us
tVCONNSourceOn	Default: 50000 us
tVCONNSourceTimeout	Default: 200000 us
tVCONNSourceTimeoutMin	Default: 100000 us
tVCONNSourceTimeoutMax	Default: 200000 us
tSenderResponse	Default: 30000 us
tBISTContMode	Default: 60000 us
tVDMBusy	Default: 50000 us
tVDMWaitModeEntry	Default: 50000 us
tVDMWaitModeExit	Default: 50000 us
tSwapSourceStart	Default: 20000 us
tSrcSwapStdbyMax	Default: 650000 us
tNewSrcMax	Default: 275000 us
tDRP	Default: 80000 us
dcSRC_DRP	Default: 50(time percent)
tCCDebounce	Default: 100000 us
tCCDebounceMin	Default: 100000 us
tCCDebounceMax	Default: 200000 us
tDRPTry	Default: 75000 us
tDRPTryMin	Default: 75000 us
tDRPTryMax	Default: 150000 us
tDRPTryWait	Default: 400000 us
tDRPTryWaitMin	Default: 400000 us
tDRPTryWaitMax	Default: 800000 us
tPDDebounce	Default: 10000 us
tPDDebounceMin	Default: 10000 us
tPDDebounceMax	Default: 20000 us
tTryCCDebounce	Default: 20000 us
tTryTimeout	Default: 1100000 us
tSinkTx	Default: 18000 us
tFRSwapTx	Default: 110 us
tFRSwapInitMax	Default: 15000 us
tFRSwapInitMin	Default: 500 us
tFRSwapComplete	Default: 0 us
tFRSwap5V	Default: 0 us
tErrorRecovery	Default: 25000 us
tChunkSenderResponse	Default: 30000 us

tChunkingNotSupported	Default: 50000 us
-----------------------	-------------------

## Result

None

## Examples

```
# Enables cable emulator
PD_Set $PdGLOBALSETTINGS.EnableCableEmulator = PD_TRUE

Main
{
    # Sets GoodCRC timeout
    PD_Set $PdTimers.tReceive = 950
    Call PD_WaitForDiscoverIdentity_Cable()
}
```

## 4.13 IfMatched/ElseMatched

Compares Exerciser settings, Received Packet Fields and Command Results to a desired value.

Using this command you can compare Exerciser settings or variables to other Exerciser settings or variables or to a constant.

## Format

```
Ifmatched(<1st_operand>, <2nd_operand>, <operator>)
{
    #command list
}
[
ElseMatched(<1st_operand>, <2nd_operand>, <operator>)
{
    #command list
}
#more optional ElseMatched(<1st_operand>, <2nd_operand>, <operator>) here
.
.
.
ElseMatched
{
    #command list
}
]
IfMatchedEnd

* ElseMatched clause is optional
```

## Parameters

### 1st\_operand

1st operand should be in one of the following formats:

\$Pdglobalsettings.<field\_name>

\$PdResult.<field\_name>  
\$<packet\_variable>.<field\_name>

List of \$PdResult fields:

Field Name	Description
<a href="#">Result</a>	Last executed command result
<a href="#">Subresult</a>	Last executed command subresult (in case of failure, this field describes the reason)
<a href="#">LastReceivedPacketOrderedSet</a>	Last received packet ordered set type
<a href="#">LastReceivedPacketType</a>	Last received packet type
<a href="#">LastReceivedPacketPowerRole</a>	Last received packet power role field value
<a href="#">LastReceivedPacketDataRole</a>	Last received packet data role field value
<a href="#">LastReceivedPacketSentToCable</a>	Indicates whether the last received packet has been sent to cable(packet towards the cable) or not
<a href="#">LastReceivedPacketMsgID</a>	Last received packet MessageId field value
<a href="#">LastReceivedPacketVdmCommand</a>	Last received packet VDM command value, if the packet is VDM packet
<a href="#">LastReceivedPacketVdmCommandType</a>	Last received packet VDM command type value, if the packet is VDM packet
<a href="#">LastReceivedPacketVdmSVID</a>	Last received packet SVID, if the packet is a VDM packet
<a href="#">LastReceivedPacketVdmObjPos</a>	Last received packet ObjectPosition, if the packet is a VDM packet
<a href="#">LastSelectedCapIndex</a>	Last received packet selected capability index, if the packet is Request message
<a href="#">LastRequestHasMismatch</a>	Last received packet HasMismatch field value, if the packet is Request message
<a href="#">ExplicitContract</a>	Indicates whether explicit contract is established or not.
<a href="#">LastReceivedUnchunkedSupport</a>	Indicates whether the UUT supports Unchunked messages or not. Applicable to PD Rev3.0 only.
<a href="#">DataRoleSwapped</a>	Indicates whether the DataRole swapped or not comparing to the initial value of PD Exerciser DataRole.
<a href="#">PowerRoleSwapped</a>	Indicates whether the PowerRole swapped or not comparing to the initial value of PD Exerciser PowerRole.

For available \$PdGlobalSettings fields refer to [PD\\_Set](#).

## 2nd\_operand

It could be as <1st\_operand> or a constant <value>.

## operator

List of possible values for operator:

```
PD_COMPARE_EQUAL
PD_COMPARE_GREATER
PD_COMPARE_LESS
PD_COMPARE_NOT_EQUAL
```

## Result

None

## Examples

```
$send_setting = PD_SendPacketSettings
{
    ResetOnError = PD_FALSE
    OrderedSetType = PD_ORDERED_SET_TYPE_SOP
}
$receive_settings = PD_ReceivePacketSettings
{
    PacketType = PD_MESSAGE_TYPE_VDM
}
#send the packet
$discover_identity = PD_VDM_Discover_Identity_Message
Call PD_SendPacket( $discover_identity, $send_setting )

#check for result
```

```

IfMatched( $PdResult.Result, PD_RESULT_OK, PD_COMPARE_EQUAL )
{
    Call PD_ReceivePacket( $receive_settings )
}
ElseMatched( $PdResult.Result, PD_RESULT_FAILED, PD_COMPARE_EQUAL )
{
    Call PD_SendHardReset()
}
ElseMatched
{
    $ping_msg = PD_PingMessage
    Call PD_SendPacket( $ping_msg, $send_setting )
}
IfMatchedEnd

```

## 4.14 PD\_Loop

Using this command you can create a loop containing other Exerciser commands.

**Note** - The limit for using nested `PD_Loop()` commands is 8.

### Format

```

PD_Loop(count)
{
    #command list
}

```

### Parameters

**count**  
Loop count

### Result

None

### Examples

```

$send_setting = PD_SendPacketSettings
{
    OrderedSetType = PD_ORDERED_SET_TYPE_SOP
}
$ping_msg = PD_PingMessage
PD_Loop(3)
{
    call PD_SendPacket( $ping_msg, $send_setting )
}

```

## 4.15 PD\_TimerLoop

Using this command you can create a loop(containing other Exerciser commands) which is bound to a predefined timer. On timer timeout, the loop will exit.

**Note** - The limit for using nested `PD_TimerLoop()` commands is 8.

### Format

```

PD_TimerLoop(timeout)
{
    #command list
}

```

### Parameters

**timeout**  
Loop duration in Micro Seconds.

### Result

None

### Examples

```
$send_setting = PD_SendPacketSettings
{
    OrderedSetType = PD_ORDERED_SET_TYPE_SOP
}
$ping_msg = PD_PingMessage
# Sending Ping message for 200ms
PD_TimerLoop(200000)
{
    call PD_SendPacket( $ping_msg, $send_setting )
}
```

## 4.16 PD\_Stop

Stops the Exerciser.

### Format

```
call PD_Stop( return_value )
```

### Parameters

**return\_value**

Value returned to Exerciser.

### Result

None

### Examples

```
call PD_Stop(0)
```

## 4.17 PD\_Disconnect

Simulates cable detach.

### Format

```
call PD_Disconnect()
```

### Parameters

None

### Result

None

### Examples

```
call PD_Disconnect()
```

## **4.18 PD\_StartUSBExerciser**

Starts specified Exercisers which are waiting for PD Exerciser's permission.

### **Format**

```
Call PD_StartUSBExerciser( ExercisersTypes )
```

### **Parameters**

#### **ExercisersTypes**

Possible values:

```
PD_USB2_EXERCISER  
PD_USB3_EXERCISER  
PD_USB4_EXERCISER  
PD_TBT3_EXERCISER
```

### **Result**

None

### **Examples**

```
Call PD_StartUSBExerciser( PD_USB2_EXERCISER | PD_USB3_EXERCISER )
```

## **4.19 PD\_RunUSB3TermDetection**

Directs the Exerciser to actively perform USB 3 Rx Termination detection. A TERM State (Report) event will be displayed in the trace.

**NOTE:** This command is state agnostic. Performing Rx Termination detection in certain states could interfere with SS communication and result in unexpected link behavior.

### **Format**

```
Call PD_RunUSB3TermDetection()
```

### **Parameters**

None

### **Result**

None

### **Examples**

```
Call PD_RunUSB3TermDetection()
```

## **4.20 PD\_ResumeUSB2Exerciser**

Resumes USB2 Exerciser execution paused by Break command.

### **Format**

```
Call PD_ResumeUSB2Exerciser()
```

### **Parameters**

None

### Result

None

### Examples

```
Call PD_ResumeUSB2Exerciser()
```

## 4.21 PD\_ReportUSB3TermStatus

Reports the last-known USB 3 Rx Termination status, typically from when the Exerciser was most recently in eSS.Inactive, Rx.Detect, U2, or U3. A TERM State (Report) event will be displayed in the trace.

### Format

```
Call PD_ReportUSB3TermStatus()
```

### Parameters

None

### Result

None

### Examples

```
Call PD_ReportUSB3TermStatus()
```

## 4.22 PD\_IncreaseMsgId

Increase Message ID(Exerciser mode: DFP/UFP).

### Format

```
Call PD_IncreaseMsgId(OrderedSetType)
```

### Parameters

#### OrderedSetType

Indicates the OrderedSet type. Possible values:

```
PD_ORDERED_SET_TYPE_SOP  
PD_ORDERED_SET_TYPE_SOP_PRIME  
PD_ORDERED_SET_TYPE_SOP_DOUBLE_PRIME
```

### Result

None

### Examples

```
Call PD_IncreaseMsgId(PD_ORDERED_SET_TYPE_SOP)
```

## 4.23 PD\_DecreaseMsgId

Decrease Message ID(Exerciser mode: DFP/UFP).

## **Format**

```
Call PD_DecreaseMsgId(OrderedSetType)
```

## **Parameters**

### **OrderedSetType**

Indicates the OrderedSet type. Possible values:

```
PD_ORDERED_SET_TYPE_SOP  
PD_ORDERED_SET_TYPE_SOP_PRIME  
PD_ORDERED_SET_TYPE_SOP_DOUBLE_PRIME
```

## **Result**

None

## **Examples**

```
Call PD_DecreaseMsgId(PD_ORDERED_SET_TYPE_SOP)
```

## **4.24 PD\_IncreaseMsgId\_Cable**

Increase Message ID(Exerciser mode: Cable Emulator).

## **Format**

```
Call PD_IncreaseMsgId_Cable(OrderedSetType)
```

## **Parameters**

### **OrderedSetType**

Indicates the OrderedSet type. Possible values:

```
PD_ORDERED_SET_TYPE_SOP_PRIME  
PD_ORDERED_SET_TYPE_SOP_DOUBLE_PRIME
```

## **Result**

None

## **Examples**

```
Call PD_IncreaseMsgId_Cable(PD_ORDERED_SET_TYPE_SOP_PRIME)
```

## **4.25 PD\_DecreaseMsgId\_Cable**

Decrease Message ID(Exerciser mode: Cable Emulator).

## **Format**

```
Call PD_DecreaseMsgId_Cable(OrderedSetType)
```

## **Parameters**

### **OrderedSetType**

Indicates the OrderedSet type. Possible values:

```
PD_ORDERED_SET_TYPE_SOP_PRIME  
PD_ORDERED_SET_TYPE_SOP_DOUBLE_PRIME
```

### **Result**

None

### **Examples**

```
call PD_DecreaseMsgId_Cable(PD_ORDERED_SET_TYPE_SOP_PRIME)
```

## **4.26 PD\_SendExternalTriggerOut**

Sends the external trigger out.

### **Format**

```
call PD_SendExternalTriggerOut()
```

### **Parameters**

None

### **Result**

None

### **Examples**

```
call PD_SendExternalTriggerout()
```

## 5 Transaction Engine™

Power Delivery Transaction Engine™ includes high level commands and auto response capability.

### 5.1 High Level Commands

#### 5.1.1 PD\_SetWorkingRevision

Sets the Exerciser working revision along with Specification Revision. It should call once in whole Exerciser script. The default working revision is `PD_SPEC_REVISION_2`.

##### Format

```
Call PD_SetWorkingRevision( revision )
```

##### Parameters

`revision`

Indicates the target revision.

Possible values:

```
PD_SPEC_REVISION_2(default),  
PD_SPEC_REVISION_3
```

##### Result

None

##### Examples

```
Call PD_SetWorkingRevision( PD_SPEC_REVISION_3 )
```

#### 5.1.2 PD\_SetNegotiationSetting\_Source

Applies settings to power negotiation related commands as Source in PD Exerciser. If the user wants to change default settings for Source Power Negotiation, has to call this function prior calling the `PD_NegotiatePower_Source` or `PD_NegotiatePower` or `PD_WaitForNegotiatePower` functions to take effect.

##### Format

```
Call PD_SetNegotiationSetting_Source( PD_Negotiation_Source_Settings $settings )
```

##### Parameters

`$settings`

Defines negotiation settings for source. Should be in type of `PD_Negotiation_Source_Settings` template. Table below shows all available fields of `PD_Negotiation_Source_Settings` template:

Field Name	Possible/Default Values	Description
<code>NegotiationResponse</code>	<code>PD_NEGOTIATION_ACCEPT</code> (default) <code>PD_NEGOTIATION_WAIT</code> <code>PD_NEGOTIATION_REJECT</code>	Indicates the response type.
<code>SourceCapsRetryCount</code>	<code>DEFAULT_SOURCE_CAPS_RETRY_COUNT</code> (default)	Source capabilities retry count.

VBusVoltage_mv	VBUS_VOLTAGE_V5_SAFE(default)	VBus voltage in millivolt.
SourceCapMsgSpecRev	PD_INVALID_VALUE(default) Or other user defined value.	If the value is not PD_INVALID_VALUE then SourceCap Message in Negotiation sequence will be transferred using this Specification Revision.
AutoSpecRev	PD_FALSE, PD_TRUE(default)	Rev3.0 only. Indicates whether the Exerciser should detect the Specification Revision automatically from Negotiation process or not.
AutoUnchunkedSupport	PD_FALSE, PD_TRUE(default)	Rev3.0 only. Indicates whether the Exerciser should detect the Unchunked Support automatically from Negotiation sequence or not.
SkipNegotiationResponse	PD_TRUE PD_FALSE(Default)	Prevents the source from sending a response back to request in the negotiation.

**Note -** If user sets the `vBusVoltage_mv`, then the PD Exerciser will set `vBusVoltage_mv` on the VBus regardless the actual voltage value which UUT selected during the negotiation process, otherwise the Exerciser will set the `VBus` using the voltage which UUT selected during the negotiation process.

Note - In order to apply voltages greater than 5V, the corresponding check box should be set in recording options (*Allow VBUS > 5v*).

## Result

None

## Examples

```
#set negotiation using default values
$settings = PD_Negotiation_Source_Settings
call PD_SetNegotiationSetting_Source( $settings )

#set negotiation using reject as response
$settings
{
    NegotiationResponse = PD_NEGOTIATION_REJECT
}
call PD_SetNegotiationSetting_Source( $settings )
```

### 5.1.3 PD\_AddSourceCap

Adds a specified Source Capability to the PD Exerciser. Before adding a group of source caps make sure that there is no unwanted source cap in the list by calling `PD_ResetSourceCaps` function. This function has to be called prior calling the `PD_NegotiatePower_Source` or `PD_NegotiatePower` or `PD_WaitForNegotiatePower` functions to take effect.

**Note -** By default there is one pre-defined source cap(vSafe5V) in the list.

## Format

```
Call PD_AddSourceCap(PD_PowerDataObject $PowerDataObject)
```

## Parameters

`$PowerDataObject`

Parameter type is `PD_PowerDataObject`. Refer to [PD\\_SourceCapabilitiesMessage](#) for available source power data objects.

## Result

None

## Examples

```
local $power_data_object = PD_PowerDataObjectFixedSupply_Source
{
    MaxCurrent_10mAUnits = 20
    Voltage_50mVUnits = 250
}
call PD_AddSourceCap($power_data_object)
```

### 5.1.4 PD\_ResetSourceCaps

Clears all *Source Capabilities* defined in PD Exerciser. It should be called prior calling the [PD\\_AddSourceCap](#) function.

## Format

`Call PD_ResetSourceCaps()`

## Parameters

None

## Result

None

## Examples

```
call PD_ResetSourceCaps()
```

### 5.1.5 PD\_NegotiatePower\_Source

This command tries to establish an explicit contract as Source.

**Note:** The [PD\\_ResetSourceCaps](#), [PD\\_AddSourceCap](#) and [PD\\_SetNegotiationSetting\\_Source](#) functions may need to be called before calling this function.

## Format

`Call PD_NegotiatePower_Source()`

## Parameters

None

## Result

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

List of result values:

Result Value	Description
PD_RESULT_OK	Command succeeded
PD_RESULT_FAILED	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the error type which has been occurred during sending or receiving data).
PD_SUBRESULT_REQUEST_MSG_INVALID_INDEX	Subresult - Invalid index in request message
PD_SUBRESULT_RESPONSE_WAIT	Subresult - Wait message has been sent as Request message response
PD_SUBRESULT_RESPONSE_REJECT	Subresult - Reject message has been sent as Request message response

## Examples

```
call PD_NegotiatePower_Source()
```

### 5.1.6 PD\_SetNegotiationSetting\_Sink

Applies power negotiation settings as Sink. If the user wants to change default settings for Sink Power Negotiation, has to call this function prior calling the [PD\\_NegotiatePower\\_Sink](#) or [PD\\_NegotiatePower](#) or [PD\\_WaitForNegotiatePower](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

#### Format

```
Call PD_SetNegotiationSetting_Sink( PD_Negotiation_Sink_Settings $settings )
```

#### Parameters

**\$settings**

Should be from `PD_Negotiation_Sink_Settings` type.

Table below shows all available fields of `PD_Negotiation_Sink_Settings` template:

Field Name	Possible/Default Values	Description
WaitTimeout	PD_DEFAULT_TIMEOUT_INFINITE(default)	Indicates the wait timeout(micro second) to receive SourceCapabilities Message. (default =)
SinkrequestData	0x1000280A(default)	Defines data object of Request message. Refer to <a href="#">PD_RequestPacket</a> for available Request RDOs.
AutoSinkRequest	PD_TRUE(Default) PD_FALSE	Builds the <code>SinkrequestData</code> automatically according to current PD Exerciser sink capabilities and received source capabilities.
RetryCountOnWait	2(default)	Indicates the retry count upon receiving Wait Message after sending the Request.
RetryDelayOnWait	100000 us(default)	Indicates the delay time before retrying the Request, upon receiving Wait Message.
RequestMsgSpecRev	PD_INVALID_VALUE(default) Or other user defined value.	If the value is not <code>PD_INVALID_VALUE</code> then Request message in Negotiation sequence will be transferred using this Specification Revision.
ExTriggerOnAccept	PD_FALSE(default) PD_TRUE	Indicates whether to notify PD Exerciser through External Trigger on receiving Accept message or not.
ExTriggerOnPSRDY	PD_FALSE(default) PD_TRUE	Indicates whether to notify PD Exerciser through External Trigger on receiving PS_RDY message or not.

AutoSpecRev	PD_FALSE, PD_TRUE(default)	Rev3.0 only. Indicates whether the Exerciser should detect the Specification Revision automatically from Negotiation process or not.
AutoUnchunkedSupport	PD_FALSE, PD_TRUE(default)	Rev3.0 only. Indicates whether the Exerciser should detect the Un-chunked Support automatically from Negotiation sequence or not.

## Result

None

## Examples

```
#Set sink negotiation settings as default
$settings = PD_Negotiation_Sink_Settings
call PD_SetNegotiationSetting_Sink( $settings )
```

### 5.1.7 PD\_AddSinkCap

Adds Sink Capabilities to PD Exerciser. Before adding a group of sink caps make sure that there is no unwanted sink cap in the list by calling [PD\\_ResetSinkCaps](#) function. This function has to be called prior calling the [PD\\_NegotiatePower\\_Sink](#) or [PD\\_NegotiatePower](#) or [PD\\_WaitForNegotiatePower](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

**Note** - By default there is one pre-defined sink cap in the list.

## Format

```
Call PD_AddSinkCap(PD_PowerDataObject $PowerDataObject)
```

## Parameters

\$PowerDataObject

Parameter type is [PD\\_PowerDataObject](#). Refer to [PD\\_SinkCapabilitiesMessage](#) for available sink power data objects.

## Result

None

## Examples

```
local $power_data_object = PD_PowerDataObjectFixedSupply_Sink
{
    OperationalCurrent_10mAUnits = 50
    Voltage_50mVUnits = 100
}
call PD_AddSinkCap($power_data_object)
```

### 5.1.8 PD\_ResetSinkCaps

Clears all *Sink Capabilities* defined for PD Exercise. It should be called prior calling the [PD\\_AddSinkCap](#) function.

## Format

```
Call PD_ResetSinkCaps()
```

## Parameters

None

## Result

None

## Examples

```
call PD_ResetSinkCaps()
```

### 5.1.9 PD\_NegotiatePower\_Sink

Tries to establish explicit contract as Sink by sending a Request message.

**Note:** The [PD\\_ResetSinkCaps](#), [PD\\_AddSinkCap](#) and [PD\\_SetNegotiationSetting\\_Sink](#) functions may need to be called before calling this function.

## Format

```
Call PD_NegotiatePower_Sink()
```

## Parameters

None

## Result

User can evaluate the command results(including sub-results) using IfMatched/ElseMatched command.

List of result values:

Result Value	Description
<a href="#">PD_RESULT_OK</a>	Command succeeded
<a href="#">PD_RESULT_FAILED</a>	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the error type which has been occurred during sending or receiving data).
<a href="#">PD_SUBRESULT_RESPONSE_REJECT</a>	Subresult - Reject received as the response
<a href="#">PD_SUBRESULT_RESPONSE_WAIT</a>	Subresult - Wait received as the response
<a href="#">PD_SUBRESULT_MSG_NOT_RECEIVED</a>	Subresult - PS_RDY message not received.

## Examples

```
call PD_NegotiatePower_Sink()
```

### 5.1.10 PD\_WaitForNegotiatePower

Tries to establish explicit contract either as Source or Sink according to the current PD Exerciser power role. If the current power role of PD Exerciser is Source, this command will wait to receive Request message and if the current power role of PD Exerciser is Sink, it will wait to receive Source\_Capabilities message.

**Note:** If the PD Exerciser is operating as Source then the [PD\\_ResetSourceCaps](#), [PD\\_AddSourceCap](#) and [PD\\_SetNegotiationSetting\\_Source](#) functions may need to be called prior calling this function and if the PD Exerciser is operating as Sink then the [PD\\_ResetSinkCaps](#), [PD\\_AddSinkCap](#) and [PD\\_SetNegotiationSetting\\_Sink](#) functions may need to be called prior calling this function.

## Format

```
call PD_WaitForNegotiatePower()
```

## Parameters

None

## Result

User can evaluate the command results(including sub-results) using IfMatched/ElseMatched command.

List of result values:

Result Value	Description
PD_RESULT_OK	Command succeeded
PD_RESULT_FAILED	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the error type which has been occurred during sending or receiving data).
PD_SUBRESULT_RESPONSE_TIMEOUT	Subresult - No response received
PD_SUBRESULT_RESPONSE_REJECT	Subresult - Reject message received as the response
PD_SUBRESULT_RESPONSE_WAIT	Subresult - Wait message received as the response
PD_SUBRESULT_MSG_NOT RECEIVED	Subresult - Request(PD Exerciser as Source)/Source_Capabilities(PD Exerciser as Sink) message not received or PS_RDY message not received(PD Exerciser as Sink)

## Examples

```
call Pd PD_WaitForNegotiatePower()
```

### 5.1.11 PD\_NegotiatePower

Negotiates power with the peer port according to PD Exerciser current power role. If PD Exerciser operates as Source, this function starts power negotiation as Source and if the PD Exerciser operates as Sink, this function starts power negotiation as Sink(will wait to receive Request message).

**Note** - If the PD Exerciser is operating as Source then the [PD\\_ResetSourceCaps](#), [PD\\_AddSourceCap](#) and [PD\\_SetNegotiationSetting\\_Source](#) functions may need to be called prior calling this function and if the PD Exerciser is operating as Sink then the [PD\\_ResetSinkCaps](#), [PD\\_AddSinkCap](#) and [PD\\_SetNegotiationSetting\\_Sink](#) functions may need to be called prior calling this function.

## Format

```
call PD_NegotiatePower()
```

## Parameters

None

## Result

If PD Exerciser operates as Source this function returns same sub-results as [PD\\_NegotiatePower\\_Source](#) function. If PD Exerciser operates as Sink this function returns same sub-results as [PD\\_NegotiatePower\\_Sink](#) function.

## Examples

```
Call PD_NegotiatePower()
```

### 5.1.12 PD\_SetSwapPowerRoleSetting

It has to be called prior calling the [PD\\_SwapPowerRole](#) or [PD\\_WaitForSwapPowerRole](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

#### Format

```
Call PD_SetSwapPowerRoleSetting( Pd_SwapPowerRole_Settings $settings )
```

#### Parameters

##### \$settings

Should be from `Pd_SwapPowerRole_Settings` type.

Following is the list of `Pd_SwapPowerRole_Settings` fields:

Field Name	Possible/Default Values	Description
SwapResponse	PD_MESSAGE_TYPE_ACCEPT (default) PD_MESSAGE_TYPE_WAIT PD_MESSAGE_TYPE_REJECT PD_RESPONSE_NOT_SUPPORTED (PD3.0 only)	Defines the response type.
SkipSwap	PD_TRUE PD_FALSE(Default)	If set to PD_TRUE, PD_SwapPowerRole AMS will not swap the power role.
WaitTimeout	PD_DEFAULT_TIMEOUT_INFINITE(default)	Timeout(in micro-seconds) to wait in order to receive the PR_SWAP message.
RetryCountOnWait	2(default)	Indicates the retry count after receiving Wait message in response to sent PR_Swap Message.
RetryDelayOnWait	100000(default)	Indicates the retry delay time(in micro-seconds) upon receiving Wait message in response to sent PR_Swap Message.
SwapResponseOnWait	PD_MESSAGE_TYPE_ACCEPT (default) PD_MESSAGE_TYPE_WAIT PD_MESSAGE_TYPE_REJECT PD_RESPONSE_NOT_SUPPORTED (PD3.0 only)	Defines the response type in a case that the DUT initially responded to PR_Swap message with a Wait message and after a while issued a PR_Swap message towards the PD Exerciser.
SkipSendingPSRDY	PD_TRUE PD_FALSE(Default)	If set to PD_TRUE, PD_SwapPowerRole AMS will not send the PS_RDY message.
NewSrcRpType	CC_RP_CUR_DEFAULT CC_RP_CUR_1_5 (Default) CC_RP_CUR_3_0	Indicates the Rp current value when swapping from Sink to Source.
SendPSRDYDelay	0 (default)	Indicates the delay (in micro-seconds) to send PS_RDY message.
SkipWaitingForVBus	PD_TRUE PD_FALSE(Default)	If set to PD_TRUE, will skip waiting for VBus On/Off operations.
NoGoodCRCToPSRDY	PD_TRUE PD_FALSE(Default)	If set to PD_TRUE, PD_SwapPowerRole AMS will not send the GoodCRC for PS_RDY message.

#### Result

None

## Examples

```
#Set response to REJECT;  
#Set response on receiving Wait message to ACCEPT;  
#Set Rp type while swapping to source as CC_RP_CUR_3_0;
```

```

$settings = Pd_SwapPowerRole_Settings
{
    SwapResponse = PD_MESSAGE_TYPE_REJECT
    SwapResponseOnWait = PD_MESSAGE_TYPE_ACCEPT
    NewSrcRpType = CC_RP_CUR_3_0
}
call PD_SetSwapPowerRoleSetting( $settings )

```

### 5.1.13 PD\_SwapPowerRole

Tries to swap power role. It will start Swap Power Role AMS.

**Note:** The [PD\\_SetSwapPowerRoleSetting](#) function may need to be called prior calling this function.

#### Format

```
call PD_SwapPowerRole()
```

#### Parameters

None

#### Result

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

List of result values:

Result Value	Description
<a href="#">PD_RESULT_OK</a>	Command succeeded
<a href="#">PD_RESULT_FAILED</a>	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the error type which has been occurred during sending or receiving data).
<a href="#">PD_SUBRESULT_RESPONSE_TIMEOUT</a>	Subresult - Response not received
<a href="#">PD_SUBRESULT_RESPONSE_REJECT</a>	Subresult - Reject message received as response
<a href="#">PD_SUBRESULT_RESPONSE_WAIT</a>	Subresult - Wait message received as response
<a href="#">PD_SUBRESULT_MSG_NOT_RECEIVED</a>	Subresult - PS_RDY message not received(PD Exerciser as Sink)
<a href="#">PD_SUBRESULT_RESPONSE_NOT_SUPPORTED</a>	Rev3.0 only. Subresult - Not_Supported message received as response

#### Examples

```
call PD_SwapPowerRole()
```

### 5.1.14 PD\_WaitForSwapPowerRole

Waits to receive `PR_Swap` message and will respond to incoming messages as part of the *Swap Power Role* AMS.

**Note:** The [PD\\_SetSwapPowerRoleSetting](#) function may need to be called prior calling this function.

#### Format

```
call PD_WaitForSwapPowerRole()
```

#### Parameters

None

## Result

User can evaluate the command results(including sub-results) using IfMatched/ElseMatched command.

List of result values:

Result Value	Description
PD_RESULT_OK	Command succeeded
PD_RESULT_FAILED	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the error type which has been occurred during sending or receiving data).
PD_SUBRESULT_RESPONSE_WAIT	Subresult - Wait message has been sent as response
PD_SUBRESULT_RESPONSE_REJECT	Subresult - Reject message has been sent as response
PD_SUBRESULT_MSG_NOT_RECEIVED	Subresult - PR_Swap message not received or PS_RDY message not received(PD Exerciser as Sink)
PD_SUBRESULT_RESPONSE_NOT_SUPPORTED	Rev3.0 only. Subresult - Not_Supported message has been sent as response

## Examples

```
call PD_WaitForSwapPowerRole()
```

### 5.1.15 Pd\_SetFRSwapNewSnkSetting

Applicable to PD Rev 3.0 only. It has to be called prior calling the [PD\\_FastRoleSwap](#) function to take effect.

#### Format

```
Call Pd_SetFRSwapNewSnkSetting( Pd_FRSwapNewSnkSettings $fr_swap_settings )
```

#### Parameters

**\$fr\_swap\_settings**

Should be from [Pd\\_FRSwapNewSnkSettings](#) type. Following are the available fields for this packet template:

Field Name	Possible/Default Values	Description
NoGoodCRCToPSRDY	PD_TRUE PD_FALSE(Default)	Indicates whether to send a GoodCRC message to receiving PS_RDY message or not.
SkipSendingPSRDY	PD_TRUE PD_FALSE(Default)	Indicates whether to skip sending PS_RDY message or not.
NoGoodCRCToFRSwap	PD_TRUE PD_FALSE(Default)	Indicates whether to send a GoodCRC message to receiving FR_Swap message or not.
SkipSendingAccept	PD_TRUE PD_FALSE(Default)	Indicates whether to skip sending Accept message or not.

## Result

None

## Examples

```
$settings = Pd_FRSwapNewSnkSettings
{
    NoGoodCRCToFRSwap = PD_TRUE
}
call Pd_SetFRSwapNewSnkSetting( $settings )
```

### 5.1.16 Pd\_SetFRSwapNewSrcSetting

Applicable to PD Rev 3.0 only. It has to be called prior calling the [PD\\_WaitForFRSwapSignal](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

#### Format

```
call Pd_SetFRSwapNewSrcSetting( Pd_FRSwapNewSrcSettings $fr_swap_settings )
```

#### Parameters

`$fr_swap_settings`

Should be from `Pd_FRSwapNewSrcSettings` type. Following are the available fields for this packet template:

Field Name	Possible/Default Values	Description
NoGoodCRCToPSRDY	PD_TRUE PD_FALSE(Default)	Indicates whether to send a GoodCRC message to receiving PS_RDY message or not.
SkipSendingPSRDY	PD_TRUE PD_FALSE(Default)	Indicates whether to skip sending PS_RDY message or not.
VBusVoltageThreshold_mV	VBUS_VOLTAGE_V5_SAFE_MAX(Default)	If the VBus drops below this value, the new Source(PD Exerciser) will turn on the VBus.
NewVBusVoltage_mV	VBUS_VOLTAGE_V5_SAFE(Default)	PD Exerciser as new Source will increase the VBus voltage up-to this value.
FRSwapSignalWaitTimeout	1000000(Default)	Time-out to wait for receiving the FR_Swap Signal (micro seconds).
FRSwapNewSrcRpCurrent	CC_RP_CUR_1_5(Default)	PD Exerciser as new Source will apply this RpCurrent value.
NoGoodCrcToAccept	PD_TRUE PD_FALSE(Default)	Indicates whether to send a GoodCRC message to receiving Accept message or not.

#### Result

None

#### Examples

```
$settings = Pd_FRSwapNewSrcSettings
{
    VBusVoltageThreshold_mV = VBUS_VOLTAGE_V5_SAFE
    NoGoodCrcToAccept = PD_TRUE
}
call Pd_SetFRSwapNewSrcSetting( $settings )
```

### 5.1.17 PD\_FastRoleSwap

Applicable to PD Rev 3.0 only. Sends the *FastRoleSwap* Signal and handles *Fast Role Swap* AMS.

**Note** - The [Pd\\_SetFRSwapNewSrcSetting](#) function may need to be called prior calling this function.

#### Format

```
call PD_FastRoleSwap()
```

#### Parameters

None

## Result

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

List of result values:

Result Value	Description
<code>PD_RESULT_OK</code>	Command succeeded.
<code>PD_RESULT_FAILED</code>	Command failed. In this case corresponding sub results for <code>PD_SendPacket</code> and <code>PD_ReceivePacket</code> are valid also (depends on the error type which has been occurred during sending or receiving data).

## Examples

```
Call PD_FastRoleSwap()
```

### 5.1.18 PD\_WaitForFRSwapSignal

Applicable to PD Rev 3.0 only. Waits for a specified time to receive the *FR\_Swap Signal*. During this time, any received messages will be handled.

**Note 1-** Received *FastRoleSwap* Signal will handle by *FastRoleSwap Event Handler* automatically.

**Note 2-** The `Pd_SetFRSwapNewSrcSetting` function may need to be called prior calling this function.

## Format

```
Call PD_WaitForFRSwapSignal()
```

## Parameters

None

## Result

None

## Examples

```
Call PD_WaitForFRSwapSignal()
```

### 5.1.19 Pd\_GetPPSStatus

Applicable to PD Rev 3.0 only. Sends `Get_PPS_Status` message and starts the *GetPPSStatus* AMS.

## Format

```
Call Pd_GetPPSStatus()
```

## Parameters

None

## Result

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

List of result values:

Result Value	Description
<a href="#">PD_RESULT_OK</a>	Command succeeded
<a href="#">PD_RESULT_FAILED</a>	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the error type which has been occurred during sending or receiving data).
<a href="#">PD_SUBRESULT_RESPONSE_TIMEOUT</a>	Subresult - Response not received
<a href="#">PD_SUBRESULT_UNEXPECTED_MSG RECEIVED</a>	Subresult - Unexpected packet received
<a href="#">PD_SUBRESULT_RESPONSE_NOT_SUPPORTED</a>	Rev3.0 only. Subresult - Not_Supported has been received as response

## Examples

```
call Pd_GetPPSStatus()
```

### 5.1.20 Pd\_SetGetPPSStatusSetting

Applicable to PD Rev 3.0 only. It must be called prior to call [Pd\\_WaitForGetPPSStatus](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

#### Format

```
call PD_SetGetPPSStatusSetting( PD_GetPPSStatus_Settings $settings )
```

#### Parameters

**\$settings**

Parameter type is [PD\\_GetPPSStatus\\_Settings](#). Available fields for this type are:

Field Names	Possible/Default Values	Description
<a href="#">WaitTimeout</a>	<a href="#">PD_DEFAULT_TIMEOUT_INFINITE</a> (default)	Wait TimeOut(micro second) to receive Get_PPS_Status message.
<a href="#">ResponseType</a>	<a href="#">PD_RESPONSE_NOT_SUPPORTED</a> , <a href="#">PD_RESPONSE_UNSPECIFIED</a> (default)	Indicates response upon receiving the Get_PPS_Status message.

#### Result

None

#### Examples

```
$get_ppsstatus_setting = PD_GetPPSStatus_Settings
{
    ResponseType = PD_RESPONSE_NOT_SUPPORTED
}
call PD_SetGetPPSStatusSetting( $get_ppsstatus_setting )
```

### 5.1.21 Pd\_SetPPSStatusDataBlock

Applicable to PD Rev 3.0 only. Sets the *PPS Status Data Block* in PD Exerciser. It must be called before [Pd\\_WaitForGetPPSStatus](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

#### Format

```
call PD_SetPPSStatusDataBlock( PD_PPSStatusDataBlock $pps_status_db )
```

#### Parameters

**\$pps\_status\_db**

Parameter type is `PD_PPSstatusDataBlock`. Refer to [Pd\\_PPSStatusMsg](#) for available fields.

## Result

None

## Examples

```
$pps_status_db = PD_PPSStatusDataBlock  
Call PD_SetPPSStatusDataBlock( $pps_status_db )
```

## 5.1.22 Pd\_ResetPPSStatusDataBlock

Applicable to PD Rev 3.0 only. Clears the *PPS Status Data Block* in PD Exerciser. Should be called prior calling the [Pd\\_SetPPSStatusDataBlock](#) function.

## Format

```
Call PD_ResetPPSStatusDataBlock()
```

## Parameters

None

## Result

None

## Examples

```
Call PD_ResetPPSStatusDataBlock()
```

## 5.1.23 Pd\_WaitForGetPPSStatus

Applicable to PD Rev 3.0 only. Waits for user-defined time-out to receive `Get_PPS_Status` message. It will respond to incoming messages as part of *GetPPSStatus* AMS.

**Note:** The [Pd\\_ResetPPSStatusDataBlock](#), [Pd\\_SetPPSStatusDataBlock](#) and [Pd\\_SetGetPPSStatusSetting](#) functions may need to be called prior calling this function.

## Format

```
Call PD_WaitForGetPPSStatus( )
```

## Parameters

None

## Result

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

List of result values:

Result Value	Description
<code>PD_RESULT_OK</code>	Command succeeded
<code>PD_RESULT_FAILED</code>	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the error type which has been occurred during sending or receiving data).

<a href="#">PD_SUBRESULT_MSG_NOT_RECEIVED</a>	Subresult - Get_PPS_Status message not received.
<a href="#">PD_SUBRESULT_RESPONSE_NOT_SUPPORTED</a>	Subresult - Not_Supported message sent as response.

## Examples

Call [PD\\_WaitForGetPPSStatus\(\)](#)

### 5.1.24 Pd\_SetPPSNegotiationSetting\_Sink

Applicable to PD Rev 3.0 only. Applies power negotiation settings as a Sink which is communicating with a PPS Source. If the user wants to change default settings for Sink Power Negotiation, has to call this function prior to call [Pd\\_StartPPSNegotiatePower\\_Sink](#) and [Pd\\_NextPPSNegotiatePower\\_Sink](#) functions to take effect. This function is not supported by [PD\\_DelayAutoResponse](#) function.

## Format

```
call PD_SetPPSNegotiationSetting_Sink( PD_PPSNegotiation_Sink_Settings $settings )
```

## Parameters

### \$settings

Should be from [PD\\_PPSNegotiation\\_Sink\\_Settings](#) type. [PD\\_PPSNegotiation\\_Sink\\_Settings](#) template contains all fields of [Pd\\_Negotiation\\_Sink\\_Settings](#)(Refer to [PD\\_SetNegotiationSetting\\_Sink](#)) and some extra fields which are listed in table below:

Field Name	Default Values	Description
<a href="#">MinOutputVolt_20mVUnits</a>	0x00	Min output voltage in 20mV units. Output Voltage will be increased from this value. Refer to <a href="#">Pd_ProgrammableRDO</a> .
<a href="#">MaxOutputVolt_20mVUnits</a>	0x00	Max output voltage in 20mV units. Output Voltage will be decreased from this value. Refer to <a href="#">Pd_ProgrammableRDO</a> .
<a href="#">OperatingCur_50mAUnits</a>	0x00	Refer to <a href="#">Pd_ProgrammableRDO</a> .
<a href="#">UnchunkedExtMsgSupported</a>	1	Refer to <a href="#">Pd_ProgrammableRDO</a> .
<a href="#">NoUsbSuspend</a>	0	Refer to <a href="#">Pd_ProgrammableRDO</a> .
<a href="#">UsbCommunicationsCapable</a>	0	Refer to <a href="#">Pd_ProgrammableRDO</a> .
<a href="#">CapabilityMismatch</a>	0	Refer to <a href="#">Pd_ProgrammableRDO</a> .
<a href="#">ObjectPosition</a>	0	Refer to <a href="#">Pd_ProgrammableRDO</a> .
<a href="#">VoltageStep_20mVUnits</a>	0x01	Voltage Step in 20mV units.
<a href="#">IncrementalStep</a>	PD_TRUE (increasing)	Indicates whether the Voltage is increasing or decreasing.

## Result

None

## Examples

```
#set pps negotiation sink settings
$pps_nego_settings = Pd_PPSNegotiation_Sink_Settings
{
    MinOutputVolt_20mVUnits = 500
    MaxOutputVolt_20mVUnits = 500
    OperatingCur_50mAUnits = 10
    ObjectPosition = 1
    VoltageStep_20mVUnits = 2
    IncrementalStep = PD_FALSE
}
call Pd_SetPPSNegotiationSetting_Sink($pps_nego_settings)
```

## 5.1.25 Pd\_StartPPSNegotiatePower\_Sink

Applicable to PD Rev 3.0 only. Starts *PPS Power Negotiation* as a Sink. This function should be called before [Pd\\_NextPPSNegotiatePower\\_Sink](#).

**Note:** The [Pd\\_SetPPSNegotiationSetting\\_Sink](#) function may need to be called prior calling this function.

### Format

```
call PD_StartPPSNegotiatePower_Sink()
```

### Parameters

None

### Result

Refer to [PD\\_NegotiatePower\\_Sink](#).

### Examples

```
call Pd_StartPPSNegotiatePower_Sink()
PD_Loop(10)
{
    call Pd_NextPPSNegotiatePower_Sink()
    call PD_DelayAutoResponse(100000)
}
```

## 5.1.26 Pd\_NextPPSNegotiatePower\_Sink

Applicable to PD Rev 3.0 only. Next *PPS Power Negotiation* as a Sink with incremented or decremented output voltage value. This function should be called after

[Pd\\_StartPPSNegotiatePower\\_Sink](#).

**Note:** The [Pd\\_SetPPSNegotiationSetting\\_Sink](#) function may need to be called prior calling this function.

### Format

```
call PD_NextPPSNegotiatePower_Sink()
```

### Parameters

None

### Result

Refer to [PD\\_NegotiatePower\\_Sink](#).

### Examples

```
call Pd_StartPPSNegotiatePower_Sink()
PD_Loop(10)
{
    call Pd_NextPPSNegotiatePower_Sink()
    call PD_DelayAutoResponse(100000)
}
```

### 5.1.27 PD\_SetDataResetSetting

Applicable to PD Rev 3.0 only. It must be called prior to call [PD\\_WaitForDataReset](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

#### Format

```
Call Pd_SetDataResetSetting( Pd_DataReset_Settings $settings )
```

#### Parameters

**\$settings**

Parameter type is [PD\\_DataReset\\_Settings](#). Available fields for this type are:

Field Names	Possible/Default Values	Description
<a href="#">DataResetWaitTimeout</a>	PD_DEFAULT_TIMEOUT_INFINITE(default)	Wait TimeOut(micro second) to receive Pd_DataResetMessage.
<a href="#">DataResetResponse</a>	PD_RESPONSE_REJECT, PD_RESPONSE_ACCEPT(default)	Indicates response upon receiving the Pd_DataResetMessage.
<a href="#">SkipSendingPSRDY</a>	PD_TRUE, PD_FALSE (default)	To skip sending PSRdy packet.
<a href="#">RunningUSBExercisers</a>	PD_USB2_EXERCISER (default) PD_USB3_EXERCISER, PD_USB4_EXERCISER, PD_TBT3_EXERCISER,	Exercisers to be run in Data Reset process

#### Result

None

#### Examples

```
$send_data_reset = PD_DataReset_Settings
{
    DataResetResponseType = PD_RESPONSE_REJECT
    RunningUSBExercisers = PD_USB2_EXERCISER | PD_USB3_EXERCISER
}
Call PD_SetDataResetSetting( $send_data_reset )
```

### 5.1.28 PD\_SendDataReset

Applicable to PD Rev 3.0 only. Sends [Pd\\_DataResetMessage](#) and starts the *DataReset* AMS.

#### Format

```
Call PD_SendDataReset()
```

#### Parameters

None

#### Result

User can evaluate the command results (including sub-results) using [IfMatched](#)/[ElseMatched](#) command.

List of result values:

Result Value	Description
<a href="#">PD_RESULT_OK</a>	Command succeeded

<a href="#">PD_RESULT_FAILED</a>	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the error type which has been occurred during sending or receiving data).
<a href="#">PD_SUBRESULT_RESPONSE_TIMEOUT</a>	Subresult - Response not received
<a href="#">PD_SUBRESULT_RESPONSE_REJECT</a>	Subresult - Reject message has been received
<a href="#">PD_SUBRESULT_UNEXPECTED_MSG RECEIVED</a>	Subresult - Unexpected message received as response

### Examples

```
call PD_SendDataReset()
```

## 5.1.29 PD\_WaitForDataReset

Waits for user-defined time-out to receive `Pd_DataResetMessage` and will respond to incoming messages as part of the *DataReset* AMS.

**Note:** The [PD\\_SetDataResetSetting](#) function may need to be called prior calling this function.

### Format

```
Call PD_WaitForDataReset()
```

### Parameters

None

### Result

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

List of result values:

Result Value	Description
<a href="#">PD_RESULT_OK</a>	Command succeeded
<a href="#">PD_RESULT_FAILED</a>	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the error type which has been occurred during sending or receiving data).
<a href="#">PD_SUBRESULT_MSG NOT RECEIVED</a>	Subresult - DataReset message not received
<a href="#">PD_SUBRESULT_RESPONSE_REJECT</a>	Subresult - Reject message has been sent as response

### Examples

```
call PD_WaitForDataReset()
```

## 5.1.30 PD\_SetSwapDataRoleSetting

It must be called before [PD\\_SwapDataRole](#) or [PD\\_WaitForSwapDataRole](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

### Format

```
Call PD_SetSwapDataRoleSetting( Pd_SwapDataRole_Settings $settings )
```

### Parameters

`$settings`

Should be from `Pd_SwapDataRole_Settings` type. Table below shows all fields of the `Pd_SwapDataRole_Settings` template which are applied to *DR\_Swap* AMS:

Field Name	Possible/Default Values	Description
SwapResponse	PD_MESSAGE_TYPE_ACCEPT(default) PD_MESSAGE_TYPE_REJECT PD_MESSAGE_TYPE_WAIT PD_RESPONSE_NOT_SUPPORTED (PD3.0 only)	Defines the response type.
WaitTimeout	PD_DEFAULT_TIMEOUT_INFINITE(default)	Timeout(in micro-seconds) to wait in order to receive DR_SWAP message.
RetryCountOnWait	2 (default)	Indicates the retry count after receiving Wait Message in response to sent DR_Swap Message.
RetryDelayOnWait	100000 (default)	Indicates the retry delay time(in micro-seconds) upon receiving Wait Message in response to sent DR_Swap Message.
SwapResponseOnWait	PD_MESSAGE_TYPE_ACCEPT (default) PD_MESSAGE_TYPE_WAIT PD_MESSAGE_TYPE_REJECT PD_RESPONSE_NOT_SUPPORTED (PD3.0 only)	Defines the response type in a case that the DUT initially responded to DR_Swap message with a Wait message and after a while issued a DR_Swap message towards the PD Exerciser.

## Result

None

## Examples

```
#Set response to REJECT;
#Set response on receiving Wait message to ACCEPT;
$settings = Pd_SwapDataRole_Settings
{
    SwapResponse = PD_MESSAGE_TYPE_REJECT
    SwapResponseOnWait = PD_MESSAGE_TYPE_ACCEPT
}
call PD_SetSwapDataRoleSetting( $settings )
```

### 5.1.31 PD\_SwapDataRole

Tries to swap the data role. It will start the *Swap Data Role AMS*.

**Note:** The [PD\\_SetSwapDataRoleSetting](#) function may need to be called prior calling this function.

#### Format

```
Call PD_SwapDataRole()
```

#### Parameters

None

## Result

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

List of result values:

Result Value	Description
PD_RESULT_OK	Command succeeded
PD_RESULT_FAILED	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the error type which has been occurred during sending or receiving data).
PD_SUBRESULT_RESPONSE_TIMEOUT	Subresult - Response not received

<a href="#">PD_SUBRESULT_RESPONSE_REJECT</a>	Subresult - Reject message has been received
<a href="#">PD_SUBRESULT_RESPONSE_WAIT</a>	Subresult - Wait message has been received
<a href="#">PD_SUBRESULT_RESPONSE_NOT_SUPPORTED</a>	Rev3.0 only. Subresult - Not_Supported message received as response

## Examples

```
call PD_SwapDataRole()
```

### 5.1.32 PD\_WaitForSwapDataRole

Waits for user-defined time-out to receive DR\_Swap message and will respond to incoming messages as part of the *Swap Data Role* AMS.

**Note:** The [PD\\_SetSwapDataRoleSetting](#) function may need to be called prior calling this function.

## Format

```
Call PD_WaitForSwapDataRole()
```

## Parameters

None

## Result

User can evaluate the command results(including sub-results) using IfMatched/ElseMatched command.

List of result values:

Result Value	Description
<a href="#">PD_RESULT_OK</a>	Command succeeded
<a href="#">PD_RESULT_FAILED</a>	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the error type which has been occurred during sending or receiving data).
<a href="#">PD_SUBRESULT_RESPONSE_REJECT</a>	Subresult - Reject message has been sent as response
<a href="#">PD_SUBRESULT_MSG_NOT_RECEIVED</a>	Subresult - DR_Swap message not received
<a href="#">PD_SUBRESULT_RESPONSE_NOT_SUPPORTED</a>	Rev3.0 only. Subresult - Not_Supported message has been sent as response

## Examples

```
call PD_WaitForSwapDataRole()
```

### 5.1.33 PD\_SetSwapVConnSetting

It has to be called prior calling the [PD\\_SwapVConn](#) or [PD\\_WaitForSwapVConn](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

## Format

```
Call PD_SetSwapVConnSetting( Pd_SwapVConn_Settings $settings )
```

## Parameters

\$settings

Should be from `Pd_SwapVConn_Settings` type. Table below shows the `Pd_SwapVConn_Settings` template fields:

Field Name	Possible/Default Values	Description
<code>SwapResponse</code>	<code>PD_MESSAGE_TYPE_ACCEPT</code> (default) <code>PD_MESSAGE_TYPE_REJECT</code> <code>PD_MESSAGE_TYPE_WAIT</code> <code>PD_RESPONSE_NOT_SUPPORTED</code> (PD3.0 only)	Defines the response type.
<code>WaitTimeout</code>	<code>PD_DEFAULT_TIMEOUT_INFINITE</code> (default)	Timeout(in micro-seconds) to wait in order to receive <code>VCONN_SWAP</code> message.
<code>SkipSwap</code>	<code>PD_TRUE</code> <code>PD_FALSE</code> (Default)	If set to <code>PD_TRUE</code> , the command skips VConn swap.
<code>RetryCountOnWait</code>	2 (default)	Indicates the retry count after receiving Wait Message in response to sent VConn Swap Message.
<code>RetryDelayOnWait</code>	100000 (default)	Indicates the retry delay time(in micro-seconds) upon receiving Wait Message in response to sent VConn Swap Message.
<code>SwapResponseOnWait</code>	<code>PD_MESSAGE_TYPE_ACCEPT</code> (default) <code>PD_MESSAGE_TYPE_WAIT</code> <code>PD_MESSAGE_TYPE_REJECT</code> <code>PD_RESPONSE_NOT_SUPPORTED</code> (PD3.0 only)	Defines the response type in a case that the DUT initially responded to VConn_Swap message with a Wait message and after a while issued a VConn_Swap message towards the PD Exerciser.

## Result

None

## Examples

```
#Set the response to REJECT;
#skip swapping in the case that PD Exerciser is initiator;
$settings = Pd_SwapVConn_Settings
{
    SwapResponse = PD_MESSAGE_TYPE_REJECT
    SkipSwap = PD_TRUE
}
call PD_SetSwapVConnSetting( $settings )
```

## 5.1.34 PD\_SwapVConn

Tries to swap VConn. It will start the *Swap VConn* AMS.

**Note:** The `PD_SetSwapVConnSetting` function may need to be called prior calling this function.

### Format

`Call PD_SwapVConn()`

### Parameters

None

## Result

User can evaluate the command results(including sub-results) using `IFMatched/ElseMatched` command.

List of result values:

Result Value	Description
<code>PD_RESULT_OK</code>	Command succeeded
<code>PD_RESULT_FAILED</code>	Command failed. In this case corresponding sub results for

	<b>PD_SendPacket</b> and <b>PD_ReceivePacket</b> are valid also (depends on the error type which has been occurred during sending or receiving data).
<b>PD_SUBRESULT_RESPONSE_TIMEOUT</b>	Subresult - Response not received
<b>PD_SUBRESULT_RESPONSE_REJECT</b>	Subresult - Reject message has been received
<b>PD_SUBRESULT_RESPONSE_WAIT</b>	Subresult - Wait message has been received
<b>PD_SUBRESULT_MSG_NOT_RECEIVED</b>	Subresult - PS_RDY message not received(PD Exerciser as VCONN Source)
<b>PD_SUBRESULT_RESPONSE_NOT_SUPPORTED</b>	Rev3.0 only. Subresult - Not_Supported message message has been received

### Examples

call PD\_SwapVConn()

### 5.1.35 PD\_WaitForSwapVConn

Waits for user-defined time-out to receive `VCONN_Swap` message and will respond to incoming messages as part of *Swap VConn AMS*.

**Note:** The `PD_SetSwapVConnSetting` function may need to be called prior calling this function.

#### Format

call PD\_WaitForSwapVConn()

#### Parameters

None

#### Result

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

List of result values:

Result Value	Description
<b>PD_RESULT_OK</b>	Command succeeded
<b>PD_RESULT_FAILED</b>	Command failed. In this case corresponding sub results for <b>PD_SendPacket</b> and <b>PD_ReceivePacket</b> are valid also (depends on the error type which has been occurred during sending or receiving data).
<b>PD_SUBRESULT_MSG_NOT_RECEIVED</b>	Subresult - <code>VCONN_Swap</code> message not received
<b>PD_SUBRESULT_RESPONSE_WAIT</b>	Subresult - <code>Wait</code> message has been sent as response
<b>PD_SUBRESULT_RESPONSE_REJECT</b>	Subresult - <code>Reject</code> message has been sent as response
<b>PD_SUBRESULT_RESPONSE_NOT_SUPPORTED</b>	Rev3.0 only. Subresult - <code>Not_Supported</code> message has been sent as response

### Examples

call PD\_WaitForSwapVConn()

### 5.1.36 PD\_SetGotoMinSetting

It has to be called prior to call `PD_WaitForGotoMin` or `PD_DelayAutoResponse` functions to take effect.

#### Format

call PD\_SetGotoMinSetting( `PD_GotoMin_Settings` \$settings )

## Parameters

`$settings`

Setting type is `PD_GotoMin_Settings`. Available fields of this type are:

Field Name	Possible/Default Values	Description
<code>WaitTimeout</code>	<code>PD_DEFAULT_TIMEOUT_INFINITE</code> (default)	Wait time-out(micro second) for receiving GotoMin message.
<code>ResponseType</code>	<code>PD_RESPONSE_UNSPECIFIED</code> (default), <code>PD_RESPONSE_NOT_SUPPORTED</code>	Indicates the response type upon receiving GotoMin message.

## Result

None

## Examples

```
$gotomin_setting = PD_GotoMin_Settings
{
    ResponseType = PD_RESPONSE_NOT_SUPPORTED
}
call PD_SetGotoMinSetting( $gotomin_setting )
```

## 5.1.37 PD\_GotoMin

Starts the *GotoMin* AMS.

### Format

```
call PD_GotoMin()
```

### Parameters

None

### Result

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

List of result values:

Result Value	Description
<code>PD_RESULT_OK</code>	Command succeeded
<code>PD_RESULT_FAILED</code>	Command failed. In this case corresponding sub results for <code>PD_SendPacket</code> are valid also (depends on the error type which has been occurred during sending data).
<code>PD_SUBRESULT_RESPONSE_NOT_SUPPORTED</code>	Rev3.0 only. Subresult - Not_Supported message has been received

## Examples

```
call PD_GotoMin()
```

## 5.1.38 PD\_WaitForGotoMin

Waits for user-defined time-out to receive `GotoMin` message and will respond to incoming messages as part of *GotoMin* AMS.

**Note:** The `PD_SetGotoMinSetting` function may need to be called prior calling this function.

## Format

```
call PD_WaitForGotoMin()
```

## Parameters

None

## Result

User can evaluate the command results(including sub-results) using IfMatched/ElseMatched command.

List of result values:

Result Value	Description
PD_RESULT_OK	Command succeeded
PD_RESULT_FAILED	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the error type which has been occurred during sending or receiving data).
PD_SUBRESULT_MSG_NOT RECEIVED	Subresult - GotoMin or PS_RDY message not received.
PD_SUBRESULT_RESPONSE_NOT_SUPPORTED	Rev3.0 only. Subresult - Not_Supported message has been sent as response

## Examples

```
call PD_WaitForGotoMin()
```

## 5.1.39 PD\_SetGetSourceCapSetting

It has to be called prior to call [PD\\_WaitForGetSourceCapabilities](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

## Format

```
call PD_SetGetSourceCapSetting( PD_GetSourceCapability_Settings $settings )
```

## Parameters

\$settings

Setting type is [PD\\_GetSourceCapability\\_Settings](#). Available fields of this type are:

Field Name	Possible/Default Values	Description
WaitTimeout	PD_DEFAULT_TIMEOUT_INFINITE(default)	Wait time-out(micro second) for receiving GetSourceCap message.
ResponseType	PD_RESPONSE_UNSPECIFIED(default), PD_RESPONSE_NOT_SUPPORTED	Indicates the response type upon receiving GetSourceCap message.
SkipNegotiationAsSink	PD_FALSE(default), PD_TRUE	Enables the sink to skips negotiation after receiving SourceCap message.

## Result

None

## Examples

```
$getsrccap_setting = PD_GetSourceCapability_Settings
{
    ResponseType = PD_RESPONSE_NOT_SUPPORTED
}
call PD_SetGetSourceCapSetting( $getsrccap_setting )
```

## 5.1.40 PD\_GetSourceCapabilities

Starts *GetSourceCapabilities* AMS.

### Format

```
Call PD_GetSourceCapabilities()
```

### Parameters

None

### Result

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

List of result values:

Result Value	Description
<code>PD_RESULT_OK</code>	Command succeeded
<code>PD_RESULT_FAILED</code>	Command failed. In this case corresponding sub results for <code>PD_SendPacket</code> and <code>PD_ReceivePacket</code> are valid also (depends on the error type which has been occurred during sending or receiving data).
<code>PD_SUBRESULT_RESPONSE_REJECT</code>	Subresult - Reject message received as response
<code>PD_SUBRESULT_RESPONSE_TIMEOUT</code>	Subresult - No messages received as response
<code>PD_SUBRESULT_RESPONSE_NOT_SUPPORTED</code>	Rev3.0 only. Subresult - Not_Supported message received as response

### Examples

```
Call PD_GetSourceCapabilities()
```

## 5.1.41 PD\_WaitForGetSourceCapabilities

Waits for user-defined time-out to receive `Get_Source_Cap` message. It will respond to incoming messages as part of the *Get\_Source\_Cap* AMS.

**Note:** The `PD_SetGetSourceCapSetting` function may need to be called prior calling this function.

### Format

```
Call PD_WaitForGetSourceCapabilities()
```

### Parameters

None

### Result

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

List of result values:

Result Value	Description
<code>PD_RESULT_OK</code>	Command succeeded
<code>PD_RESULT_FAILED</code>	Command failed. In this case corresponding sub results for <code>PD_SendPacket</code> and <code>PD_ReceivePacket</code> are valid also

	(depends on the error type which has been occurred during sending or receiving data).
PD_SUBRESULT_MSG_NOT_RECEIVED	Subresult - Get_Source_Cap message not received
PD_SUBRESULT_REQUEST_MSG_INVALID_INDEX	Subresult - Invalid index in request message
PD_SUBRESULT_RESPONSE_WAIT	Subresult - Wait message has been sent as request message response
PD_SUBRESULT_RESPONSE_REJECT	Subresult - Reject message has been sent as request message response
PD_SUBRESULT_RESPONSE_NOT_SUPPORTED	Rev3.0 only. Subresult - Not_Supported message has been sent as response

### Examples

Call `PD_WaitForGetSourceCapabilities()`

### 5.1.42 PD\_SetGetSinkCapSetting

It has to be called prior to call `PD_WaitForGetSinkCapabilities` or `PD_DelayAutoResponse` functions to take effect.

#### Format

Call `PD_SetGetSinkCapSetting( PD_GetSinkCapability_Settings $settings )`

#### Parameters

`$settings`

Setting type is `PD_GetSinkCapability_Settings`. For available fields of this type are:

Field Name	Possible/Default Values	Description
WaitTimeout	PD_DEFAULT_TIMEOUT_INFINITE(default)	Wait time-out(micro second) for receiving GetSourceCap message.
ResponseType	PD_RESPONSE_UNSPECIFIED(default), PD_RESPONSE_NOT_SUPPORTED	Indicates the response type upon receiving GetSourceCap message.
NoGoodCRCToSnkCap	PD_FALSE(default), PD_TRUE	Prevents the source device from sending GoodCRC for the SinkCap messages.

#### Result

None

### Examples

```
$getsnkcap_setting = PD_GetSinkCapability_Settings
{
    ResponseType = PD_RESPONSE_NOT_SUPPORTED
}
Call PD_SetGetSinkCapSetting( $getsnkcap_setting )
```

### 5.1.43 PD\_GetSinkCapabilities

Starts the `GetSinkCapabilities` AMS.

#### Format

Call `PD_GetSinkCapabilities()`

#### Parameters

None

## Result

User can evaluate the command results(including sub-results) using IfMatched/ElseMatched command.

List of result values:

Result Value	Description
PD_RESULT_OK	Command succeeded
PD_RESULT_FAILED	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the error type which has been occurred during sending or receiving data).
PD_SUBRESULT_RESPONSE_REJECT	Subresult - Reject message received as response
PD_SUBRESULT_RESPONSE_TIMEOUT	Subresult - No messages received as response
PD_SUBRESULT_RESPONSE_NOT_SUPPORTED	Rev3.0 only. Subresult - Not_Supported message received as response

## Examples

```
call PD_GetSinkCapabilities()
```

### 5.1.44 PD\_WaitForGetSinkCapabilities

Waits for user-defined timeout to receive `Get_Sink_Cap` message. It will respond to incoming messages as part of *GetSinkCapabilities* AMS.

**Note:** The [PD\\_SetGetSinkCapSetting](#) function may need to be called prior calling this function.

## Format

```
call PD_WaitForGetSinkCapabilities()
```

## Parameters

None

## Result

User can evaluate the command results(including sub-results) using IfMatched/ElseMatched command.

List of result values:

Result Value	Description
PD_RESULT_OK	Command succeeded
PD_RESULT_FAILED	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the error type which has been occurred during sending or receiving data).
PD_SUBRESULT_MSG_NOT_RECEIVED	Subresult - <code>Get_Sink_Cap</code> message not received.
PD_SUBRESULT_RESPONSE_REJECT	Subresult - Reject message has been sent as response.
PD_SUBRESULT_RESPONSE_NOT_SUPPORTED	Rev3.0 only. Subresult - Not_Supported message has been sent as response

## Examples

```
call PD_WaitForGetSinkCapabilities()
```

## 5.1.45 PD\_SendBISTCarrierMode

Starts *BISTCarrierMode* AMS.

### Format

```
Call PD_SendBISTCarrierMode(OrderedSetType)
```

### Parameters

#### OrderedSetType

Indicates the Ordered Set type

possible values:

```
PD_ORDERED_SET_TYPE_SOP  
PD_ORDERED_SET_TYPE_SOP_PRIME  
PD_ORDERED_SET_TYPE_SOP_DOUBLE_PRIME
```

### Result

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

List of result values:

Result Value	Description
<code>PD_RESULT_OK</code>	Command succeeded
<code>PD_RESULT_FAILED</code>	Command failed

### Examples

```
Call PD_SendBISTCarrierMode(PD_ORDERED_SET_TYPE_SOP)
```

## 5.1.46 PD\_SendBISTTestData

Starts *BISTTestData* AMS.

### Format

```
Call PD_SendBISTTestData( OrderedSetType, PD_BISTTestData $test_data )
```

### Parameters

#### OrderedSetType

Indicates the Ordered Set type

possible values:

```
PD_ORDERED_SET_TYPE_SOP  
PD_ORDERED_SET_TYPE_SOP_PRIME  
PD_ORDERED_SET_TYPE_SOP_DOUBLE_PRIME
```

#### \$test\_data

Defines the Test Data to be sent to the UUT

### Result

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

List of result values:

Result Value	Description
<a href="#">PD_RESULT_OK</a>	Command succeeded
<a href="#">PD_RESULT_FAILED</a>	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> are valid also (depends on the error type which has been occurred during sending data).

### Examples

```
$test_data = PD_BISTTestData
{
    TestData = { 00 00 00 00
                 AA AA AA AA
                 AA AA 00 00
                 AA AA AA AA
                 00 00 AA AA
                 AA AA AA AA }
}

call PD_SendBISTTestData( PD_ORDERED_SET_TYPE_SOP_PRIME, $test_data )
```

## 5.1.47 PD\_GetSourceCapExtended

Applicable to PD Rev 3.0 only. Starts *GetSourceCapExtended* AMS.

### Format

```
call PD_GetSourceCapExtended()
```

### Parameters

None

### Result

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

List of result values:

Result Value	Description
<a href="#">PD_RESULT_OK</a>	Command succeeded
<a href="#">PD_RESULT_FAILED</a>	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the error type which has been occurred during sending or receiving data).
<a href="#">PD_SUBRESULT_RESPONSE_TIMEOUT</a>	Subresult - No response received.
<a href="#">PD_SUBRESULT_RESPONSE_NOT_SUPPORTED</a>	Subresult - Not_Supported message received.

### Examples

```
call PD_GetSourceCapExtended()
```

## 5.1.48 PD\_SetGetSrcCapExtSetting

Applicable to PD Rev 3.0 only. It has to be called prior to call [PD\\_WaitForGetSrcCapExtended](#) or [PD\\_DelayAutoResponse](#) functions.

## Format

```
Call PD_SetGetSrcCapExtSetting( PD_GetSourceCapExtented_Settings $settings )
```

## Parameters

**\$settings**

Setting type is `PD_GetSourceCapExtented_Settings`. Available fields for this type are:

Field Names	Possible/Default Values	Description
<code>WaitTimeout</code>	<code>PD_DEFAULT_TIMEOUT_INFINITE</code> (default)	Wait TimeOut(micro second) to receive <code>Get_Source_Cap_Extended</code> message. Default:
<code>ResponseType</code>	<code>PD_RESPONSE_NOT_SUPPORTED</code> , <code>PD_RESPONSE_UNSPECIFIED</code> (default)	Indicates response upon receiving the <code>Get_Source_Cap_Extended</code> message.
<code>SkipSrcCapExt</code>	<code>PD_TRUE</code> , <code>PD_FALSE</code> (default)	Indicates whether to skip sending <code>Source_Capabilities_Extended</code> message or not.
<code>SendSrcCapExtDelay</code>	0(default)	Defines the delay before sending <code>Source_Capabilities_Extended</code> message.

## Result

None

## Examples

```
$getsrcapext_setting = PD_GetSourceCapExtented_Settings
{
    ResponseType = PD_RESPONSE_NOT_SUPPORTED
}
Call PD_SetGetSrcCapExtSetting( $getsrcapext_setting )
```

## 5.1.49 PD\_WaitForGetSrcCapExtended

Applicable to PD Rev 3.0 only. Wait for user-defined time-out to receive `Get_Source_Cap_Extended` message. It will respond to incoming messages as part of `GetSourceCapExtended` AMS.

**Note:** The `PD_SetGetSrcCapExtSetting`, `PD_SetSrcCapExtDataBlock` and `PD_ResetSrcCapExtDataBlock` functions may need to be called prior calling this function.

## Format

```
Call PD_WaitForGetSrcCapExtended()
```

## Parameters

None

## Result

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

List of result values:

Result Value	Description
<code>PD_RESULT_OK</code>	Command succeeded
<code>PD_RESULT_FAILED</code>	Command failed. In this case corresponding sub results for <code>PD_SendPacket</code> and <code>PD_ReceivePacket</code> are valid also (depends

	on the error type which has been occurred during sending or receiving data).
<a href="#">PD_SUBRESULT_MSG_NOT_RECEIVED</a>	Subresult - Get_Source_Cap_Extended message not received.
<a href="#">PD_SUBRESULT_RESPONSE_NOT_SUPPORTED</a>	Subresult - Not_Supported message sent as response.

### Examples

```
Call PD_WaitForGetSrcCapExtended()
```

## 5.1.50 PD\_SetSrcCapExtDataBlock

Applicable to PD Rev 3.0 only. Sets *Source Capabilities Extended Data Block* in PD Exerciser. It has to be called prior calling the [PD\\_WaitForGetSrcCapExtended](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

### Format

```
Call PD_SetSrcCapExtDataBlock( PD_SourceCapExtDataBlock $src_cap_ext )
```

### Parameters

\$src\_cap\_ext

parameter type is `PD_SourceCapExtDataBlock`. Refer to [PD\\_SourceCapExtendedMsg](#) for available data fields.

### Result

None

### Examples

```
$src_cap_ext = PD_SourceCapExtDataBlock
Call PD_SetSrcCapExtDataBlock( $src_cap_ext )
```

## 5.1.51 PD\_ResetSrcCapExtDataBlock

Applicable to PD Rev 3.0 only. Clears the *Source Capabilities Extended Data Block* in PD Exerciser. It should be called before calling the [PD\\_SetSrcCapExtDataBlock](#) function.

### Format

```
Call PD_ResetSrcCapExtDataBlock()
```

### Parameters

None

### Result

None

### Examples

```
Call PD_ResetSrcCapExtDataBlock()
```

## 5.1.52 PD\_GetStatus

Applicable to PD Rev 3.0 only. Starts the *GetStatus* AMS.

### Format

Call `PD_GetStatus()`

### Parameters

None

### Result

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

List of result values:

Result Value	Description
<code>PD_RESULT_OK</code>	Command succeeded
<code>PD_RESULT_FAILED</code>	Command failed. In this case corresponding sub results for <code>PD_SendPacket</code> and <code>PD_ReceivePacket</code> are valid also (depends on the error type which has been occurred during sending or receiving data).
<code>PD_SUBRESULT_RESPONSE_TIMEOUT</code>	Subresult - No response received.
<code>PD_SUBRESULT_RESPONSE_NOT_SUPPORTED</code>	Subresult - Not_Supported message received.

### Examples

Call `PD_GetStatus()`

## 5.1.53 PD\_SetGetStatusSetting

Applicable to PD Rev 3.0 only. It has to be called prior calling the `PD_WaitForGetStatus` or `PD_DelayAutoResponse` functions to take effect.

### Format

Call `PD_SetGetStatusSetting( PD_GetStatus_Settings $settings )`

### Parameters

`$settings`

Parameter type is `PD_GetStatus_Settings`. Available fields for this type are:

Field Names	Possible/Default Values	Description
<code>WaitTimeout</code>	<code>PD_DEFAULT_TIMEOUT_INFINITE</code> (default)	Wait TimeOut(micro second) to receive Get_Status message.
<code>ResponseType</code>	<code>PD_RESPONSE_NOT_SUPPORTED</code> , <code>PD_RESPONSE_UNSPECIFIED</code> (default)	Indicates response upon receiving the Get_Status message.

### Result

None

### Examples

```
$getstatus_setting = PD_GetStatus_Settings
{
    ResponseType = PD_RESPONSE_NOT_SUPPORTED
}
Call PD_SetGetStatusSetting( $getstatus_setting )
```

### 5.1.54 PD\_WaitForGetStatus

Applicable to PD Rev 3.0 only. Waits for user-defined time-out to receive `Get_Status` message. It will respond to incoming messages as part of `GetStatus` AMS.

**Note:** The `PD_SetGetStatusSetting`, `PD_SetStatusDataBlock` and `PD_ResetStatusDataBlock` functions may need to be called prior calling this function.

#### Format

```
Call PD_WaitForGetStatus( )
```

#### Parameters

None

#### Result

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

List of result values:

Result Value	Description
<code>PD_RESULT_OK</code>	Command succeeded
<code>PD_RESULT_FAILED</code>	Command failed. In this case corresponding sub results for <code>PD_SendPacket</code> and <code>PD_ReceivePacket</code> are valid also (depends on the error type which has been occurred during sending or receiving data).
<code>PD_SUBRESULT_MSG_NOT RECEIVED</code>	Subresult - <code>Get_Status</code> message not received.
<code>PD_SUBRESULT_RESPONSE NOT SUPPORTED</code>	Subresult - <code>Not_Supported</code> message sent as response.

#### Examples

```
Call PD_WaitForGetStatus()
```

### 5.1.55 PD\_SetStatusDataBlock

Applicable to PD Rev 3.0 only. Sets the *Status Data Block* in PD Exerciser. It has to be called prior calling the `PD_WaitForGetStatus` or `PD_DelayAutoResponse` functions to take effect.

#### Format

```
Call PD_SetStatusDataBlock( PD_StatusDataBlock $status_db )
```

#### Parameters

`$status_db`

Parameter type is `PD_StatusDataBlock`. Refer to `PD_StatusMsg` for available fields.

#### Result

None

#### Examples

```
$status_db = PD_StatusDataBlock  
Call PD_SetStatusDataBlock( $status_db )
```

### **5.1.56 PD\_ResetStatusDataBlock**

Applicable to PD Rev 3.0 only. Clears the *Status Data Block* in PD Exerciser. It should be called prior calling the [PD\\_SetStatusDataBlock](#) function.

#### **Format**

```
Call PD_ResetStatusDataBlock()
```

#### **Parameters**

None

#### **Result**

None

#### **Examples**

```
Call PD_ResetStatusDataBlock()
```

### **5.1.57 PD\_GetBatteryStatus**

Applicable to PD Rev 3.0 only. Starts the *GetBatteryStatus* AMS.

**Note:** The [PD\\_SetGetBatteryStatusDataBlock](#) may need to be called prior calling this function.

#### **Format**

```
Call PD_GetBatteryStatus()
```

#### **Parameters**

None

#### **Result**

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

List of result values:

Result Value	Description
<a href="#">PD_RESULT_OK</a>	Command succeeded
<a href="#">PD_RESULT_FAILED</a>	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the error type which has been occurred during sending or receiving data).
<a href="#">PD_SUBRESULT_RESPONSE_TIMEOUT</a>	Subresult - No response received.
<a href="#">PD_SUBRESULT_RESPONSE_NOT_SUPPORTED</a>	Subresult - Not_Supported message received.

#### **Examples**

```
Call PD_GetBatteryStatus()
```

### **5.1.58 PD\_SetGetBatteryStatusDataBlock**

Applicable to PD Rev 3.0 only. Sets the *GetBatteryStatus Data Block* in PD Exerciser. It has to be called before [PD\\_GetBatteryStatus](#) function to take effect.

#### **Format**

```
Call PD_SetGetBatteryStatusDataBlock( PD_GetBatteryStatusDataBlock  
$get_battery_stat_db )
```

### Parameters

`$get_battery_stat_db`

Parameter type is `PD_GetBatteryStatusDataBlock`. Refer to [PD\\_GetBatteryStatusMsg](#) for available fields.

### Result

None

### Examples

```
$get_battery_stat_db = PD_GetBatteryStatusDataBlock  
Call PD_SetGetBatteryStatusDataBlock( $get_battery_stat_db )
```

## 5.1.59 PD\_SetGetBatteryStatusSetting

Applicable to PD Rev 3.0 only. It has to be called prior calling the [PD\\_WaitForGetBatteryStatus](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

### Format

```
Call PD_SetGetBatteryStatusSetting( PD_GetBatteryStatus_Settings $settings )
```

### Parameters

`$settings`

Parameter type is `PD_GetBatteryStatus_Settings`. Available fields of this type are:

Field Names	Possible/Default Values	Description
<code>WaitTimeout</code>	<code>PD_DEFAULT_TIMEOUT_INFINITE</code> (default)	Wait TimeOut(micro second) to receive <code>Get_Battery_Status</code> message.
<code>ResponseType</code>	<code>PD_RESPONSE_NOT_SUPPORTED</code> , <code>PD_RESPONSE_UNSPECIFIED</code> (default)	Indicates response upon receiving the <code>Get_Battery_Status</code> message.

### Result

None

### Examples

```
$getbattstatus_setting = PD_GetBatteryStatus_Settings  
{  
    ResponseType = PD_RESPONSE_NOT_SUPPORTED  
}  
Call PD_SetGetBatteryStatusSetting( $getbattstatus_setting )
```

## 5.1.60 PD\_WaitForGetBatteryStatus

Applicable to PD Rev 3.0 only. Waits for user-defined time-out to receive `Get_Battery_Status` message. It will respond to incoming messages as part of `GetBatteryStatus` AMS.

**Note:** The [PD\\_SetGetBatteryStatusSetting](#), [PD\\_SetBatteryStatusDO](#) and [PD\\_ResetBatteryStatusDO](#) functions may need to be called prior to call this function.

### Format

```
Call PD_WaitForGetBatteryStatus()
```

### Parameters

None

### Result

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

List of result values:

Result Value	Description
<code>PD_RESULT_OK</code>	Command succeeded
<code>PD_RESULT_FAILED</code>	Command failed. In this case corresponding sub results for <code>PD_SendPacket</code> and <code>PD_ReceivePacket</code> are valid also (depends on the error type which has been occurred during sending or receiving data).
<code>PD_SUBRESULT_MSG_NOT_RECEIVED</code>	Subresult - <code>Get_Battery_Status</code> message not received.
<code>PD_SUBRESULT_RESPONSE_NOT_SUPPORTED</code>	Subresult - <code>Not_Supported</code> message sent as response.

### Examples

```
Call PD_WaitForGetBatteryStatus()
```

## 5.1.61 PD\_SetBatteryStatusDO

Applicable to PD Rev 3.0 only. Sets the *BatteryStatus Data Object* in PD Exerciser. It has to be called prior calling the `PD_WaitForGetBatteryStatus` or `PD_DelayAutoResponse` functions to take effect.

### Format

```
Call PD_SetBatteryStatusDO( PD_BatteryStatusDataObject $battery_status )
```

### Parameters

`$battery_status`

Parameter type is `PD_BatteryStatusDataObject`. Refer to `PD_BatteryStatusMsg` for available fields of this type.

### Result

None

### Examples

```
$battery_status = PD_BatteryStatusDataObject  
Call PD_SetBatteryStatusDO( $battery_status )
```

## 5.1.62 PD\_ResetBatteryStatusDO

Applicable to PD Rev 3.0 only. Clears the *BatteryStatus Data Object* in PD Exerciser. It should be called prior to call the `PD_SetBatteryStatusDO` function.

### Format

```
Call PD_ResetBatteryStatusDO()
```

## Parameters

None

## Result

None

## Examples

```
call PD_ResetBatteryStatusDO()
```

## 5.1.63 PD\_Alert

Applicable to PD Rev 3.0 only. Starts *Alert* AMS.

**Note:** The [PD\\_SetAlertDO](#) function may need to be called prior to call this function.

## Format

```
call PD_Alert()
```

## Parameters

None

## Result

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

List of result values:

Result Value	Description
<a href="#">PD_RESULT_OK</a>	Command succeeded
<a href="#">PD_RESULT_FAILED</a>	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> are valid also (depends on the error type which has been occurred during sending data).

## Examples

```
call PD_Alert()
```

## 5.1.64 PD\_SetAlertDO

Applicable to PD Rev 3.0 only. Sets *Alert Data Object* in PD Exerciser. It has to be called prior calling the [PD\\_Alert](#) function to take effect.

## Format

```
call PD_SetAlertDO( PD_AlertDataObject $alert_do )
```

## Parameters

`$alert_do`

Parameter type is `PD_AlertDataObject`. Refer to [PD\\_AlertMsg](#) for available fields of this type.

## Result

None

## Examples

```
$alert_do = PD_AlertDataobject  
Call PD_SetAlertDO( $alert_do )
```

### 5.1.65 PD\_SetAlertSetting

Applicable to PD Rev 3.0 only. It has to be called prior calling the [PD\\_WaitForAlert](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

#### Format

```
Call PD_SetAlertSetting( PD_Alert_Settings $settings )
```

#### Parameters

##### \$settings

Parameter type is `PD_Alert_Settings`. Available fields for this type are:

Field Names	Possible/Default Values	Description
<code>WaitTimeout</code>	<code>PD_DEFAULT_TIMEOUT_INFINITE</code> (default)	Wait TimeOut(micro second) to receive Alert message.
<code>ResponseType</code>	<code>PD_RESPONSE_NOT_SUPPORTED</code> , <code>PD_RESPONSE_UNSPECIFIED</code> (default)	Indicates response upon receiving the Alert message.

#### Result

None

## Examples

```
$alert_setting = PD_Alert_Settings  
{  
    ResponseType = PD_RESPONSE_NOT_SUPPORTED  
}  
Call PD_SetAlertSetting( $alert_setting )
```

### 5.1.66 PD\_WaitForAlert

Applicable to PD Rev 3.0 only. Waits for a user-defined time-out to receive `Alert` message. It will respond to incoming messages as part of the `Alert` AMS.

**Note:** The [PD\\_SetAlertSetting](#) function may need to be called prior to call this function.

#### Format

```
Call PD_WaitForAlert()
```

#### Parameters

None

#### Result

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

List of result values:

Result Value	Description
<code>PD_RESULT_OK</code>	Command succeeded
<code>PD_RESULT_FAILED</code>	Command failed. In this case corresponding sub results for

	<a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the error type which has been occurred during sending or receiving data).
<a href="#">PD_SUBRESULT_MSG_NOT_RECEIVED</a>	Subresult - Alert message not received.
<a href="#">PD_SUBRESULT_RESPONSE_NOT_SUPPORTED</a>	Subresult - Not_Supported message sent as response.

## Examples

Call [PD\\_WaitForAlert\(\)](#)

### 5.1.67 PD\_GetBatteryCap

Applicable to PD Rev 3.0 only. Starts the *GetBatteryCap* AMS.

**Note:** The [PD\\_SetGetBatteryCapDataBlock](#) function may need to be called prior to call this function.

#### Format

Call [PD\\_GetBatteryCap\(\)](#)

#### Parameters

None

#### Result

User can evaluate the command results(including sub-results) using [IfMatched](#)/[ElseMatched](#) command.

List of result values:

Result Value	Description
<a href="#">PD_RESULT_OK</a>	Command succeeded
<a href="#">PD_RESULT_FAILED</a>	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the error type which has been occurred during sending or receiving data).
<a href="#">PD_SUBRESULT_RESPONSE_TIMEOUT</a>	Subresult - No response received.
<a href="#">PD_SUBRESULT_RESPONSE_NOT_SUPPORTED</a>	Subresult - Not_Supported message received.

## Examples

Call [PD\\_GetBatteryCap\(\)](#)

### 5.1.68 PD\_SetGetBatteryCapDataBlock

Applicable to PD Rev 3.0 only. Sets the *GetBatteryCap Data Block* in PD Exerciser. It has to be called prior calling the [PD\\_GetBatteryCap](#) function to take effect.

#### Format

Call [PD\\_SetGetBatteryCapDataBlock\( PD\\_GetBatteryCapDataBlock \\$get\\_battery\\_cap\\_db \)](#)

#### Parameters

[\\$get\\_battery\\_cap\\_db](#)

Parameter type is [PD\\_GetBatteryCapDataBlock](#). Refer to [PD\\_GetBatteryCapMsg](#) for available fields of this type.

## Result

None

## Examples

```
$get_battery_cap_db = PD_GetBatteryCapDataBlock  
Call PD_SetGetBatteryCapDataBlock( $get_battery_cap_db )
```

## 5.1.69 PD\_SetGetBatteryCapSetting

Applicable to PD Rev 3.0 only. It has to be called prior calling the [PD\\_WaitForGetBatteryCap](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

## Format

```
Call PD_SetGetBatteryCapSetting( PD_GetBatteryCap_Settings $settings )
```

## Parameters

### \$settings

Parameter type is [PD\\_GetBatteryCap\\_Settings](#). Available fields for this type are:

Field Names	Possible/Default Values	Description
<a href="#">WaitTimeout</a>	PD_DEFAULT_TIMEOUT_INFINITE(default)	Wait TimeOut(micro second) to receive Get_Battery_Cap message.
<a href="#">ResponseType</a>	PD_RESPONSE_NOT_SUPPORTED, PD_RESPONSE_UNSPECIFIED(default)	Indicates response upon receiving the Get_Battery_Cap message.

## Result

None

## Examples

```
$getbattcap_setting = PD_GetBatteryCap_Settings  
{  
    ResponseType = PD_RESPONSE_NOT_SUPPORTED  
}  
Call PD_SetGetBatteryCapSetting( $getbattcap_setting )
```

## 5.1.70 PD\_WaitForGetBatteryCap

Applicable to PD Rev 3.0 only. Waits for user-defined time-out to receive `Get_Battery_Cap` message. It will respond to incoming messages as part of the `GetBatteryCap` AMS.

**Note:** The [PD\\_SetGetBatteryCapSetting](#), [PD\\_SetBatteryCapDataBlock](#) and [PD\\_ResetBatteryCapDataBlock](#) functions may need to be called prior to call this function.

## Format

```
Call PD_WaitForGetBatteryCap()
```

## Parameters

None

## Result

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

List of result values:

Result Value	Description
<a href="#">PD_RESULT_OK</a>	Command succeeded
<a href="#">PD_RESULT_FAILED</a>	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the error type which has been occurred during sending or receiving data).
<a href="#">PD_SUBRESULT_MSG_NOT_RECEIVED</a>	Subresult - Get_Battery_Cap not received.
<a href="#">PD_SUBRESULT_RESPONSE_NOT_SUPPORTED</a>	Subresult - Not_Supported message sent as response.

### Examples

```
Call PD_WaitForGetBatteryCap()
```

## 5.1.71 PD\_SetBatteryCapDataBlock

Applicable to PD Rev 3.0 only. Sets the *BatteryCap Data Block* in PD Exerciser. It has to be called prior calling the [PD\\_WaitForGetBatteryCap](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

### Format

```
Call PD_SetBatteryCapDataBlock( PD_BatteryCapDataBlock $battery_cap_db )
```

### Parameters

\$battery\_cap\_db

Parameter type is [PD\\_BatteryCapDataBlock](#). Refer to [PD\\_BatteryCapabilitiesMsg](#) for available fields of this type.

### Result

None

### Examples

```
$battery_cap_db = PD_BatteryCapDataBlock  
Call PD_SetBatteryCapDataBlock( $battery_cap_db )
```

## 5.1.72 PD\_ResetBatteryCapDataBlock

Applicable to PD Rev 3.0 only. Clears the *BatteryCap Data Block* in PD Exerciser. Should be called before calling [PD\\_SetBatteryCapDataBlock](#) command.

### Format

```
Call PD_ResetBatteryCapDataBlock()
```

### Parameters

None

### Result

None

### Examples

```
Call PD_ResetBatteryCapDataBlock()
```

## 5.1.73 PD\_GetManufacturerInfo

Applicable to PD Rev 3.0 only. Starts *GetManufacturerInfo* AMS.

**Note:** The [PD\\_SetGetManufacturerInfoDataBlock](#) function may need to be called prior to call this function.

### Format

```
Call PD_GetManufacturerInfo( OrderedSetType )
```

### Parameters

OrderedSetType

possible values:

```
PD_ORDERED_SET_TYPE_SOP  
PD_ORDERED_SET_TYPE_SOP_PRIME  
PD_ORDERED_SET_TYPE_SOP_DOUBLE_PRIME
```

### Result

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

List of result values:

Result Value	Description
<a href="#">PD_RESULT_OK</a>	Command succeeded
<a href="#">PD_RESULT_FAILED</a>	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the error type which has been occurred during sending or receiving data).
<a href="#">PD_SUBRESULT_RESPONSE_TIMEOUT</a>	Subresult - No response received.
<a href="#">PD_SUBRESULT_RESPONSE_NOT_SUPPORTED</a>	Subresult - Not_Supported message received.

### Examples

```
Call PD_GetManufacturerInfo( PD_ORDERED_SET_TYPE_SOP )
```

## 5.1.74 PD\_SetGetManufacturerInfoDataBlock

Applicable to PD Rev 3.0 only. Sets *GetManufacturerInfo Data Block* in PD Exerciser. It has to be called prior calling the [PD\\_GetManufacturerInfo](#) function to take effect.

### Format

```
Call PD_SetGetManufacturerInfoDataBlock( PD_GetManufacturerInfoDataBlock  
$get_manuf_info_db )
```

### Parameters

\$get\_manuf\_info\_db

Parameter type is [PD\\_GetManufacturerInfoDataBlock](#). Refer to [PD\\_GetManufacturerInfoMsg](#) for available fields of this type.

### Result

None

## Examples

```
$get_manuf_info_db = PD_GetManufacturerInfoDataBlock  
Call PD_SetGetManufacturerInfoDataBlock( $get_manuf_info_db )
```

### 5.1.75 PD\_SetGetManufacturerInfoSetting

Applicable to PD Rev 3.0 only. It has to be called prior calling the [PD\\_WaitForGetManufacturerInfo](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

#### Format

```
Call PD_SetGetManufacturerInfoSetting( PD_GetManufacturerInfo_Settings $settings )
```

#### Parameters

**\$settings**

Parameter type is PD\_GetManufacturerInfo\_Settings. Available fields of this type are:

Field Names	Possible/Default Values	Description
<a href="#">WaitTimeout</a>	PD_DEFAULT_TIMEOUT_INFINITE(default)	Wait TimeOut(in micro seconds) to receive Get_Manufacturer_Info message.
<a href="#">ResponseType</a>	PD_RESPONSE_NOT_SUPPORTED, PD_RESPONSE_UNSPECIFIED(default)	Indicates response upon receiving the Get_Manufacturer_Info message.

#### Result

None

## Examples

```
$getmaninfo_setting = PD_GetManufacturerInfo_Settings  
{  
    WaitTimeout = 50000  
}  
Call PD_SetGetManufacturerInfoSetting( $getmaninfo_setting )
```

### 5.1.76 PD\_WaitForGetManufacturerInfo

Applicable to PD Rev 3.0 only. Waits for user-defined time-out to receive Manufacturer\_Info message. It will respond to incoming messages as part of the *GetManufacturerInfo* AMS.

**Note:** The [PD\\_SetGetManufacturerInfoSetting](#) and [PD\\_SetManufacturerInfoDataBlock](#) functions may need to be called prior to call this function.

#### Format

```
Call PD_WaitForGetManufacturerInfo()
```

#### Parameters

None

#### Result

User can evaluate the command results(including sub-results) using IfMatched/ElseMatched command.

List of result values:

Result Value	Description
--------------	-------------

<a href="#">PD_RESULT_OK</a>	Command succeeded
<a href="#">PD_RESULT_FAILED</a>	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the error type which has been occurred during sending or receiving data).
<a href="#">PD_SUBRESULT_MSG_NOT_RECEIVED</a>	Subresult - Get_Manufacturer_Info message not received.
<a href="#">PD_SUBRESULT_RESPONSE_NOT_SUPPORTED</a>	Subresult - Not_Supported message sent as response.

### Examples

```
Call PD_WaitForGetManufacturerInfo()
```

## 5.1.77 PD\_SetManufacturerInfoDataBlock

Applicable to PD Rev 3.0 only. Sets *ManufacturerInfo Data Block* in PD Exerciser. It has to be called prior calling the [PD\\_WaitForGetManufacturerInfo](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

### Format

```
Call PD_SetManufacturerInfoDataBlock( PD_ManufacturerInfoDataBlock  
$manufacturer_info_db )
```

### Parameters

`$manufacturer_info_db`

Parameter type is `PD_ManufacturerInfoDataBlock`. Refer to [PD\\_ManufacturerInfoMsg](#) for available fields of this type.

### Result

None

### Examples

```
$manufacturer_info_db = PD_ManufacturerInfoDataBlock  
Call PD_SetManufacturerInfoDataBlock( $manufacturer_info_db )
```

## 5.1.78 PD\_SetSecurityRequestSetting

Applicable to PD Rev 3.0 only. It has to be called prior calling the [PD\\_WaitForSecurityRequest](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

### Format

```
Call PD_SetSecurityRequestSetting( PD_SecurityRequest_Settings $settings )
```

### Parameters

`$settings`

Parameter type is `PD_SecurityRequest_Settings`. Available fields for this type are:

Field Names	Possible/Default Values	Description
<a href="#">WaitTimeout</a>	<code>PD_DEFAULT_TIMEOUT_INFINITE</code> (default)	Wait TimeOut(in micro seconds) to receive Security_Request message.
<a href="#">ResponseType</a>	<code>PD_RESPONSE_NOT_SUPPORTED</code> , <code>PD_RESPONSE_UNSPECIFIED</code> (default)	Indicates response upon receiving the Security_Request message.

### Result

None

### Examples

```
$secreq_settings = PD_SecurityRequest_Settings
{
    WaitTimeout = 50000
}
Call PD_SetSecurityRequestSetting( $secreq_settings )
```

## 5.1.79 PD\_SecurityRequest

Applicable to PD Rev 3.0 only. Starts the *SecurityRequest* AMS.

**Note:** The [PD\\_SetSecurityRequestDataBlock](#) function may need to be called prior to call this function.

### Format

```
Call PD_SecurityRequest( OrderedSetType )
```

### Parameters

OrderedSetType

Possible values:

```
PD_ORDERED_SET_TYPE_SOP
PD_ORDERED_SET_TYPE_SOP_PRIME
PD_ORDERED_SET_TYPE_SOP_DOUBLE_PRIME
```

### Result

User can evaluate the command results(including sub-results) using IfMatched/ElseMatched command.

List of result values:

Result Value	Description
PD_RESULT_OK	Command succeeded
PD_RESULT_FAILED	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the error type which has been occurred during sending or receiving data).
PD_SUBRESULT_RESPONSE_TIMEOUT	Subresult - No response received.
PD_SUBRESULT_RESPONSE_NOT_SUPPORTED	Subresult - Not_Supported message received.

### Examples

```
Call PD_SecurityRequest( PD_ORDERED_SET_TYPE_SOP )
```

## 5.1.80 PD\_SetSecurityRequestDataBlock

Applicable to PD Rev 3.0 only. Sets the *SecurityRequest Data Block* in PD Exerciser. It has to be called prior calling the [PD\\_SecurityRequest](#) function to take effect.

### Format

```
Call PD_SetSecurityRequestDataBlock( PD_SecurityRequestDB $security_req_db )
```

### Parameters

\$security\_req\_db

Parameter type is PD\_SecurityRequestDB. Refer to [PD\\_SecurityRequestMsg](#) for available types which are derived from this type.

## Result

None

## Examples

```
$security_req_db = PD_SRQDB_GetDigests  
Call PD_SetSecurityRequestDataBlock( $security_req_db )
```

### 5.1.81 PD\_WaitForSecurityRequest

Applicable to PD Rev 3.0 only. Waits for user-defined time-out to receive Security\_Request message. It will respond to incoming messages as part of the *SecurityRequest* AMS.

**Note:** The [PD\\_SetSecurityRequestSetting](#) and [PD\\_SetSecurityResponseDataBlock](#) functions may need to be called prior to call this function.

## Format

```
Call PD_WaitForSecurityRequest()
```

## Parameters

None

## Result

User can evaluate the command results(including sub-results) using IfMatched/ElseMatched command.

List of result values:

Result Value	Description
PD_RESULT_OK	Command succeeded
PD_RESULT_FAILED	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the error type which has been occurred during sending or receiving data).
PD_SUBRESULT_MSG_NOT RECEIVED	Subresult - Security_Request message not received.
PD_SUBRESULT_RESPONSE_NOT_SUPPORTED	Subresult - Not_Supported message sent as response.

## Examples

```
Call PD_WaitForSecurityRequest()
```

### 5.1.82 PD\_SetSecurityResponseDataBlock

Sets the SecurityResponse Data Block in PD Exerciser. It must be called before [PD\\_WaitForSecurityRequest](#) or [PD\\_DelayAutoResponse](#) to take effect.

## Format

```
Call PD_SetSecurityResponseDataBlock( PD_SecurityResponseDB $security_resp_db )
```

## Parameters

\$security\_resp\_db

Parameter type is `PD_SecurityResponseDB`. Refer to [PD\\_SecurityResponseMsg](#) for available types which are derived from this type.

## Result

None

## Examples

```
$security_resp_db = PD_SRPPDB_Certificate
Call PD_SetSecurityResponseDataBlock( $security_resp_db )
```

## 5.1.83 Pd\_SetGetCountryInfoSetting

Applicable to PD Rev 3.0 only. It has to be called prior to call [Pd\\_WaitForGetCountryInfo](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

## Format

```
Call Pd_SetGetCountryInfoSetting( Pd_GetCountryInfo_Settings $settings )
```

## Parameters

`$settings`

Setting type is `Pd_GetCountryInfo_Settings`. Available fields for this type are:

Field Names	Possible/Default Values	Description
<code>WaitTimeout</code>	<code>PD_DEFAULT_TIMEOUT_INFINITE</code> (default)	Wait TimeOut(micro second) to receive <code>Get_Country_Info</code> message.
<code>ResponseType</code>	<code>PD_RESPONSE_NOT_SUPPORTED</code> , <code>PD_RESPONSE_UNSPECIFIED</code> (default)	Indicates response upon receiving the <code>Get_Country_Info</code> message.

## Result

None

## Examples

```
$getcountryinfo_setting = Pd_GetCountryInfo_Settings
{
    ResponseType = PD_RESPONSE_NOT_SUPPORTED
}
Call Pd_SetGetCountryInfoSetting( $getcountryinfo_setting )
```

## 5.1.84 Pd\_SetCountryInfoDataBlock

Applicable to PD Rev 3.0 only. Sets *CountryInfo Data Block* in PD Exerciser. It has to be called prior to call [Pd\\_WaitForGetCountryInfo](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

## Format

```
Call Pd_SetCountryInfoDataBlock( Pd_CountryInfoDataBlock $country_info_db )
```

## Parameters

`$country_info_db`

parameter type is `Pd_CountryInfoDataBlock`. Refer to [Pd\\_CountryInfoMsg](#) for available data fields.

## Result

None

### Examples

```
$country_info_db = Pd_CountryInfoDataBlock  
Call Pd_SetCountryInfoDataBlock( $country_info_db )
```

## 5.1.85 Pd\_ResetCountryInfoDataBlock

Applicable to PD Rev 3.0 only. Clears the *CountryInfo Data Block* in PD Exerciser. Should be called prior to call [Pd\\_SetCountryInfoDataBlock](#).

### Format

```
Call Pd_ResetCountryInfoDataBlock()
```

### Parameters

None

### Result

None

### Examples

```
Call Pd_ResetCountryInfoDataBlock()
```

## 5.1.86 Pd\_SetGetCountryInfoDO

Applicable to PD Rev 3.0 only. Sets *GetCountryInfo Data Object* in PD Exerciser. It has to be called prior to call [Pd\\_GetCountryInfo](#) function to take effect.

### Format

```
Call Pd_SetGetCountryInfoDO( Pd_GetCountryInfoDO $get_country_info_do )
```

### Parameters

`$get_country_info_do`

parameter type is `Pd_GetCountryInfoDO`. Refer to [Pd\\_GetCountryInfoMsg](#) for available data fields.

### Result

None

### Examples

```
$get_country_info_do = Pd_GetCountryInfoDO  
Call Pd_SetGetCountryInfoDO( $get_country_info_do )
```

## 5.1.87 Pd\_GetCountryInfo

Applicable to PD Rev 3.0 only. Starts *GetCountryInfo AMS*.

Note: The [Pd\\_SetGetCountryInfoDO](#) function may need to be called prior calling this function.

### Format

```
Call Pd_GetCountryInfo( OrderedSetType )
```

## Parameters

OrderedSetType

Possible values:

PD\_ORDERED\_SET\_TYPE\_SOP  
PD\_ORDERED\_SET\_TYPE\_SOP\_PRIME  
PD\_ORDERED\_SET\_TYPE\_SOP\_DOUBLE\_PRIME

## Result

User can evaluate the command results(including sub-results) using IfMatched/ElseMatched command.

List of result values:

Result Value	Description
PD_RESULT_OK	Command succeeded
PD_RESULT_FAILED	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the error type which has been occurred during sending or receiving data).
PD_SUBRESULT_RESPONSE_TIMEOUT	Subresult - No response received.
PD_SUBRESULT_RESPONSE_NOT_SUPPORTED	Subresult - Not_Supported message received.

## Examples

```
call Pd_GetCountryInfo(PD_ORDERED_SET_TYPE_SOP)
```

### 5.1.88 Pd\_WaitForGetCountryInfo

Applicable to PD Rev 3.0 only. Wait for user-defined time-out to receive `Get_Country_Info` message. It will respond to incoming messages as part of `GetCountryInfo` AMS.

**Note:** The [Pd\\_SetGetCountryInfoSetting](#), [Pd\\_SetCountryInfoDataBlock](#) and [Pd\\_ResetCountryInfoDataBlock](#) functions may need to be called prior calling this function.

## Format

```
call Pd_WaitForGetCountryInfo()
```

## Parameters

None

## Result

User can evaluate the command results(including sub-results) using IfMatched/ElseMatched command.

List of result values:

Result Value	Description
PD_RESULT_OK	Command succeeded
PD_RESULT_FAILED	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the error type which has been occurred during sending or receiving data).
PD_SUBRESULT_MSG_NOT_RECEIVED	Subresult - <code>Get_Country_Info</code> not received.
PD_SUBRESULT_RESPONSE_NOT_SUPPORTED	Subresult - <code>Not_Supported</code> message sent as response.

## Examples

```
Call Pd_WaitForGetCountryInfo()
```

### 5.1.89 Pd\_SetGetCountryCodesSetting

Applicable to PD Rev 3.0 only. It has to be called prior to call [Pd\\_WaitForGetCountryCodes](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

#### Format

```
Call Pd_SetGetCountryCodesSetting( Pd_GetCountryCodes_Settings $settings )
```

#### Parameters

**\$settings**

Setting type is [Pd\\_GetCountryCodes\\_Settings](#). Available fields for this type are:

Field Names	Possible/Default Values	Description
<a href="#">WaitTimeout</a>	PD_DEFAULT_TIMEOUT_INFINITE(default)	Wait TimeOut(micro second) to receive Get_Country_Codes message.
<a href="#">ResponseType</a>	PD_RESPONSE_NOT_SUPPORTED, PD_RESPONSE_UNSPECIFIED(default)	Indicates response upon receiving the Get_Country_Codes message.

#### Result

None

## Examples

```
$getcountrycodes_setting = Pd_GetCountryCodes_Settings
{
    ResponseType = PD_RESPONSE_NOT_SUPPORTED
}
Call Pd_SetGetCountryCodesSetting( $getcountrycodes_setting )
```

### 5.1.90 Pd\_SetCountryCodesDataBlock

Applicable to PD Rev 3.0 only. Sets *CountryCodes Data Block* in PD Exerciser. It has to be called prior to call [Pd\\_WaitForGetCountryCodes](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

#### Format

```
Call Pd_SetCountryCodesDataBlock( Pd_CountryCodesDataBlock $country_codes_db )
```

#### Parameters

**\$country\_codes\_db**

parameter type is [Pd\\_CountryCodesDataBlock](#). Refer to [Pd\\_CountryCodesMsg](#) for available data fields.

#### Result

None

## Examples

```
$country_codes_db = Pd_CountryCodesDataBlock
Call Pd_SetCountryCodesDataBlock( $country_codes_db )
```

## 5.1.91 Pd\_ResetCountryCodesDataBlock

Applicable to PD Rev 3.0 only. Clears the *CountryCodes Data Block* in PD Exerciser. Should be called prior to call [Pd\\_SetCountryCodesDataBlock](#).

### Format

```
Call Pd_ResetCountryCodesDataBlock()
```

### Parameters

None

### Result

None

### Examples

```
Call Pd_ResetCountryCodesDataBlock()
```

## 5.1.92 Pd\_GetCountryCodes

Applicable to PD Rev 3.0 only. Starts *GetCountryCodes* AMS.

### Format

```
Call Pd_GetCountryCodes( OrderedSetType )
```

### Parameters

#### OrderedSetType

Possible values:

```
PD_ORDERED_SET_TYPE_SOP  
PD_ORDERED_SET_TYPE_SOP_PRIME  
PD_ORDERED_SET_TYPE_SOP_DOUBLE_PRIME
```

### Result

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

List of result values:

Result Value	Description
<a href="#">PD_RESULT_OK</a>	Command succeeded
<a href="#">PD_RESULT_FAILED</a>	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the error type which has been occurred during sending or receiving data).
<a href="#">PD_SUBRESULT_RESPONSE_TIMEOUT</a>	Subresult - No response received.
<a href="#">PD_SUBRESULT_RESPONSE_NOT_SUPPORTED</a>	Subresult - Not_Supported message received.

### Examples

```
Call Pd_GetCountryCodes(PD_ORDERED_SET_TYPE_SOP)
```

### 5.1.93 Pd\_WaitForGetCountryCodes

Applicable to PD Rev 3.0 only. Wait for user-defined time-out to receive `Get_Country_Codes` message. It will respond to incoming messages as part of *GetCountryCodes* AMS.

**Note:** The `Pd_SetGetCountryCodesSetting`, `Pd_SetCountryCodesDataBlock` and `Pd_ResetCountryCodesDataBlock` functions may need to be called prior calling this function.

#### Format

```
call Pd_WaitForGetCountryCodes()
```

#### Parameters

None

#### Result

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

List of result values:

Result Value	Description
<code>PD_RESULT_OK</code>	Command succeeded
<code>PD_RESULT_FAILED</code>	Command failed. In this case corresponding sub results for <code>PD_SendPacket</code> and <code>PD_ReceivePacket</code> are valid also (depends on the error type which has been occurred during sending or receiving data).
<code>PD_SUBRESULT_MSG_NOT_RECEIVED</code>	Subresult - <code>Get_Country_Codes</code> not received.
<code>PD_SUBRESULT_RESPONSE_NOT_SUPPORTED</code>	Subresult - Not_Supported message sent as response.

#### Examples

```
call Pd_WaitForGetCountryCodes()
```

### 5.1.94 PD\_EnterUSB

Applicable to PD Rev 3.0 only. Starts *EnterUSB* AMS.

#### Format

```
call Pd_EnterUSB( OrderedSetType )
```

#### Parameters

`OrderedSetType`

Possible values:

```
PD_ORDERED_SET_TYPE_SOP  
PD_ORDERED_SET_TYPE_SOP_PRIME  
PD_ORDERED_SET_TYPE_SOP_DOUBLE_PRIME
```

#### Result

User can evaluate the command results (including sub-results) using `IfMatched/ElseMatched` command.

List of result values:

Result Value	Description
--------------	-------------

<code>PD_RESULT_OK</code>	Command succeeded
<code>PD_RESULT_FAILED</code>	Command failed. In this case corresponding sub results for <code>PD_SendPacket</code> and <code>PD_ReceivePacket</code> are valid also (depends on the error type which has been occurred during sending or receiving data).
<code>PD_SUBRESULT_RESPONSE_REJECT</code>	Subresult - Reject message has been sent as Request message response
<code>PD_SUBRESULT_RESPONSE_TIMEOUT</code>	Subresult - No response received.

## Examples

Call `Pd_EnterUSB(PD_ORDERED_SET_TYPE_SOP)`

### 5.1.95 PD\_WaitForEnterUSB

Applicable to PD Rev 3.0 only. Wait for user-defined time-out to receive `EnterUSB` message. It will respond to incoming messages as part of *EnterUSB* AMS.

Note: The `PD_SetEnterUSBSetting` function may need to be called prior calling this function.

#### Format

Call `Pd_WaitForEnterUSB()`

#### Parameters

None

#### Result

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

List of result values:

Result Value	Description
<code>PD_RESULT_OK</code>	Command succeeded
<code>PD_RESULT_FAILED</code>	Command failed. In this case corresponding sub results for <code>PD_SendPacket</code> and <code>PD_ReceivePacket</code> are valid also (depends on the error type which has been occurred during sending or receiving data).
<code>PD_SUBRESULT_RESPONSE_REJECT</code>	Subresult - Reject message has been sent as response
<code>PD_SUBRESULT_RESPONSE_TIMEOUT</code>	Subresult - No response received.

## Examples

Call `Pd_WaitForEnterUSB()`

### 5.1.96 PD\_SetEnterUSBSetting

Applicable to PD Rev 3.0 only. It has to be called prior to call `PD_WaitForEnterUSB` or `PD_DelayAutoResponse` functions to take effect.

#### Format

Call `Pd_SetEnterUSBSetting( Pd_EnterUSB_Settings $settings )`

#### Parameters

`$settings`

Setting type is `Pd_EnterUSB_Settings`. Available fields for this type are:

Field Names	Possible/Default Values	Description
WaitTimeout	PD_DEFAULT_TIMEOUT_INFINITE(default)	Wait TimeOut(micro second) to receive EnterUSB message.
ResponseType	PD_RESPONSE_REJECT, PD_RESPONSE_ACCEPT(default)	Indicates response upon receiving the EnterUSB message.

## Result

None

## Examples

```
$enterusb_setting = Pd_EnterUSB_Settings
{
    ResponseType = PD_RESPONSE_REJECT
}
Call Pd_SetEnterUSBSetting( $enterusb_setting )
```

## 5.1.97 PD\_SetEnterUSBDO

Applicable to PD Rev 3.0 only. Sets *PD\_EnterUSBDataObject* in PD Exerciser. It has to be called prior to call [PD\\_EnterUSB](#) function to take effect.

### Format

```
Call Pd_SetEnterUSBDO( Pd_EnterUSBDataObject $enter_usb_do )
```

### Parameters

**\$enter\_usb\_do**

Parameter type is *Pd\_EnterUSBDataObject*. Refer to [PD\\_EnterUSBDataObject](#) for available data fields.

## Result

None

## Examples

```
$enter_usb_do = Pd_EnterUSBDataObject
Call Pd_SetEnterUSBDO( $enter_usb_do )
```

## 5.1.98 PD\_ResetEnterUSBDO

Applicable to PD Rev 3.0 only. Clears the *Pd\_EnterUSBDataObject* in PD Exerciser. Should be called prior to call [PD\\_SetEnterUSBDO](#).

### Format

```
Call Pd_ResetEnterUSBDO()
```

### Parameters

None

## Result

None

## Examples

```
Call Pd_ResetEnterUSBDO()
```

### 5.1.99 Pd\_SetGetSnkCapExtSetting

Applicable to PD Rev 3.0 only. It has to be called before [Pd\\_GetSinkCapExtended](#) or [Pd\\_WaitForGetSnkCapExtended](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

#### Format

```
Call Pd_SetGetSnkCapExtSetting( Pd_GetSinkCapExtented_Settings $settings )
```

#### Parameters

\$settings

Setting type is [Pd\\_GetSinkCapExtented\\_Settings](#). Available fields for this type are:

Field Names	Possible/Default Values	Description
WaitTimeout	PD_DEFAULT_TIMEOUT_INFINITE(default)	Wait TimeOut(micro second) to receive Get_Sink_Cap_Extended message.
ResponseType	PD_RESPONSE_NOT_SUPPORTED, PD_RESPONSE_UNSPECIFIED(default)	Indicates response upon receiving the Get_Sink_Cap_Extended message.
SkipSnkCapExt	PD_TRUE, PD_FALSE(default)	Indicates whether to skip sending Sink_Capabilities_Extended message or not.
SendSnkCapExtDelay	0(default)	Defines the delay before sending Sink_Capabilities_Extended message.

#### Result

None

#### Examples

```
$getsnkcapext_setting = Pd_GetSinkCapExtented_Settings
{
    ResponseType = PD_RESPONSE_NOT_SUPPORTED
}
Call Pd_SetGetSnkCapExtSetting( $getsnkcapext_setting )
```

### 5.1.100 Pd\_SetSnkCapExtDataBlock

Applicable to PD Rev 3.0 only. Sets *Sink Capabilities Extended Data Block* in PD Exerciser. It has to be called before [Pd\\_WaitForGetSnkCapExtended](#) or [PD\\_DelayAutoResponse](#) to take effect.

#### Format

```
Call Pd_SetSnkCapExtDataBlock( Pd_SinkCapExtDataBlock $snk_cap_ext )
```

#### Parameters

\$snk\_cap\_ext

parameter type is [Pd\\_SinkCapExtDataBlock](#). Refer to [Pd\\_SinkCapExtendedMsg](#) for available data fields.

#### Result

None

#### Examples

```
$snk_cap_ext = Pd_SinkCapExtDataBlock
Call Pd_SetSnkCapExtDataBlock( $snk_cap_ext )
```

### **5.1.101 Pd\_ResetSnkCapExtDataBlock**

Applicable to PD Rev 3.0 only. Clears the *Sink Capabilities Extended Data Block* in PD Exerciser. Should be called prior to call [Pd\\_SetSnkCapExtDataBlock](#).

#### **Format**

```
Call Pd_ResetSnkCapExtDataBlock()
```

#### **Parameters**

None

#### **Result**

None

#### **Examples**

```
Call Pd_ResetSnkCapExtDataBlock()
```

### **5.1.102 Pd\_GetSinkCapExtended**

Applicable to PD Rev 3.0 only. Starts *GetSinkCapExtended* AMS.

**Note:** The [Pd\\_SetGetSnkCapExtSetting](#) function may need to be called prior calling this function.

#### **Format**

```
Call Pd_GetSinkCapExtended()
```

#### **Parameters**

None

#### **Result**

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

List of result values:

Result Value	Description
<a href="#">PD_RESULT_OK</a>	Command succeeded
<a href="#">PD_RESULT_FAILED</a>	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the error type which has been occurred during sending or receiving data).
<a href="#">PD_SUBRESULT_RESPONSE_TIMEOUT</a>	Subresult - No response received.
<a href="#">PD_SUBRESULT_RESPONSE_NOT_SUPPORTED</a>	Subresult - Not_Supported message received.

#### **Examples**

```
Call Pd_GetSinkCapExtended()
```

### **5.1.103 Pd\_WaitForGetSnkCapExtended**

Applicable to PD Rev 3.0 only. Wait for user-defined time-out to receive `Get_Sink_Cap_Extended` message. It will respond to incoming messages as part of *GetSinkCapExtended* AMS.

**Note:** The [Pd\\_SetGetSnkCapExtSetting](#), [Pd\\_SetSnkCapExtDataBlock](#) and [Pd\\_ResetSnkCapExtDataBlock](#) functions may need to be called prior calling this function.

### Format

```
Call Pd_WaitForGetSnkCapExtended()
```

### Parameters

None

### Result

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

List of result values:

Result Value	Description
<a href="#">PD_RESULT_OK</a>	Command succeeded
<a href="#">PD_RESULT_FAILED</a>	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the error type which has been occurred during sending or receiving data).
<a href="#">PD_SUBRESULT_MSG_NOT_RECEIVED</a>	Subresult - <code>Get_Sink_Cap_Extended</code> not received.
<a href="#">PD_SUBRESULT_RESPONSE_NOT_SUPPORTED</a>	Subresult - <code>Not_Supported</code> message sent as response.

### Examples

```
Call Pd_WaitForGetSnkCapExtended()
```

## 5.1.104 PD\_SetDiscoverIdentitySetting

It must be called prior calling the [PD\\_DiscoverIdentity](#) or [PD\\_WaitForDiscoverIdentity](#) or [PD\\_PerformDiscoveryProcess](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

### Format

```
Call PD_SetDiscoverIdentitySetting( PD_DiscoverIdentity_Settings $settings )
```

### Parameters

`$settings`

Should be from `PD_DiscoverIdentity_Settings` type. Table below shows the available fields of `PD_DiscoverIdentity_Settings` template:

Field Name	Possible/Default Values	Description
<a href="#">DiscoverIdentityRetryCount</a>	20 (default)	Indicates the DiscoverIdentity retry count.
<a href="#">DiscoverIdentityResponse</a>	<a href="#">PD_DISCOVERIDENTITY_ACK</a> (default) <a href="#">PD_DISCOVERIDENTITY_BUSY</a> <a href="#">PD_DISCOVERIDENTITY_NAK</a>	Indicates the response type.
<a href="#">WaitTimeout</a>	<a href="#">PD_DEFAULT_TIMEOUT_INFINITE</a> (default)	Timeout(micro second) to wait for receiving Discover Identity Command.
<a href="#">RetryCountOnWait</a>	4(default)	Indicates the retry count if <code>Wait</code> message received as response.
<a href="#">RetryDelayOnWait</a>	50000(default)	Indicates the retry delay time(micro second) if <code>Wait</code> message received as response.
<a href="#">AutoSpecRevCable</a>	<a href="#">PD_TRUE</a> (default)	Only applicable for Rev.3.0 or higher.

		Indicates whether to detect Specification Revision of messages towards the cable automatically or not.
SendResponseDelay	0(default)	Sends response after specified delay.

## Result

None

## Examples

```
#apply settings
$settings = PD_DiscoverIdentity_Settings
{
    DiscoverIdentityRetryCount = 5
}
call PD_SetDiscoverIdentitySetting( $settings )
```

## 5.1.105 PD\_AddDiscoverIdentityVDO

Adds *DiscoverIdentity VDO* in PD Exerciser. It has to be called prior calling the [PD\\_WaitForDiscoverIdentity](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

### Format

```
call PD_AddDiscoverIdentityVDO( PD_DiscoverIdentity_VDO $vdo )
```

### Parameters

\$vdo

Parameter type is PD\_DiscoverIdentity\_VDO. Refer to [PD\\_VDM\\_Discover\\_Identity\\_Response](#) for available DiscoverID VDOs.

## Result

None

## Examples

```
#In this example, PD working revision is PD_SPEC_REVISION_2
#Add a ID Header VDO
$vdo = PD_VDM_Discover_Identity_ID_Header_VDO
{
    IDHeaderVDO_USBVendorID = 0xFF01
    IDHeaderVDO_Mode1OperationSupported = 1
    IDHeaderVDO_ProductType = PD_VDM_ID_HEADER_VDO_PRODUCT_TYPE_PERIPHERAL
    IDHeaderVDO_DataCapableAsUSBDevice = 1
}
call PD_AddDiscoverIdentityVDO( $vdo )
```

## 5.1.106 PD\_ResetDiscoverIdentityVDO

Clears *DiscoverIdentity VDOs* in PD Exerciser. It should be called prior calling the [PD\\_AddDiscoverIdentityVDO](#) function.

### Format

```
call PD_ResetDiscoverIdentityVDO()
```

### Parameters

None

## Result

None

### Examples

```
call PD_ResetDiscoverIdentityVDO()
```

## 5.1.107 PD\_DiscoverIdentity

Starts *DiscoverIdentity* AMS.

### Format

```
Call PD_DiscoverIdentity( OrderedSetType )
```

### Parameters

OrderedSetType

possible values:

```
PD_ORDERED_SET_TYPE_SOP  
PD_ORDERED_SET_TYPE_SOP_PRIME  
PD_ORDERED_SET_TYPE_SOP_DOUBLE_PRIME
```

### Result

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

Result Value	Description
PD_RESULT_OK	Command succeeded
PD_RESULT_FAILED	Command failed. In this case corresponding sub results for <code>PD_SendPacket</code> and <code>PD_ReceivePacket</code> are valid also (depends on the error type which has been occurred during sending or receiving data).
PD_SUBRESULT_RESPONSE_TIMEOUT	Subresult - No response received
PD_SUBRESULT_RESPONSE_NAK	Subresult - NAK received as response
PD_SUBRESULT_RESPONSE_BUSY	Subresult - BUSY received as response

### Examples

```
call PD_DiscoverIdentity(PD_ORDERED_SET_TYPE_SOP)
```

## 5.1.108 PD\_WaitForDiscoverIdentity

Waits for user-defined time-out to receive DISCOVERIDENTITY command. It will respond to incoming messages as part of *DiscoverIdentity* AMS.

**Note:** The `PD_SetDiscoverIdentitySetting`, `PD_AddDiscoverIdentityVDO` and `PD_ResetDiscoverIdentityVDO` functions may need to be called prior calling this function.

### Format

```
Call PD_WaitForDiscoverIdentity()
```

### Parameters

None

### Result

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

Result Value	Description
PD_RESULT_OK	Command succeeded
PD_RESULT_FAILED	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the error type which has been occurred during sending or receiving data).
PD_SUBRESULT_MSG_NOT_RECEIVED	Subresult - DISCOVERIDENTITY command not received
PD_SUBRESULT_RESPONSE_NAK	Subresult - NAK has been sent as response
PD_SUBRESULT_RESPONSE_BUSY	Subresult - BUSY has been sent as response

### Examples

```
call PD_WaitForDiscoverIdentity()
```

## 5.1.109 PD\_SetDiscoverSVIDSetting

It has to be called prior calling the [PD\\_DiscoverSvids](#) or [PD\\_WaitForDiscoverSvids](#) or [PD\\_PerformDiscoveryProcess](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

### Format

```
Call PD_SetDiscoverSVIDSetting( PD_DiscoverSvids_Settings $settings )
```

### Parameters

**\$settings**

Should be from `PD_DiscoverSvids_Settings` type. Table below shows the available fields of `PD_DiscoverSvids_Settings` template:

Field Name	Possible/Default Values	Description
DiscoverSvidsResponse	PD_DISCOVERSVIDS_ACK(default) PD_DISCOVERSVIDS_BUSY PD_DISCOVERSVIDS_NAK	Indicates the response type.
WaitTimeout	PD_DEFAULT_TIMEOUT_INFINITE(default)	Timeout(micro second) to wait for receiving Discover SVID Command.
RetryCountOnWait	4(default)	Indicates the retry count if wait message received as response.
RetryDelayOnWait	50000(default)	Indicates the retry delay time(micro second) if wait message received as response.

### Result

None

### Examples

```
#Using default settings
$settings = PD_DiscoverSvids_Settings
call PD_SetDiscoverSVIDSetting( $settings )
```

## 5.1.110 PD\_AddSvid

Adds *SVIDs* to PD Exerciser. It has to be called prior calling the [PD\\_DiscoverSvids](#) or [PD\\_WaitForDiscoverSvids](#) or [PD\\_PerformDiscoveryProcess](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

**Note** - Up to 11 *SVIDs* can be added using this command.

### Format

```
Call PD_AddSvid(value)
```

## Parameters

### value

SVID value to add

## Result

None

## Examples

```
call PD_AddSvid(0xFF01)
```

## 5.1.111 PD\_ResetSvids

Clears SVIDs which is added to PD Exerciser. It should be called prior calling the [PD\\_AddSvid](#) function.

## Format

```
call PD_ResetSvids()
```

## Parameters

None

## Result

None

## Examples

```
call PD_ResetSvids()
```

## 5.1.112 PD\_DiscoverSvids

Starts DiscoverSVID AMS.

**Note** - PD Exerciser supports only one(first) DiscoverSVIDs Ack message.

## Format

```
call PD_DiscoverSvids(OrderedSetType)
```

## Parameters

### OrderedSetType

possible values:

```
PD_ORDERED_SET_TYPE_SOP  
PD_ORDERED_SET_TYPE_SOP_PRIME  
PD_ORDERED_SET_TYPE_SOP_DOUBLE_PRIME
```

## Result

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

Result Value	Description
<a href="#">PD_RESULT_OK</a>	Command succeeded
<a href="#">PD_RESULT_FAILED</a>	Command failed. In this case corresponding sub results for

	<code>PD_SendPacket</code> and <code>PD_ReceivePacket</code> are valid also (depends on the error type which has been occurred during sending or receiving data).
<code>PD_SUBRESULT_RESPONSE_TIMEOUT</code>	Subresult - No response received
<code>PD_SUBRESULT_RESPONSE_NAK</code>	Subresult - NAK received as response
<code>PD_SUBRESULT_RESPONSE_BUSY</code>	Subresult - BUSY received as response

## Examples

```
call PD_DiscoverSvids(PD_ORDERED_SET_TYPE_SOP)
```

### 5.1.113 PD\_WaitForDiscoverSvids

Waits for user-defined time-out to receive DISCOVERSVID command. It will respond to incoming messages as part of the *DiscoverSVIDs* AMS.

**Note:** The `PD_SetDiscoverSVIDSetting`, `PD_AddSvid` and `PD_ResetSvids` functions may need to be called prior calling this function.

#### Format

```
Call PD_WaitForDiscoverSvids()
```

#### Parameters

None

#### Result

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

Result Value	Description
<code>PD_RESULT_OK</code>	Command succeeded
<code>PD_RESULT_FAILED</code>	Command failed. In this case corresponding sub results for <code>PD_SendPacket</code> and <code>PD_ReceivePacket</code> are valid also (depends on the error type which has been occurred during sending or receiving data).
<code>PD_SUBRESULT_MSG_NOT_RECEIVED</code>	Subresult - DISCOVERSVIDS message not received
<code>PD_SUBRESULT_RESPONSE_NAK</code>	Subresult - NAK has been sent as response
<code>PD_SUBRESULT_RESPONSE_BUSY</code>	Subresult - BUSY has been sent as response

## Examples

```
call PD_WaitForDiscoverSvids()
```

### 5.1.114 PD\_SetDiscoverModeSetting

It has to be called prior calling the `PD_DiscoverModes` or `PD_WaitForDiscoverModes` or `PD_PerformDiscoveryProcess` or `PD_DelayAutoResponse` functions to take effect.

#### Format

```
Call PD_SetDiscoverModeSetting( PD_DiscoverModes_Settings $settings )
```

#### Parameters

`$settings`

It should be from `PD_DiscoverModes_Settings` type. Table below describes the `PD_DiscoverModes_Settings` template:

Field Name	Possible/Default Values	Description
------------	-------------------------	-------------

<a href="#">DiscoverModesResponse</a>	PD_DISCOVERMODES_ACK(default) PD_DISCOVERMODES_BUSY PD_DISCOVERMODES_NAK	Response type
<a href="#">WaitTimeout</a>	PD_DEFAULT_TIMEOUT_INFINITE(default)	Timeout(micro second) to wait for receiving Discover Modes command.
<a href="#">RetryCountOnWait</a>	4(default)	Indicates the retry count if Wait message received as response.
<a href="#">RetryDelayOnWait</a>	50000(default)	Indicates the retry delay time(micro second) if Wait message received as response.

## Result

None

## Examples

```
#apply settings
$settings = PD_DiscoverModes_Settings
{
    DiscoverModesResponse = PD_DISCOVERMODES_BUSY
}
call PD_SetDiscoverModeSetting( $settings )
```

## 5.1.115 PD\_AddMode

Adds *Modes* to the PD Exerciser. It has to be called prior calling the [PD\\_DiscoverModes](#) or [PD\\_WaitForDiscoverModes](#) or [PD\\_PerformDiscoveryProcess](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

### Format

```
call PD_AddMode(Mode)
```

### Parameters

#### Mode

Mode to add

### Result

None

## Examples

```
call PD_AddMode(0x00000001)
```

## 5.1.116 PD\_AddModeVDO

Adds *Mode with VDO* to the PD Exerciser. It has to be called prior calling the [PD\\_DiscoverModes](#) or [PD\\_WaitForDiscoverModes](#) or [PD\\_PerformDiscoveryProcess](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

### Format

```
call PD_AddModeVDO(PD_Generic_VDO $Modevdo)
```

### Parameters

#### \$Modevdo

Parameter type is `PD_Generic_VDO`. Refer to [PD\\_VDM\\_Discover\\_Modes\\_Response](#) for available VDOs which can be used as this parameter.

## Result

None

## Examples

```
local $vdo_1 = PD_VDO
{
    Data = 0x01
}
call PD_AddModeVDO($vdo_1)
```

## 5.1.117 PD\_ResetModes

Clears `Modes` which are added to PD Exerciser. It should be called prior calling the [PD\\_AddMode](#) or [PD\\_AddModeVDO](#) functions.

### Format

```
call PD_ResetModes()
```

### Parameters

None

## Result

None

## Examples

```
call PD_ResetModes()
```

## 5.1.118 PD\_DiscoverModes

Starts `DiscoverModes` AMS.

### Format

```
call PD_DiscoverModes(OrderedSetType, selectedSvid)
```

### Parameters

#### OrderedSetType

possible values:

```
PD_ORDERED_SET_TYPE_SOP
PD_ORDERED_SET_TYPE_SOP_PRIME
PD_ORDERED_SET_TYPE_SOP_DOUBLE_PRIME
```

#### selectedSvid

Indicates the SVID value

## Result

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

Result Value	Description
PD_RESULT_OK	Command succeeded
PD_RESULT_FAILED	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the error type which has been occurred during sending or receiving data).
PD_SUBRESULT_RESPONSE_TIMEOUT	Subresult - No response received
PD_SUBRESULT_RESPONSE_NAK	Subresult - NAK received as response
PD_SUBRESULT_RESPONSE_BUSY	Subresult - BUSY received as response

### Examples

```
call PD_DiscoverModes(PD_ORDERED_SET_TYPE_SOP, 0xFF00)
```

## 5.1.119 PD\_WaitForDiscoverModes

Waits for user-defined time-out to receive DISCOVERMODE command. It will respond to incoming messages as part of *DiscoverModes* AMS.

**Note:** The [PD\\_SetDiscoverModeSetting](#), [PD\\_AddMode](#), [PD\\_AddModeVDO](#) and [PD\\_ResetModes](#) functions may need to be called prior calling this function.

### Format

```
call PD_WaitForDiscoverModes()
```

### Parameters

None

### Result

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

Result Value	Description
PD_RESULT_OK	Command succeeded
PD_RESULT_FAILED	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the error type which has been occurred during sending or receiving data).
PD_SUBRESULT_MSG_NOT_RECEIVED	Subresult - DISCOVERMODES message not received
PD_SUBRESULT_RESPONSE_NAK	Subresult - NAK has been sent as response
PD_SUBRESULT_RESPONSE_BUSY	Subresult - BUSY has been sent as response

### Examples

```
call PD_WaitForDiscoverModes()
```

## 5.1.120 PD\_SetEnterModeSetting

It has to be called prior calling the [PD\\_WaitForEnterMode](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

### Format

```
call PD_SetEnterModeSetting( PD_EnterMode_Settings $settings )
```

### Parameters

`$settings`

Should be from `PD_EnterMode_Settings` type. Table below describes the `PD_EnterMode_Settings` template:

Field Name	Possible/Default Values	Description
<code>EnterModeResponse</code>	<code>PD_ENTERMODE_ACK</code> (default) <code>PD_ENTERMODE_NAK</code>	Response type.
<code>WaitTimeout</code>	<code>PD_DEFAULT_TIMEOUT_INFINITE</code> (default)	Timeout(micro second) to wait for receiving Enter Mode command.
<code>SkipSendingResponse</code>	<code>PD_FALSE</code> (default) <code>PD_TRUE</code>	If set to <code>PD_TRUE</code> , will skip sending the EnterMode response.

## Result

None

## Examples

```
#Using default setting
$settings = PD_EnterMode_Settings
call PD_SetEnterModeSetting( $settings )
```

### 5.1.121 PD\_EnterMode

Starts *EnterMode* AMS.

#### Format

Call `PD_EnterMode(OrderedSetType, selectedSvid, modeIndex)`

#### Parameters

##### orderedSetType

possible values:

`PD_ORDERED_SET_TYPE_SOP`  
`PD_ORDERED_SET_TYPE_SOP_PRIME`  
`PD_ORDERED_SET_TYPE_SOP_DOUBLE_PRIME`

##### selectedSvid

Indicates the SVID

##### modeIndex

Indicates the mode index for the specified SVID

## Result

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

List of result values:

Result Value	Description
<code>PD_RESULT_OK</code>	Command succeeded
<code>PD_RESULT_FAILED</code>	Command failed. In this case corresponding sub results for <code>PD_SendPacket</code> and <code>PD_ReceivePacket</code> are valid also (depends on the error type which has been occurred during sending or receiving data).
<code>PD_SUBRESULT_RESPONSE_TIMEOUT</code>	Subresult - No response received
<code>PD_SUBRESULT_RESPONSE_NAK</code>	Subresult - NAK received as response

## Examples

```
call PD_EnterMode(PD_ORDERED_SET_TYPE_SOP, 0xFF00, 1)
```

### 5.1.122 PD\_EnterModeVdo

Starts *EnterMode* AMS. It sends the specified *VDO* using the *EnterMode* command.

#### Format

```
Call PD_EnterModeVdo( orderedSetType, selectedSvid, modeId, PD_Generic_VDO $vdo )
```

#### Parameters

##### OrderedSetType

Indicates the ordered set type. Possible values:

```
PD_ORDERED_SET_TYPE_SOP  
PD_ORDERED_SET_TYPE_SOP_PRIME  
PD_ORDERED_SET_TYPE_SOP_DOUBLE_PRIME
```

##### selectedSvid

Indicates the SVID

##### modeId

Indicates the mode index related to the specified SVID

##### \$vdo

Vendor defined data object. It should be from `PD_VDO`(Inherited from `PD_Generic_VDO`) type.  
(Refer to [PD\\_VDO](#))

Field Name	Description
<a href="#">Data</a>	VDO data

#### Result

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

Result Value	Description
<a href="#">PD_RESULT_OK</a>	Command succeeded
<a href="#">PD_RESULT_FAILED</a>	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the error type which has been occurred during sending or receiving data).
<a href="#">PD_SUBRESULT_RESPONSE_TIMEOUT</a>	Subresult - No response received
<a href="#">PD_SUBRESULT_RESPONSE_NAK</a>	Subresult - NAK received as response

#### Examples

```
$vdo = PD_VDO
{
    Data = 0x00
}
call PD_EnterModeVdo(PD_ORDERED_SET_TYPE_SOP, 0xFF01, 1, $vdo)
```

### 5.1.123 PD\_WaitForEnterMode

Waits for user-defined time-out to receive ENTERMODE command. It will respond to incoming messages as part of *EnterMode* AMS.

**Note:** The [PD\\_SetEnterModeSetting](#) function may need to be called prior calling this function.

## Format

```
call PD_WaitForEnterMode()
```

## Parameters

None

## Result

User can evaluate the command results(including sub-results) using IfMatched/ElseMatched command.

Result Value	Description
PD_RESULT_OK	Command succeeded
PD_RESULT_FAILED	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the error type which has been occurred during sending or receiving data).
PD_SUBRESULT_MSG_NOT RECEIVED	Subresult - ENERMODE message not received
PD_SUBRESULT_RESPONSE_NAK	Subresult - NAK has been sent as response

## Examples

```
call PD_WaitForEnterMode()
```

### 5.1.124 PD\_SetExitModeSetting

It has to be called prior calling the [PD\\_WaitForExitMode](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

## Format

```
call PD_SetExitModeSetting( PD_ExitMode_Settings $settings )
```

## Parameters

\$settings

Should be from [PD\\_ExitMode\\_Settings](#) type. Table below describes the [PD\\_ExitMode\\_Settings](#) template:

Field Name	Possible/Default Values	Description
ExitModeResponse	PD_EXITMODE_ACK(default) PD_EXITMODE_NAK	Indicates the response type.
WaitTimeout	PD_DEFAULT_TIMEOUT_INFINITE(default)	Timeout(micro second) to wait for receiving the Exit Mode command.

## Result

None

## Examples

```
#Using default settings
$settings = PD_ExitMode_Settings
call PD_SetExitModeSetting( $settings )
```

### 5.1.125 PD\_ExitMode

Starts *ExitMode* AMS.

## Format

```
call PD_ExitMode(OrderedSetType, selectedSvid, modeIndex)
```

## Parameters

### OrderedSetType

possible values:

```
PD_ORDERED_SET_TYPE_SOP  
PD_ORDERED_SET_TYPE_SOP_PRIME  
PD_ORDERED_SET_TYPE_SOP_DOUBLE_PRIME
```

### selectedSvid

Indicates the SVID

### modeIndex

Indicates the mode index related to the specified SVID

## Result

User can evaluate the command results(including sub-results) using IfMatched/ElseMatched command.

Result Value	Description
PD_RESULT_OK	Command succeeded
PD_RESULT_FAILED	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the error type which has been occurred during sending or receiving data).
PD_SUBRESULT_RESPONSE_TIMEOUT	Subresult - No response received
PD_SUBRESULT_RESPONSE_NAK	Subresult - NAK received as response

## Examples

```
call PD_ExitMode(PD_ORDERED_SET_TYPE_SOP, 0xFF00, 1)
```

### 5.1.126 PD\_WaitForExitMode

Waits for user-defined time-out to receive EXITMODE command. It will respond to incoming messages as part of *ExitMode* AMS.

**Note:** The [PD\\_SetExitModeSetting](#) function may need to be called prior calling this function.

## Format

```
call PD_WaitForExitMode()
```

## Parameters

None

## Result

User can evaluate the command results(including sub-results) using IfMatched/ElseMatched command.

Result Value	Description
PD_RESULT_OK	Command succeeded
PD_RESULT_FAILED	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the

	error type which has been occurred during sending or receiving data).
PD_SUBRESULT_MSG_NOT_RECEIVED	Subresult - EXITMODE message not received
PD_SUBRESULT_RESPONSE_NAK	Subresult - NAK has been sent as response

## Examples

```
call PD_WaitForExitMode()
```

### 5.1.127 PD\_Attention

Starts *Attention* AMS.

#### Format

```
Call PD_Attention( OrderedSetType, selectedSvid, modeIndex )
```

#### Parameters

##### OrderedSetType

Indicates the ordered set type. possible values:

```
PD_ORDERED_SET_TYPE_SOP
PD_ORDERED_SET_TYPE_SOP_PRIME
PD_ORDERED_SET_TYPE_SOP_DOUBLE_PRIME
```

##### selectedSvid

Indicates the SVID

##### modeIndex

Indicates the mode index related to the specified SVID

#### Result

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

Result Value	Description
PD_RESULT_OK	Command succeeded
PD_RESULT_FAILED	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> are valid also (depends on the error type which has been occurred during sending data).

## Examples

```
call PD_Attention(PD_ORDERED_SET_TYPE_SOP, 0xFF01, 1 )
```

### 5.1.128 PD\_AttentionVdo

Starts *Attention* AMS. It sends the specified VDO using the *Attention* command.

#### Format

```
Call PD_AttentionVdo( OrderedSetType, selectedSvid, modeIndex, PD_Generic_VDO
$Vdo )
```

#### Parameters

##### OrderedSetType

Indicates the ordered set type. Possible values:

```
PD_ORDERED_SET_TYPE_SOP
```

```
PD_ORDERED_SET_TYPE_SOP_PRIME  
PD_ORDERED_SET_TYPE_SOP_DOUBLE_PRIME
```

#### **selectedSvid**

Indicates the SVID

#### **modeId**

Indicates the mode index related to the specified SVID

#### **\$vdo**

Vendor defined data object. Should be from `PD_VDO`(Inherited from `PD_Generic_VDO`) type. (Refer to [PD\\_VDO](#))

Field Name	Description
<a href="#">Data</a>	VDO data

### **Result**

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

Result Value	Description
<a href="#">PD_RESULT_OK</a>	Command succeeded
<a href="#">PD_RESULT_FAILED</a>	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> are valid also (depends on the error type which has been occurred during sending data).

### **Examples**

```
$vdo = PD_VDO
{
    Data = 0x00
}
call PD_AttentionVdo(PD_ORDERED_SET_TYPE_SOP, 0xFF01, 1, $vdo)
```

## [5.1.129 PD\\_SetDiscoveryProcessSetting](#)

It has to be called prior calling the `PD_PerformDiscoveryProcess` function to take effect.

### **Format**

```
Call PD_SetDiscoveryProcessSetting(PD_DiscoveryProcess_Settings $settings)
```

### **Parameters**

#### **\$settings**

Should be from `PD_DiscoveryProcess_Settings` type. Table below describes the `PD_DiscoveryProcess_Settings` template:

Field Name	Possible/Default Values	Description
<a href="#">Discover_SOP_PP_During_SOP_P</a>	PD_TRUE PD_FALSE(Default)	Indicates whether perform SOP Double Prime discovery during SOP Prime discovery process or not.
<a href="#">SkipEnterMode</a>	PD_FALSE(Default)	Indicates whether to skip the EnterMode phase or not.

### **Result**

None

### **Examples**

```
#Using default settings
```

```
$settings = PD_DiscoveryProcess_Settings
call PD_SetDiscoveryProcessSetting( $settings )
```

### 5.1.130 PD\_PerformDiscoveryProcess

Performs full discovery process.

**Note 1:** PD Exerciser supports only one(first) DiscoverSVIDs Ack message (up to 12 SVIDs).

**Note 2:** The [PD\\_SetDiscoveryProcessSetting](#) function may need to be called prior calling this function.

#### Format

```
call PD_PerformDiscoveryProcess( OrderedSetType )
```

#### Parameters

##### OrderedSetType

Indicates the ordered set type. Possible values:

```
PD_ORDERED_SET_TYPE_SOP
PD_ORDERED_SET_TYPE_SOP_PRIME
PD_ORDERED_SET_TYPE_SOP_DOUBLE_PRIME
```

#### Result

None

#### Examples

```
call PD_PerformDiscoveryProcess(PD_ORDERED_SET_TYPE_SOP)
```

### 5.1.131 PD\_SetDisplayPortSetting

It has to be called prior calling the [PD\\_DisplayPort\\_UpdateStatus](#) or [PD\\_DisplayPort\\_Configure](#) or [PD\\_WaitForDisplayPortStatus](#) or [PD\\_WaitForDisplayPortConfigure](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

#### Format

```
call PD_SetDisplayPortSetting( PD_DisplayPort_Settings $settings )
```

#### Parameters

##### \$settings

Should be from [PD\\_DisplayPort\\_Settings](#) type. Table below describes the [PD\\_DisplayPort\\_Settings](#) template:

Field Name	Possible/Default Values	Description
ConfigureResponse	PD_DISPLAYPORT_ACK(Default) PD_DISPLAYPORT_NAK	Indicates the response for incoming Display Port Configure command.
DisplayPortModelIndex	0x01(Default)	Mode index related to the Display Port SVID.
StatusVdo	0x00(Default)	Indicates the <i>Display Port Status Vendor Defined Data Object</i> which can be used in Display Port Update Status initiator or responder messages.
ConfigureVdo	0x00(Default)	Indicates the <i>Display Port Configure Vendor Defined Data Object</i> which can be used in

		Display Port Configure initiator message.
WaitTimeout	PD_DEFAULT_TIMEOUT_INFINITE(Default)	Timeout(micro second) to wait for receiving <i>Display Port Update Status or Configure</i> command.

## Result

None

## Examples

```
#Using default settings
#####
$settings = PD_DisplayPort_Settings
call PD_SetDisplayPortSetting($settings)

#Set the StatusVdo
#####
$update_status = PD_VDM_DisplayPort_Status_VDO
{
    DFPD_UFPD_Connected      = PD_DISPLAYPORT_DFPD_CONNECTED
    PowerLow                  = 0x00
    AdaptorEnabled            = 0x01
    MultiFunctionPreferred   = 0x01
    UsbConfigurationRequest  = 0x00
    ExitDisplayModeRequest   = 0x00
    HPD_State                 = 0x00
    IRQ_HPD                  = 0x00
    Reserved_DPS_1           = 0x00
}
$settings
{
    StatusVdo = $update_status
}
Call PD_SetDisplayPortSetting($settings)

#Set the ConfigureVdo to default
#####
$config = PD_VDM_DisplayPort_Configure_VDO
$settings
{
    ConfigureVdo = $config
}
Call PD_SetDisplayPortSetting($settings)
```

## 5.1.132 PD\_DisplayPort\_UpdateStatus

Starts *DisplayPortUpdateStatus*(Structured VDM) AMS.

**Note:** The [PD\\_SetDisplayPortSetting](#) function may need to be called prior calling this function.

### Format

```
Call PD_DisplayPort_UpdateStatus()
```

### Parameters

None

## Result

User can evaluate the command results(including sub-results) using [IfMatched/ElseMatched](#) command.

Result Value	Description
<a href="#">PD_RESULT_OK</a>	Command succeeded
<a href="#">PD_RESULT_FAILED</a>	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the error type which has been occurred during sending or receiving data).
<a href="#">PD_SUBRESULT_RESPONSE_TIMEOUT</a>	Subresult - No response received

## Examples

```
call PD_DisplayPort_UpdateStatus()
```

### 5.1.133 PD\_DisplayPort\_Configure

Starts *DisplayPortConfigure*(Structured VDM) AMS.

**Note:** The [PD\\_SetDisplayPortSetting](#) function may need to be called prior calling this function.

#### Format

```
Call PD_DisplayPort_Configure()
```

#### Parameters

None

#### Result

User can evaluate the command results(including sub-results) using [IfMatched](#)/[ElseMatched](#) command.

Result Value	Description
<a href="#">PD_RESULT_OK</a>	Command succeeded
<a href="#">PD_RESULT_FAILED</a>	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the error type which has been occurred during sending or receiving data).
<a href="#">PD_SUBRESULT_RESPONSE_TIMEOUT</a>	Subresult - No response received
<a href="#">PD_SUBRESULT_RESPONSE_NAK</a>	Subresult - NAK received as response

## Examples

```
call PD_DisplayPort_Configure()
```

### 5.1.134 PD\_WaitForDisplayPortStatus

Waits for user-defined time-out to receive DisplayPort STATUS command. It will respond to incoming messages as part of the *DisplayPortStatus*(Structured VDM) AMS.

**Note:** The [PD\\_SetDisplayPortSetting](#) function may need to be called prior calling this function.

#### Format

```
Call PD_WaitForDisplayPortStatus()
```

#### Parameters

None

#### Result

User can evaluate the command results(including sub-results) using [IfMatched](#)/[ElseMatched](#) command.

Result Value	Description
<a href="#">PD_RESULT_OK</a>	Command succeeded
<a href="#">PD_RESULT_FAILED</a>	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the

	error type which has been occurred during sending or receiving data).
<a href="#">PD_SUBRESULT_MSG_NOT_RECEIVED</a>	Subresult - UPDATE_STATUS message not received

### Examples

call PD\_WaitForDisplayPortStatus()

### 5.1.135 PD\_WaitForDisplayPortConfigure

Waits for user-defined time-out to receive DisplayPort CONFIGURE command. It will respond to incoming messages as part of *DisplayPortConfigure*(Structured VDM) AMS.

**Note:** The [PD\\_SetDisplayPortSetting](#) function may need to be called prior calling this function.

#### Format

Call PD\_WaitForDisplayPortConfigure()

#### Parameters

None

#### Result

User can evaluate the command results(including sub-results) using IfMatched/ElseMatched command.

Result Value	Description
<a href="#">PD_RESULT_OK</a>	Command succeeded
<a href="#">PD_RESULT_FAILED</a>	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the error type which has been occurred during sending or receiving data).
<a href="#">PD_SUBRESULT_MSG_NOT_RECEIVED</a>	Subresult - Configure message not received
<a href="#">PD_SUBRESULT_RESPONSE_NAK</a>	Subresult - NAK has been sent as response

### Examples

call PD\_WaitForDisplayPortConfigure()

### 5.1.136 PD\_SetDiscoverIdentitySetting\_Cable

It has to be called prior calling the [PD\\_WaitForDiscoverIdentity\\_Cable](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

**Note** - PD Exerciser should also act as a Cable Plug to be able to process this function.

#### Format

```
Call PD_SetDiscoverIdentitySetting_Cable( PD_DiscoverIdentity_Settings_SOPPrime
$settings )
Call PD_SetDiscoverIdentitySetting_Cable( PD_DiscoverIdentity_Settings_SOPDPrime
$settings )
```

#### Parameters

\$settings

For SOP Prime, use [PD\\_DiscoverIdentity\\_Settings\\_SOPPrime](#) and for SOP Double Prime, use [PD\\_DiscoverIdentity\\_Settings\\_SOPDPrime](#). Refer to [PD\\_SetDiscoverIdentitySetting](#) for more details. Only [DiscoverIdentityResponse](#) and [WaitTimeout](#) settings applied.

## Result

None

## Examples

```
PD_Set $PdGlobalSettings.EnableCableEmulator = PD_TRUE  
PD_Set $PdGlobalSettings.EnableCableDPrimeEmulator = PD_TRUE  
. .  
#Using default settings  
$settings = PD_DiscoverIdentity_Settings_SOPPrime  
call PD_SetDiscoverIdentitySetting_Cable( $settings )  
  
$settings_dprime = PD_DiscoverIdentity_Settings_SOPDPrime  
call PD_SetDiscoverIdentitySetting_Cable( $settings_dprime )
```

### 5.1.137 PD\_WaitForDiscoverIdentity\_Cable

Waits for user-defined time-out to receive DISCOVERIDENTITY command. It will respond to incoming messages as part of the *DiscoverIdentity* AMS.

**Note 1:** PD Exerciser should also act as Cable Plug to be able to process this command.

**Note 2:** The [PD\\_SetDiscoverIdentitySetting\\_Cable](#), [PD\\_AddDiscoverIdentityVDO\\_Cable](#) and [PD\\_ResetDiscoverIdentityVDO\\_Cable](#) functions may need to be called prior calling this function.

## Format

```
Call PD_WaitForDiscoverIdentity_Cable( ordered_set )
```

## Parameters

**ordered\_set**

Possible values:

```
PD_ORDERED_SET_TYPE_SOP_PRIME  
PD_ORDERED_SET_TYPE_SOP_DOUBLE_PRIME
```

## Result

User can evaluate the command results(including sub-results) using [IfMatched/ElseMatched](#) command.

Result Value	Description
PD_RESULT_OK	Command succeeded
PD_RESULT_FAILED	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the error type which has been occurred during sending or receiving data).
PD_SUBRESULT_MSG_NOT_RECEIVED	Subresult - DISCOVER_IDENTITY message not received
PD_SUBRESULT_RESPONSE_NAK	Subresult - NAK has been sent as response
PD_SUBRESULT_RESPONSE_BUSY	Subresult - BUSY has been sent as response

## Examples

```
PD_Set $PdGlobalSettings.EnableCableEmulator = PD_TRUE  
. .  
Call PD_WaitForDiscoverIdentity_Cable( PD_ORDERED_SET_TYPE_SOP_PRIME )
```

### 5.1.138 PD\_AddDiscoverIdentityVDO\_Cable

Adds *DiscoverIdentity VDO*(for cable) to the PD Exerciser. It has to be called prior calling the [PD\\_WaitForDiscoverIdentity\\_Cable](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

**Note** - PD Exerciser should also act as Cable Plug to be able to process this command.

#### Format

```
call PD_AddDiscoverIdentityVDO_Cable( PD_DiscoverIdentity_VDO $vdo, ordered_set )
```

#### Parameters

**\$vdo**

Parameter type is PD\_DiscoverIdentity\_VDO. Refer to [PD\\_VDM\\_Discover\\_Identity\\_Response](#) for available DiscoverID VDOs.

**ordered\_set**

Possible values:

```
PD_ORDERED_SET_TYPE_SOP_PRIME  
PD_ORDERED_SET_TYPE_SOP_DOUBLE_PRIME
```

#### Result

None

#### Examples

```
PD_Set $PdGlobalSettings.EnableCableEmulator = PD_TRUE  
. . .  
#Add a Cable VDO  
$vdo = PD_VDM_Discover_Identity_Cable_VDO  
call PD_AddDiscoverIdentityVDO_Cable( $vdo, PD_ORDERED_SET_TYPE_SOP_PRIME )
```

### 5.1.139 PD\_ResetDiscoverIdentityVDO\_Cable

Clears *DiscoverIdentity VDOs*(for cable) in PD Exerciser. It should be called prior to call [PD\\_AddDiscoverIdentityVDO\\_Cable](#) function.

**Note** - PD Exerciser should also act as Cable Plug to be able to process this command.

#### Format

```
call PD_ResetDiscoverIdentityVDO_Cable( ordered_set )
```

#### Parameters

**ordered\_set**

Possible values:

```
PD_ORDERED_SET_TYPE_SOP_PRIME  
PD_ORDERED_SET_TYPE_SOP_DOUBLE_PRIME
```

#### Result

None

#### Examples

```
PD_Set $PdGlobalSettings.EnableCableEmulator = PD_TRUE
```

```
call PD_ResetDiscoverIdentityVDO_Cable( PD_ORDERED_SET_TYPE_SOP_PRIME )
```

### 5.1.140 PD\_SetDiscoverSVIDSetting\_Cable

It has to be called prior calling the [PD\\_WaitForDiscoverSvids\\_Cable](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

**Note** - PD Exerciser should also act as a Cable Plug to be able to process this command.

#### Format

```
Call PD_SetDiscoverSVIDSetting_Cable( PD_DiscoverSvids_Settings_SOPPrime  
$settings )
```

```
Call PD_SetDiscoverSVIDSetting_Cable( PD_DiscoverSvids_Settings_SOPDPrime  
$settings )
```

#### Parameters

**\$settings**

For SOP Prime, use `PD_DiscoverSvids_Settings_SOPPrime` and for SOP Double Prime, use `PD_DiscoverSvids_Settings_SOPDPrime`. Refer to [PD\\_SetDiscoverSVIDSetting](#) for more details.  
Only `DiscoverSvidsResponse` and `WaitTimeout` settings applied.

#### Result

None

#### Examples

```
PD_Set $PdGlobalSettings.EnableCableEmulator = PD_TRUE  
PD_Set $PdGlobalSettings.EnableCableDPrimeEmulator = PD_TRUE  
  
#using default settings  
$settings = PD_DiscoverSvids_Settings_SOPPrime  
call PD_SetDiscoverSVIDSetting_Cable( $settings )  
  
$settings_dprime = PD_DiscoverSvids_Settings_SOPDPrime  
call PD_SetDiscoverSVIDSetting_Cable( $settings_dprime )
```

### 5.1.141 PD\_WaitForDiscoverSvids\_Cable

Waits for user-defined time-out to receive DISCOVERSVID command. It will respond to incoming messages as part of *DiscoverSVIDs* AMS.

**Note 1:** PD Exerciser should also act as Cable Plug to be able to process this command.

**Note 2:** The [PD\\_SetDiscoverSVIDSetting\\_Cable](#), [PD\\_AddSvid\\_Cable](#) and [PD\\_ResetSvids\\_Cable](#) functions may need to be called prior calling this function.

#### Format

```
Call PD_WaitForDiscoverSvids_Cable( ordered_set )
```

#### Parameters

**ordered\_set**

Possible values:

```
PD_ORDERED_SET_TYPE_SOP_PRIME  
PD_ORDERED_SET_TYPE_SOP_DOUBLE_PRIME
```

## Result

User can evaluate the command results(including sub-results) using IfMatched/ElseMatched command.

Result Value	Description
PD_RESULT_OK	Command succeeded
PD_RESULT_FAILED	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the error type which has been occurred during sending or receiving data).
PD_SUBRESULT_MSG_NOT_RECEIVED	Subresult - DISCOVER_SVIDS message not received
PD_SUBRESULT_RESPONSE_NAK	Subresult - NAK has been sent as response
PD_SUBRESULT_RESPONSE_BUSY	Subresult - BUSY has been sent as response

## Examples

```
PD_Set $PdGlobalSettings.EnableCableEmulator = PD_TRUE  
.  
call PD_WaitForDiscoverSvids_Cable( PD_ORDERED_SET_TYPE_SOP_PRIME )
```

### 5.1.142 PD\_AddSvid\_Cable

Adds SVIDs (Cable Plug) to the PD Exerciser. It has to be called prior calling the [PD\\_WaitForDiscoverSvids\\_Cable](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

**Note** - PD Exerciser should also act as Cable Plug to be able to process this command.

#### Format

```
call PD_AddSvid_Cable(value, ordered_set)
```

#### Parameters

**value**

SVID value to add

**ordered\_set**

Possible values:

```
PD_ORDERED_SET_TYPE_SOP_PRIME  
PD_ORDERED_SET_TYPE_SOP_DOUBLE_PRIME
```

#### Result

None

## Examples

```
PD_Set $PdGlobalSettings.EnableCableEmulator = PD_TRUE  
.  
call PD_AddSvid_Cable(0xFF81, PD_ORDERED_SET_TYPE_SOP_PRIME)
```

### 5.1.143 PD\_ResetSvids\_Cable

Clears SVIDs(for cable) which is added to PD Exerciser. It should be called prior to call [PD\\_AddSvid\\_Cable](#) function.

**Note** - PD Exerciser should also act as Cable Plug to be able to process this command.

#### Format

```
Call PD_ResetSvids_Cable( ordered_set )
```

### Parameters

ordered\_set

Possible values:

```
PD_ORDERED_SET_TYPE_SOP_PRIME  
PD_ORDERED_SET_TYPE_SOP_DOUBLE_PRIME
```

### Result

None

### Examples

```
PD_Set $PdGlobalSettings.EnableCableEmulator = PD_TRUE  
. . .  
call PD_ResetSvids_Cable( PD_ORDERED_SET_TYPE_SOP_PRIME )
```

## 5.1.144 PD\_SetDiscoverModeSetting\_Cable

It has to be called prior calling the [PD\\_WaitForDiscoverModes\\_Cable](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

**Note** - PD Exerciser should also act as Cable Plug to be able to process this command.

### Format

```
Call PD_SetDiscoverModeSetting_Cable( PD_DiscoverModes_Settings_SOPPrime  
$settings )  
Call PD_SetDiscoverModeSetting_Cable( PD_DiscoverModes_Settings_SOPDPrime  
$settings )
```

### Parameters

\$settings

For SOP Prime, use `PD_DiscoverModes_Settings_SOPPrime` and for SOP Double Prime, use `PD_DiscoverModes_Settings_SOPDPrime`. Refer to [PD\\_SetDiscoverModeSetting](#) for more details.  
Only `DiscoverModesResponse` and `WaitTimeout` settings applied.

### Result

None

### Examples

```
PD_Set $PdGlobalSettings.EnableCableEmulator = PD_TRUE  
PD_Set $PdGlobalSettings.EnableCableDPrimeEmulator = PD_TRUE  
. . .  
#Using default settings  
$settings = PD_DiscoverModes_Settings_SOPPrime  
call PD_SetDiscoverModeSetting_Cable( $settings )  
  
$settings_dprime = PD_DiscoverModes_Settings_SOPDPrime  
call PD_SetDiscoverModeSetting_Cable( $settings_dprime )
```

### 5.1.145 PD\_WaitForDiscoverModes\_Cable

Waits for user-defined time-out to receive DISCOVERMODE command. It will respond to incoming messages as part of *DiscoverModes* AMS.

**Note 1:** PD Exerciser should also act as Cable Plug to be able to process this command.

**Note 2:** The [PD\\_SetDiscoverModeSetting\\_Cable](#), [PD\\_AddModeVDO\\_Cable](#), [PD\\_AddMode\\_Cable](#) and [PD\\_ResetModes\\_Cable](#) functions may need to be called prior calling this function.

#### Format

```
Call PD_WaitForDiscoverModes_Cable( ordered_set )
```

#### Parameters

ordered\_set

Possible values:

```
PD_ORDERED_SET_TYPE_SOP_PRIME  
PD_ORDERED_SET_TYPE_SOP_DOUBLE_PRIME
```

#### Result

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

Result Value	Description
<a href="#">PD_RESULT_OK</a>	Command succeeded
<a href="#">PD_RESULT_FAILED</a>	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the error type which has been occurred during sending or receiving data).
<a href="#">PD_SUBRESULT_MSG_NOT_RECEIVED</a>	Subresult - DISCOVER_MODES message not received
<a href="#">PD_SUBRESULT_RESPONSE_NAK</a>	Subresult - NAK has been sent as response
<a href="#">PD_SUBRESULT_RESPONSE_BUSY</a>	Subresult - BUSY has been sent as response

#### Examples

```
PD_Set $PdGlobalSettings.EnableCableEmulator = PD_TRUE  
.  
Call PD_WaitForDiscoverModes_Cable( PD_ORDERED_SET_TYPE_SOP_PRIME )
```

### 5.1.146 PD\_AddModeVDO\_Cable

Adds *Mode*(for cable) with VDO to the PD Exerciser. It has to be called prior calling the [PD\\_WaitForDiscoverModes\\_Cable](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

**Note** - PD Exerciser should also act as Cable Plug to be able to process this command.

#### Format

```
Call PD_AddModeVDO_Cable(PD_Vdo $ModeVdo, ordered_set)
```

#### Parameters

\$ModeVdo

Should be from [PD\\_Vdo](#) type. Table below describes the [PD\\_VDO](#) template that can be use as ModeVdo (Refer to [PD\\_VDO](#)):

Field Name	Description
Data	VDO

**ordered\_set**

Possible values:

PD\_ORDERED\_SET\_TYPE\_SOP\_PRIME  
PD\_ORDERED\_SET\_TYPE\_SOP\_DOUBLE\_PRIME

## Result

None

## Examples

```
PD_Set $PdGlobalSettings.EnableCableEmulator = PD_TRUE
.
local $vdo_1 = PD_VDO
{
    Data = 0x01
}
call PD_AddModeVDO_Cable($vdo_1, PD_ORDERED_SET_TYPE_SOP_PRIME)
```

## 5.1.147 PD\_AddMode\_Cable

Adds *Mode*(Cable Plug) to the PD Exerciser. It has to be called prior calling the [PD\\_WaitForDiscoverModes\\_Cable](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

**Note** - PD Exerciser should also act as Cable Plug to be able to process this command.

### Format

Call PD\_AddMode\_Cable(*Mode*, *ordered\_set*)

### Parameters

**Mode**

Mode to add

**ordered\_set**

Possible values:

PD\_ORDERED\_SET\_TYPE\_SOP\_PRIME  
PD\_ORDERED\_SET\_TYPE\_SOP\_DOUBLE\_PRIME

## Result

None

## Examples

```
PD_Set $PdGlobalSettings.EnableCableEmulator = PD_TRUE
.
call PD_AddMode_Cable(0x00000001, PD_ORDERED_SET_TYPE_SOP_PRIME)
```

## 5.1.148 PD\_ResetModes\_Cable

Clears *Modes*(for cable) which are added to PD Exerciser. It should be called prior calling the [PD\\_AddModeVDO\\_Cable](#) and [PD\\_AddMode\\_Cable](#) functions.

**Note** - PD Exerciser should also act as Cable Plug to be able to process this command.

### Format

```
Call PD_ResetModes_Cable( ordered_set )
```

### Parameters

ordered\_set

Possible values:

```
PD_ORDERED_SET_TYPE_SOP_PRIME  
PD_ORDERED_SET_TYPE_SOP_DOUBLE_PRIME
```

### Result

None

### Examples

```
PD_Set $PdGlobalSettings.EnableCableEmulator = PD_TRUE  
. . .  
Call PD_ResetModes_Cable( PD_ORDERED_SET_TYPE_SOP_PRIME )
```

## 5.1.149 PD\_SetEnterModeSetting\_Cable

It has to be called prior calling the [PD\\_WaitForEnterMode\\_Cable](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

**Note** - PD Exerciser should also act as Cable Plug to be able to process this command.

### Format

```
Call PD_SetEnterModeSetting_Cable( PD_EnterMode_Settings_SOPPrime $settings )  
Call PD_SetEnterModeSetting_Cable( PD_EnterMode_Settings_SOPDPrime $settings )
```

### Parameters

\$settings

For SOP Prime, use [PD\\_EnterMode\\_Settings\\_SOPPrime](#) and for SOP Double Prime, use [PD\\_EnterMode\\_Settings\\_SOPDPrime](#). Refer to [PD\\_SetEnterModeSetting](#) for more details.

### Result

None

### Examples

```
PD_Set $PdGlobalSettings.EnableCableEmulator = PD_TRUE  
PD_Set $PdGlobalSettings.EnableCableDPrimeEmulator = PD_TRUE  
. . .  
#Using default setting  
$settings = PD_EnterMode_Settings_SOPPrime  
call PD_SetEnterModeSetting_Cable( $settings )  
  
$settings_dprime = PD_EnterMode_Settings_SOPDPrime  
call PD_SetEnterModeSetting_Cable( $settings_dprime )
```

### 5.1.150 PD\_WaitForEnterMode\_Cable

Waits for user-defined time-out to receive ENTERMODE command. It will respond to incoming messages as part of *EnterMode* AMS.

**Note 1:** PD Exerciser should also act as Cable Plug to be able to process this command.

**Note 2:** The [PD\\_SetEnterModeSetting\\_Cable](#) function may need to be called prior calling this function.

#### Format

```
Call PD_WaitForEnterMode_Cable( ordered_set )
```

#### Parameters

ordered\_set

Possible values:

```
PD_ORDERED_SET_TYPE_SOP_PRIME  
PD_ORDERED_SET_TYPE_SOP_DOUBLE_PRIME
```

#### Result

User can evaluate the command results(including sub-results) using IfMatched/ElseMatched command.

Result Value	Description
PD_RESULT_OK	Command succeeded
PD_RESULT_FAILED	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the error type which has been occurred during sending or receiving data).
PD_SUBRESULT_MSG_NOT RECEIVED	Subresult - ENTER_MODE message not received
PD_SUBRESULT_RESPONSE_NAK	Subresult - NAK has been sent as response

#### Examples

```
PD_Set $PdGlobalSettings.EnableCableEmulator = PD_TRUE  
. . .  
Call PD_WaitForEnterMode_Cable( PD_ORDERED_SET_TYPE_SOP_PRIME )
```

### 5.1.151 PD\_SetExitModeSetting\_Cable

It has to be called prior calling the [PD\\_WaitForExitMode\\_Cable](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

**Note** - PD Exerciser should also act as Cable Plug to be able to process this command.

#### Format

```
Call PD_SetExitModeSetting_Cable( PD_ExitMode_Settings_SOPPrime $settings )  
Call PD_SetExitModeSetting_Cable( PD_ExitMode_Settings_SOPDPrime $settings )
```

#### Parameters

\$settings

For SOP Prime, use `PD_ExitMode_Settings_SOPPrime` and for SOP Double Prime, use `PD_ExitMode_Settings_SOPDPrime`. Refer to [PD\\_SetExitModeSetting](#) for more details.

#### Result

None

### Examples

```
PD_Set $PdGlobalSettings.EnableCableEmulator = PD_TRUE
PD_Set $PdGlobalSettings.EnableCableDPrimeEmulator = PD_TRUE
.
.
.
#Using default settings
$settings = PD_ExitMode_Settings_SOPPrime
call PD_SetExitModeSetting_Cable( $settings )

$settings_dprime = PD_ExitMode_Settings_SOPDPrime
call PD_SetExitModeSetting_Cable( $settings_dprime )
```

### 5.1.152 PD\_WaitForExitMode\_Cable

Waits for user-defined time-out to receive EXITMODE command. It will respond to incoming messages as part of *ExitMode* AMS.

**Note 1:** PD Exerciser should also act as Cable Plug to be able to process this command.

**Note 2:** The [PD\\_SetExitModeSetting\\_Cable](#) function may need to be called prior calling this function.

#### Format

```
Call PD_WaitForExitMode_Cable( ordered_set )
```

#### Parameters

ordered\_set

Possible values:

```
PD_ORDERED_SET_TYPE_SOP_PRIME
PD_ORDERED_SET_TYPE_SOP_DOUBLE_PRIME
```

#### Result

User can evaluate the command results(including sub-results) using [IfMatched/ElseMatched](#) command.

Result Value	Description
PD_RESULT_OK	Command succeeded
PD_RESULT_FAILED	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the error type which has been occurred during sending or receiving data).
PD_SUBRESULT_MSG_NOT_RECEIVED	Subresult - EXIT_MODE message not received
PD_SUBRESULT_RESPONSE_NAK	Subresult - NAK has been sent as response

### Examples

```
PD_Set $PdGlobalSettings.EnableCableEmulator = PD_TRUE
.
.
.
Call PD_WaitForExitMode_Cable( PD_ORDERED_SET_TYPE_SOP_PRIME )
```

### 5.1.153 PD\_SetManufacturerInfoDataBlock\_Cable

Applicable to PD Rev 3.0 only. Sets *ManufacurerInfo Data Block*(for cable) to the PD Exerciser. It has to be called prior calling the [PD\\_WaitForGetManufacturerInfo\\_Cable](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

**Note** - PD Exerciser should also act as Cable Plug to be able to process this command.

#### Format

```
Call PD_SetManufacturerInfoDataBlock_Cable( PD_ManufacturerInfoDataBlock  
$manufacturer_info_db )
```

#### Parameters

\$manufacturer\_info\_db

Parameter type is PD\_ManufacturerInfoDataBlock. Refer to [PD\\_ManufacturerInfoMsg](#) for available fields of this type.

#### Result

None

#### Examples

```
PD_Set $PdGlobalSettings.EnableCableEmulator = PD_TRUE  
. . .  
$manufacturer_info_db = PD_ManufacturerInfoDataBlock  
Call PD_SetManufacturerInfoDataBlock_Cable( $manufacturer_info_db )
```

### 5.1.154 [PD\\_SetGetManufacturerInfoSetting\\_Cable](#)

Applicable to PD Rev 3.0 only. It has to be called prior calling the [PD\\_WaitForGetManufacturerInfo\\_Cable](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

**Note** : PD Exerciser should also act as Cable Plug to be able to process this command.

#### Format

```
Call PD_SetGetManufacturerInfoSetting_Cable( PD_GetManufacturerInfo_Settings  
$settings )
```

#### Parameters

\$settings

Refer to [PD\\_SetGetManufacturerInfoSetting](#) for more details.

#### Result

None

#### Examples

```
PD_Set $PdGlobalSettings.EnableCableEmulator = PD_TRUE  
. . .  
$getmaninfo_setting = PD_GetManufacturerInfo_Settings  
{  
    WaitTimeout = 50000  
}  
Call PD_SetGetManufacturerInfoSetting_Cable( $getmaninfo_setting )
```

### 5.1.155 [PD\\_WaitForGetManufacturerInfo\\_Cable](#)

Applicable to PD Rev 3.0 only. Waits for user-defined time-out to receive Manufacturer\_Info message. It will respond to incoming messages as part of *GetManufacturerInfo* AMS.

**Note 1:** PD Exerciser should also act as Cable Plug to be able to process this command.

**Note 2:** The [PD\\_SetGetManufacturerInfoSetting\\_Cable](#) and [PD\\_SetManufacturerInfoDataBlock\\_Cable](#) functions may need to be called prior calling this function.

### Format

```
Call PD_WaitForGetManufacturerInfo_Cable()
```

### Parameters

None

### Result

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

List of result values:

Result Value	Description
<a href="#">PD_RESULT_OK</a>	Command succeeded
<a href="#">PD_RESULT_FAILED</a>	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the error type which has been occurred during sending or receiving data).
<a href="#">PD_SUBRESULT_MSG_NOT_RECEIVED</a>	Subresult - Get_Manufacturer_Info message not received.

### Examples

```
PD_Set $PdGlobalSettings.EnableCableEmulator = PD_TRUE
.
.
Call PD_WaitForGetManufacturerInfo_Cable()
```

## 5.1.156 [PD\\_SetSecurityResponseDataBlock\\_Cable](#)

Applicable to PD Rev 3.0 only. Sets the *SecurityResponse Data Block*(for cable) to the PD Exerciser. It has to be called prior calling the [PD\\_WaitForSecurityRequest\\_Cable](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

**Note** - PD Exerciser should also act as Cable Plug to be able to process this command.

### Format

```
Call PD_SetSecurityResponseDataBlock_Cable( PD_SecurityResponseDB
$security_resp_db )
```

### Parameters

`$security_resp_db`

Parameter type is `PD_SecurityResponseDB`. Refer to [PD\\_SecurityResponseMsg](#) for available types which are derived from this type.

### Result

None

### Examples

```
PD_Set $PdGlobalSettings.EnableCableEmulator = PD_TRUE
.
.

```

```
$security_resp_db = PD_SRPDB_Certificate
Call PD_SetSecurityResponseDataBlock_Cable( $security_resp_db )
```

### 5.1.157 PD\_SetSecurityRequestSetting\_Cable

Applicable to PD Rev 3.0 only. It has to be called prior calling the [PD\\_WaitForSecurityRequest\\_Cable](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

**Note** - PD Exerciser should also act as Cable Plug to be able to process this command.

#### Format

```
Call PD_SetSecurityRequestSetting_Cable( PD_SecurityRequest_Settings $settings )
```

#### Parameters

**\$settings**

Refer to [PD\\_SetSecurityRequestSetting](#) for more details.

#### Result

None

#### Examples

```
PD_Set $PdGlobalSettings.EnableCableEmulator = PD_TRUE
.
$secreq_settings = PD_SecurityRequest_Settings
{
    WaitTimeout = 50000
}
Call PD_SetSecurityRequestSetting( $secreq_settings )
```

### 5.1.158 PD\_WaitForSecurityRequest\_Cable

Applicable to PD Rev 3.0 only. Waits for user-defined time-out to receive Security\_Request message. It will respond to incoming messages as part of *SecurityRequest* AMS.

**Note 1:** PD Exerciser should also act as Cable Plug to be able to process this command.

**Note 2:** The [PD\\_SetSecurityResponseDataBlock\\_Cable](#) and [PD\\_SetSecurityRequestSetting\\_Cable](#) functions may need to be called prior calling this function.

#### Format

```
Call PD_WaitForSecurityRequest_Cable()
```

#### Parameters

None

#### Result

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

List of result values:

Result Value	Description
<a href="#">PD_RESULT_OK</a>	Command succeeded
<a href="#">PD_RESULT_FAILED</a>	Command failed. In this case corresponding sub results for

	<a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the error type which has been occurred during sending or receiving data).
<a href="#">PD_SUBRESULT_MSG_NOT_RECEIVED</a>	Subresult - Security_Request message not received.

### Examples

```
PD_Set $PdGlobalSettings.EnableCableEmulator = PD_TRUE
.
Call PD_WaitForSecurityRequest_Cable()
```

## 5.1.159 Pd\_SetGetStatusSetting\_Cable

Applicable to PD Rev 3.0 only. It has to be called prior calling the [Pd\\_WaitForGetStatus\\_Cable](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

**Note** - PD Exerciser should also act as Cable Plug to be able to process this command.

### Format

```
Call Pd_SetGetStatusSetting_Cable( Pd_GetStatus_Settings $settings )
```

### Parameters

\$settings

Parameter type is [PD\\_GetStatus\\_Settings](#). Refer to [Pd\\_SetGetStatusSetting](#) for available settings:

### Result

None

### Examples

```
$getstatus_setting = PD_GetStatus_Settings
{
    WaitTimeout = 250000
}
Call Pd_SetGetStatusSetting_Cable( $getstatus_setting )
```

## 5.1.160 PD\_SetStatusDataBlock\_Cable

Applicable to PD Rev 3.0 only. Sets the *Cable Status Data Block* in PD Exerciser. It has to be called prior calling the [Pd\\_WaitForGetStatus\\_Cable](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

**Note** - PD Exerciser should also act as Cable Plug to be able to process this command.

### Format

```
Call PD_SetStatusDataBlock_Cable( Pd_StatusDataBlock_Cable $status_db )
```

### Parameters

\$status\_db

Parameter type is [Pd\\_StatusDataBlock\\_Cable](#). Refer to [Pd\\_StatusMsg\\_Cable](#) for available fields.

### Result

None

### Examples

```
$cable_status_db = Pd_StatusDataBlock_Cable  
Call PD_SetStatusDataBlock_Cable( $cable_status_db )
```

## 5.1.161 Pd\_ResetStatusDataBlock\_Cable

Applicable to PD Rev 3.0 only. Clears the *Cable Status Data Block* in PD Exerciser. It should be called prior calling the [PD\\_SetStatusDataBlock\\_Cable](#) function.

**Note** - PD Exerciser should also act as Cable Plug to be able to process this command.

### Format

```
Call Pd_ResetStatusDataBlock_Cable()
```

### Parameters

None

### Result

None

### Examples

```
Call Pd_ResetStatusDataBlock_Cable()
```

## 5.1.162 Pd\_WaitForGetStatus\_Cable

Applicable to PD Rev 3.0 only. Waits for user-defined time-out to receive *Get\_Status* message. It will respond to incoming messages as part of *GetStatus* AMS.

**Note 1:** PD Exerciser should also act as Cable Plug to be able to process this command.

**Note 2:** The [Pd\\_SetGetStatusSetting\\_Cable](#), [PD\\_SetStatusDataBlock\\_Cable](#) and [Pd\\_ResetStatusDataBlock\\_Cable](#) functions may need to be called prior calling this function.

### Format

```
Call Pd_WaitForGetStatus_Cable( )
```

### Parameters

None

### Result

User can evaluate the command results(including sub-results) using *IfMatched/ElseMatched* command.

List of result values:

Result Value	Description
<a href="#">PD_RESULT_OK</a>	Command succeeded
<a href="#">PD_RESULT_FAILED</a>	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the error type which has been occurred during sending or receiving data).
<a href="#">PD_SUBRESULT_MSG_NOT_RECEIVED</a>	Subresult - <i>Get_Status</i> message not received.

### Examples

```
Call Pd_WaitForGetStatus_Cable()
```

### **5.1.163 PD\_SetEnterUSBSetting\_Cable**

Applicable to PD Rev 3.0 only. It has to be called prior calling the [PD\\_WaitForEnterUSB\\_Cable](#) or [PD\\_DelayAutoResponse](#) functions to take effect.

**Note :** PD Exerciser should also act as Cable Plug to be able to process this command.

#### **Format**

```
Call PD_SetEnterUSBSetting_Cable( PD_EnterUSB_Settings $settings )
```

#### **Parameters**

**\$settings**

Refer to [PD\\_SetEnterUSBSetting](#) for more details.

#### **Result**

None

#### **Examples**

```
PD_Set $PdGlobalSettings.EnableCableEmulator = PD_TRUE
.
$enter_usb_setting = PD_EnterUSB_Settings
{
    WaitTimeout = 50000
}
Call PD_SetEnterUSBSetting_Cable( $enter_usb_setting )
```

### **5.1.164 PD\_WaitForEnterUSB\_Cable**

Applicable to PD Rev 3.0 only. Waits for user-defined time-out to receive `EnterUSB` message. It will respond to incoming messages as part of *EnterUSB* AMS.

**Note 1:** PD Exerciser should also act as Cable Plug to be able to process this command.

**Note 2:** The [PD\\_SetEnterUSBSetting\\_Cable](#) functions may need to be called prior calling this function.

#### **Format**

```
Call PD_WaitForEnterUSB_Cable()
```

#### **Parameters**

None

#### **Result**

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

List of result values:

Result Value	Description
<a href="#">PD_RESULT_OK</a>	Command succeeded
<a href="#">PD_RESULT_FAILED</a>	Command failed. In this case corresponding sub results for <a href="#">PD_SendPacket</a> and <a href="#">PD_ReceivePacket</a> are valid also (depends on the error type which has been occurred during sending or receiving data).

<code>PD_SUBRESULT_RESPONSE_REJECT</code>	Subresult - Reject message has been sent as response
<code>PD_SUBRESULT_MSG_NOT_RECEIVED</code>	Subresult – EnterUSB message not received.

## Examples

```
PD_Set $PdGlobalSettings.EnableCableEmulator = PD_TRUE
.
.
Call PD_WaitForEnterUSB_Cable()
```

### 5.1.165 Pd\_SetHardResetSetting

It has to be called prior calling the `PD_DelayAutoResponse` function or any other *HighLevel Transaction Engine™* functions to take effect.

#### Format

```
Call Pd_SetHardResetSetting( Pd_HardResetSettings $settings )
```

#### Parameters

`$settings`

Should be from `Pd_HardResetSettings` type. Following are the available fields of this packet template:

Field Name	Possible/Default Values	Description
<code>WaitTimeOut</code>	<code>PD_DEFAULT_TIMEOUT_INFINITE</code> (Default)	Indicates the time-out for waiting to receive the HardReset. Only applies to the <code>Pd_WaitForHardReset</code> function.
<code>NoResponse</code>	<code>PD_FALSE</code> (Default)	Indicates whether the PD Exerciser should respond to received HardResets or not. It applies to all <i>HighLevel Transaction Engine™</i> functions as well as <code>PD_DelayAutoResponse</code> function.

#### Result

None

## Examples

```
#Ignore all received HardResets
$settings = Pd_HardResetSettings
{
    NoResponse = PD_TRUE
}
call Pd_SetHardResetSetting( $settings )
```

### 5.1.166 Pd\_WaitForHardReset

Waits for user-defined time-out to receive `HardReset` signal. It handles the `HardReset` signal.

**Note:** The `Pd_SetHardResetSetting` function may need to be called prior calling this function.

#### Format

```
Call Pd_WaitForHardReset()
```

#### Parameters

None

#### Result

User can evaluate the command results(including sub-results) using `IfMatched/ElseMatched` command.

Result Value	Description
<code>PD_RESULT_OK</code>	Command succeeded
<code>PD_RESULT_FAILED</code>	Command failed. In this case corresponding sub results for <code>PD_ReceivePacket</code> are valid also (depends on the error type which has been occurred while receiving data).
<code>PD_SUBRESULT_MSG_NOT_RECEIVED</code>	Subresult - HardReset signal not received

### Examples

```
call Pd_WaitForHardReset()
```

## 5.2 Auto Responses Capability

To gain auto response capability, use below command. This command will respond to any incoming Power Delivery messages according to current operational settings. In addition to this command, at the start of each High-Level command Auto-Response is activated.

### 5.2.1 PD\_DelayAutoResponse

#### Format

```
Call PD_DelayAutoResponse( duration_micro_Sec )
```

#### Parameters

`duration_micro_Sec`

Command waits for maximum specified duration and responses to received packet automatically.

#### Examples

```
call PD_DelayAutoResponse( 1000 )
```

### 5.2.2 PD\_PauseAutoResponse

Responsive PD Exerciser pause which waits until `ResumePDGeneration()` called by the *Automation Application*. By calling this function, an *Automation Application* get notified that PD Exerciser Engine is paused. Refer to **USBAnalyzerAutomationManual** for more information on `waitForPDGenerationPauseTag()` and `ResumePDGeneration()` API calls.

**Note:** All the rules which are applied to the `PD_DelayAutoResponse` function, will apply to this function too.

#### Format

```
Call PD_PauseAutoResponse( tag )
```

#### Parameters

`tag`

Makes each call to `PD_PauseAutoResponse` unique.

#### Examples

```
# PD Exerciser Script example:  
call PD_PauseAutoResponse( 1 )  
  
' WSH example:  
Set Analyzer = wscript.CreateObject("CATC.USBTracer")  
Analyzer.WaitForPDGenerationPauseTag 15000, diff_time, pauseTag, isGenDone  
  
If pauseTag <> 0 Then  
    WScript.Quit  
End If  
  
Analyzer.ResumePDGeneration
```

## 6 Appendix A:

### How to Contact Teledyne LeCroy

Send e-mail...	<a href="mailto:psgsupport@teledyne.com">psgsupport@teledyne.com</a>
Contact support...	<a href="http://teledynelecroy.com/support/contact">teledynelecroy.com/support/contact</a>
Visit Teledyne LeCroy's web site...	<a href="http://teledynelecroy.com">teledynelecroy.com</a>
Tell Teledyne LeCroy...	Report a problem to Teledyne LeCroy Support via e-mail by selecting <b>Help &gt; Tell Teledyne LeCroy</b> from the application toolbar. This requires that an e-mail client be installed and configured on the host machine.