# Errata

Title & Document Type: 6203B DC Power Supply Operating and Service Manual

Manual Part Number: 06203-90001

**Revision Date: July 1966** 

# **About this Manual**

We've added this manual to the Agilent website in an effort to help you support your product. This manual provides the best information we could find. It may be incomplete or contain dated information, and the scan quality may not be ideal. If we find a better copy in the future, we will add it to the Agilent website.

# **HP References in this Manual**

This manual may contain references to HP or Hewlett-Packard. Please note that Hewlett-Packard's former test and measurement, life sciences, and chemical analysis businesses are now part of Agilent Technologies. The HP XXXX referred to in this document is now the Agilent XXXX. For example, model number HP8648A is now model number Agilent 8648A. We have made no changes to this manual copy.

# **Support for Your Product**

Agilent no longer sells or supports this product. You will find any other available product information on the Agilent Test & Measurement website:

# www.agilent.com

Search for the model number of this product, and the resulting product page will guide you to any available information. Our service centers may be able to perform calibration if no repair parts are needed, but no other support from Agilent is available.



DC POWER SUPPLY
LAB SERIES, MODEL 6203B
SERIAL NUMBER PREFIX 6B

Printed: 11y, 1966

Stock Number: 06203-90001

### TABLE OF CONTENTS

	Page No.		tion	1	Page No.
I GENERAL INFORMATION		IV		PLES OF OPERATION	
1-1, Description	1-1 ,	! !	4-6.	Series Regulator	4-3
1-7. Instrument Identification	1-1	:	4-8,	Constant Voltage Input Circuit	4-3
1-10. Ordering Additional Manuals	1-1		4-12.	Constant Current Input Circuit	4-4
	4	The project	4-17,	Voltage Clamp Circuit	4-5
II INSTALLATION		' · · · · ·	4-20.	Mixer and Error Amplifiers	4-5
2-1. Initial Inspection	2-1		4-23.	Reference Circuit .	4-6
2-3. Mechanical Check	2-1	- A	4-26.	Meter Circuit	4-6
2-5. Electrical Check	2-1		4-32.	Operation of Regulating	1
2-7. Installation Data	2-1,			Feedback Loop	4-7
2-9. Location	2-1				
2-11. Rack Mounting	2-1	V		ENANCE	
2-15. Input Power Requirements	2-2	i	5-1.	Introduction	5-1
2-17. Connections for 230 Volt		100	5-3,	General Measurement	
Operation	2-2			Techniques	5-1
2-19. Power Cable	2-3		5 <b>-8.</b>	Test Equipment Required .	5-1
2-22. Repackaging for Shipment	2-3		5-10.	Performance Test	5-3
III OPERATING INSTRUCTIONS	:		5-12.		5-4
	,		5-20.	Output Impedance	5-6
3-1. Operating Controls and Indicators	3-1		5-22.	Output Inductance	5-6
3-3. Operating Modes	3-1 3-1		5-24,	Constant Current Tests	5-6
3-5. Normal Operating Mode			5-28.	Troubleshooting	5-7
3-7. Constant Voltage	3-1		5-30.	Trouble Analysis	5-7
3-9. Constant Current	3-1 3-1		5-38.	Repair and Replacement	5 <b>-10</b> ,
3-11. Connecting Load	3-2		5-40.		5-13
3-14. Optional Operating Modes	3-2 3-2		5-42.		5-13
3-15. Remote Programming, Constan			5-44.		5-13
Voltage Voltage	3-2		5-46,	Ammeter Tracking	5-13
3-22. Remote Programming, Constan			5-48.	Constant Voltage Programming	
Current	3-3	•	5-51.	Current	5-13
3-28. Remote Sensing	3-3		5-51,	Constant Current Programming	
3-33. Series Operation	3-3 3-4	I		Current	5-14
3-37. Parallel Operation	3-4 3-5		5-54.	Reference Circuit Adjustments	5-14
3-40. Auto-tracking Operation	3-3 3-6		5 <b>-</b> 56.	Constant Voltage Transient	
3-43. Special Operating	3-0			Response	5-14
Considerations	3-6	VI	DEDIA	CEABLE PARTS	r
3-44. Pulse Loading	3-6		6-1.	Introduction	6-1
3-46. Output Capacitance	3-7	· .	6-4.	Ordering Information	6-1
3-49. Reverse Voltage Loading	3-7		0 - 1,	Reference Designators	0-1
3-51. Reverse Current Loading	3-7 : <sup>1</sup>	,	e) - '	Abbreviations	10
Fig.	3-1	i.	· · ),	Manufacturers	3
IV PRINCIPLES OF OPERATION	13	1.1	6-8.	Code List of Manufacturers	): 6_2
4-1. Overall Block Diagram			<b>~ 0.</b>	Parts List Table	6-2
Discussion	4-1	۱,	-:	- dra mat faha	
4-4. Simplified Schematic	4-2	•	, É <b>)</b>	$\mathcal{J}$	t
- 14 ANICHTAGE DOTTONIGHO	7-Z			) , , , , , , , , , , , , , , , , , , ,	

# TABLE OF CONTENTS (CONTINUED)

# LIST OF TABLES

Table		Page No.	Table	Page No.
1-1	Specifications	1-2	5,-6 Selected Semiconductor	_
5-1	Test Equipment Required	5-2	Characteristics	5-10
5-2	Reference Circuit Troubleshooting	5-8	5-7 Checks and Adjustments After Repl	ace-
5-3	High Output Voltage Troubleshooting	5-8	ment of Semiconductor Devices	5-12
5-4	Low Output Voltage Troubleshooting	5-9	5-8 Calibration Adjustment Summary	5-13
	Common Troubles	5-9		1 .

#### LIST OF ILLUSTRATIONS

2-2 Rack Mounting, One Unit 2-2 4-6 Mixer and Error Amplifiers, 2-3 Primary Connections 2-2 Simplified Schematic 4-3-1 Front Panel Controls and Indicators 3-1 4-7 Meter Circuit, Simplified Schematic 4-8 Voltmeter Connections, 3-9 Remote Resistance Programming (Constant Voltage) 3-1 4-8 Voltmeter Connections, 3-2 Simplified Schematic 4-8 Voltmeter Connections, 3-9 Simplified Schematic 3-1 4-8 Voltmeter Connections, 3-1 A-8 Voltmeter Connections, 3-1 Simplified Schematic 4-9 Ammeter Connections, 3-1 Simplified Schematic 3-1 Front Panel Terminal Connections 3-2 Simplified Schematic 4-9 Aumeter Connections 3-1 Front Panel Terminal Connections 3-2 Output Current Measurement 3-3 Technique 3-3 Differential Voltmeter Substitute, 3-4 Test Setup 3-5 Output Current, Test Setup 3-6 Remote Sensing 3-7 Remote Sensing 3-8 Normal Series 3-9 AUTO-Series, Two and Three Units 3-4 Ripple and Noise, Constant Voltage 5-6 Ripple and Noise, Constant Voltage	-5 -5 -6 -7
Primary Connections 2-2 Simplified Schematic 4-3-1 Front Panel Controls and Indicators 3-1 4-7 Meter Circuit, Simplified Schematic 4-3-2 Normal Strapping Pattern 3-1 4-8 Voltmeter Connections, Simplified Schematic 4-3-3-3 Remote Resistance Programming (Constant Voltage) 3-2 4-9 Ammeter Connections, Simplified Schematic 4-3-4 Remote Voltage Programming (Constant Voltage) 3-2 5-1 Front Panel Terminal Connections 5-3-5 Remote Resistance Programming (Constant Current) 3-3 Technique 5-3 Differential Voltage Programming (Constant Current) 3-3 Test Setup 5-3-8 Remote Sensing 3-3 5-4 Output Current, Test Setup 5-3-8 Normal Series 3-4 5-5 Load Regulation, Constant Voltage 5-3-9 AUTO-Series, Two and Three Units 3-4 Series 5-6 Ripple and Noise, Constant Voltage 5-3-9 Report Sensing 5-4 Ripple and Noise, Constant Voltage 5-3-9 Report Sensing 5-4 Ripple and Noise, Constant Voltage 5-3-9 Report Sensing 5-4 Ripple and Noise, Constant Voltage 5-3-9 Report Sensing 5-4 Ripple and Noise, Constant Voltage 5-3-9 Report Sensing 5-4 Ripple and Noise, Constant Voltage 5-3-9 Report Sensing 5-4 Ripple and Noise, Constant Voltage 5-3-9 Report Sensing 5-4 Ripple and Noise, Constant Voltage 5-3-9 Report Sensing 5-4 Ripple and Noise, Constant Voltage 5-3-9 Report Sensing 5-4 Ripple and Noise, Constant Voltage 5-3-9 Report Sensing 5-4 Ripple and Noise, Constant Voltage 5-3-9 Report Sensing 5-4 Ripple and Noise, Constant Voltage 5-3-9 Report Sensing 5-4 Ripple and Noise, Constant Voltage 5-3-9 Report Sensing 5-4 Report Sensing 5-4 Report Sensing 5-4 Report Sensing 5-4 Report Sensing 5-5 Report S	-6 -7
3-1 Front Panel Controls and Indicators 3-1 3-2 Normal Strapping Pattern 3-1 4-8 Voltmeter Connections, 3-3 Remote Resistance Programming (Constant Voltage) 3-2 4-9 Ammeter Connections, 3-4 Remote Voltage Programming (Constant Voltage) 3-2 5-1 Front Panel Terminal Connections 3-5 Remote Resistance Programming (Constant Current) 3-6 Remote Voltage Programming (Constant Current) 3-7 Remote Sensing 3-8 Normal Series 3-9 AUTO-Series, Two and Three Units 3-1 A-8 Voltmeter Connections, 3-1 A-9 Voltmeter Connections, 3-1 A-9 Voltmeter Connections, 3-1 A-9 Voltmeter Connections, 3-1 A-9 Voltmeter Connections, 3-2 A-9 Auto-Series 3-1 Front Panel Terminal Connections 3-2 Output Current Measurement 3-3 Differential Voltmeter Substitute, 3-4 Output Current, Test Setup 3-5 Load Regulation, Constant Voltage 3-6 Ripple and Noise, Constant Voltage 3-7 Remote Sensing 3-8 Remote Sensing 3-9 Auto-Series, Two and Three Units 3-1 A-8 Voltmeter Connections, 3-2 Auto-Series 3-1 Front Panel Terminal Connections 3-2 Output Current Measurement 3-3 Differential Voltmeter Substitute, 3-4 Output Current, Test Setup 3-5 Load Regulation, Constant Voltage 3-6 Ripple and Noise, Constant Voltage 3-7 Remote Sensing 3-8 Remote Sensing 3-9 Auto-Series, Two and Three Units 3-1 A-8 Voltmeter Connections, 3-2 A-9 Memeter Connections, 3-3 A	-6 -7
3-2 Normal Strapping Pattern 3-1 4-8 Voltmeter Connections, Simplified Schematic 4- (Constant Voltage) 3-2 4-9 Ammeter Connections, Simplified Schematic 4- (Constant Voltage) 3-2 5-1 Front Panel Terminal Connections 3-5 Remote Resistance Programming (Constant Current) 3-6 Remote Voltage Programming (Constant Current) 3-7 Remote Sensing 3-8 Normal Series 3-9 AUTO-Series, Two and Three Units 3-1 A-8 Voltmeter Connections, Simplified Schematic 4- 5-1 Front Panel Terminal Connections 5-2 Output Current Measurement Technique 5-3 Differential Voltmeter Substitute, Test Setup 5-3 Output Current, Test Setup 5-4 Output Current, Test Setup 5-5 Load Regulation, Constant Voltage 5-6 Ripple and Noise, Constant Voltage 5-6 Ripple and Noise, Constant Voltage 5-6 Ripple and Noise, Constant Voltage 5-7 Remote Sensing Series 5-8 Ripple and Noise, Constant Voltage 5-9 Remote Sensing Series 5-9 AUTO-Series, Two and Three Units Series	-7
3-3 Remote Resistance Programming (Constant Voltage) 3-2 4-9 Ammeter Connections, Simplified Schematic 4-9 Aumeter	
(Constant Voltage) 3-2 4-9 Ammeter Connections, Simplified Schematic 4- (Constant Voltage) 3-2 5-1 Front Panel Terminal Connections 5- 3-5 Remote Resistance Programming 5-2 Output Current Measurement (Constant Current) 3-3 Technique 5- 3-6 Remote Voltage Programming 5-3 Differential Voltage Test Setup 5- 3-7 Remote Sensing 3-3 5-4 Output Current, Test Setup 5- 3-8 Normal Series 3-4 5-5 Load Regulation, Constant Voltage 5- 3-9 AUTO-Series, Two and Three Units 3-4 5-6 Ripple and Noise, Constant Voltage 5-	
3-4 Remote Voltage Programming (Constant Voltage) 3-2 5-1 Front Panel Terminal Connections 5-3 3-5 Remote Resistance Programming (Constant Current) 3-3 Technique 5-3 Differential Voltmeter Substitute, (Constant Current) 3-3 Test Setup 5-3 Output Current, Test Setup 5-3 Differential Voltmeter Substitute, 5-4 Output Current, Test Setup 5-5 Load Regulation, Constant Voltage 5-6 Ripple and Noise, Constant Voltage 5-7 Remote Sensing 5-8 AUTO-Series, Two and Three Units 5-9 AUTO-Series, Two and Three Units 5-1 Front Panel Terminal Connections 5-2 Output Current Measurement 5-3 Differential Voltmeter Substitute, 5-4 Output Current, Test Setup 5-5 Load Regulation, Constant Voltage 5-6 Ripple and Noise, Constant Voltage 5-7 Remote Sensing 5-8 Remote Resistance Programming 5-9 AUTO-Series, Two and Three Units 5-9 Remote Resistance Programming 5-1 Front Panel Terminal Connections 5-1 Output Current Measurement 5-2 Output Current Measurement 5-3 Differential Voltmeter Substitute, 5-4 Output Current, Test Setup 5-5 Remote Sensing 5-7 Remote Sensing 5-8 Remote Voltage Programming 5-9 Remote Voltage Programming 5-	_7
(Constant Voltage) 3-2 5-1 Front Panel Terminal Connections 5-3 Remote Resistance Programming (Constant Current) 3-3 Technique 5-3 Differential Voltage Programming (Constant Current) 3-3 Test Setup 5-3 Remote Sensing 3-3 5-4 Output Current, Test Setup 5-3 Normal Series 3-4 5-5 Load Regulation, Constant Voltage 5-3 Ripple and Noise, Constant Voltage 5-3 Ripple And Noi	_7
3-5 Remote Resistance Programming (Constant Current) 3-3 Technique 5-3 3-6 Remote Voltage Programming (Constant Current) 3-3 Differential Voltmeter Substitute, Test Setup 5-3 3-7 Remote Sensing 3-8 Normal Series 3-9 AUTO-Series, Two and Three Units 3-4 Series 3-5 Coutput Current, Test Setup 5-6 Ripple and Noise, Constant Voltage 5-7 Remote Sensing 3-8 Normal Series 3-9 AUTO-Series, Two and Three Units 3-8 Remote Resistance Programming 5-9 Output Current Measurement Technique 5-9 Differential Voltmeter Substitute, Test Setup 5-9 Coutput Current Measurement Technique 5-9 Differential Voltmeter Substitute, Test Setup 5-8 Remote Sensing 5-9 Coutput Current Measurement Technique 5-9 Differential Voltmeter Substitute, Test Setup 5-9 Coutput Current Measurement Technique 5-9 Differential Voltmeter Substitute, Test Setup 5-9 Coutput Current Measurement Technique 5-9 Differential Voltmeter Substitute, Test Setup 5-9 Coutput Current, Test Setup 5-9 Coutput Current Measurement Technique 5-9 Coutput Current Measurement Technique 5-9 Coutput Current Measurement Technique 5-9 Coutput Current Test Setup Te	-,
(Constant Current) 3-3 Technique 5-3 3-6 Remote Voltage Programming 5-3 Differential Voltmeter Substitute, (Constant Current) 3-3 Test Setup 5-3 3-7 Remote Sensing 3-3 5-4 Output Current, Test Setup 5-3 3-8 Normal Series 3-4 5-5 Load Regulation, Constant Voltage 5-3 3-9 AUTO-Series, Two and Three Units 3-4 5-6 Ripple and Noise, Constant Voltage 5-3	-1
3-6 Remote Voltage Programming (Constant Current) 3-3 Test Setup 5-3 Differential Voltmeter Substitute, Test Setup 5-3 Output Current, Test Setup 5-4 Output Current, Test Setup 5-5 Load Regulation, Constant Voltage 5-6 Ripple and Noise, Constant Voltage 5-7 Remote Sensing 5-8 Normal Series 5-9 AUTO-Series, Two and Three Units 5-8 Ripple and Noise, Constant Voltage 5-9 Ripple and Noise, Constant Voltage	
(Constant Current) 3-3 Test Setup 5-3 3-7 Remote Sensing 3-3 S-4 Output Current, Test Setup 5-3 Normal Series 3-4 5-5 Load Regulation, Constant Voltage 5-6 Ripple and Noise, Constant Voltage 5-6 Ripple and Noise, Constant Voltage 5-7 Remote Sensing 5-8 Ripple and Noise, Constant Voltage 5-9 Ripple and Noise, Constant Voltage	-1
3-7 Remote Sensing 3-3 5-4 Output Current, Test Setup 5-3-8 Normal Series 3-4 5-5 Load Regulation, Constant Voltage 5-6 Ripple and Noise, Constant Voltage 5-7 Ripple and Nois	
3-8 Normal Series 3-4 5-5 Load Regulation, Constant Voltage 5-3-9 AUTO-Series, Two and Three Units 3-4 5-6 Ripple and Noise, Constant Voltage 5-6	-3
3-8 Normal Series 3-4 5-5 Load Regulation, Constant Voltage 5-3-9 AUTO-Series, Two and Three Units 3-4 5-6 Ripple and Noise, Constant Voltage 5-6	-4
A SA SE DE LES	-4
3-10 Normal Parallel 3-5 5-7 Transient Postage Took Cotum 5-	-5
a / Management for post postup of	-5
3-11 Auto-Parallel, Two and Three Units 3-5 5-8 Transient Response, Waveforms 5-8	-5
3-12 Auto-Tracking, Two and Three Units 3-6 5-9 Output Impedance, Test Setup 5	-6
4-1 Overall Block Diagram 4-1 5-10 Load Regulation, Constant Current 5	-6
	-7
	-11
Simplified Schematic 4-3	
4-4 Constant Current Input Circuit,	
Simplified Schematic 4-4	

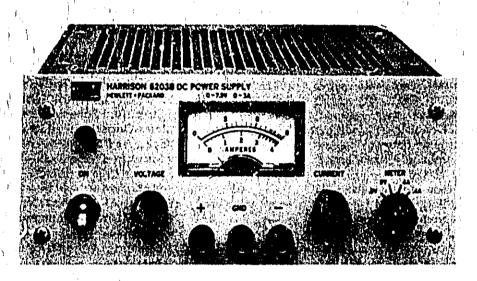


Figure 1-1. DC Power Supply, Model 6203B

# SECTION I GENERAL INFORMATION

# 1-1 DESCRIPTION

- This power supply, Figure 1-1, is completely transistorized and suitable for either bench or relay rack operation. It is a compact, well-regulated, Constant Voltage / Constant Current supply that will furnish full rated output vollage at the maximum rated output current or can be continuously adjusted throughout the output range. The front panel CURRENT controls can be used to establish the output current limit (overload or short circuit) when the supply is used as a constant voltage source and the VOLTAGE control can be used to establish the voltage limit (ceiling) when the supply is used as a constant current source. The supply will automatically crossover from constant voltage to constant current operation and vice versa if the output current or voltage exceeds these preset limits.
- 1-3 The power supply has both front and rear terminals. Either the positive or negative output terminal may be grounded or the power supply can be operated floating at up to a maximum of 300 volts off ground.
- 1-4 A single meter is used to measure either output voltage or output current in one of two ranges. The voltage or current ranges are selected by a METER switch on the front panel.
- 1-5 Barrier strip terminals located at the rear of the unit allow ease in adapting to the many operational capabilities of the power supply. A brief description of these capabilities is given below:

# a. Remote Programming

The power supply may be programmed from a remote location by means of an external voltage source or resistance.

# b. Remote Sensing

The degradation in regulation which would occur at the load because of the voltage drop in the load leads can be reduced by using the power supply in the remote sensing mode of operation.

### c. Series and Auto-Series Operation

Power supplies may be used in series when a higher output voltage is required in the voltage mode of operation or when greater voltage compliance is required in the constant current mode of operation. Auto-Series operation permits one knob control of the total output voltage from a "master" supply.

# d. Parallel and Auto-Parallel Operation

The power supply may be operated in parallel with a similar unit when greater output current capability is required. Auto-Parallel operation permits one knob control of the total output current from a "master" supply.

# e. Auto-Tracking

The power supply may be used as a "master" supply, having control over one (or more) "slave" supplies that furnish various voltages for a system.

# 1-6 SPECIFICATIONS

1-7 Detailed specifications for the power supply are given in Table/1-1.

# 1-8 OPTIONS

1-9 Options are factory modifications of a standard instrument that are requested by the customer. The following options are available for the instrument covered by this manual. Where necessary, detailed coverage of the options is included throughout the manual.

# Option No.

# Description

05

50 Hz Regulator Realignment: Standard instruments will operate satisfactorily at both 60 and 50 Hz without adjustment. However Option 05 factory realignment results in more efficient operation at 50 Hz, and is recommended for all applications when continuous operation from a 50 Hz ac input is intended.

# INPUT:

105-125/210-250VAC; single phase, 50-400 cps.

#### OUTPUT:

0-7.5 volts @ 3,0 amps. 11

#### LOAD REGULATION:

Constant Voltage -- Less than 5mv for a full load to no load change in output current.

Constant Current -- Less than 0.03% plus 250µa for a zero to maximum change in output voltage.

#### LINE REGULATION:

Constant Voltage -- Less than 3mv for any line voltage change within the input rating.

Constant Current -- Less than 0.01% plus 250µa for any line voltage change within the input rating.

### RIPPLE AND NOISE:

Constant Voltage -- Less than 200µv rms. Constant Current -- Less than 500µa rms.

### TEMPERATURE RANGES!

Operating: 0 to 50°C. Storage: -40 to +85°C.

# TEMPERATURE COEFFICIENT:

<u>Constant Voltage</u> -- Less than 0.02% plus 1mv per degree Centigrade.

Constant Current -- Less than 0,02% plus 2ma per degree Centigrade.

#### STABILITY:

Con.:ant Voltage -- Less than 0.10% plus 5mv total drift for 8 hours after an initial warmup time of 30 minutes at constant ambient, constant line voltage, and constant load.

Constant Current -- Less than 0,10% plus 10ma total drift for 8 hours after an initial warmup time of 30 minutes at constant ambient, constant line voltage, and constant load.

# INTERNAL IMPEDANCE AS A CONSTANT VOLTAGE SOURCE:

Less than 0.02, from DC to 1Kc.

Less than 0.5 from 1Kc to 100Kc.

Less than 3.00 from 100Kc to 1 Mc.

#### TRANSIENT RECOVERY TIME:

Less than  $50\mu\text{sec}$  for output recovery to within 10mv following a full load current change in the output.

# OVERLOAD PROTECTION:

A continuously acting constant current circuit protects the power supply for all overloads including a direct short placed across the terminals

in constant voltage operation. The constant voltage circuit limits the output voltage in the constant current mode of operation.

#### METER:

The front panel meter can be used as either a 0-9 or 0-,8 volt voltmeter or as a 0-4 or 0-,4 amp

#### **OUTPUT CONTROLS:**

Coarse and fine voltage controls and coarse and fine current controls are provided on the front panel,

### **OUTPUT TERMINALS:**

Three "five-way" output posts are provided on the front panel and an output terminal strip is located on the rear of the chassis. All power supply output terminals are isolated from the chassis and either the positive or negative terminal may be connected to the chassis through a separate ground terminal located on the output terminal strip.

== 5

:==

== =

#### ERROR SENSING:

Error sensing is normally accomplished at the front terminals if the load is attached to the front or at the rear terminals if the load is attached to the rear terminals. Also, provision is included on the rear terminal strip for remote sensing.

# REMOTE PROGRAMMING:

Remote programming of the supply output at approximately 200 ohms per volt in constant voltage is made available at the rear terminals. In constant current mode of operation, the current can be remotely programmed at approximately 500 ohms per ampere.

# COOLING:

Convection cooling is employed. The supply has no moving parts.

#### SIZE:

3-1/2" H x 12-5/8" D x 8-1/2" W. Two of the units can be mounted side by side in a standard 19" relay rack.

# WEIGHT:

14 lbs. net, 19 lbs. shipping.

# FINISH:

Light gray front panel with dark gray case,

### POWER CORD:

A three-wire, five-foot power cord is provided with each unit.

# 2-1 INITIAL INSPECTION

2-2 Before shipment, this instrument was inspected and found to be free of mechanical and electrical defects. As soon as the instrument is unpacked, inspect for any damage that may have occurred in transit. Save all packing materials until the inspection is completed. If damage is found, proceed as described in the Claim for Damage in Shipment section of the warranty page at the rear of this manual.

#### 2-3 MECHANICAL CHECK

2-4 This check should confirm that there are no broken knobs or connectors, that the cabinet and panel surfaces are free of dents and scratches, and that the meter is not scratched or cracked.

# 2-5 ELECTRICAL CHECK

2-6 The instrument should be checked against its electrical specifications. Section V includes an "incabinet" performance check to verify proper instrument operation.

# 2-7 INSTALLATION DATA

2-8 The instrument is shipped ready for bench operation. It is necessary only to connect the in-

strument to a source of power and it is ready for operation.

#### 2-9 LOCATION

2-10. This instrument is air cooled. Sufficient space should be allotted so that a free flow of cooling air can reach the sides and rear of the instrument when it is in operation. It should be used in an area where the ambient temperature does not exceed 50°C.

#### 2-11 RACK MOUNTING

2-12 This instrument may be rack mounted in a standard 19 inch rack panel either alongside a similar unit or by itself. Figures 2-1 and 2-2 show how both types of installations are accomplished.

2-13 To mount two units side-by-side, proceed as follows:

panels of both units.

b.' Slide rack mounting ears between the front panel and case of each unit.

c. Slide combining strip between the front panels and cases of the two units.

d. After fastening rear portions of units together using the bolt, nut, and spacer, replace panel screws.

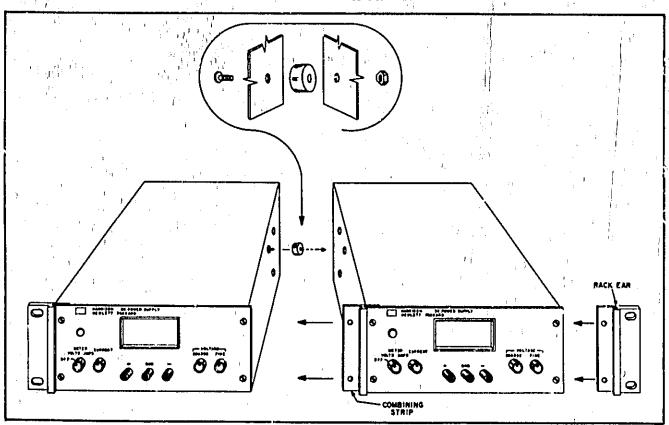


Figure 2-1. Rack Mounting, Two Units

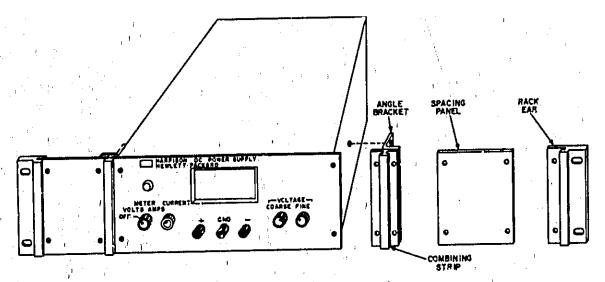
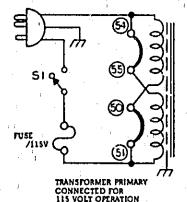


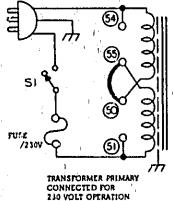
Figure 2-2. Rack Mounting, One Unity

- 2-14 To mount a single unit in the rack panel, proceed as follows:
- a. Bolt rack mounting ears, combining straps, and angle brackets to each side of center spacing panels. Angle brackets are placed behind combining straps as shown in Figure 2-2.
- b. Remove four screws from front panel of unit.
- c. Slide combining strips between front panel and case of unit.
- d. Bolt angle brackets to front sides of case and replace front panel screws.

### 2-15 INPUT POWER REQUIREMENTS

- 2-16 This power supply may be operated from either a nominal 115 voit or 230 volt 50-500 cycle power source. The unit, as shipped from the factory, is wired for 115 volt operation. The input power required when operated from a 115 volt 60 cycle power source at full load is 70 watts and 0.85 amperes.
- 2-17 CONNECTIONS FOR 230 VOLT OPERATION (Figure 2-3)
- 2-18 Normally, the two primary windings of the input transformer are connected in parallel for operation from 115 volt source. To convert the power supply to operation from a 230 volt source, the power transformer windings are connected in series as follows:
- a. Unplug the line cord and remove the unit from case.
- b. Break the copper between 54 and 55 and also between 50 and 51 on the printed circuit board. These are shown in Figure 2-3, and are labeled on copper side of printed circuit board.





NOTE: CONNECTIONS BETWEEN 150 & 51, 54 & 25, ARE MADE WITH COPPER ON THE PRINTED CIRCUIT BOARD. THESE CONNECTIONS MUST BE REMOVED FOR 230V OPERATION. THE CONNECTIONS ON THE PRINTED CIRCUIT BOARD MUST BE BROKEN AND A SEPARATE EXTERNAL CONNECTION MADE BETWEEN POINTS 50 & 55.

Figure 2-3, Primary Connections

- c. Add strap between 50 and 55.
- d. Replace existing fuse with 1 ampere, 230 volt fuse. Return unit to case and operate normally.

2-20 To protect operating personnel, the National Electrical Manufacturers Association (NEMA) recommends that the instrument panel and cabinet be grounded. This instrument is equipped with a three conductor power cable. The third conductor is the ground conductor and when the cable is plugged into an appropriate receptacle, the instrument is grounded. The offset pin on the power cable three-prong connector is the ground connection,

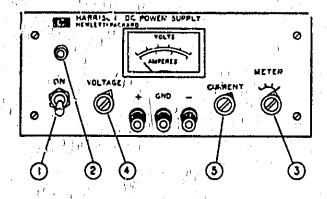
2-21 To preserve the protection feature when operating the instrument from a two-contact outlet, use a three-prong to two-prong adapter and connect the green lead on the adapter to ground.

# 2-22 REPACKAGING FOR SHIPMENT

2-23 To insure safe shipment of the instrument, it is recommended that the package designed for the instrument be used. The criginal packaging material is reusable. If it is not available, contact your local Hewlett-Packard field office to obtain the materials. This office will also furnish the address of the nearest service office to which the instrument can be shipped. Be sure to attach a tag to the instrument which specifies the owner, model number, full serial number, and service required, or a brief description of the trouble.

# SECTION III OPERATING INSTRUCTIONS

The front panel controls and indicators, together with the normal turn-on sequence, are shown in Figure 3-1.



#### TURN-ON SEQUENCE

- SET AC POWER SWITCH TO ON. OBSERVE THAT PILOT LIGHT GOES ON.
- SET METER SWITCH TO DESIRED VOLTAGE RANGE.
  ADJUST COARSE AND FINE VOLTAGE CONTROLS UNTIL
- DESIRED OUTPUT VOLTAGE IS INDICATED ON METER. SHORT CIRCUIT OUTPUT TERMINALS, SET METER
- SWITCH TO DESIRED CURRENT RANGE, AND ADJUST.
  CURRENT CONTROLS FOR DESIRED OUTPUT CURRENT.
  PEMCYE SHORT AND CONNECT LOAD TO OUTPUT TENMINALS (FRONT OR REAR).

Figure 3-1. Front Panel Controls and Indicators

#### 3-3 OPERATING MODES

The power supply is designed so that its mode of operation can be selected by making strapping connections between particular terminals on the terminal strip at the rear of the power supply. The terminal designations are stenciled in white on the power supply above their respective terminals. Although the strapping patterns illustrated in this section show the positive terminal grounded, the operator can ground either terminal or operate the power supply up to 300 vdc off ground (floating). The following paragraphs describe the procedures for utilizing the various operational capabilities of the power supply. A more theoritical description concerning the operational features of this supply is contained in a power supply Application Manual and in various Tech. Letters published by the Harrison Division. Copies of these can be obtained from your local Hewlett-Packard field office.

# 3-5 NORMAL OPERATING MODE

The power supply is normally shipped with its rear terminal strapping connections arranged for Constant Voltage / Constant Current, local sensing, local programming, single unit mode of operation, This strapping pattern is illustrated in Figure 3-2. The operator selects either a constant voltage or a constant current output using the front panel controls (local programming, no strapping changes are necessary).

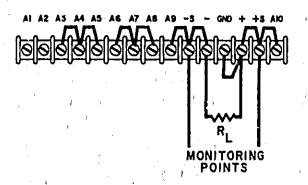


Figure 3-2. Normal Strapping Pattern

# CONSTANT VOLTAGE

3-8. To select a constant voltage output, proceed as follows:

a. Turn-on power supply and adjust) 11 -VOLTAGE controls for desired output voltage (output terminals open).

in ib, i Short output terminals and adjust CUR-RENT controls for maximum output current allowable (current limit), as determined by load conditions. If a load change causes the current limit to be exceeded, the power supply will automatically crossover to constant current output at the preset current limit and the output voltage will drop proportionately. In setting the current limit, allowance must be made for high peak current which can cause unwanted cross-over. (Refer to Paragraph 3-44.)

# CONSTANT CURRENT

3-10 To select a constant current output, proceed as follows:

a. Short output terminals and adjust CUR-RENT controls for desired output current,

b. Open output terminals and adjust VOLIAGE controls for maximum output voltage allowable (voltage limit), as determined by load conditions. If a load change causes the voltage limit to be exceeded, the power supply will automatically crossover to constant voltage output at the preset voltage limit and the output current will drop proportionately. In setting the voltage limit, allowance must be made for high peak voltages which can cause unwanted crossover. (Refer to Paragraph 3-44).

# 3-11 CONNECTING LOAD

3-12 Each load should be connected to the power supply output terminals using separate pairs of connecting wires. This will minimize mutual coupling effects between loads and will retain full advantage of the low output impedance of the power supply. Each pair of connecting wires should be as short as possible and twisted or shielded to reduce noise pickup. (If shield is used, connect one end to power supply ground terminal and leave the other end unconnected.)

3-13 If load considerations require that the output power distribution terminals be remotely located from the power supply, then the power supply output terminals should be connected to the remote distribution terminals via a pair of twisted or shielded wires and each load separately connected to the remote distribution terminals. For this case, remote sensing should be used (Paragraph 3-28).

# 3-14 OPTIONAL OPERATING MODES

3-15 REMOTE PROGRAMMING, CONSTANT VOLTAGE

3-16 The constant voltage output of the power supply can be programmed (controlled) from a remote location if required. Lither a resistance or voltage source can be used for the programming device. The wires connecting the programming terminals of the supply to the remote programming device should be twisted or shielded to reduce noise pick-up. The VOLTAGE controls on the front panel are disabled according to the following procedures.

3-17 Resistance Programming (Figure 3-3). In this mode, the output voltage will vary at a rate determined by the programming coefficient -- 200 ohms per volt (i.e. the output voltage will increase 1 volt for each 200 ohms added in series with programming terminals). The programming coefficient is determined by the programming current. This current is adjusted to within 2% of 5ma at the factory. If greater programming accuracy is required, it may be achieved by changing resistor R13.

3-18 The output voltage of the power supply should be zero volts  $\pm 20$  millivolts when zero ohms is connected across the programming terminals. If

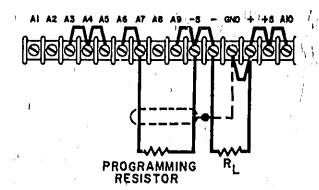


Figure 3-3. Remote Resistance Programming (Constant Voltage)

a zero ohm voltage closer than this is required, it may be achieved by changing resistor R6 or R8 as described in Paragraph 5-49.

3-19 To maintain the stability and temperature coefficient of the power supply, use programming resistors that have stable, low noise, and low temperature (less than 30ppm per degree Centigrade) characteristics. A switch can be used in conjunction with various resistance values in order to obtain discrete output voltages. The switch should have make-before-break contacts to avoid momentarily opening the programming terminals during the switching interval.

3-20 Voltage Programming (Figure 3-4). Employ the strapping pattern shown on Figure 3-4 for voltage programming. In this mode, the output voltage will vary in a 1 to 1 ratio with the programming voltage (reference voltage) and the load on the programming voltage source will not exceed 25 microamperes.

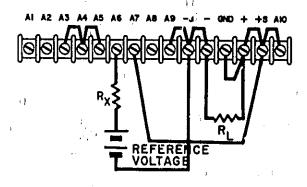


Figure 3-4. Remote Voltage Programming (Constant Voltage)

3-21 The impedance  $(R_X)$  looking into the external programming voltage source should be approximately 1000 ohms if the temperature and stability specifications of the power supply are to be maintained.

# 3-22 REMOTE PROGRAMMING, CONSTANT CURRENT

3-23 Either a resistance or a voltage source can be used to control the constant current output of the supply. The CURRENT controls on the front panel are disabled according to the following procedures.

3-24 Resistance Programming (Figure 3-5). In this mode, the output current varies at a rate determined by the programming coefficient -- 1000 ohms per ampere for Models 6201B, 6202B, and 6200B (0-0.75 ampere range), and 500 ohms per ampere for Models 6203B and 6200B (0-1.5 ampera range).

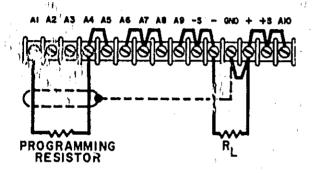


Figure 3-5. Remote Resistance Programming (Constant Current)

The programming coefficient is determined by the programming current. This current is adjusted to within 10% of 1 milliampere at the factory. If greater programming accuracy is required, it may be achieved by changing resistor R19.

3-25 Use stable, low noise, low temperature coefficient (less than 30 ppm/°C) programming resistors to maintain the power supply temperature coefficient and stability specifications. A switch may be used to set discrete values of output current. A make-before-break type of switch should be used since the output current will exceed the maximum rating of the power supply if the switch contacts open during the switching interval.

### CAUTION

If the programming terminals (A1 and A4) should open at any time during this mode, the output current will rise to a value that may damage the power supply and/or the load. To avoid this possibility, connect a 1.5K resistor across the programming terminals and in parallel with a remote programming resistor. Like the programming resistor, the 1.5K resistor should be of the low noise, low temperature coefficient type.

3-26 Voltage Programming (Figure 3-6). In this mode, the output current will vary linearly with changes in the programming voltage. The programming voltage should not excess. Voltage in excess of 1,5 volts will result in excessive power dissipation in the instrument and possible damage.

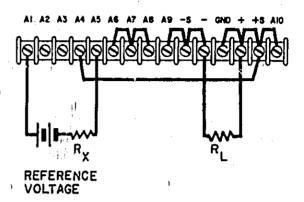


Figure 3-6. Remote Voltage Programming (Constant Current)

3-27 The output current will be the programming voltage divided by 1 ohm. The current required from the voltage source will be less than 25 microamperes. The impedance  $(R_X)$  as seen looking into the programming voltage source should be approximately 500 ohms if the temperature coefficient and stability specifications of the power supply are to be maintained,

# 3-28 REMOTE SENSING (See Figure 3-7)

3-19 Remote sensing is used to maintain good regulation at the load and reduce the degradation of regulation which would occur due to the voltage drop in the leads between the power supply and the load. Remote sensing is accomplished by utilizing the strapping pattern shown in Figure 3-7. The power supply should be turned off before changing strapping patterns. The leads from the +S terminals to the load will carry less than 10 milliamperes of current, and it is not required that these leads be as heavy as the load leads. However, they must be twisted or shielded to minimize noise pick-up,

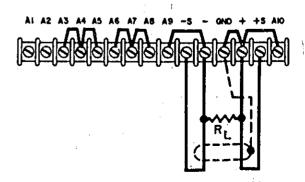


Figure 3-7. Remote Sensing

# CAUTION

Observe polarity when connecting the sensing leads to the load.

3-30 Note that it is desirable to minimize the drop in the load leads and it is recommended that the drop not exceed 1 volt per lead if the power supply is to meet its DC specifications. If a larger drop must be tolerated, please consult a Hewlett-Packard field representative.

3-31 The procedure just described will result in a low DC output impedance at the load. If a low AC impedance is required, it is recommended that the following precautions be taken:

a. Disconnect output capacitor C20, by disconnecting the strap between A10 and +S.

b. Connect a capacitor having similar characteristics (approximately sane capacitance, same voltage rating or greater, and having good high frequency characteristics) across the load using short leads,

3-32 Although the strapping patterns shown in Figures 3-3 through 3-6 employ local sensing, note that it is possible to operate a power supply simultaneously in the remote sensing and Constant Voltage / Constant Current remote programming modes,

#### NOTE

It is necessary to readjust the current limit when the instrument is operated in the remote sensing mode,

### 3-33 SERIES OPERATION

3-34 Normal Series Connections (Figure 3-8). Two or more power supplies can be operated in series to obtain a higher voltage than that available from a single supply. When this connection is used, the output voltage is the sum of the voltages of the individual supplies. Each of the individual supplies must be adjusted in order to obtain the total output voltage. The power supply contains a protective diode connected internally across the output which protects the supply if one power supply is turned off while its series partner(s) is on.

3-35 Auto-Series Connections (Figure 3-9). The Auto-Series configuration is used when it is desirable to have the output voltage of each of the series connected supplies vary in accordance with the setting of a control unit. The control unit is called the master; the controlled units are called slaves. At maximum output voltage, the voltage of the slaves is determined by the setting of the front panel VOLTAGE control on the master. The

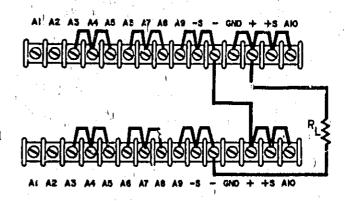
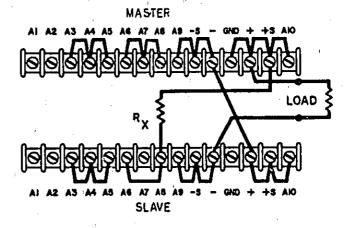


Figure 3-8. Normal Series



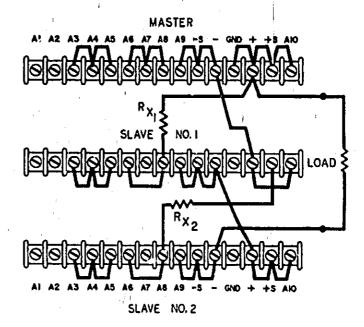


Figure 3-9. AUTO-Series, Two and Three Units

master supply must be the most positive supply of the series. The output CURRENT controls of all series units are operative and the current limit is equal to the lowest control setting. If any output CURRENT controls are set too low, automatic crossover to constant current operation will occur and the output voltage will drop. Remote sensing and programming can be used; however, the strapping arrangements shown in the applicable figures show local sensing and programming.

3-36 In order to maintain the temperature coefficient and stability specifications of the power supply, the external resistors (Rx) shown in Figure 3-9 should be stable, low noise, low temperature coefficient (less than 30 ppm per degree Centigrade) resistors. The value of each resistor is dependant on the maximum voltage rating of the "master" supply. The value of  $R_{\rm x}$  is this voltage divided by the voltage programming current of the slave supply (1/ $K_{\rm p}$  where  $K_{\rm p}$  is the voltage programming coefficient). The voltage contribution of the slave is determined by its voltage control setting.

# 3-37 PARALLEL OPERATION

3-38 Normal Parallel Connections (Figure 3-10), Two or more power supplies can be connected in parallel to obtain a total output current greater than that available from one power supply. The total output current is the sum of the output currents of the individual power supplies. The output CUR-RENT controls of each power supply can be separately set. The output voltage controls of one power supply should be set to the desired output voltage; the other power supply should be set for a slightly larger output voltage. The supply set to the lower output voltage will act as a constant voltage source; the supply set to the higher output will act as a constant current source, dropping its output voltage until it equals that of the other supply.

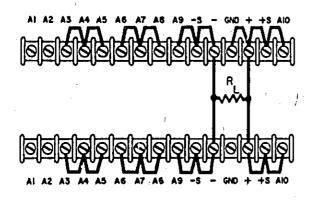
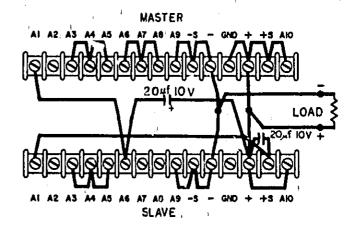


Figure 3-10. Normal Parallel

3-39 Auto-Parallel. The Strapping Patterns for Auto-Parallel operation of two and three power supplies are shown in Figure 3-11. Auto-Parallel operation permits equal current sharing under all load conditions, and allows complete control of output current from one master power supply. The output current of each slave is approximately equal to the master's. Because the output current controls of each slave are operative, they should be set to maximum to avoid having the slave revert to constant current operation; this would occur if the master output current setting exceeded the slave's.



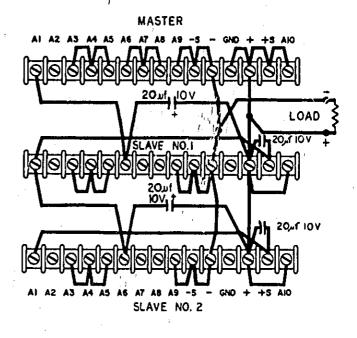


Figure 3-11. Auto-Parallel, Two and Three Units

# 3-40 AUTO-TRACKING OPERATION (See Figure 3-12)

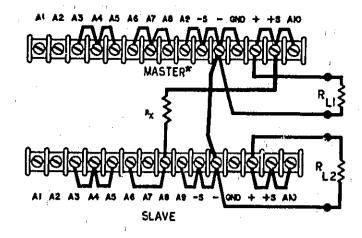
3-41 The Auto-Tracking configuration is used when it is necessary that several different voltages referred to a common bus, vary in proportion to the setting of a particular instrument (the control or master). A fraction of the master's output voltage is fed to the comparison amplifier of the slave supply, thus controlling the slave's output. The master must have the largest output voltage of any power supply in the group (must be the most positive supply in the example shown on Figure 3-12).

3-42 The output voltage of the slave is a percentage of the master's output voltage, and is determined by the voltage divider consisting of Rx (or Rx and Ry) and the voltage control of the slave supply, Rp where: Es = Rp/(Rx+Rp). Turn-on and turn-off of the power supplies is controlled by the master. Remote sensing and programming can be used; although the strapping patterns for these modes show only local sensing and programming. In order to maintain the temperature coefficient and stability specifications of the power supply, the external resistors should be stable, low noise, low temperature (less than 30ppm per°C) resistors.

# 3-43 SPECIAL OPERATING CONSIDERATIONS

#### 3-44 PULSE LOADING

3-45 The power supply will automatically cross over from constant voltage to constant current operation, or the reverse, in response to an increase (over the preset limit) in the output current or voltage, respectively. Although the preset limit may be set higher than the average output current or voltage, high peak currents or voltages (as occur in pulse loading) may exceed the preset limit and cause crossover is occur. If this crossover limiting is not desired, set the preset limit for the peak I quirement and not the average.



MASTER MUST BE POSITIVE SUPPLY

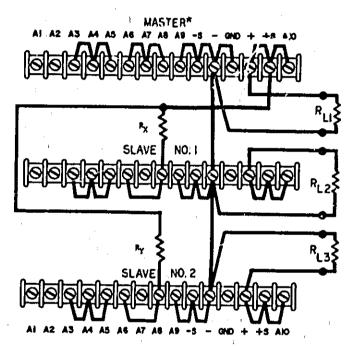


Figure 3-12. Auto-Tracking, Two and Three Units

# 3-46 OUTPUT CAPACITANCE

3-47 There is a capacitor (internal) across the output terminals of the power supply. This capacitor helps to supply high current pulses of short duration during constant voltage operation. Any capacitance added externally will improve the pulse current capability, but will decrease the safety provided by the constant current circuit. A high-current pulse may damage load components before the average output current is large enough to cause the constant current circuit to operate.

3-48 The effects of the output capacitor during constant <u>current</u> operation are as follows:

a. The output impedance of the power supply decreases with increasing frequency.

b. The recovery time of the output voltage is longer for load resistance changes.

c. A large surge current causing a high power power dissipation in the load occurs when the load resistance is reduced rapidly.

# 3-49 REVERSE VOLTAGE LOADING

3-50 A diode is connected across the output terminals. Under normal operating conditions, the diode is reverse biased (anode connected to negative terminal). If a reverse voltage is applied to the output terminals (positive voltage applied to negative terminal), the diode will conduct, shunting current across the output terminals and limiting the voltage to the forward voltage drop of the diode. This d'ode protects the series transistors and the output electrolytic capacitors.

# 3-51 REVERSE CURRENT LOADING

3-52 Active loads connected to the power supply may actually deliver a reverse current to the power supply during a portion of it's operating cycle. An external source cannot be allowed to pump current into the supply without loss of regulation and possible damage to the output capacitor. To avoid these effects, it is necessary to preload the supply with a dummy load resistor so that the power supply delivers current through the entire operating cycle of the load device.

# SECTION IV PRINCIPLES OF OPERATION

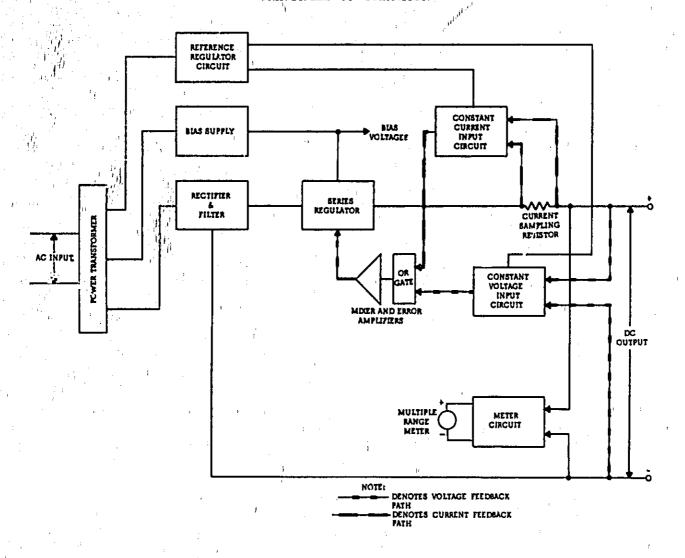


Figure 4-1. Overall Block Diagram

# 4-1 OVERALL BLOCK DIAGRAM DISCUSSION

- 4-2 The power supply, as shown on the overall block diagram on Figure 4-1, consists of a power transformer, a rectifier and filter, a series regulator, the mixer and error amplifiers, an "OR" gate, a constant voltage input circuit, a constant current input circuit, a reference regulator circuit, a bias supply, and a metering circuit.
- 4-3 The input line voltage passes through the power transformer to the rectifier and filter where it is converted to raw DC. The DC current passes through the series regulator to the positive output terminal via a current sampling resistor. The regulator, part of the feedback loop, is made to alter it's conduction to maintain a constant output

voltage or current. The voltage developed across the current sampling resistor is the input to the constant current input circuit. The output voltage of the power supply is sampled by the voltage input circuit by means of the sensing terminals (±S). Any changes in output voltage / current are detected in the constant voltage/constant current input circuit, amplified by the mixer and error amplifiers, and applied to the series regulator in the correct phase and amplitude to counteract any change in output voltage/output current. The reference circuit provides stable reference voltages which are used by the constant voltage/current input circuits for comparison purposes. The bias supply furnishes voltages which are used throughout the instrument for biasing purposes. The meter circuit provides an indication of output voltage or current.

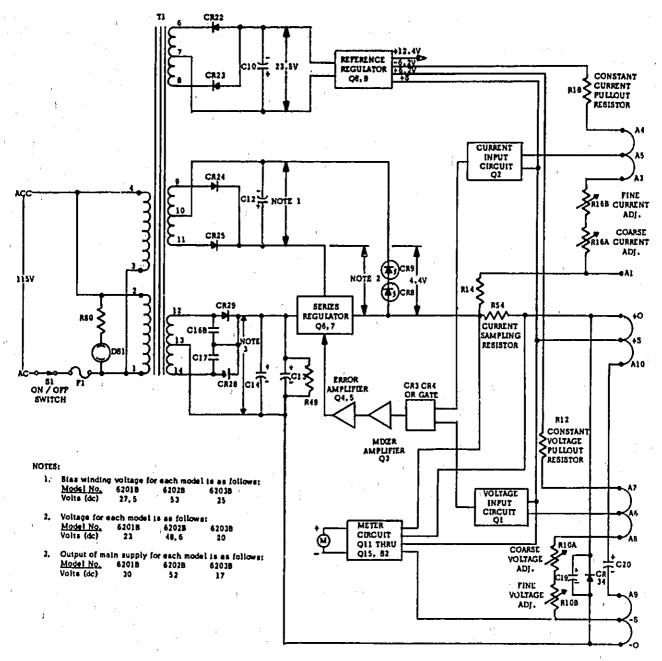


Figure 4-2, Simplified Schematic

# 4-4 SIMPLIFIED SCHEMATIC

4-5 A simplified schematic of the power supply is shown in Figure 4-2. It shows the operating controls; the ON-off switch, the voltage programming controls (R10A and R10B), and the current programming controls (R16A and R16B). The METER switch, included in the meter circuit block on Figure 4-2, allows the meter to read output voltage or current in either of two ranges. Figure 4-2 also shows the internal sources of bias and reference voltages and their nominal magnitudes. Diode CR34, connected across the output terminals of the

power supply, is a protective device which prevents internal damage that might occur if a reverse voltage were applied across the output terminals. Output capacitor, C20, is also connected across the output terminals when the normal strapping pattern shown on Figure 4-2 is employed. Note that this capacitor can be removed if an increase in the programming speed is desired. Under these conditions, capacitor C19 serves to insure loop stability.

# 4-6 SERIES REGULATOR

4-7 The series regulator consists of transistor stages Q6 and Q7 (see schematic at rear of manual). The transistors are connected in parallel so that approximately half of the output current flows through each one. The regulator serves as a series control element by altering it's conduction so that the output voltage or current is kept constant. The conduction of the transistors is controlled by the feedback voltage from the error amplifier. Diode CR11, connected across the regulator circuit, protects the series transistors against reverse voltages that could develop across them during parallel or auto-parallel operation if one supply is turned on before the other.

# 4-8 CONSTANT VOLTAGE INPUT CIRCUIT (Pigure 4-3)

4-9 The circuit consists of the coarse and fine programming resistors (R10A and R10B), and a differential amplifier stage (Q1 and associated components). Transistor Q1 consists of two silicon transistors housed in a single package. The transistors have matched characteristics minimizing differential voltages due to mismatched stages. Moreover, drift due to thermal differentials is minimized, since both transistors operate at essentially the same temperature.

4-10 The constant voltage input circuit continuously compares a fixed reference voltage with a portion
of the output voltage and, if a difference exists,
produres an error voltage whose amplitude and
phase is proportional to the difference. The error
output is fed back to the series regulator, through
an OR gate and the mixer/error amplifiers. The
error voltage changes the conduction of the series
regulator which, in turn, alters the output voltage
so that the difference between the two input
voltages applied to the differential amplifier is
reduced to zero. This action maintains the output
voltage constant,

4-11 Stage Q1B of the differential amplifier is connected to a common (+S) potential through impedance equalizing assistor R5. Resistor R6 and R8 are used to zero bias the input stage, offsetting minor base to emitter voltage differences in Q1. The base of Q1A is connected to a summing point at the junction of the programming resistors and the current pullout resistor R12. Instantaneous changes in output voltage result in an increase or decrease in the summing point potential. Q1A is then made to conduct more or less, in accordance with summing point voltage change. The resultant output error voltage is fed back to the series regulator via the remaining components of the feedback loop.

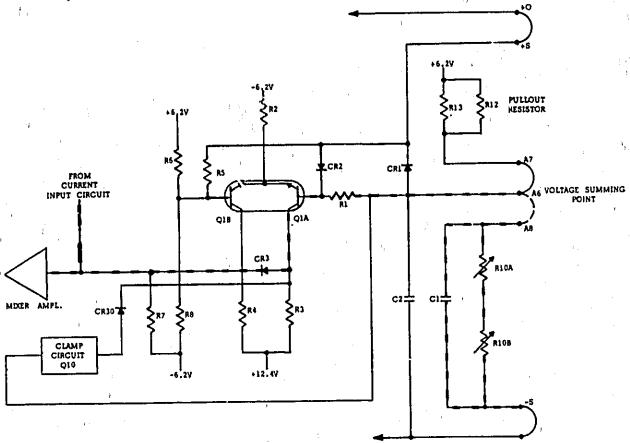


Figure 4-3. Constant Voltage Input Circuit, Simplified Schematic

Resistor R1, in series with the base Q1A, limits the current through the programming resistors during rapid voltage turn-down. Diodes CR1 and CR2 form a limiting network which prevent excessive voltage excursions from over driving stage Q1A. Capacitors C1 and C2, shunting the programming resistors, increase the high frequency gain of the input amplifier. Resistor R13, shunting pullout resistor R12, serves as a trimming adjustment for the programming current.

# 4-12 CONSTANT CURRENT INPUT CIRCUIT (Figure 4-4)

4-13 This circuit is similar in appearance and operation to the constant voltage input circuit. It consists of the coarse and fine current programming resistors (R16A and R16B), and a differential amplifier stage (Q2 and associated components). Like transistor Q1 in the voltage input circuit, Q2 consists of two transistors, having matched characteristics, that are housed in a single package.

4-14 The constant current input circuit continuously compares a fixed reference voltage with the voltage drop across current sampling resistor R54. If a difference exists, the differential amplifier produces an error voltage which is proportional to this difference. The remaining components in the feedback loop (amplifiers and series regulator) function to maintain the drop across the current sampling resistor, and consequently the output current, at a constant value.

4-15 Stage Q2B is connected to the +S through impedance equalizing resistor R26. Resistors R25 and R28 are used to zero bias the input stage, offsetting minor base to emitter voltage differences in Q2. Instantaneous changes in output current on the positive line are felt at the current summing point and, hence, the base of Q2A. Stage Q2A varies its conduction in accordance with the polarity of the change at the summing point. The change in O2A's conduction also varies the conduction of Q2B due to the coupling effects of the common emitter resistor, R22. The error voltage is taken from the collector Q2B and fed back to the series regulator through OR-gate diode CR4 and the remaining components of the feedback loop. The error voltage then varies the conduction of the regulator so that the output current is maintained at the proper level.

4-16 Resistor R20, in conjunction with R2 and C3, helps stabilize the feedback loop. Diod2 CR5 limits voltage excursions on the base of Q2A. Resistor R1°, shunting the pullout resistor, serves as a trimming adjustment for the programming current flowing through R16A and B.

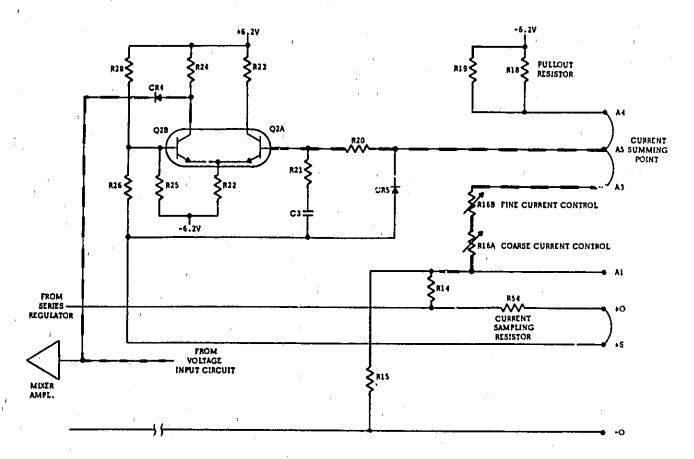


Figure 4-4. Constant Current Input Circuit, Simplified Schematic

# 4-17 VOLTAGE CLAMP CIRCUIT (Figure 4-5)

4-18 During constant current operation the constant voltage programming resistors are a shunt load across the output terminals of the power supply. If the output voltage changed, the current through these resistors would tend to change resulting in an output current change. The clamp circuit is a return path for the voltage programming current, the current that normally flows through the programming resistors. The circuit maintains the current into the constant voltage summing point (A6) constant thus eliminating the error due to shunting effects of the constant voltage programming resistors.

4-19 The voltage divider, R51, R52, and CR31, back biases CR30 and Q10 during constant voltage operation. When the power supply goes into constant current operation, CR30 becomes forward biased by the collector voltage of Q1A. This results in conduction of Q10 and the clamping of the summing point at a potential only slightly more negative than the normal constant voltage potential. Clamping this voltage at approximately the same potential that exists in constant voltage operation, results in a constant voltage across, and consequently a constant current through, the current pullout resistor (R12).

# 4-20 MIXER AND ERROR AMPLIFIERS (Figure 4-6)

4-21 The mixer and error amplifiers amplify the error signal from the constant voltage or constant current input circuit to a level sufficient to drive the series regulator transistors. The emitter bias

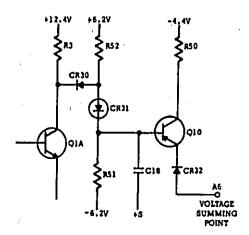


Figure 4-5. Voltage Clamp Circuit

potential for mixer amplifier Q3 is established by voltage divider CR6, CR7, and R29. Transistor Q3 receives the error voltage input from either the constant voltage or constant current circuit via the ORgate diode (CR3 or CR4) that is conducting at the time. Diode CR3 is forward biased, and CR4 reversed biased, during constant voltage operation. The reverse is true during constant current operation,

4-22 The RC network, composed of C5 and R30, is an equalizing network which provides for high frequency roll off in the loop gain response in order to stabilize the feedback loop. Emitter follower transistors Q4 and Q5 are the error amplifiers serving as the driver and predriver elements, respectively, for the series regulator. Transistor Q4, together with diode CR17, provides a low resistance discharge path for the output capacitance of the power supply during rapid down programming.

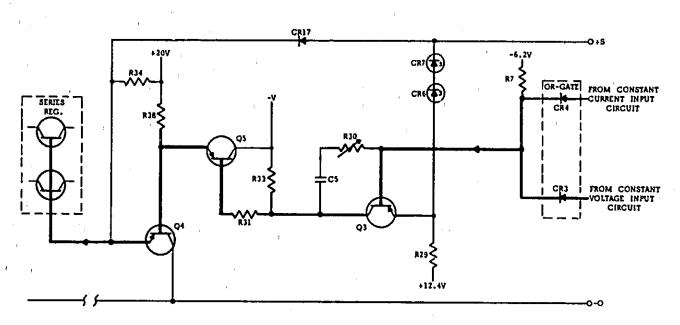


Figure 4-6. Mixer and Error Amplifiers, Simplified Schematic

# 4-23 REFERENCE CIRCUIT

4-24 The reference circuit (see schematic) is a feedback power supply similar to the main supply. It provides stable reference voltages which are used throughout the unit. The reference voltages are all derived from smoothed dc obtained from the full wave rectifier (CR22 and CR23) and filter capacitor Cl0. The +6.2 and -6.2 voltages, which are used in the constant voltage and current input circuits for comparison purposes, are developed across temperature compensated Zener diodes VR1 and VR2. Resistor R43 limits the current through the Zener diodes to establish an optimum bias level.

4-25 The regulating circuit consists of series regulating transistor Q9 and error amplifier Q8. Output voltage changes are detected by Q8 whose base is

connected to the junction of a voltage divider (R41, R42) connected directly across the supply. Any error signals are amplified and inverted by Q8 and applied to the base of series transistor Q9. The series element then alters its conduction in the direction and by the amount necessary to maintain the voltage across VR1 and VR2 constant. Resistor R46, the emitter resistor for Q8, is connected in a manner which minimizes changes in the reference voltage caused by variations in the input line. Output capacitor C7 stabilizes the regulator loop.

# 4-26 METER CIRCUIT (Figure 4-7)

4-27 The meter circuit provides continuous indications of output voltage or current on a single multiple range meter. The meter can be used either as a voltmeter or an ammeter depending upon the position of METER switch S2 on the front panel of the supply.

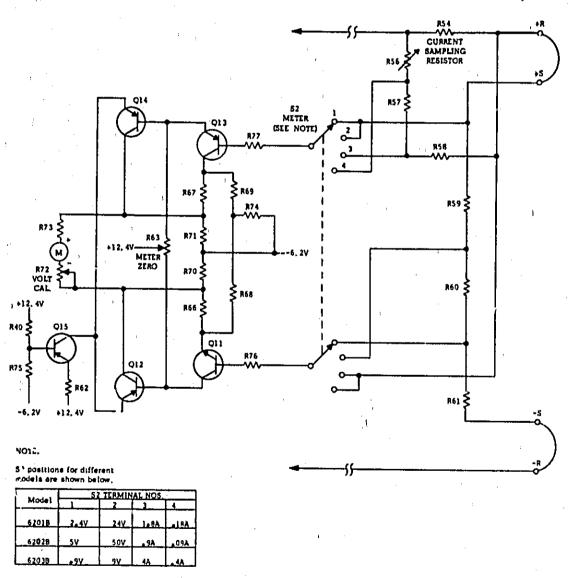


Figure 4-7. Meter Circuit, Simplified Schematic

This switch also selects one of two meter ranges on each scale. The metering circuit consists basically of a selection circuit (switch S2 and associated voltage dividers), a stable differential amplifier stage (Q.1 through Q14), and the meter movement.

4-28 The selection circuit determines which voltage divider is connected to the differential amplifier input. When S2 is in one of the voltage positions, the voltage across divider R58, R60, and R61 (connected across the output of the supply) is the input to the differential amplifier. When S2 is in one of the current positions, the voltage across divider R56, R57, and R58 (connected across current sampling resistor R54) is the input to the differential amplifier. The amplified output of the differential amplifier is used to deflect the meter.

4-29 The differential amplifier is a stable device helving a fixed gain of tan. Stage Q11 of the differential amplifier receives a negative voltage from the applicable voltage di der when S2 is in one of the voltage positions while stage Q13 is connected to the +S (common) terminal. With S2 in a current position, stage Q13 receives a positive voltage from the applicable voltage divider while stage Q11 's connected to the +S terminal. The differential cutput of the amplifier is taken from the collectors of Q12 and Q14. Transistor Q15 is a constant current source which sets up the proper bias current for the amplifier. Potentiometer R63 permits zeroing of the meter. The meter amplifier stage contains an inherent current limiting feature which protects the meter movement against overloads. For example, if METER switch S2 is placed in position 4, (low current range) when the power supply is actually delivering a higher ampere output, the differential amplifiers are quickly driven into saturation. This action limits the current through the meter to a safe value.

4-30 Figures 4-8 and 4-9 show the meter connections when S2 is in the higher voltage and current positions, respectively. For the sake of simplicity, some of the actual circuit components are not shown on these drawings. With METER switch S2 in the higher voltage range, position (2), the voltage drop across R59 is the input to the meter amplifier and the meter indicates the output voltage across the +S and -S terminals. For low output voltages, S2 can be switched to position 1 resulting in the application of a larger percentage of the output voltage (drop across F59 and R60) to the meter amplifier.

4-31 With S2 in the higher current range position (Figure 4-9) the voltage drop across R58 is applied to the meter amplifier and the meter indicates the output current which flows through R54. For low values of output current, S2 can be switched to

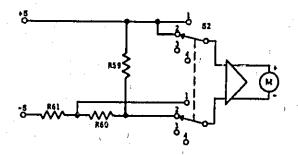


Figure 4-3. Voltmeter Connections, Simplified Schematic

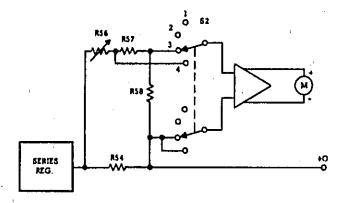


Figure 4-9, Ammeter Connections, Simplified Schematic

position 4 and the voltage drop across R57 and R58 is applied to the meter amplifier.

# 4-32 OPERATION OF REGULATING FZEDBACK TOOP

4-33 The feedback loop functions continuously to keep the output voltage constant, during constant voltage operation, and the output current constant, during constant current operation. For purposes of this discussion, assume that the unit is in constant voltage operation and that the programming resistors have been adjusted so that the supply is yielding the desired output voltage. Further assume that the output voltage instantaneously rises (goes positive) due to a variation in the external load circuit.

4-34 Note that the change raty be in the form of a slow rise in the output voltage or a positive going ac signal. An ac signal is coupled to summing point A6 through capacitor C1 and a dc voltage is coupled to A6 through R10.

4-35 The rise in output voltage causes the voltage at A6 and thus the base of Q1A to decrease (go negative). Q1A now decreases its conduction and its collector voltage rises. The positive going error voltage is amplified and inverted by Q3 and fed to

the bases of series transistors Q6 and Q7 via emitter followers Q5 and Q4. The negative going input causes Q6 and Q7 to decrease their conduction so that they drop more of the line voltage, and reduce the output voltage to its original level.

4-36 If the external load resistance is decreased to a certain crossover point, the output current increases until transistor Q2A begins to conduct, During this time, the output voltage has also decreased to a level so that the base of Q1A is at a

high positive potential. With QIA in full conduction, its collector voltage decreases by the amount necessary to back bias OR gate diode CR3 and the supply is now in the constant current mode of operation. The crossover point at which constant current operation commences is determined by the setting of CURRENT control R16. The operation of the feedback loop during the constant current operating mode is similar to that occuring during constant voltage operation except that the input to the differential amplifier comparison circuit is obtained from current sampling resistor R54.

# SECTION V MAINTENANCE

# 5-1 <u>INTRODUCTION</u>

Upon receipt of the power supply, the performance check (Paragraph 5-10) should be made, This check is suitable for incoming inspection, If a fault is detected in the power supply while making the performance check or during normal operation, proceed to the troubleshooting procedures (Paragraph 5-28). After troubleshooting and repair (Paragraph 5-38), perform any necessary adjustments and calibrations (Paragraph 5-40). Before returning the power supply to normal operation, repeat the performance check to ensure that the fault has been properly corrected and that no other faults exist. Before doing any maintenance checks, turn-on power supply, allow a half-hour warm-up, and read the general information regarding measurement techniques (Paragraph 5-3).

# 5-3 GENERAL MEASUREMENT TECHNIQUES

- 5-4 The measuring device must be connected across the sensing leads of the supply or as close to the output terminals as possible when measuring the output impedance, transient response, regulation, or ripple of the power supply in order to achieve valid measurements. A measurement made across the load includes the impedance of the leads to the load and such lead lengths can easily have an impedance several orders of magnitude greater than the supply impedance, thus invalidating the measurement.
- 5-5 The monitoring device should be connected to the +S and -S terminals (see Figure 3-2) or as shown in Figure 5-1. The performance characteristics should never be measured on the front terminals if the load is connected across the rear terminals. Note that when measurements are made at the front terminals, the monitoring leads are connected at A, not B, as shown in Figure 5-1. Failure to connect the measuring device at A will result in a measurement that includes the resistance of the leads between the output terminals and the point of connection.

5-6 For output current measurements, the current sampling resistor should be a four-terminal resistor. The four terminals are connected as shown in Figure 5-2. In addition, the resistor should be of the low noise, low temperature coefficient (less than 30 ppm/ $^{\circ}$ C) type and should be used at no more than 5% of its rated power so that its temperature rise will be minimized,

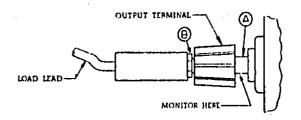


Figure 5-1. Front Panel Terminal Connections

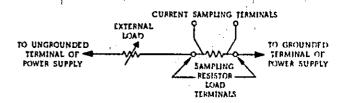


Figure 5-2. Output Current Measurement Technique

5-7 When using an oscilloscope, ground one terminal of the power supply and then ground the case of the oscilloscope to this same point. Make certain that the case is not also grounded by some other means (power line). Connect both oscilloscope input leads to the power supply ground terminal and check that the oscilloscope is not exhibiting a ripple or transient due to ground loops, pick-up, or other means.

# 5-8 TEST EQUIPMENT REQUIRED

5-9 Table 5-1 lists the test equipment required to perform the various procedures described in this Section.

Table 5-1. Test Equipment Required

TYPE	REQUIRED CHARACTERISTICS	USE	RECOMMENDED MODEL
Differential	Sensitivity: 1mv full scale (min.). Input impedance: 10 megohms (min.).	Measure dc voltages; calibration procedures	Ø 3420 (See Note)
Variable Voltage Transformer	Range: 90-130 volts. Equipped with voltmeter accurate within 1 volt.	Vary AC input	R 40 M 40
AC Voltmeter	Accuracy: 2% Sensitivity: lmv full scale deflection (min.).	Measure AC voltages and ripple	<b>∳</b> 40^B
Oscilloscope	Sensitivity: 100μv/cm. Differ- ential input.	Display transient response waveforms	₱ 140A plus 1400A plug in.
Oscillator	Range: 5Hz to 600KHz. Accu- racy: 2%.	Impedance checks	<b>№ 200CD</b>
DC Voltmeter	Accuracy: 1%. Input resist- ance: 20,000 ohms/volt (min.).	Measure dc voltages	<b>№</b> 412A
Repetitive Load Switch	Rate: 60-400Hz, 2µsec rise and fall time.	Measure transient response	See Figure 5-7
Resistor	Value: See Paragraph 5-14, ±5%, 75 watts.	Load Resistor	
Resistor	Value: See Figure 5-4. 1%, 200 watts, 20ppm, 4-Terminal.	Current sampling	******
Resistor	lKn ±1%, 2 watt non-inductive	Measure impedance	# = =
Resistor	'100 ohms, ±5% 10 watt	Measure impedance	
Resistor	Value: See Paragraph 5-50. ±0.1%, 5 watt.	Calibrate programming current	
Resistor	Value: See Paragraph 5-53. ±0.1%, 5 watt.	Calibrate programming current	
Capacitor	500µſ, 50w vdc.	Measure impedance	

Table 5-1. Test Equipment Required (Continued)

ТУРЕ	REQUIRED CHARACTERISTICS	USE	RECOMMENDED MODEL
Decade Resistance Box	Range: 0-150K (min.). Accu- racy: 0.1% plus 1 ohm. Make- before-break contacts.	Measure programming coefficients	

# NOTE

A satisfactory substitute for a differential voltmeter is to arrange a reference voltage source and null detector as shown in Figure 5-3. The reference voltage source is adjusted so that the voltage difference between the supply being measured and the reference voltage will have the required resolution for the measurement being made. The voltage difference will be a function of the null detector that is used. Examples of satisfactory null detectors are: @419A null detector, a dc coupled oscilloscope utilizing differential input, or a 50mv meter movement with a 100 division scale. For the latter, a 2mv change in voltage will result in a meter deflection of four divisions.

### CAUTION

Care must be exercised when using an electronic null detector in which one input terminal is grounded to avoid ground loops and circulating currents.

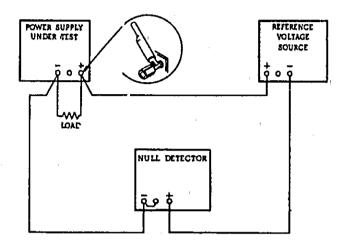


Figure 5-3. Differential Voltmeter Substitute,
Test Setup

# 5-10 PERFORMANCE TEST

5-11 The following test can be used as an incoming inspection check and appropriate portions of the test can be repeated either to check the operation of the instrument after repairs or for periodic maintenance tests. The tests are performed using a 115Vac 60Hz, single phase input power source. If the correct result is not obtained for a particular check, do not adjust any controls; proceed to troubleshooting (Paragraph 5-28).

# 5-12 CONSTANT VOLTAGE TESTS

# 5-13 Rated Output and Meter Accuracy,

# 5-14 Voltage. Proceed as follows:

 a. Connect load resistor across rear output terminals of supply, Resistor value to be as follows:

Model No. 6200B 6201B 6202B 6203B Resistance (Ohms) 53 13 53 2.5

- b. Connect differential voltmeter across +S
   and -S terminals of supply observing correct polarity.
- c. Set METER switch to highest voltage range (and RANGE switch to 40V for Model 6200B) and turn on supply.
- d. Adjust VOLTAGE controls until front panel meter indicates exactly the maximum rated output voltage.
- e. Differential voltmeter should indicate maximum rated output voltage within ±2%.

# 5-15 Current. Proceed as follows:

- a. Connect test setup shown in Figure 5-4.
- b. Turn CURRENT controls fully clockwise.
- c. Set METER switch to highest current range (and RANGE switch to 20V mode for Model 6200B) and turn on supply.
- d. Adjust VOLTAGE controls until front panel meter indicates exactly the maximum rated output current.
- e. Differential voltmeter should read 1.5  $\pm$  0.03 Vdc.

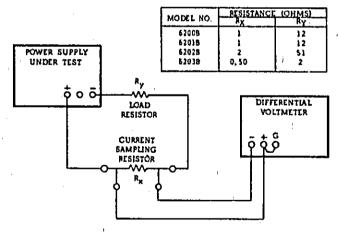


Figure 5-4. Output Current, Test Setup

5-16 Load Regulation, To check constant voltage load regulation, proceed as follows:

a. Connect test setup as shown in Figure 5-5.

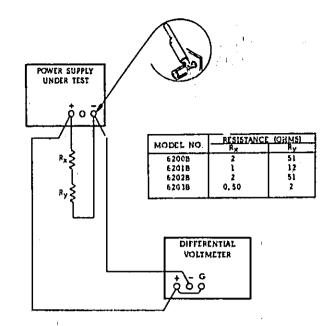


Figure 5-5. Load Regulation. Constant Voltage

- b. Turn CURRENT controls fully clockwise.
- c. Set METER switch to highest current range (and RANGE switch to 40V for Model 6200B) and turn on supply.
- d. Adjust VOLTAGE controls until front panel meter indicates exactly the maximum rated output current,
- e. Read and record voltage indicated on differential voltmeter.
  - f. Disconnect load resistors.
- g. Reading on differential voltmeter should not vary from reading recorded in step e by more than the following:

Model No. 6200B 6201B 6202B 6203B Variation (mvdc) ±8 ±6 ±8 ±5

# 5-17 <u>Line Regulation</u>. To check the line regulation, proceed as follows:

- a. Connect variable auto transformer between input power source and power supply power input,
  - b, Turn CURRENT controls fully clockwise.
  - c. Connect test setup shown in Figure 5-5.
- d. Adjust variable auto transformer for 105 VAC input.
- e. Set METER switch to highest voltage range (and RANGE switch to 40 V for Model 6200B) and turn on supply.
- f. Adjust VOLTAGE controls until front panel meter indicates exactly the maximum rated output voltage.
- g. Read and record voltage indicated on differential voltmeter.
- h. Adjust variable auto transformer for 125 VAC input.

i. Reading on differential voltmeter should not vary from reading recorded in step g by more than the following:

Model No. 6200B 6201B 6202B 6203B Variation (mvdc) ±8 ±6 ±8 ±3

- 5-18 <u>Ripple and Noise</u>. To check the ripple and noise, proceed as follows:
- a. Retain test setup used for previous line regulation test except connect AC voltmeter across output terminals as shown in Figure 5-6,
- b. Adjust variable auto transformer for 125 VAC input
- c. Set METER switch to highest current range (and RANGE switch to 40V for Model 6200B)
- d. Turn CURRENT controls fully clockwise and adjust VOLTAGE controls until front panel meter indicates exactly the maximum rated output current.
- e. AC voltmeter should read less than 0.20mv.

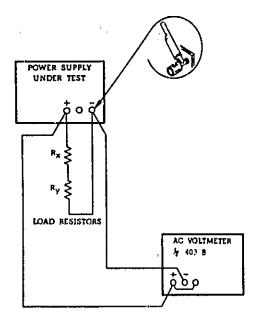
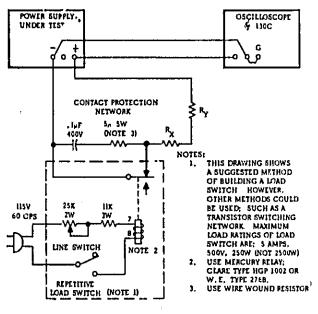


Figure 5-6. Ripple and Noise, Constant Voltage

- 5-19 <u>Transient Recovery Time</u>, To check the transient recovery time proceed as follows:
  - a. Connect test setup shown in Figure 5-7,
  - b. Turn CURRENT controls fully clockwise.
- c. Set METER switch to highest current range and turn on supply.
- d. Adjust VOLTAGE controls until front panel meter indicates exactly the maximum rated output current.

- e. Close line switch on repetitive load switch setup.
- f. Adjust 25K potentiometer until a stable display is obtained on oscilloscope. Waveform should be within the tolerances shown in Figure 5-8. (output should return to within 10 my of original value in less than 50 microseconds).



MODEL NO.	RESISTANC RX	E (OHMS)	MODEL NO.	PESISTANC RX	λy
62008 62018 62028 62038	1 1 2 0, 50	12 12 51 2	6204B 6205B 6206B 6207B 6209B	3 3 10 10	10 10 29 790 1190

Figure 5-7. Transient Response, Test Setup

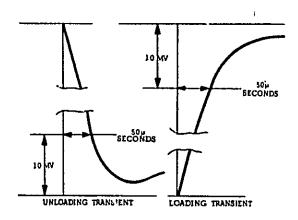


Figure 5-8. Transient Response, Waveforms

# 5-20 OUTPUT IMPEDANCE

5-21 To check the output impedance, proceed as follows:

- a. Connect test setup shown in Figure 5-9.
- b. Set METER switch to highest voltage range and turn on supply.
- c. Adjust VOLTAGE controls until front panel meter reads 20 volts (5 volts for Model 6203B supplies).
- d. Set AMPLITUDE control on Oscillator to 10 volts (Ein), and FREQUENCY control to 100 Hz.
- e. Record voltage across output terminals of the power supply (Eo) as indicated on AC voltmeter.
- f. Calculate the output impedance by the following formula:

$$Z_{out} = \frac{E_{o}R}{E_{in} - E_{o}}$$

R = 1000

 $E_{in} = 10 \text{ volts}$ 

- g. The output impedance ( $Z_{out}$ ) should be less than 0.020 ohms.
- h. Using formula of step f, calculate output impedance at frequencies of 50Kc and 500Kc. Values should be less than 0.5 ohm and 3.0 ohms, respectively.

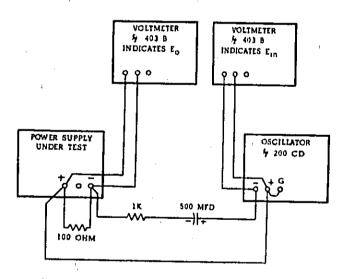


Figure 5-9. Output Impedance, Test Setup

# 5-22 OUTPUT INDUCTANCE

5-23 To check the output inductance, repeat steps a through f at frequencies of 10Kc, 50Kc and 100Kc. Calculate the output inductance (L) using the following formula:

$$L = \frac{XL}{2 \pi f}$$
 (See Note)

The oscillator frequency is equivalent to f in the equation. The output inductance should be less than 20 microhenries.

# NOTE

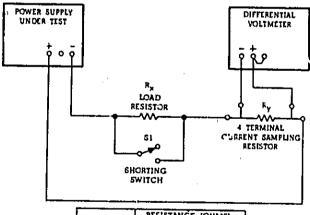
The equation assumes that  $X_L$  is much greater than  $R_{out}$  and therefore  $X_L = Z_{out}$ .

# 5-24 CONSTANT CURRENT TESTS

5-25 <u>Load Regulation</u>. To check the load regulation, proceed as follows:

- a. Connect test setup as shown in Figure 5-10,
  - b. Turn VOLTAGE controls fully clockwise.
- c. Set METER switch to highest current range (and RANGE switch to 20V for Model 6200B) and turn on supply.
- d. Adjust CURRENT control until front panel meter reads exactly the maximum rated output current.
- e. Read and record voltage indicated on differential voltmeter.
- f. Short out load resistor by closing switch S1.
- g. Reading on differential voltmeter should not vary from reading recorded in step e by more than the following:

Model No. 6200B 6201B 6202B 6203B Variation (mvdc) ±0.70 ±0.70 ±0.950 ±0.575



RESISTAN	CE (OHMS)
R <sub>X</sub>	- R.
12	ı
12	1 1
51	2
2	0.50
	12 12

Figure 5-10. Load Regulation, Constant Current

5-26 <u>Line Regulation</u>. To check the line regulation proceed as follows:

- a. Utilize test setup shown in Figure 5-10 leaving switch S1 open throughout test.
- b. Connect variable auto transformer between input power source and power supply power input.
  - c. Adjust auto transformer for 105 VAC input:
  - d. Turn\_VOLTAGE controls fully clockwise.
- e. Set METER switch to highest current range (RANGE switch to 20V for Model 6200B) and turn on supply.
- f. Adjust CURRENT controls until front panel meter reads exactly the maximum rated output current.
- g. Read and record voltage indicated on differential voltmeter.
- h. Adjust variable auto transformer for 125 VAC input.
- i. Reading on differential voltmeter should not vary from reading recorded in step g by more than the following:

Model No. 6200B 6201B 6202B 6203B Variation (mvdc) ±0.40 ±0.40 ±0.650 ±0.275

5-27 <u>Ripple and Noise</u>. To check the ripple and noise, proceed as follows:

a. Connect test setup shown in Figure 5-11.

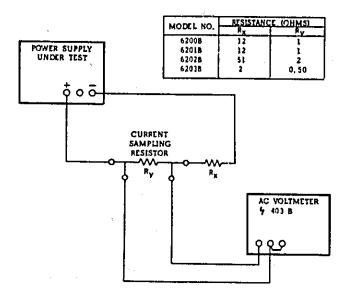


Figure 5-11. Ripple and Noise, Constant Current

- b. Rotate VOLTAGE controls fully clockwise.
- c. Set METER switch to highest current range and turn on supply,
- d. Adjust CURRENT controls until front panel meter indicates exactly the maximum rated output current.

- e. Turn range switch on AC voltmeter to 1 my position.
- f. The AC voltmeter should read as follows:

  Model No. 6200B 6201B 6202B 6203B

  Reading (mvac) 0.50 0.50 1 0.250

# 5-28 TROUBLESHOOTING

5-29 Components within Hewlett-Packard power supplies are conservatively operated to provide maxim. m reliability. In spite of this, parts within a supply may fail. Usually the instrument must be immediately repaired with a minimum of "down time" and a systematic approach as outlined in succeeding paragraphs can greatly simplify and speed up the repair.

#### 5-30 TROUBLE ANALYSIS

5-31 General, Before attempting to trouble shoot this instrument, ensure that the fault is with the instrument and not with an associated circuit. The performance test (Paragraph 5-10) enables this to be determined without having to remove the instrument from the cabinet.

5-32 Once it is determined that the power supply is at fault, check for obvious troubles such as an open fuse, a defective power cable, or an input power failure. Next, remove the top and bottom covers (each held by four retaining screws) and inspect for open connections, charred components, etc. If the trouble source cannot be detected by visual inspection, follow the defailed procedure outlined in succeeding paragraphs. Once the defective component has been leasted (by means of visual inspection or trouble analysis) correct it and re-conduct the performance test. If a component is replaced, refer to the repair and replacement and adjustment and calibration paragraphs in this section.

5-33 A good understanding of the principles of operation is a helpful aid in troubleshooting, and it is recommended that the reader review Section IV of the manual before attempting to troubleshoot the unit in detail. Once the principles of operation are understood, logical application of this knowledge used in conjunction with the normal voltage readings shown on the schematic and the additional procedures given in the following paragraphs should suffice to isolate a fault to a component or small group of components. The normal voltages shown on the schematic are positioned adjacent to the applicable test points (identified by encircled numbers on the schematic and printed wiring boards). Additional test procedures that will aid in isolating troubles are as follows:

- a. Reference circuit check (Paragraph 5-35). This circuit provides critical operating voltages for the supply and faults in the circuit could affect the overall operation in many ways.
  - b. Feedback loop checks (Paragraph 5-36).
- c. Procedures for dealing with common troubles (Paragraph 5-37).
- 5-34 The test points referred to throughout the following procedures are identified on the schematic diagram by encircled numbers.

#### 5-35 Reference Circuit.

a. Make an ohmmeter check to be certain that neither the positive nor negative output termi-

nal is grounded.

- b. Turn front-panel VOLTAGE and CURRENT controls fully clockwise (maximum).
  - c. Turn-on power supply (no load connected)
  - d. Proceed as instructed in Table 5-2.
- 5-36 Feedback Circuit. Generally, malfunction of the feedback circuit is indicated by high or low output voltages. If one of these situations occur, disconnect the load and proceed as instructed in Table 5-3 or Table 5-4.
- 5-37 <u>Common Troubles</u>. Table 5-5 lists the symptoms, checks, and probable causes for common troubles.

Table 5-2. Reference Circuit Troubleshooting

STEP	METER COMMON	METER POSITIVE	NORMAL INDICATION	IF INDICATION ABNORMAL, TAKE THIS ACTION
1	+\$	33	6.2 ± 0.3vdc	Check 12.4 volt bias or VR1
2	31	+S	6.2 ± 0,3vdc	Check 12.4 volt bias or VR2
3	+\$	37	12.4 ± 1.0vdc	Check Q8, Q9, CR22, CR23, C10, T1

Table 5-3. High Output Voltage Troubleshooting

STEP	MEASURE	RESPONSE	PROBABLE CAUSE
1	Voltage between +S and A6	0V to +0.8V	a. Open strap between A7 and A8 b. R10 open
		More negative than 0V	Proceed to Step 2.
2	Voltage between +S and 12	Less positive than +2.0V	a. QIA shorted b. QIB open c. R3 open
	·	+2.0V to +3.8V	Proceed to Step 3.
3	Voltage between +S and 19	More positive than -0.7V	a. Q3 shorted b. C5 shorted
:		More negative than -0.7V	Proceed to Step 4.
4	Voltage between 22 and 23	0V or negative	a. Q6 and/or Q7 shorted. b. CR11 shorted
		More positive than 0V	<ul><li>a. Q4 or Q5 open</li><li>b. R34 or R30 shorted or low resistance.</li></ul>

Table 5-4. Low Output Voltage Troubleshooting

STEP	MEASURE	RESPONSE	PROBABLE CAUSE
1	Disable Q2 by discon-	Normal output voltage,	<ul> <li>a. Constant current circuit faulty, check CR4 and Q2A for short.</li> <li>b. R16 or Q2B open.</li> </ul>
		Low output voltage.	Reconnect CR4 and proceed to Step 2.
2	Voltage between +S and A6,	More negative than OV. OV to +0.8V.	<ul> <li>a. Open strap A6 - A7.</li> <li>a. Check R10, C1, or C2 for short.</li> <li>b. Proceed to Step 3.</li> </ul>
3	Voltage between +S and 12.	More positive than $+3.8$ V. $+2$ V to $+3.8$ V.	a. Q1A open. b. Q1B or R3 shorted. Proceed to Step 4.
4	Voltage between +S and 19.	More negative than -0.7V.  More positive than -0.7V.	a. Q3 open. b. R33 shorted or low. a. Q5 shorted. b. Proceed to Step 5.
5	Voltage between 22 and 23.	More negative than OV.  More positive than OV.	a. R34 open, b. Q4 shorted, a. Q6 and Q7 open.

Table 5-5. Common Troubles

SYMPTOM	CHECKS AND PROBABLE CAUSES
High ripple	<ul> <li>a. Check operating setup for ground loops.</li> <li>b. If output floating, connect lµf capacitor between output and ground.</li> <li>c. Ensure that supply is not crossing over to constant current mode under loaded conditions.</li> </ul>
Poor line regulation	<ul><li>a. Check reference circuit (Paragraph 5-35).</li><li>b. Check reference circuit adjustment (Paragraph 5-54).</li></ul>
Poor load regulation (Constant Voltage)	<ul> <li>a. Measurement technique. (Paragraph 5-16)</li> <li>b. Check the regulation characteristics of Zener diode VR1 as follows: <ol> <li>(1) Connect differential voltmeter across VR1.</li> <li>(2) Connect appropriate load resistor (Ry), given in Figure 5-5, across (+) and (-) output terminals.</li> <li>(3) Perform steps b through f of Paragraph 5-16.</li> <li>(4) If the differential voltmeter reading varies by more than 1.8mV, replace VR1.</li> </ol> </li> </ul>
	<ul> <li>c. Ensure that supply is not going into current limit. Check constant cur- rent input circuit.</li> </ul>

Table 5-5. Common Troubles (Continued)

SYMPTOM	CHECKS AND PROBABLE CAUSES	
Poor load regulation (Constant Current)	<ul> <li>a. Check the regulation characteristics of Zener diode VR2 as follows: <ol> <li>(1) Connect differential voltmeter across VR2,</li> <li>(2) Connect appropriate load resistor (Ry), given in Figure 5-5, across (+) and (-) output terminals.</li> <li>(3) Perform steps b through f of Paragraph 5-25.</li> <li>(4) If the differential voltmeter reading varies by more than the following, replace VR2. <ol> <li>6200B</li> <li>6201B</li> <li>6202B</li> <li>6203B</li> <li>1.2mV</li> <li>1.8mV</li> <li>1.2mV</li> <li>4mV</li> </ol> </li> <li>b. C19, C20, and CR34 leaky,</li> <li>c. Check clamp circuit Q10, CR30, CR31, and CR32.</li> <li>d. Ensure that supply is not going into voltage limit. Check constant voltage input circuit.</li> </ol></li></ul>	
Oscillates (Constant Voltage/Constant Current)	a. Check C5 for open, adjustment of R30 (Paragraph 5-56).	
Poor Stability (Constant Voltage)	Noisy programming resistor R10.  CR1, CR2 leaky.  Check R1, R12, R13, C2 for noise or drift.  Stage Q1 defective.	
Poor Stability (Constant Current)	a. Noisy programming resistor R16. b. CR5, CR6, C2, C3 leaky. c. Check R18, R19, R20, R21, C3, for noise or drift. d. Stage Q2 defective.	

Table 5-6. Selected Semiconductor Characteristics

REFERENCE DESIGNATOR	CHARACTERISTICS	♠ PART NO.	SUGGESTED REPLACEMENT
Q1,2	Matched differential amplifier. NPN Si Planar. 70 (min.) hgg ic = 1mA. VCE = 5V. Ico 0.01μA @ Vcbo = 5V.	1854-0229	2N2917 G.E.
Q4	PNP Icex = 0.1mA (max) @ Vce = 90V, VBE = 4V.	1853-0040	2N3741 Motorola
Q6,7	NPN Power hre=35 (min.) @ Ic=4A, VCE=4V.	1854-0225	2N3055 R.C.A.
CR1-5,20, 30,32	Si, rectifier, 200mA, 180prv	1901-0033	lN485B Sylvania
CR8,9,31	Si. diode, 2.4V @ 100mA	1901-0460	1N4830 G.E.
CR11, 17, 22-25, 34	Si. rectifier, 500mA, 200prv	1901-0026	1N3253 R.C.A.
CR26-29	Si. rectifier, 900mA, 200prv	1901-0327	1N5059 G.E.

# 5-38 REPAIR AND REPLACEMENT

5-39 Before servicing a printed wiring board, refer to Figure 5-12. Section VI of this manual contains a list of replaceable parts. Before replacing a semiconductor device, refer to Table 5-6 which lists the

special characteristics of selected semiconductors. If the device to be replaced is not listed in Table 5-6. the standard manufacturers part number listed in Section VI is applicable. After replacing a semiconductor device, refer to Table 5-7 for checks and adjustments that may be necessary.

Excessive heat or pressure can lift the copper strip from the board. Avoid damage by using a low power soldering iron (50 watts maximum) and following these instructions. Copper that lifts off the board should be cemented in place with a quick drying acetate base cement having good electrical insulating properties,

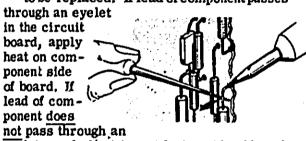
A break in the copper should be repaired by soldering a short length of tinned copper wire across the break.

Use only high quality rosin core solder when repairing etched circuit boards. NEVER USE PASTE FLUX. After soldering, clean off any excess flux and coat the repaired area with a high quality electrical varnish or lacquer,

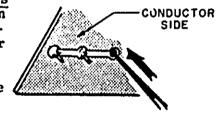
When replacing components with multiple mounting pins such as tube sockets, electrolytic capacitors, and potentiometers, it will be necessary to lift each pin slightly, working around the components several times until it is free.

WARNING: If the specific instructions outlined in the steps below regarding etched circuit boards without eyelets are not followed, extensive damage to the etched circuit board will result.

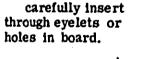
1. Apply heat sparingly to lead of component to be replaced. If lead of component passes

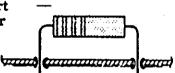


If hole does not have an eyelet, insert awl or a #57 drill from conductor side of board.



eyelet, apply heat to conductor side of board. 3. Bend clean tinned lead on new part and



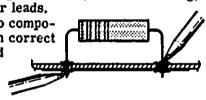


4. Hold part against board (avoid overheating) and solder leads.

2. Reheat solder in vacant eyelet and quickly

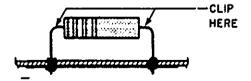
insert a small awl to clean inside of hole.

Apply heat to component leads on correct side of board as explained in step 1.



In the event that either the circuit board has been damaged or the conventional method is impractical, use method shown below. This is especially applicable for circuit boards without eyelets.

1. Clip lead as shown below.



2. Bend protruding leads upward. Bend lead

of new APPLY SOLDER component around protruding lead. Apply solder using a pair of long nose pliers as a heat sink,

This procedure is used in the field only as an alternate means of repair. It is not used within the factory.

Figure 5-12. Servicing Printed Wiring Boards

Table 5-7. Checks and Adjustments After Replacement of Semiconductor Devices

REFERENCE	FUNCTION	CHECK	ADJUST
Q1 ,	Constant voltzye differential amplifier	Constant voltage (CV) line and load regulation. Zero volt output.	
Q2	Constant current differential amplifier	Constant current (CC) line and load regulation. Zero current cutput.	
Q3,Q4,Q5	Mixer and error amplifiers	CV load regulation. CV transient response. CC load regulation.	R30
Q6,Q7	Series regulator	CV load regulation.	
Q8,Q9	Reference regulator	Reference circuit line regulation.	R46
Q10	Clamp circuit	CC load regulation.	
Q11-Q15	Meter circuit	Meter zero. Voltmeter/ ammeter tracking.	R63, R72, R56
CR1, CR2	Limiting diodes	CV load regulation.	
CR3, CR4	OR-gate diodes	CV/CC load regulation.	
CR5	Limiting diode	CC load regulation,	
CR8, CR9	Forward bias regulator	Voltage across each diode 2.0 to 2.4 volts.	<b>=</b> 10 to 10
CR22, CR23, CR24, CR25, CR28, CR29	Rectifier diodes	Voltage across appropri- ate filter capacitor.	
CR34	Protection diode	Output voltage	P0 W0 -2 -20
VR1	Positive reference voltage	Positive reference volt- age (+6.2V).	
VR2	Negative reference voltage	Negative reference volt- age (-6,2V).	

Table 5-8. Calibration Adjustment Summary

ADJUSTMENT OR CALIBRATION	PARAGRAPH	CONTROL DEVICE
Meter Zero	5-42	Pointer
Voltmeter Tracking	5-44	R63 and R72
Ammeter Tracking	5-46	R56
"Zero" Vol: Output	5-49	R6 or R8
"Voltage" Programming Current	5-50	R13
"Zero" Current Output	5-52	R25 or R28
"Current" Programming Current	5 <sub>;</sub> ∙53	R19
Reference Circuit Line Voltage Adjustment	5-54	R46
Transiert Response	5-56	R30

# 5-40 ADJUSTMENT AND CALIBRATION

5-41 Adj::stment and calibration may be required after performance testing, troubleshooting, or repair and replacement. Perform only those adjustments that affect the operation of the faulty circuit and no others. Table 5-8 summarizes the adjustments and calibrations contained in the following paragraphs.

# 5-42 METER ZERO

# 5-43 Proceed as follows to zero meter:

- a. Turn off instrument (after it has reached normal operating temperature) and allow 30 seconds for all capacitors to discharge.
- b. Insert sharp pointed object (pen point or awl) into the small hole at top of round black plastic disc located directly below meter face.
- c. Rotate plastic disc clockwise (cw) until meter reads zero, then rotate ccw slightly in order to free adjustment screw from meter suspension. If pointer moves, repeat steps b and c.

# 5-44 VOLTMETER TRACKING

5-45 To calibrate voltmeter tracking, proceed as follows:

- a. Set METER switch to highest current position and, with supply on and no load connected, adjust R63 until front panel meter reads zero.
- b. Connect differential voltmeter across supply, observing correct polarity.
- c. Set METER switch to highest voltage range and turn on supply. Adjust VOLTAGE control until differential voltmeter reads exactly the maximum rated output voltage.
- d. Adjust R72 until front panel meta also indicates maximum rated output voltage.

#### 5-46 AMMETER TRACKING

5-47 To calibrate ammeter tracking proceed as follows:

- a. Repeat steps a through e of Paragraph5-15.
- b. Adjust R56 until front panel meter indicates exactly the maximum rated output current.

# 5-48 CONSTANT VOLTAGE PROGRAMMING CURRENT

5-49 To calibrate the zero volt programming accuracy, proceed as follows:

- a. Connect differential voltmeter between +S and -S terminals.
- b. Short out voltage controls by connecting jumper between terminals A6 and -S.
- c. Rotate CURRENT controls fully clockwis J and turn in supply.
  - d. Observe reading on differential voltmeter.
- e. If it is more positive than 0 volts, shunt resistor R6 with a decade resist nce box (105K min)
- f. Adjust decade resistance until differential voltmeter reads zero, then shunt R6 with resistance value equal to that of the decade resistance.
- g. If reading of step d is more negative than colts, shunt resistor R8 with the decade resistance box.
- h. Adjust decade resistance until differential voltmeter reads zero then shunt R8 with a resistance value equal to that of the decade box.
- 5-50 To calibrate the programming current, proceed is as follows:
- a. Connect a 1.5K, 0.1% resistor between terminals -S and A6 on rear barrier strip.
- b. Disconnect jumper between A7 and A8 (leaving A6 and A7 jumpered) on rear terminal barrier strip.
- c. Connect a decade resistance in place of R13.
- d. Connect a differential voltmeter between +S and -S and turn on supply.
- e. Adjust decade resistance box so that differential voltmeter indicates maximum rated output voltage within  $\pm 0.15$  volts.
- f. Replace decade resistance with resistor of appropriate value in R13 position.
- 5-51 CONSTANT CURRENT PROGRAMMING CURRENT
- 5-52 To calibrate the zero current programming accuracy, proceed as follows:
- a. Connect differential voltmeter between +S and -S terminals.
- b. Short out current controls by connecting jumper between terminals Al and A5.
- c. Rotate VOLTAGE controls fully clockwise and turn on supply.
  - d. Observe reading on differential voltmeter.
- e. If it is more positive than 0 volts, shunt resistor R25 with a decade resistance box (105K min)
- f. Adjust decade resistance until differential voltmeter reads zero, then shunt R25 with resistance value equal to that of decade resistance.

- g. If reading of step d is more negative than 0 volts, shunt registor R28 with decade resistance.
- h. Adjust decade resistance until differential voltmeter reads zero, then shunt 928 with resistance value equal to that of decade bo
- 5-53 To calibrate the programming current, proceed as follows:
- a. Connect power supply as shown in Figure 5-4.
- b. Remove strap between A3 at 1 A4 (leaving P4 and A5 jumperec).
- c. Connec' a 1.5Ka, (750a for Model 6200B) 0.1% resistor between Al and A5.
- d. Connect decade resistance box in place of R19.
- e. Set METER switch to highest current range and turn on supply.
- f. Adjust the decade resistance so that the differential voltmeter indicates 1.5  $\pm 0.030V$ ,
- g. Replace decade resistance with appropriate value resistor in R19 position.
- 5-54 REFERENCE CIRCUIT ADJUSTMENTS
- 5-55 <u>Line Regulation.</u> To adjust the line regulation capabilities of the instrument, proceed as follows:
- a. Connect the differential voltmeter between +S (common) and 33 (positive).
- b. Connect variable voltage transformer between supply and input power source.
  - c. Adjust line to 105 VAC.
  - c. Connect decade resistance in place of R46.
  - e. Turn on supply.
- f. Adjust decade resistance so that voltage indicated by differential voltmeter does not change more than 0.2 millivolts as input line voltage is varied from 105 to 125 VAC.
- g. Replace decade resistance with appropriate value resistor in R46 position.
- 5-56 CONSTANT VOLTAGE TRANSIENT RESPONSE
- 5-57 To adjust the transient response, proceed as follows:
  - a. Connect test scup as shown in Figure 5-7.
- b. Repeat steps a through e as outlined in Paragraph 5-19.
- c. Adjust R30 so that the transient response is as shown in Figure 5-8.

# SECTION VI REPLACEABLE PARTS

#### 6-1 INTRODUCTION

- 6-2 This section contains information for ordering replacement parts. Table 6-4 lists parts in alphanumeric order by reference designators and provides the following information:
  - a. Reference Designators. Refer to Table 6-1,
- b. Description. Refer to Table 6-2 for abbreviations.
- c. Total Quantity (TQ). Given only the first time the part number is listed except in instruments containing many sub-modular assemblies, in which case the TQ appears the first time the part number is listed in each assembly.
  - d. Manufacturer's Part Number or Type,
- e. Manufacturer's Federal Supply Code Number. Refer to Table 6-3 for manufacturer's name and address.
  - f. Hewlett-Packard Part Number.
- g, Recommended Spare Parts Quantity (RS) for complete maintenance of one instrument during one year of isolated service.
- h. Parts not identified by a reference designator are listed at the end of Table 6-4 under Mechanical and/or Miscellaneous. The former consists of parts belonging to and grouped by individual assemblies; the latter consists of all parts not immediately associated with an assembly.

# 6-3 ORDERING INFORMATION

6-4 To order a replacement part, address order or inquiry to your local Hewlett-Packard sales office (see lists at rear of this manual for addresses). Specify the following information for each part: Model, complete serial number, and any Option or special modification (1) numbers of the instrument; Hewlett-Packard part number; circuit reference designator; and description. To order a part not listed in Table 6-4, give a complete description of the part, its function, and its location.

Table 6-1. Reference Designators

A = assembly B = blower (fan) C = capacitor CB = circuit breaker CR = diode DS = device, signal- ing (lamp)	E = miscellaneous electronic part F = fuse J = jack, jumper K = relay L = inductor M = meter
---	--

Table 6-1. Reference Designators (Continued)

S T	= plug = 'transistor = resistor = switch = transformer = terminal block = thermal switch	V = vacuum tube neon bulb, photocell, e VR = zener diode X = socket Z = integrated cl cuit or netwo	tc,
--------	--	---	-----

Table 6-2. Description Abbreviations

Table 6-2. Descr	iption Abbreviations
A = ampere	mfr = manufacturer
ac = alternating	mod, = modular or
current	modified
assy, = assembly	mtg = mounting
bd = board	$n = nano = 10^{-9}$
bkt = bracket '	NC = normally closed
°C = degree	NO = normally open
Centigrade	NP = nickel-plated
cd = card	ohm :
coef = coefficient	obd = order by
comp = composition	description
CRT = cathode-ray	OD = outside
tube	diameter
CT = center-tapped	p = pico = 10 <sup>-12</sup>
dc = direct current	P, C, = printed circuit
DPDT = double pole,	pot. = potentiometer
double throw	p-p = peak-to-peak
DPST = double pole,	ppm: = parts per
single throw	million
elect = electrolytic	pvr = peak reverse
encap = encapsulated	voltage
F = fared	rect = rectifier
or = degree	rms = root mean
Farenheit	square
fxd = fixed	Si = silicon
Ge = germanium	SPDT = single pole,
H = Henry	double throw
Hz = Hertz	SPST = single pole,
IC = integrated	single throw
circuit	SS = small signal
ID = inside diameter	T = slow-blow
incnd = incandescent k = kilo = 103	tan. = tantulum
	Ti = titanium
	V = volt
	var = variable
	ww = wirewound
met. = metal	W = Watt

	, ,	70210 0 01 000
	CODE NO.	MANUFACTURER ADDRESS
	00629	EBY Sales Co., Inc. Jamaica, N.Y.
	00656	Aerovox Corp. New Bedford, Mass.
	00853	Sangamo Electric Co.
	00053	
		S, Carolina Div. Pickens, S.C.
3	01121	Allen Bradley Co, Milwaukee, Wis,
	01255	Litton Industries, Inc.
		Beverly Hills, Calif.
-	J1281	TRW Semiconductors, Inc.  Lawndale, Calif.
	01295	Texas Instruments, Inc.
	01230	
		Semiconductor-Components Div.
1	01.000	Dallas, Texas
	01686	RCL Electron'ss, Inc. Manchester, N. H.
	01930	Amerock Corp. Rockford, Ill.
	02107	Sparta Mfg. Co. Dover, Ohio
1	02114	Ferroxcube Corp. Saugerties, N.Y.
1	02606	Fenwal Laboratories Morton Grove, Ill.
1	02660	Amphenol Corp, Broadview, Ill.
ı	02735	
ı	02/33	Radio Curp, of America, Solid State
ı		and Receiving Tube Div. Somerville, N.J.
ı	03508	G. E. Semiconductor Products Dept.
ı	1 1	Syracuse, N.Y.
ı	03797	Eldema Corp. Compton, Galif.
ı	03877	Transitron Electronic Corp.
Į		Wakefield, Mass.
	03888	Pyrofilm Resistor Co. Inc.
ı		Cedar Knolls, N.J.
İ	04009	Array, Hart and Hegeman Electric Co.
1	01005	
1	0.4000	Hartford, Conn.
I	04072	ADC Electronics, Inc. Harbor City, Calif.
ı	04213	Caddell & Burns Mfg. Co. Inc.
		Mineola, N.Y.
ı	04404	*Hewlett-Packard Co, Palo Alto Div.
ı	1	Palo Alto, Calif,
١	04713	Motorola Semiconductor Prod. Inc.
ł		Phoenix, Arizona
í	05277	Westinghouse Electric Corp.
ı	3021,	Companduater Deat Vous-ward De
1	05347	Semiconductor Dept, Youngwood, Pa.
ı		Ultronix, Inc. Grand Junction, Colo,
I	05820	Wakefield Engr. Inc. Wakefield, Mass.
ł	06001	General Elect, Co, Electronic
1		Capacitor & Battery Dept, Irmo, S.C.
ı	06004	Bassik Div. Stewart-Warner Corp.
I	•	Bridgeport, Conn.
ı	06486	IRC Div. of TRW Inc.
I	1 :	Semiconductor Plant Lynn, Mass.
I	06540	Amatom Electronic Hardware Co. Inc.
ı		
١	06555	New Rochelle, N.Y. Beede Electrical Instrument Co.
ł	00333	
I	00000	Penacook, N.H.
۱	06666	General Devices Co, Inc.
ı		Indianapolis, Ind.
l	06751	Semcor Div, Components, Inc.
١		Phoenix, Arizona
I	06776	Robinson Nugent, Inc. New Albany, Ind.
١	06812	Torrington Mfg. Co., West Div.
ł		Van Nuys, Calif,
ı	07137	Transistor Electronics Corp.
١	V, 10/	
l		Minneapolis, Minn,
•		<del></del>

CODE NO.	MANUFACTURER ADDRESS
07138	Westinghouse Electric Corp.
07263	Electronic Tube Div. Elmira, N.Y. Fairchild Camera and Instrument Corp. Semiconductor Div.
07387 07397	Mountain View, Calif, Birtcher Corp., The Los Angeles, Calif, Sylvania Electric Prod, Inc,
07716	Sylvania Electronic Systems Western Div. Mountain View, Calif. IRC Div. of TRW Inc. Burlington Plant
07910	Burlington, Iowa Continental Device Corp,
07933	Hawthorne, Calif, Raytheon Co. Components Div. Semiconductor Operation
08484	Mountain View, Calif. Breeze Corporations, Inc. Union, N.J.
08530	Reliance Mica Corp, Brooklyn, N.Y.
08717	Reliance Mica Corp. Brooklyn, N.Y. Sloan Company, The Sun Valley, Calif.
08730	Vemaline Products Co. Inc. Wyckoff, N.J.
08806	General Elect, Co. Minia-
	ture Lamp Dept. Cleveland, Ohio Nylomatic Corp. Norrisville, Pa. RCH Supply Co. Vernon, Calif
08863	Nylomatic Corp. Norrisville, Pa.
08919	10111011 Oditi,
09021	Airco Speer Electronic Components
09182	Bradford, Pa,  *Hewlett-Packard Co, New Jersey Div.  Rockaway, N.J.
09213	General Elect. Co. Semiconductor Prod. Dept. Buffalo. N.Y.
09214	General Elect, Co. Semiconductor
09353	C & K Components Inc. Newton, Mass.
09922	Burndy Corp. Norwalk, Conn.
11115	burndy Corp. Norwalk, Conn.
1	Tung-Sol Div. Bloomfield, N T
11236	Tung-Sol Div.  CTS of Berne, Inc.  Chicago Telephone of Cal. Inc.
11237	Chicago Telephone of Cal, Inc, So, Pasadena, Calif,
11502	IRC Div. of TRW Inc. Boone Plant Boone, N.C.
11711	General Instrument Corp
12136	Rectifier Div, Newark, N, J, Philadelphia Handle Co, Inc. Camden, N. J.
12615	U.S. Terminals, Inc. Cincinnati, Ohio
12617	
	Hamlin Inc. Lake Mills, Wisconsin
12697	Clarostat Mfg. Co. Inc. Dover, N. H.
13103	Thermalloy Co, Dallas, Texas
14493	*Hewlett-Packard Co. Loveland Div. Loveland, Colo.
14655	Cornell-Dubilier Electronics Div. Federal Pacific Electric Co.
14936	Newark, N.J. General Instrument Corp. Semicon- du-tor Prod. Group Hicksville, N.Y.
15801	Fenwal Elect. Framingham, Mass.
16299	Corning Glass Works, Electronic
	Components Div. Raleigh, N.C.

<sup>\*</sup>Use Code 28480 assigned to Hewlett-Packard Co., Palo Al... California

Table 6-3. Code List of Manufacturers (Continued)

		-		
CODE NO.	MANUFACTURER ADDRESS		GODE NO.	MANUFACTURER ADDRESS
16758	Delco Radio Div. of General Motors Corp.	]	70563	
17545	Kokomo, Ind. Atlantic Semiconductors, Inc.		70901 70903	Belden Corp. Chicago, Ill.
17803	Fairchild Camera and Instrument Corp		71218 71279	
1.	Semiconductor Div. Transducer Plant Mountain View, Calif.		71400	Cambridge, Mass.
17870	Daven Div. Thomas A, Edison Industries McGraw-Edison Go. Orange, N. J.	7 3 1 3 1 3 1	71450	Edison Co. St. Louis, Mo.
18324	Signetics Corp, Sunnyvale, Calif.		71468	CTS Corp. Elkhart, Ind. I. T. T. Cannon Electric Inc.
19315	Bendix Corp. The Navigation and Control Div. Teterboro, N.J.		71590	Los Angeles, Calif.
19701	Electra/Midland Corp.	<i>[</i>		Centralab Div, Milwaukee, Wis,
21520	Mineral Wells, Texas Pansteel Metallurgical Corp.		71700	General Cable Corp. Cornish Wire Co. Div. Williamstown, Mass.
	No. Chicago, Ill.	i i e	71707	Coto Coil Co. Inc. Providence, R. I.
22229	Union Carbide Corp. Electronics Div.  Mountain View, Calif.		71744	Chicago Miniature Lamp Works Chicago, Ill.
22753	UID Electronics Corp. Hollywood, Fla. Pamotor, Inc. Pampa, Texas		71785	Ginch Mfg. Co. and Howard
24446	Pamotor, Inc. Pampa, Texas General Electric Co. Schenectady, N.Y.		71984	B. Jones Div. Chicago, Ill. Dow Coming Corp. Midland, Mich.
24455	General Electric Co, Lamp Div, of Con-		72136	Electro Motive Mfg. Co. Inc.
	sumer Prod. Group Nela Park, Cleveland, Ohio	1	72619	Willimantic, Conn. Dialight Corp.  Brooklyn, N. Y.
24655	General Radio Co, 'West Concord, Mass.	1	72699	General Instrument Corp. Newark, N. J.
24681	LTV Electrosystems Inc Memcor/Com-		72765	Drake Mfg. Co. Harwood Heights, Ill,
26982	ponents Operations Huntington, Ind. Dynacool Mfg. Co. Inc. Saugerties, N.Y.		72962	Elastic Stop Nut Div. of Amerace Esna Corp. Union, N.J.
27014	National Semiconductor Corp.		72982	Erie Technological Products Inc. Erie, Pa,
	Santa Clara, Calif,	1	73096	Hart Mfg. Co. Hartford, Conn.
28480 28520	Hewlett-Packard Co. Palo Alto, Calif. Heyman Mfg. Co. Kenilworth, N. I.		73138	Beckman Instruments Inc.
28875	Heyman Mfg. Co. Kenilworth, N.J. IMC Magnetics Corp.		73168	Helipot Div. Fullerton, Calif. Fenwal, Inc. Ashland, Mass.
	New Hampshire Div. Rochester, N. H.		73293	Hughes Aircraft Co. Electron
31514	SAE Advance Packaging, Inc.			Dynamics Div. Torrance, Calif.
31827	Santa Ana, Calif. Budwig Mfg. Co. Ramona, Calif.	,	73445	Amperex Electronic Corp.
33173	G. E. Co. Tube Dept. Owensboro, Ky.		73596	Hicksville, N.Y. Bradley Semiconductor Corp.
35434	Lectrohm, Inc. Chicago, Ill.		1	New Haven, Conn.
37942	P. R. Mallory & Co. Inc.		73559	Carling Electric, Inc. Hartford, Conn.
42190	Indianapolis, Ind.  Muter Co.  Chicago, Ill.		73734	Federal Screw Products, Inc.
43334	New Departure-Hyatt Bearings Div.		74193	Chicago, Ill. Heinemann Electric Co. Trenton, N. J.
	General Motors Corp. Sandusky, Ohio		74545	Hubbell Harvey Inc. Bridgeport, Conn.
44655 46384	Ohmite Manufacturing Co. Skokie, Ill. Penn Engr. and Mfg. Corp.	) .	74868	Amphenol Corp. Amphenol RF Div.
	Doylestown, Pa.		74970	Danbury, Conn. E. F. Johnson Co. Waseca, Minn.
47904	Polaroid Corp. Cambridge, Mass.		75042	IRC Div. of TRW, Inc. Philadelphia, Pa.
49956 55026	Raytheon Co, Lexington, Mass, Simpson Electric Co, Div, of American		75183	*Howard B. Jones Div. of Cinch
00020	Gage and Machine Co. Chicago, Ill.		75376	Mfg, Corp. New York, N Kurz and Kasch, Inc. Dayton, Ohio
56289	Sprague Electric Co, North Adams, Mass.		75382	Kilka Electric Corp. Mt. Vernon, N.Y.
58474	Superior Electric Co. Bristol, Conn.		75915	Littlefuse, Inc. Des Plaines, Ill.
58849	Syntron Div, of FMC Corp.  Homer City, Pa.		76381	Minnesota Mining and Mfg. Co. St. Paul, Minn,
59730	Thomas and Betts Co. Philadelphia, Pa.		75385	Minor Rubber Co. Inc. Bloomfield, N. I.
61637	Union Carbide Corp. New York, N. Y.		76487	James Millen Mfg. Co. Inc.
63743	Ward Leonard Electric Co, Mt. Vernon, N.Y.		76493	Malden, Mass.  J. W. Milier Co. Compton, Calif.
				Compton Catt.

<sup>\*</sup>Use Code 71785 assigned to Cinch Mfg. Co., Chicago, III.

Table 6-3, Code List of Manufacturers (Continued)

CODE NO.	MANUFACTURER ADDRESS
76530	Cinch City of Industry Calif
1 ,	Cinch City of Industry, Calif. Oak Mfg. Co. Div. of Oak
76854	
77060	Electro/Netics Corp., Crystal Lake, Ill.
7706B	Bendix Corp., Electrodynamics Div.
77122	No, Hollywood, Calif, Palnut Co. Mountainside, N.J. Patton-MacGuyer Co. rovidence, R.I.
	Painut Co, Mountainside, N.),
77147	Patton-MacGuyer Co, Providence, R. I.
77221	Phaostron Instrument and Electronic Co.
77252	South Pasadena, Calif.
1/252	Philadelphia Steel and Wire Corp.
77342	Philadelphia, Pa,
//342	American Machine and Foundry Co.
22520	Potter and Brumfield Div. Princeton, Ind.
77630	TRW Electronic Components Div.
	Camden, N.J.
77754	Resistance Products Co. Harrisburg, Pa.
78189	Illinois Tool Works Inc. Shakeproof Div.
	Elgin, Ill.
78452	Everlock Chicago, Inc. Chicago, Ill.
78488	Stackpole Carbon Co. St. Marys, Pa.
78526	Stanwyck Winding Div. San Fernando
43	Electric Mfg. Co. Inc. Newburgh, N.Y.
78553	Tinnerman Products, Inc. Cleveland, Ohio
78584	Stewart Stamping Corp, Yonkers, N.Y.
79136	Waldes Kohinoor, Inc. L.I.C., N.Y.
79307	Stewart Stamping Corp.  Waldes Kohinoor, Inc.  Whitehaad Metals Inc.  Yonkers, N.Y.  L.I.C., N.Y.  New York, N.Y.
79727	Continental-Wirt Electronics Corp.
	Philadelphia, Pa.
79963	Zierick Mfg. Co. Mt. Kisco, N.Y.
B0031	Mepco Div, of Sessions Clock Co,
المممما	Morristown, N. J.
80294	Bourns, Inc. Riverside, Calif.
81042	Howard Industries Div. of Msl Ind. Inc.
81073	Racine, Wisc. Grayhill, Inc. La Grange, Ill.
	Grayhill, Inc. La Grange, Ill,
81483	International Rectifier Corp.
03.053	El Segundo, Calif,
81751	Columbus Electronics Corp. Yonkers, N. Y.
82099	Goodyear Sundries & Mechanical Co. Inc.
82142	New York, N. Y.
04142	Airco Speer Electronic Components
82219	Du Bois, Pa. Sylvania Electric Products Inc.
02213	Flectronic Tube Div, Receiving
;	Tube Operations Emporium, Pa.
82389	Switchcraft, Inc. Chicago, Ill.
82647	Metals and Controls Inc. Control
020-97	Products Group Attleboro, Mass.
82866	Research Products Corp. Madison, Wis.
82877	Ro.ron Inc. Woodstock, N.Y.
82893	Vector Electronic Co. Glendale, Calif.
83058	Carr Fastener Co. Cambridge, Mass.
83186	Victory Engineering Corp.
*****	Springfield, N. J.
83298	Bendix Corp, Electric Power Div.
55255	Eatontown, N. J.
83330	Herman H. Smith, Inc. Brooklyn, N.Y.
83385	Central Screw Co. Chicago, Ill.
83501	Gavitt Wire and Cable Div. of
	Amerace Esna Corp, Brookfield, Mass.
	The state of the s

CODE NO.	MANUFACTURER ADDRESS
83508	Grant Pulley and Hardware Co. West Nyack, N.Y.
83594	Burroughs Corp, Electronic
83835 83877	
84171	New York, N.Y.
84411	TRW Capacitor Div. Ogallala, Neb.
86684	RCA Corp, Electronic Components Harrison, N. J.
86838	
87034	Marco & Oak Industries a Div. of Oak
87216	Electro/netics Corp. Anaheim, Calif. Philco Corp. Lansdale Div. Lansdale, Pa.
87585	
	Philadelphia, Pa.
87929 88140	
0140	and Control Div. Lincoln Plant
	Lincoln, Ill.
88245	Litton Precision Products Inc, USECO Div, Litton Industries Van Nuys, Calif,
90634	
90763	onited-car inc,   onicago, m, [
91345	Miller Dial and Nameplate Co,
91418	Radio Materials Co. El Monte, Calif.  Chicago, Ill.
91506	, Augat, Inc. Attleboro, Mass. I
91637 91662	Dale Electronics, Inc. Columbus, Neb.
91929	Elco Corp, Willow Grove, Pa, Honeywell Inc. Div, Micro Switch
1 .	Freeport, Ill.
92825 93332	
93410	conductor Prod. Div. Woburn, Mass.
33410	Controls Div, Mansfield, Ohio
94144	Raytheon Co, Components Div,
94154	Ind. Components Oper, Quincy, Mass. Wagner Electric Corp.
94222	Tung-Sol Div. Livingston, N.J. Southco Inc. Lester, Pa.
95263	Leecraft Mfg. Co. Inc. L.I.C., N.Y.
95354	Methode Mfg. Co. Rolling Meadows, Ill.
95712	Bendix Corp. Microwave Devices Div. Franklin, Ind.
95987	Weckesser Co. Inc. Chicago, Ill.
96791	Amphenol Corp. Amphenol Controls Div. Janesville, Wis.
97464	Industrial Retaining Ring Co.  Irvington, N.J.
97702	IMC Magnetics Corp. Eastern Div. Westbury, N.Y.
98291	Sealectro Corp. Mamaroneck, N.Y.
98410	ETC Inc. Cleveland, Ohio
98978	International Electronic Research Corp.  Burbank, Calif.
99934	Renbrandt, Inc. Boston, Mass.

. De ference			Mfr. Part #		Mfr.	<b>Q</b>	
·Reference <u>Designator</u>	Description Qu	antity	or Type	Mfr,	Code	Stock No.	RS
Designator	Description Qu	<u>antity</u>	<u> </u>	17.4.1			11.0
C1,9	fxd, elect 4.7µf 35vdc	2	150D475X9035B2	Sprague	56289	0180-0100	1
C2, 18	fxd, film . 01µf 200vdc	. 2	192P10392	Sprague	56289	0160-0761	ì
C3	fxd, film 0. 1µf 200vdc	1	192P10492	Sprague	56289	0160-0168	1
C4,6-8,11,1	15 NOT ASSIGNED	-	•	-	-		-
C5	fxd, film .001µf 200vdc	1	192P10292	Sprague	56289	0160-0153	1
C10	fxd, elect 100µf 50vdc	1	D32218	Sprague	56289	0180-1852	1
C12, 20	fxd, elect 490µf 85vdc	2	D38618	HLAB	09182	0180-1888	1
C13, 14	fxd, elect 1500µf 40vdc	2	D38733	HLAB	09182	0180-1394	1
C16, 17	fxd, ceramic .05µf 500vdc	2	33C17A	Sprague	56289	0150-0052	1
C19	fxd, elect 15µf 50vdc	1	150D156X005 OR2	Sprague	56289	0180-1834	1
	•						
CR1-5, 20,	D4 100 1		3.32.40CD	a		1001 0000	,
30, 32	Rect. si. 200ma 180prv	8	1N485B	Sylvania	93332	1901-0033	6
CR6-9, 31	Diode, si. 2,4V @ 100ma	5	GD8-001	G, I,	11711	1901-0460	5
CR10, 12-16,		1	•				
19, 21, 26, 2					4		
33, 35	NOT ASSIGNED	-	-	-	-	-	-
CR11, 28,	Post of 28 200nm		14D1022D	Matanala	04212	1001 0416	
29, 34	Rect. si. 3A 200prv Rect. si. 500ma 200prv	<b>4</b> 5	MR1032B 1N3253	Motorola		1901-0416 1901-0389	4
OR17, 22-23	Rect. St. Sooma Zooptv	)	1143233	R, C, A.	02735 ,	1901-0909	5
DS1	Indicator Lamp, Neon	1	858-R	Sloan	08717	1450-0048	1
	,	_					-
F1	Fuse cartridge, 2A@250V3AG	1	312002	Littlefuse	75915	2100-0002	5
01.0	CO MINT ALSO	_	MT11 01 000				_
Q1,2 Q3,5,8,12,	SS NPN diff, amp. si.	2	#JX12A839	G, E,	03508	1854-0229	2
10, 14, 15	SS PNP si.	7	23120073	Communica	E C 0 0 0	1052_0000	e
Q4	SS PNP si.	1	2N2907A 40362	Sprague HIAB	56289	1853-0099	6
Q6,7	Power NPN si.	2	36616	HLAB	09182 09182	1853-0041	1
Q9	SS NPN si.	ĺ				1854-0225	2
Q11,13	SS NPN si.	2	2N3417 SK1124	G. E.	03508	1854-0087	1
Q11, 13	DO MANA RI'	<b>, 4</b>	SK1124	T.I.	01295	1854-0071	2
R1	fxd, ww 1K, ±5% 3w 20ppm	1	242E1025	Sprague	56289	0813-0001	1
R2, 22, 23	fxd, film 6, 2K <sub>A</sub> ±1% 1/8w	3	DIEBIORO	I, R. C.		0698-5087	i
R3	fxd, film 15K <sub>0</sub> ±1% 1/8w	ĭ		I. R. C.	07716	0757-0446	î
R4, 64, 65	fxd, film 20K <sub>0</sub> ±1% 1/8w	3				0757-0449	_
	fxd, film 1,5K <sub>0</sub> ±1% 1/8w	4		I. R. C. I. R. C.	07716 07716	0757-0449	1
R6, 25	fxc, comp 360% ±5% w	2		A. B.	01121	0686-3645	1
R7	fxd, film 61.9K <sub>0</sub> ±1% 1/8w	ī	•	I, R, C,	07716	0757-0460	1 1
R8,28	fxd, comp 560K <sub>0</sub> ±5% ½w	2		A, B,	01121	0686-5645	ì
R9, 11, 17, 35		_		Λ, ω,	UIIZI	0000-3045	•
39,53,55,	• •						
78, 79	NOT ASSIGNED	-	_	-	_		_
R10,15	var. ww DUAL 1, $8K_0 = 20_0$	2	100149-2	HLAB	09182	2100-0995	1
R12		1	242E1325	Sprague	56289	0811-1803	ī
R13,19	fxd, comp SELECTED ±5% 3w	2	Type EB	A, B.	01121	-	•
R14	fxd, comp 3, 3, ±5% \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	ī	-46	A, B,	01121	0686-0335	1
R15	fxd, comp 56Ka ±5% \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	ì		A. B.	01121	0686-5635	i
R18 ,	fxd, ww 6.5Ka ±5% 3w 20ppm	ī	242E6525	Sprague	56289	0811-1814	1
R20,48	fxd, film 1K, ±1% \}w	2	Type CEB T-O	I. R. C.	07712	0757-0338	ì
R21	fxd, comp 39, ±5% \underset{\frac{1}{2}}w	ĩ	-16 1	A. B	01121	0686-3905	i
R24	fxd, film 4,75Ka ±1% 1/8w	ī		I, R, C.	07716	0757-0437	i
R27, 32	fxd, ww . 24, ±5%	2	Type BWH	I, R, C,	07716	0811-1758	î
R29	fxd, comp 6. 2K, ±5% \ w	ī	-15	A. B.	01121	0686-6225	i
R30	var. ww 5Kn (Modify)	ī	Type 110-F4	C. T. S.	11236	2100-1824	î
R31	fxd, comp 1K, ±5% w	ī	-45	A, B,	01121	0686-1025	ì
		_	. •	,,		200 1050	•

Reference	$\frac{C_{0}}{C_{0}} = \frac{C_{0}}{C_{0}} = \frac{C_{0}}{C$	•	Mfr. Part #		Mfr.	<b>€</b> , †	
Designator	Description	Quantity		Mfr.	Code	Stock No.	RS
naa	End annual total arms 1	_		1 .			
R33	fxd, comp 10K <sub>h</sub> ±5% ½w	1	m	A, B,	01121	0686-1035	1
R34 R38	fxd, film 300, ±5% 2w	I	Type C42S	Corning	16299	0698-3630	1
	fxd, comp 91K <sub>0</sub> ±5% ½w	1		A, B,	01121	0686-9135	1
R40, 62 R41	fxd, film 619, ±1% \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	2 1		I. R. C.	07716		1
R42	fxd, comp 12K <sub>1</sub> ±5% ½w	1		A, B.	01121	0686-1235	1
R43	fxd, comp 6, 8K, ±5% ½w	Ţ		Λ, Β.	01121	0686-6825	1
20.4.4	fxd, film 470, ±1% \dag{w}	, 1		I, R, C,	07716	0698-3506	1.
R44 ))	fxd, comp 47K <sub>2</sub> ±5% ½w	1		A. B.	01121	0686-4735	1
R46	fxd, comp 5, 1Ka ±5% \dagger w	Ţ		A, B,	01121	0686-5125	1
R47	fxd, comp 100K <sub>A</sub> ±5% ½w	1		A. B.	01121	0686-1045	1
R49	fxd, comp 430, ±5% \(\frac{1}{2}\tw \)	Ţ	M 0400	A, B,	01121	0686-4315	1
R50	fxd, film 510 <sub>0</sub> ±5% 2w	,	Type C42S	Corning	16299	0698-0030	1
R51	fxd, comp $10_{\Lambda} \pm 5\% \frac{1}{4}$ w fxd, comp $30K_{\Lambda} \pm 5\% \frac{1}{4}$ w	, .		A. B.	01121	,0686-1005	1
R52	fxd, comp 22K, ±5% \{w	ì		A. B.	01121	0686-3035	- 1
R54	fxd, ww .5, C. T. ±5% 20v	_		A. B.	01121	0686-2235	1
NOT	20ppm	_	m 030544			****	_
R56	var. ww 3K <sub>h</sub> (Modify)	1	Type 2AS544	Н, Н,	73978	0811-0958	1
R57,60	fxd, film 900 <sub>A</sub> ±1% 1/8w	1	Type 110-F4	C, T, S,	11236	2100-1823	1
R58,59	fxd, film 100, ±1% 1/8w	2		I.R.C.	07716	0757-1099	1
R61	fxd, film 7.5 $K_h \pm 1\%$ 1/8w	2		I, R, C,	07716	0757-0401	1
R63	var, ww 10K <sub>h</sub>	1	W 220 D4	I, R, C,	07716	0757-0440	1
R66, 67	fxd, film 3.40 $K_h \pm 1\% \frac{1}{2}w$	1	Type 110-F4	C, T, S,	11236	2100-0396	1
R68,69	fxd, film $365_{\Lambda} \pm 1\% \frac{1}{4}$	2 2		I.R.C.	07716	0698-4640	1
R70,71,75	fxd, film 3K <sub>h</sub> ±1% 1/8w	3		I, R, C,	07716	0757-0723	1
R72	var. ww 250 <sub>h</sub> (Modify)		m 110 m	I.R.C.	07716	0757-1093	1
R73	fxd, film 750 <sub>A</sub> ±1% 1/8w	1 1	Type 110-F4	C.T.S.	11236	2100-0439	. 1
R7.4	fxd, film 9.09K <sub>h</sub> ±1% 1/8w	. –		I.R.C.	07716	0757-0420	1
R80	fxd, comp 33K <sub>0</sub> ±5% \(\frac{1}{2}\text{w}\)	1		I.R.C.	07716	0757-0288	1
	ind, comb saw 13% in	1	•	A.B.	01121	0686-3335	1
S1	Switch, SPST ON/OFF	1	T110-62	Carling	73559	3101-1055	,
S2	Meter Rotary Switch	ī	100311-A	HLAB	09182	3100-1910	1
;	, , , , , , , , , , , , , , , , , , , ,	: -	100011 //	IIIAD	03102	\$100-1910	7
Tl	Power Transformer	1	HT6203	HLAB	09182	9100-1819	1
VR1, 2	Diode, zener 6.2V ±5%	2	1N821	NA Elect.	06486	1902-0761	2
•	5 Way binding post (maroon	n) 1	DF21RC	Superior	58474	1510-0040	1
	5 Way binding post (black)		DF21BC	Superior	58474	1510-0039	i
	Fastener	1	C12008-014-4	Tinnerman		0510-0123	î
	Line cord, plug PH151 73 f	t. 1	HK4096	Beldon	70903	8120-0050	î
	Strain Relief Bushing	1	SR-5P-1	Неусо	28520	0400-0013	ì
	Jumper	8	422-13-11 013	Cinch	71785	0360-1143	2
	Barrier Strip	1	100237-15	HLAB	09182	0360-1234	ī
	Rubter bumper	4	MB50	Stockwell		0403-0088	î
•	Rubber bumper	3	4072	Stockwell		0403-0086	i
	Knob, 1 insert pointer	1		HLAB	09182	0370-0084	i
•	Knob, 17/64 insert pointer	2		HLAB	09182	0370-0101	i
	Knob, 3/16 insert pointer	2		HLAB	09182	0370-0179	i
	Bezel, Meter, 1/6 Mod.	1		HLAB -	09182	4040-0295	i
	Fuse holder	1 '	342014	Littlefuse	75915	1400-0048	i
•	Meter, 2¼", 0-9V; 0-4A	1	<del>-</del>	HLAB	09182	1120-1229	1
	Meter Spring	4			09182	1460-0720	ì
	Fastener	8	C8091 632-24B	Tinnerman		0510-0275	2
	Captive Nut	8	CLA-632-2	Pem Eng.	46384	0590-0393	2
•	Heat Dissipator	1 .	TXBF-032025P	E. R. C.	98978	1205-0011	ī
	Mica Insulator	1	734	Reliance	08530	0340-0174	ì
	Insulator, transistor pin	2	100146-1	HLAB	09182	0340-0166	ī
t	Insulator	2	100151-1	HLAB	09182	0340-0168	ī
	· ·						-

#### OPTIONS

Option Number	Description Q	uantity	Mfr. Part # or Type	Mír.	Mfr. Code	₩ Stock No.	RS
.06	Overvoltage Crowbar	1		HLAB	09182	Model 6916A	1,
07	Voltage 10-turn Potentiomete	er 1	Series 8400	IRC	07716	2100-1864	1
08	Current 10-turn Potentiomete	er 1	Series 3400	IRC	07716	2100-1864	1
09	Voltage 10-turn Potentiomete		Series 8400	IRC	07716	2100-1864	1
	Current 10-turn Potentiomete	er 1	Series 8400	IRC	07716	2100-1864	1 ,
13	Voltage Decadial Control	1	(Includes:)				
	Voltage 10-turn Pot.	1 .	Series 8400	IRC	07716	2100-1854	.1
·	Decaclal Assembly	1	RD-411	IRC	07716	1140-0020	1
14	Current Decadial Control	1	(Includes:)				
	Current 10-turn Pot.	1	Series 8400	IRC	07716	2100-1864	1
	Decadial Assembly	1	RD-411	IRC	07716	1140-0376	1

# APPENDIX A

Option 11, Overvoltage Protection "Crowbar"

#### DESCRIPTION:

This option is installed in DC Power Supplies, 6200B, 6201B, 6202B, 6203B, 6204B, and 6206B, and tested at the factory. It consists of a printed circuit board, screwdriver-type front panel potentiometer, and six wires that are soldered to the main power supply board.

The crowbar monitors he output voltage of the power supply and fires an SCR that shorts the output when it exceeds the preset trip voltage. The trip voltage is determined by the setting of the CROWBAR ADJUST control on the front panel. The trip voltage range is as follows:

Model	6200B	6201B	6202B	6203B	6204B	6205B	6206B
Trip Voltage Runge	2.5-44V	, 2.5-23V	2.5-44V	2.5-10V	2.5-44V	2.5-44V	2.5-65V

To prevent transients from falsely tripping the crowbar, the trip voltage must be set higher than the power supply output voltage by the following margin: 4% of the output voltage pius 2V. The margin represents the minimum crowbar trip setting for a given output voltage; the trip voltage can always be set higher than this margin.

# OPERATION:

- 1. Turn the CROWBAR ADJUST fully clockwise to set the trip voltage to maximum.
- 2. Set the power supply VOLTAGE control for the desired crowbar trip voltage. To prevent false crowbar tripping, the trip voltage should exceed the desired output voltage by the following amount: 4% of the output voltage plus 2V,
  - 3. Slowly turn the CROWBAR ADJUST ccw until the crowbar trips, output goes to 0 Volt.
- 4. The crowbar will remain activated and the output shorted until the supply is turned off. To reset the crowbar, turn the supply off, then on.
- 5. If the CROWBAR must be completely disabled, remove the lead attached to the CROWBAR ADJUST potentiometer R5.

Table A-1. Replaceable Parts

REF, DESIG.	DESCRIPTION	TQ	MFR. PART NO.	MFR. CODE	PART NO.	RS
C1 C2	fxd, elect. 1µf 50Vdc fxd, mica 510µf 500Vdc	1 1	30D105G050BA2 RCM15E511J	56289 04062	0180-0108 0140-0047	1
CR1-CR3 CR4	Rect. Si. 200mA 200prv SCR 7.4A 100prv	3 1	1N485B G20A	93332 03508	1901-0033 1884-0031	3
Q1,2 R1 R2 R3 R4 R5 R6 R7 R8	fxd, met. film 10a ±1% 1/8W fxd, comp 3Ka ±5% 2W fxd, met. film 1.21Ka ±1% 1/8W fxd, met. film 7.5Ka ±1% 1/8W var. ww 10Ka ±5% fxd, ww 1Ka ±5% 3W fxd, comp 22a ±5% ½ W fxd, met. film 196a ±1% 1/8W Transformer, Pulse	1 1 1 1 1 1 1	2N3417 Type CEA T-O Type C42S Type CEA T-O Type CEA T-O 242E1025 EB-2205 Type CEA T-O	03508 07716 16299 07716 07716 09182 56289 01121 07716 09182	1854-0087 0757-0346 0698-3642 0757-0274 0757-0440 2100-1854 0813-0001 0686-2205 0698-3440 5080-7122	1 1 1 1 1 1 1 1
VR1 VR2	Diode, Zener 6.19V ±5% Diode, Zener 2.37V ±5%	1	1N753 1N4370	04713 04713	1902-0049 1902-3002	1 1
	MISCELLANEOUS  Printed Circuit Board (Blank)  P. C. Board (Includes Components)  Heat Sink  Insulator (CR4)  Mica Washer  Cable Clamp  Front Panel (Modified)	1 1 1 1 1	T4-4	09182 09182 09182 09182 09182 79307 09182	5020-5750 5060-6174 5000-6229 0340-0462 2190-0709 1400-0330 06203-60003	1 1

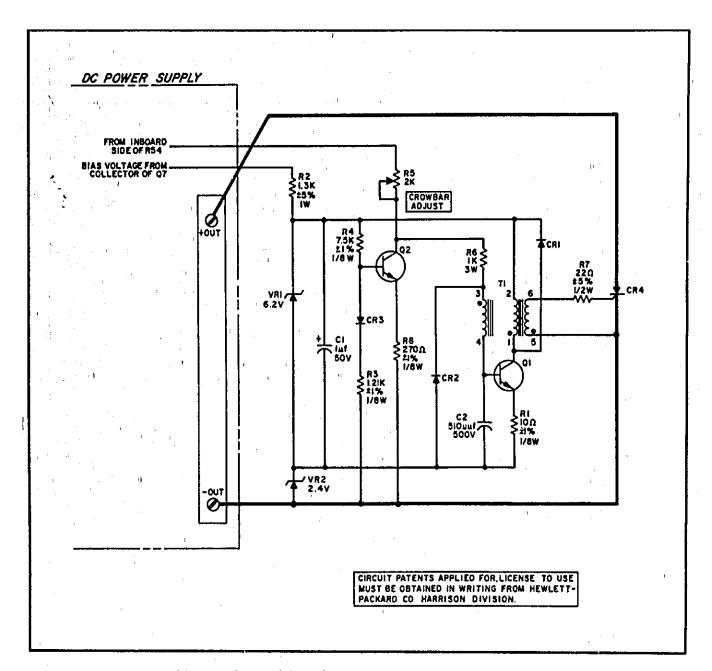
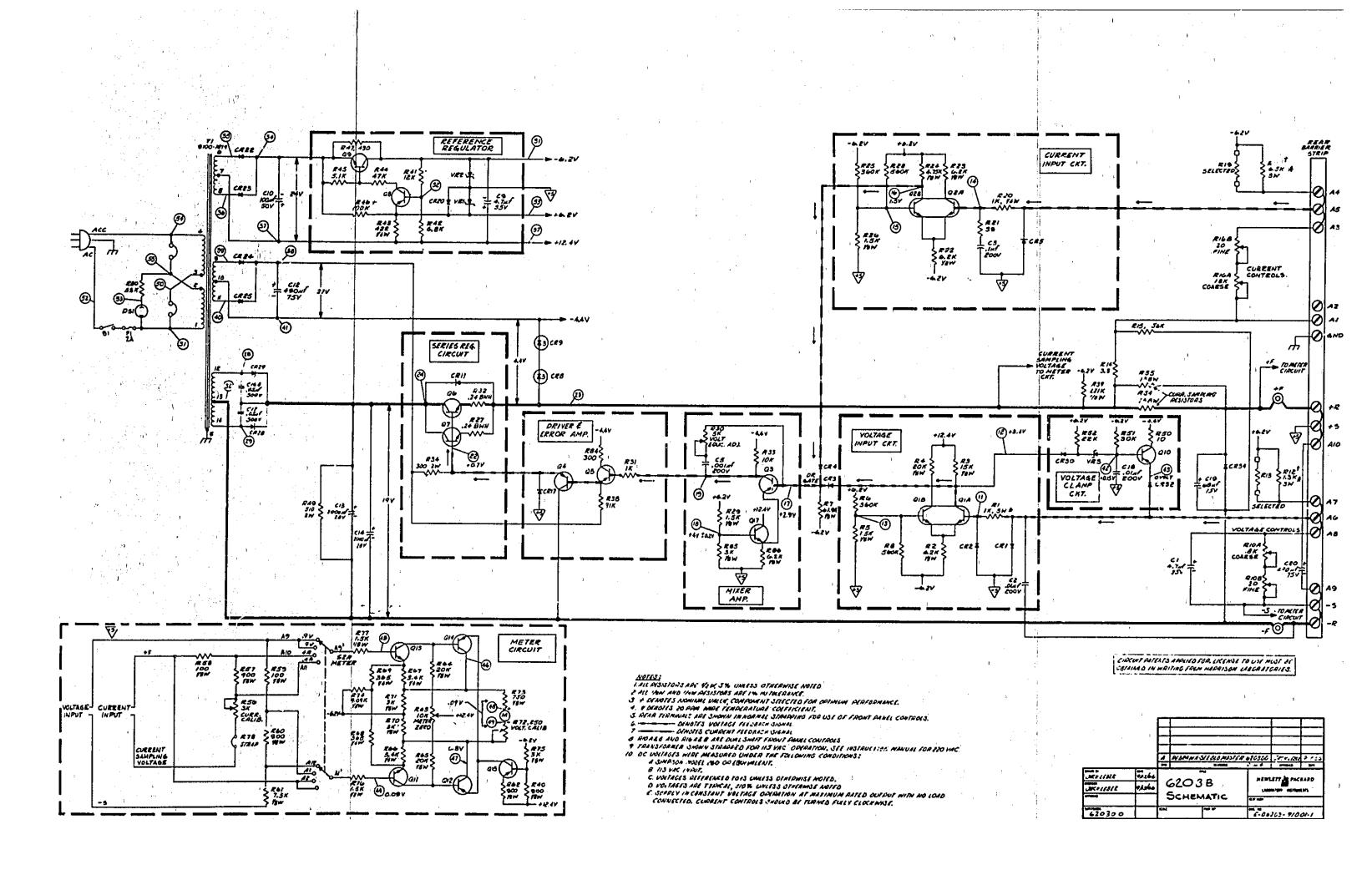


Figure A-1. Model 6203B Overvoltage Protection "Crowbar"



# MANUAL CHANGES Model 6203B DC Power Supply Manual HP Part No. 06203-90001

Make all corrections in the manual according to errata below, then check the following table for your instrument's serial number and enter any listed change(s) in the manual.

i	SER	IAL	MAKE
	Prefix	Number	CHANGES
	All 6K 6K	0251-0560 0561-0815	Errata 1 1,2
	6K 6K 1148A 1927A 2040A	0816-1435 1436-1515 1516-1605 1606-2835 2836-3015 3016-3435	1-3 1-4 1-5 1-7 1-8 1-9
•	2229A 2241A	3436-3465 3466-up	1-10 1-11

#### ERRATA:

On the schematic, change Q3 to PNP. In the parts list, change Q3,5,8,10,12,14,15 to 2N2907A, Sprague, HP Part No. 1853-0099, and rubber bumper (qty 4) to 0403-0002.

In the parts list and on the schematic, change R12 to 1.4k ±5%, 3W 30ppm, HP Part No. 0811-1804. On the schematic, the correct value of R10A is 1.8k.

In Table 1-1, change the INTERNAL IMPE-DANCE AS A CONSTANT VOLTAGE SOURCE (Output Impedance) specification to read: Output Impedance(Typical): Approximated by a 2 milliohm resistance in series with a 1 microhenry inductance.

Effective January 1, 1977, Options 007 (10-turn voltage control) and 008 (10-turn current control) are no longer available individually, but they are still available combined as Option 909. Likewise, Options 013 (10-turn voltage control with decadial) and 014 (19-turn current control with decadial)

are no longer available individually, but they are available combined into a single new option designated Option 015. Make these changes wherever Option 007,008,013, or 014 is mentioned in the manual.

The blue-gray meter bezel has been replaced with a black one, HP Part No. 4040-0414.

The standard colors for this instrument are now mint gray (for front panel) and olive gray (for all other external surfaces). Option X95 designates use of the former color scheme of light gray and blue gray. Option A85 designates use of a light gray front panel with olive gray used for all other external surfaces. New part numbers are shown below:

The front panel binding posts have been changed to a type with better designed insulation. Delete the two types of postalisted on page 6-6 of the parts list and add: black binding post, HP Part No. 1510-0114 (qty 2); and red binding post, HP Part No. 1510-0115 (qty 1).

Change the part number of DS1 to 1450-0566. This new light is more reliable than the former one.

For all instruments delivered on or after July 1, 1978, change the HP Part No. for fuseholder from 1400-0084 to fuseholder body 2110-0564 and fuseholder carrier 2110-0565. Change the HP Part No. for fuseholder nut from 2950-0038 to 2110-0569. If old fuseholder must be replaced for any reason, replace complete fuseholder and n:t with new fuseholder parts. Do not replace new parts with old parts.

	HP PART NUMBER				
DESCRIPTION	STANDARD	OPTION A85	OPTION X95		
Front Panel, Lettered	06203-60004	06203-60001	<b>——</b>		
Heatsink, Rear	5060-7965	4	5060-6120		
Chassis, Right Side	5060-7956	<b></b>	5060-6118		
Chassis, Left Side	5060-7955	<b></b>	5060-6119		
Cover, Top	5000-9424	<b>4</b>	5000-6061		
Rack Kit (accy.)	14523A	14523A-A85	4		

MANUAL CHANGES/MODEL 6203B MANUAL HP PART No. 06203-90001 Page -2-

#### CHANGE 1:

On the Title Page change Serial Number Prefix from "6B" to "6K."

In Figure 4-5 and Paragraph 4-19, change CR31 to VR3 (zener diode).

In Figure 4-6 delete CR6,7 and R29 connected to emitter of Q3 and connect transistor Q17 and associated components as shown on the schematic at the rear of the manual.

In Paragraph 4-21, change "The emitter bias potential for mixer amplifier Q3 is established by voltage divider CR6,7 and R29" to "The emitter bias potential for mixer amplifier Q3 is established by emitter follower Q17."

In Table 5-6, "Selected Semiconductor Characteristics," add VR3, 4.22V, 40mW, HP Part No. 1902-3070, 1N749 Motorola. Delete CR6,7 and CR31.

In the replaceable parts list change: C13,14 to 2000µF, 28V, HP Part No. 0180-1916; C19 to 68µF, 15V; Q4 to MJ2268, HP Part No. 1853-0063; Q9 to 2N3391, G.E., HP Part No. 1854-0071; R29 to 1.5k, 1/8W, HP Part No. 0757-0427; R40,62 to  $900\Omega$ , 1/8W, HP Part No. 0698-6335; R43 to 422 $\Omega$ . 1/4W, HP Part No. 0698-5590; R47 to 470 $\Omega$ , 1/4W, HP Part No. 0686-4715; R54 to  $1\Omega$ , 8W, HP Part No. 0811-2133; and delete CR6,7; CR31 and R48. Also add: Q17 with Q9,11, and 13, HP Part No. 1854-0071; R55, 1Ω, 8W, HP Part No. 0811-2133; R84, 300Ω, 1/2W, HP Part No. 0686-3015; R85, 3k, 1/8W, HP Part 0757-1093; and R86, 6.2k, 1/8W, HP Part No. 0698-5087.

#### CHANGE 2:

In the replaceable parts list change: R63 to 5k potentiometer, HP Part No. 2100-1824; R62 to 7500, 1/8W, HP Part No. 0757-0420; R64 to 12k, 1/8W, HP Part No. 0698-5088; and delete R40.

Delete Q11 and Q13 and replace with a new single differential amplifier (HF Part No. 1854-0221). Circuit references for Q11 and Q13 remain the same with Q11 serving as the "A" side and Q13 the "B" side of the new transistor. All circuit connections to Q11 (A) and Q13 (B) are unchanged on the schematic.

Also add VR4, 4.22V, 400mW, HP Part No. 190 3070. On the schematic (meter circuit) delete R40 and connect VR4 in it place. Anode to base of Q15 and cathode to +12.4V.

## CHANGE 3:

In the replaceable parts list and on the schematic, add R83,  $100\Omega$ , 1/2W, HY Part No. 0686-1015, and connect it between base of Q4 and emitter of Q5.

#### CHANGE 4:

In the replaceable part lists add Terminal Strip, HP Part No. 0360-0401-

## CHANGE 5:

In the replaceable parts list and on the schematic, change power transformer, Tl to HP Part No. 06203-80091.

#### CHANGE 6:

The Serial Prefix of this unit has been changed to 1148A. This is the only change.

#### CHANGE 7:

In Appendix A, Option 11 Replacement Parts Table A-1, change Cr4 from HP Part No. 1884-0031 to 1884-0032.

#### CHANGE 8:

In the parts list, change the HP Part No. for the binding posts and associated hardware to the following:

Red binding post, qty 2, HP Part No. 1510-0091 Terminal lug, qty 1, HP Part No. 0360-0042; Nut, qty 2, HP Part No. 2500-0001; Black binding post, qty 1, HP Part No. 1510-0107; Terminal lug, qty 1, HP Part No. 0360-1190; Nut, qty 3, 2950-0144.

# CHANGE 9:

In the replaceable parts list, change S1 to HP Part No. 3101-2424. On the schematic diagram, change S1 to show two switch sections, one which breaks the AC line (as shown), the other breaks the ACC line.

#### CHANGE '10:

In the replaceable parts list and on the schematic, change Rl0,16 to var. ww 2k 10-turn HP Part No. 21CO-2029, qty 2. Also delete Knob 17/64 insert pointer and Knob 3/16 insert pointer. Add: Knob, round HP Part No. 0370-0137, qty 2. This change eliminates Option 009 because Option 009 is now standard equipment.

#### CHANGE 11:

In the replaceable parts list, change R19 to 150k 2% 1/8W, HP Part No. 0757-0976; and VR2 to 6.2V 2%, HP Part No. 1902-0509.

8-20-82