# OPERATING GUIDE GPIB DC POWER SUPPLIES Agilent Technologies Models 664xA, 665xA, 667xA, and 668xA

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AGILENT Model 6641A: 3217A-00111 and Above *
AGILENT Model 6642A: 3204A-00111 and Above *
AGILENT Model 6643A: 3205A-00111 and Above *
AGILENT Model 6644A: 3213A-00111 and Above *
AGILENT Model 6645A: 3215A-00111 and Above *
AGILENT Model 6651A: 3130A-00171 and Above *
AGILENT Model 6652A: 3201A-00381 and Above *
AGILENT Model 6653A: 3145A-00551 and Above *
AGILENT Model 6654A: 3148A-00391 and Above *
AGILENT Model 6655A: 3152A-00176 and Above *
AGILENT Model 6671A: 3129A-00218 and Above *
AGILENT Model 6672A: 3138A-00101 and Above *
AGILENT Model 6673A: 3138A-00101 and Above *
AGILENT Model 6674A: 3133A-00161 and Above *
AGILENT Model 6675A: 3138A-00101 and Above *
AGILENT Model 6680A: 3302A-00101 and Above *
AGILENT Model 6681A: 3250A-00101 and Above *
AGILENT Model 6682A: 3339A-00101 and Above *
AGILENT Model 6683A: 3339A-00161 and Above *
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AGILENT Model 6684A: 3339A-00101 and Above \*



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<sup>\*</sup> For instruments with higher Serial Numbers, a change page may be included.

### CERTIFICATION

Agilent Technologies certifies that this product met its published specifications at time of shipment from the factory. Agilent Technologies further certifies that its calibration measurements are traceable to the United States National Bureau of Standards, to the extent allowed by the Bureau's calibration facility, and to the calibration facilities of other International Standards Organization members.

### WARRANTY

This Agilent Technologies hardware product is warranted against defects in material and workmanship for a period of three years from date of delivery. Agilent Technologies software and firmware products, which are designated by Agilent Technologies for use with a hardware product and when properly installed on that hardware product, are warranted not to fail to execute their programming instructions due to defects in material and workmanship for a period of 90 days from date of delivery. During the warranty period Agilent Technologies will, at its option, either repair or replace products which prove to be defective. Agilent Technologies does not warrant that the operation of the software, firmware, or hardware shall be uninterrupted or error free.

For warranty service, with the exception of warranty options, this product must be returned to a service facility designated by Agilent Technologies. Customer shall prepay shipping charges by (and shall pay all duty and taxes) for products returned to Agilent Technologies for warranty service. Except for products returned to Customer from another country, Agilent Technologies shall pay for return of products to Customer.

Warranty services outside the country of initial purchase are included in Agilent Technologies' product price, only if Customer pays Agilent Technologies international prices (defined as destination local currency price, or U.S. or Geneva Export price).

If Agilent Technologies is unable, within a reasonable time to repair or replace any product to condition as warranted, the Customer shall be entitled to a refund of the purchase price upon return of the product to Agilent Technologies.

# **LIMITATION OF WARRANTY**

The foregoing warranty shall not apply to defects resulting from improper or inadequate maintenance by the Customer, Customer-supplied software or interfacing, unauthorized modification or misuse, operation outside of the environmental specifications for the product, or improper site preparation and maintenance. NO OTHER WARRANTY IS EXPRESSED OR IMPLIED. Agilent Technologies SPECIFICALLY DISCLAIMS THE IMPLIED WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE.

### **EXCLUSIVE REMEDIES**

THE REMEDIES PROVIDED HEREIN ARE THE CUSTOMER'S SOLE AND EXCLUSIVE REMEDIES. AGILENT TECHNOLOGIES SHALL NOT BE LIABLE FOR ANY DIRECT, INDIRECT, SPECIAL, INCIDENTAL, OR CONSEQUENTIAL DAMAGES, WHETHER BASED ON CONTRACT, TORT, OR ANY OTHER LEGAL THEORY.

### **ASSISTANCE**

The above statements apply only to the standard product warranty. Warranty options, extended support contracts, product maintenance agreements and customer assistance agreements are also available. Contact your nearest Agilent Technologies Sales and Service offices for further information on Agilent Technologies' full line of Support Programs.

# SAFETY SUMMARY

The following general safety precautions must be observed during all phases of operation, service, and repair of this instrument. Failure to comply with these precautions or with specific warnings elsewhere in this manual violates safety standards of design, manufacture, and intended use of the instrument. Agilent Technologies assumes no liability for the customer's failure to comply with these requirements.

### **BEFORE APPLYING POWER.**

Verify that the product is set to match the available line voltage and the correct fuse is installed.

#### GROUND THE INSTRUMENT.

This product is a Safety Class 1 instrument (provided with a protective earth terminal). To minimize shock hazard, the instrument chassis and cabinet must be connected to an electrical ground. The instrument must be connected to the ac power supply mains through a three-conductor power cable, with the third wire firmly connected to an electrical ground (safety ground) at the power outlet. For instruments designed to be hard-wired to the ac power lines (supply mains), connect the protective earth terminal to a protective conductor before any other connection is made. Any interruption of the protective (grounding) conductor or disconnection of the protective earth terminal will cause a potential shock hazard that could result in personal injury. If the instrument is to be energized via an external autotransformer for voltage reduction, be certain that the autotransformer common terminal is connected to the neutral (earthed pole) of the ac power lines (supply mains).

#### FUSES.

Only fuses with the required rated current, voltage, and specified type (normal blow, time delay, etc.) should be used. Do not use repaired fuses or short circuited fuseholders. To do so could cause a shock or fire hazard.

#### DO NOT OPERATE IN AN EXPLOSIVE ATMOSPHERE.

Do not operate the instrument in the presence of flammable gases or fumes.

### KEEP AWAY FROM LIVE CIRCUITS.

Operating personnel must not remove instrument covers. Component replacement and internal adjustments must be made by qualified service personnel. Do not replace components with power cable connected. Under certain conditions, dangerous voltages may exist even with the power cable removed. To avoid injuries, always disconnect power, discharge circuits and remove external voltage sources before touching components.

### DO NOT SERVICE OR ADJUST ALONE.

Do not attempt internal service or adjustment unless another person, capable of rendering first aid and resuscitation, is present.

### DO NOT EXCEED INPUT RATINGS.

This instrument may be equipped with a line filter to reduce electromagnetic interference and must be connected to a properly grounded receptacle to minimize electric shock hazard. Operation at line voltages or frequencies in excess of those stated on the data plate may cause leakage currents in excess of 5.0 mA peak.

### **SAFETY SYMBOLS.**



Instruction manual symbol: the product will be marked with this symbol when it is necessary for the user to refer to the instruction manual (refer to Table of Contents).



Indicates hazardous voltages.



Indicate earth (ground) terminal.



The WARNING sign denotes a hazard. It calls attention to a procedure, practice, or the like, which, if not correctly performed or adhered to, could result in personal injury. Do not proceed beyond a WARNING sign until the indicated conditions are fully understood and met.



The CAUTION sign denotes a hazard. It calls attention to an operating procedure, or the like, which, if not correctly performed or adhered to, could result in damage to or destruction of part or all of the product. Do not proceed beyond a CAUTION sign until the indicated conditions are fully understood and met.

### DO NOT SUBSTITUTE PARTS OR MODIFY INSTRUMENT.

Because of the danger of introducing additional hazards, do not install substitute parts or perform any unauthorized modification to the instrument. Return the instrument to an Agilent Technologies Sales and Service Offices for service and repair to ensure that safety features are maintained.

Instruments which appear damaged or defective should be made inoperative and secured against unintended operation until they can be repaired by qualified service personnel.

### SAFETY SUMMARY (continued)

### GENERAL

Any LEDs used in this product are Class 1 LEDs as per IEC 825-1.

### **ENVIRONMENTAL CONDITIONS**

With the exceptions noted, all instruments are intended for indoor use in an installation category II, pollution degree 2 environment. They are designed to operate at a maximum relative humidity of 95% and at altitudes of up to 2000 meters. Refer to the specifications tables for the ac mains voltage requirements and ambient operating temperature range.

**Exceptions:** Agilent Technologies Models 6680A, 6681A, 6682A, 6683A, 6684A, 6814A, and 6834A are intended for use in an installation category III environment.

# **SAFETY SYMBOL DEFINITIONS**

Symbol	Description	Symbol	Description
===	Direct current	L	Terminal for Line conductor on permanently installed equipment
~	Alternating current	Â	Caution, risk of electric shock
$\sim$	Both direct and alternating current		Caution, hot surface
3~	Three-phase alternating current	$\stackrel{\textstyle \bigwedge}{}$	Caution (refer to accompanying documents)
<u></u>	Earth (ground) terminal	þ	In position of a bi-stable push control
	Protective earth (ground) terminal		Out position of a bi-stable push control
<del></del>	Frame or chassis terminal		On (supply)
N	Terminal for Neutral conductor on permanently installed equipment	0	Off (supply)
	Terminal is at earth potential(Used for measurement and control circuits designed to be operated with one terminal at earth potential.)	9	Standby (supply) Units with this symbol are not completely disconnected from ac mains when this switch is off. To completely disconnect the unit from ac mains, either disconnect the power cord or have a qualified electrician install an external switch.

### Herstellerbescheinigung

Diese Information steht im Zusammenhang mit den Anforderungen der Maschinenläminformationsverordnung vom 18 Januar 1991.

\* Schalldruckpegel Lp <70 dB(A) \* Am Arbeitsplatz \* Normaler Betrieb \* Nach EN 27779 (Typprufung).

### **Manufacturer's Declaration**

This statement is provided to comply with the requirements of the German Sound Emission Directive, from 18 January 1991.

\* Sound Pressure Lp <70 dB(A) \*At Operator Position \* Normal Operation \* According to EN 27779 (Type Test).

according to ISO/IEC Guide 22 and EN 45014

Manufacturer's Name: Agilent Technologies Inc.

Manufacturer's Address: 140 Green Pond Road

Rockaway, New Jersey 07866

U.S.A.

declares that the Product

Product Name: a) Single Output System Power Supply

b) General Purpose Power Supply

Model Number: a) Agilent 6641A, 6642A, 6643A, 6644A, 6645A

b) Agilent 6541A, 6542A, 6543A, 6544A, 6545A

conforms to the following Product Specifications:

Safety: IEC 348:1978 / HD 401S1: 1981 <sup>1</sup>

EMC: CISPR 11:1990 / EN 55011:1991 - Group 1 Class B

IEC 801-2:1991 / EN 50082-1:1992 - 4 kV CD, 8 kV AD

IEC 801-3:1984 / EN 50082-1:1992 - 3 V / m

IEC 801-4:1988 / EN 50082-1:1992 - 0.5 kV Signal Lines

1 kV Power Lines

Supplementary Information:

The product herewith complies with the requirements of the Low Voltage Directive 73/23/EEC and the EMC Directive 89/336/EEC and carries the CE-marking accordingly.

Note 1: The product family was introduced prior to 12/93.

New Jersey January 1997

Location Date Bruce Krueger / Quality Manager

European Contact: Your local Agilent Technologies Sales and Service Office or Agilent Technologies GmbH, Department TRE, Herrenberger Strasse 130, D-71034 Boeblingen (FAX:+49-7031-14-3143)

according to ISO/IEC Guide 22 and EN 45014

Manufacturer's Name: Agilent Technologies Inc.

Manufacturer's Address: 140 Green Pond Road

Rockaway, New Jersey 07866

U.S.A.

declares that the Product

Product Name: a) Single Output System Power Supply

b) General Purpose Power Supply

Model Number: a) Agilent 6651A, 6652A, 6653A, 6654A, 6655A

b) Agilent 6551A, 6552A, 6553A, 6554A, 6555A

conforms to the following Product Specifications:

Safety: IEC 348:1978 / HD 401S1: 1981 <sup>1</sup>

EMC: CISPR 11:1990 / EN 55011:1991 - Group 1 Class B

IEC 801-2:1991 / EN 50082-1:1992 - 4 kV CD, 8 kV AD

IEC 801-3:1984 / EN 50082-1:1992 - 3 V / m

IEC 801-4:1988 / EN 50082-1:1992 - 0.5 kV Signal Lines

1 kV Power Lines

Supplementary Information:

The product herewith complies with the requirements of the Low Voltage Directive 73/23/EEC and the EMC Directive 89/336/EEC and carries the CE-marking accordingly.

Note 1: The product family was introduced prior to 12/93.

New Jersey January 1997
Location Date

Bruce Krueger / Quality Manager

European Contact: Your local Agilent Technologies Sales and Service Offices or Agilent Technologies GmbH, Department TRE, Herrenberger Strasse 130, D-71034 Boeblingen (FAX:+49-7031-14-3143)

according to ISO/IEC Guide 22 and EN 45014

Manufacturer's Name: Agilent Technologies Inc.

Manufacturer's Address: 140 Green Pond Road

Rockaway, New Jersey 07866

U.S.A.

declares that the Product

Product Name: a) Single Output System Power Supply

b) General Purpose Power Supply

a) Agilent 6671A, 6672A, 6673A, 6674A, 6675A Model Number:

b) Agilent 6571A, 6572A, 6573A, 6754A, 6575A

conforms to the following Product Specifications:

IEC 348:1978 / HD 401S1: 1981 1 Safety:

CISPR 11:1990 / EN 55011:1991 - Group 1 Class B EMC:

IEC 801-2:1991 / EN 50082-1:1992 - 4 kV CD, 8 kV AD

IEC 801-3:1984 / EN 50082-1:1992 - 3 V / m

IEC 801-4:1988 / EN 50082-1:1992 - 0.5 kV Signal Lines

1 kV Power Lines

Supplementary Information:

The product herewith complies with the requirements of the Low Voltage Directive 73/23/EEC and the EMC Directive 89/336/EEC and carries the CE-marking accordingly.

Note 1: The product family was introduced prior to 12/93.

January 1997 New Jersey

Location Bruce Krueger / Quality Manager Date

European Contact: Your local Agilent Technologies Sales and Service Offices or Agilent Technologies GmbH, Department TRE, Herrenberger Strasse 130, D-71034 Boeblingen (FAX:+49-7031-14-3143)

according to ISO/IEC Guide 22 and EN 45014

Manufacturer's Name: Agilent Technologies Inc.

Manufacturer's Address: 140 Green Pond Road

Rockaway, New Jersey 07866

U.S.A.

declares that the Product

Product Name: Single Output System Power Supply

Model Number: Agilent 6680A, 6681A, 6682A, 6683A, 6684A

conforms to the following Product Specifications:

Safety: IEC 348:1978 / HD 401S1: 1981 <sup>1</sup>

EMC: CISPR 11:1990 / EN 55011:1991 - Group 1 Class A

IEC 801-2:1991 / EN 50082-1:1992 - 4 kV CD, 8 kV AD

IEC 801-3:1984 / EN 50082-1:1992 - 3 V / m

IEC 801-4:1988 / EN 50082-1:1992 - 0.5 kV Signal Lines 1 kV Power Lines

Supplementary Information:

The product herewith complies with the requirements of the Low Voltage Directive 73/23/EEC and the EMC Directive 89/336/EEC and carries the CE-marking accordingly.

Note 1: The product family was introduced prior to 12/93.

New Jersey January 1997

Location Date Bruce Krueger / Quality Manager

European Contact: Your local Agilent Technologies Sales and Service Office or Agilent Technologies GmbH, Department TRE, Herrenberger Strasse 130, D-71034 Boeblingen (FAX:+49-7031-14-3143)

### PRINTING HISTORY

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Edition 1 - November, 1993 Edition 2 - March, 1995 Reprinted - April 2000

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# **General Information**

# Introduction

Two guides are shipped with your power supply - an Operating Guide (this document) and a Programming Guide. You will find information on the following tasks in these guides:

# **Quick Document Orientation**<sup>1</sup>

Location
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# **Safety Considerations**

This power supply is a Safety Class 1 instrument, which means it has a protective earth terminal. That terminal must be connected to earth ground through a power source equipped with a 3-wire ground receptacle. Refer to the Safety Summary page at the beginning of this guide for general safety information. Before installation or operation, check the power supply and review this guide for safety warnings and instructions. Safety warnings for specific procedures are located at appropriate places in the guide.

### Instrument Identification

The power supply is identified by a unique two-part serial number, such as, 3343A-00177. The first part, or prefix, is a number-letter combination that provides the following information:

- 3343 = The year and week of manufacture or last significant design change. Add 1960 to the first two digits to determine the year. For example, 32=1992, 33=1993, etc. The last two digits specify the week of the year (43 = the 43rd week).
- A = The letter indicates the country of manufacture, where A = USA.

# **Options**

**List of Options** 

Option	Description	Used with Agilent Series			
•	•		665xA	667xA	668xA
100	Input power 100 Vac, nominal	X	X		
200	Input power 200 Vac, nominal			X	
220	Input power 220 Vac, nominal	X	X		
240	Input power 240 Vac, nominal	X	X		
400	Input power 360-440 Vac, 3 -phase				X
601	Output connector kit required for bench applications				X
602	Bus bar spacers for paralleling power supplies				X
831	Power cord, 12 AWG, UL listed, CSA certified, without plug			X	
832	Power cord, 4 mm <sup>2</sup> , harmonized, without plug			X	
834	Power cord, 10 AWG, UL listed, CSA certified, without plug			X	
841	Power cord, 12 AWG, UL listed, CSA certified, with NEMA 6-20P 20A/250V plug			Х	
842	Power cord, 4 mm <sup>2</sup> , harmonized, with IEC 309 32A/220V plug			х	
843	Power cord, 12 AWG, UL listed, CSA certified, with JIS C8303 25A/250V plug			X	
844	Power cord, 10 AWG, UL listed, CSA certified, with NEMA L6-30P-30A/250V locking plug			Х	
861	Power cord, 10 AWG, UL listed, 300 V, CSA certified, without plug				х
862	Power cord, 2.5 mm <sup>2</sup> , 4-wire, harmonized, without plug				Х
908	Rack mount kit (Agilent 5062-3974)	Х			
	Rack mount kit (Agilent 5062-3977) <b>Support rails (E3663A)</b> are required.		Х	Х	
	Rack mount kit (Agilent 5062-3977 & 5062-3974) Support rails (E3663A) are required.				X

**List of Options (continued)** 

Option	Description	Used with Agilent Series			
-	·		665xA	667xA	668xA
909	Rack mount kit with handles (Agilent 5062-3975)	X			
909	Rack mount kit with handles (Agilent 5062-3983) <b>Support</b> rails (E3663A) are required.		X	Х	
	Rack mount kit with handles (Agilent 5062-3983 & 5062-3974) <b>Support rails (E3663A) are required.</b>				X
910	Service manual with extra Operating and Programming Guides	X	X	Х	X
ABD	Quick-Start Guide German	X	X	X	X
ABE	Quick-Start Guide, Spanish	X	X	Х	X
ABF	Quick-Start Guide, French	X	X	X	X
ABJ	Operating Manual, Japanese	X	X	X	X
ABZ	Quick-Start Guide, Italian	X	X	X	X
AB0	Quick-Start Guide, Taiwanese	X	X	X	Х

# Accessories

## **List of Accessories**

Description Agilent No.	Agilent No.		
Fuse replacement kit for Series 668xA			
16 AM for 360-440 Vac, 3-phase line	5060-3512		
30 AM for 180-235 Vac, 3-phase line	5060-3513		
GPIB cable (all models)			
0.5 meters (1.6 ft)	10833D		
1.0 meter (3.3 ft)	10833A		
2.0 meters (6.6 ft)	10833B		
4.0 meters (13.2 ft)	10833C		
Serial link cable (all models)			
2.0 meters (6.6 ft)	5080-2148		
Slide mount kit			
heavy duty, for Series 667xA/668xA	1494-0058		
standard, for Series 664xA/665xA	1494-0059		

# **Description**

These units form a family of unipolar, GPIB programmable power supplies organized as follows:

Power	Models
200 W	AGILENT 6641A, 6642A, 6643A, 6644A, 6645A
500 W	AGILENT 6651A, 6652A, 6653A, 6654A, 6655A
2000 W	AGILENT 6671A, 6672A, 6673A, 6674A, 6675A
5000 W	AGILENT 6680A, 6681A, 6682A, 6683A, 6684A
	200 W 500 W 2000 W

Each power supply is programmable locally from the front panel or remotely via a rear-panel analog control port.

Operational features include:

- Constant voltage (CV) or constant current (CC) output over the rated output range.
- Built-in overvoltage (OV), overcurrent (OC), and overtemperature (OT) protection.
- Automatic turn-on selftest.
- Pushbutton nonvolatile storage and recall of up to 5 operating states (4 in Series 668xA supplies).
- Local or remote sensing of output voltage.
- Auto-parallel operation for increased total current.
- Series operation for increased total voltage.
- Analog input for remote programming of voltage and current.
- Voltage output for external monitoring of output current.
- User calibration from the front panel.

### **Front Panel Programming**

The front panel has both rotary (RPG) and keypad controls for setting the output voltage and current. The panel display provides digital readouts of the output voltage and current. Other front panel controls permit:

- Enabling or disabling the output.
- Setting the overvoltage protection (OVP) trip voltage.
- Enabling or disabling the overcurrent protection (OCP) feature.
- Saving and recalling operating states.
- Setting the GPIB address.
- Reading GPIB error message codes.
- Calibrating the power supply, including changing the calibration protection password.

### **Remote Programming**

The power supply may be remotely programmed via the GPIB bus and/or from an analog input port. GPIB programming is with SCPI (Standard Commands for Programmable Instruments) commands that make the power supply programs compatible with those of other GPIB instruments. (A software-controlled Compatibility Mode also permits programming in the command set of the Agilent 6030xA Autoranging Series.) In addition to control functions, SCPI programming permits writing to the front panel LCD and complete calibration functions. Power supply status registers permit remote monitoring of the following conditions:

- Overvoltage, overcurrent, overtemperature, and unregulated states.
- Operating mode (constant voltage or constant current).
- State of the RI (remote inhibit) input signal.
- Power-on status (PON).
- Status of the output queue (QYE).
- Pending triggers (WTG).
- GPIB interface programming errors (CME, DDE, and EXE).
- Calibration state (enabled or disabled).

The status registers can be programmed to generate an output fault signal (FLT) upon the occurrence of one or more selected status events.

### **Analog Programming**

The power supply has an analog port for remote programming. The output voltage and/or current of the power supply may be controlled by individual d-c programming voltages applied to this port. The port also provides a monitor output that supplies a d-c voltage proportional to the output current.

### **Output Characteristic**

### General

The power supply can operate in either CV (constant voltage) or CC (constant current) over its voltage and current ratings (see Table 1-1). The operating locus is shown by the Output Characteristic Curve in Table 1-2. The operating point is determined by the voltage setting (V<sub>s</sub>), the current setting (I<sub>s</sub>), and the load impedance. Two operating points are shown. Point 1 is defined by the load line cutting the operating locus in the constant-voltage region. This region defines the CV mode. Point 2 is defined by the load line cutting the operating locus in the constant-current region. This region defines the CC mode.

### **Downprogramming**

The power supply can sink current for more rapid down programming in the CV mode. For Series 664xA and 665xA supplies, this capability is defined by the second quadrant area (-I<sub>s</sub>) of the Output Characteristic Curve. These supplies can sink about 20% of their maximum rated positive output current. For Series 667xA and 668xA power supplies, this is an uncharacterized current-sinking area that provides a limited downprogramming capability.

# **Specifications and Supplemental Characteristics**

Tables 1-1 through 1-4 list the specifications and supplemental characteristics for the Series 664xA, 665xA, 667xA, and 668xA power supplies. The organization is as follows:

Series	Specifications	Characteristics
6641A-6645A	Table 1-la	Table 1-lb
6651A-6655A	Table 1-2a	Table 1-2b
6671A-6675A	Table 1-3a	Table 1-3b
6680A-6684A	Table 1-4a	Table 1-4b

**Specifications** are performance parameters warranted over the specified temperature range.

Supplemental Characteristics are not warranted but are descriptions of performance determined either by design or type testing.

	Table 1-1a. Pe	rformance Spec	ifications for	Series 664xA	1	
Paramet	er		Agilent	Model Numb	er	
		6641A	6642A	6643A	6644A	6645A
Output Ratings						
Voltage:		0 - 8 V	0 - 20 V	0 - 35 V	0 - 60 V	0 - 120 V
Current:@ 40°C		0 - 20 A	0 - 10 A	0 - 6 A	0 - 3.5 A	0 - 1.5 A
Current:@ 50°C		0 - 18 A	0 - 9 A	0 - 5.4 A	0 - 3.2 A	0 - 1.4 A
Current:@ 55°C		0 - 17 A	0 - 8.5 A	0 - 5.1 A	0 - 3.0 A	0 -1.4 A
currence ce		0 1,11	0 0.011	0 01111	0 0.011	0 11.11
Programming Accuracy	(@ 25 + 5 °C)		I	l	I	
Voltage:	0.06% +	5 mV	10 mV	15 mV	26 mV	51 mV
v ortuge.	0.0070	3 m v	10 111 4	13 111 4	20 111 1	31 111 4
Current:	0.15 % +	26 mA	13 mA	6.7 mA	4.1 mA	1.7 mA
Current.	0.15 /0 1	20 1111 1	13 11111	0.7 1111 1	7.1 1112 \$	1.7 1112 \$
Ripple & Noise (from 20	Hz to 20 MHz witl	n outnuts unground	led or with eith	er output termin	al grounded)	
Constant Voltage:	rms	300 μV	300 μV	400 μV	500 μV	700 μV
Constant Voltage:		3 mV	3 mV	400 μV 4 mV	5 mV	700 μ V
Constant Voltage.  Constant Current:	p-p rms	10 mA	5 mA	3 mA	1.5 mA	1 mA
Constant Current.	11115	10 IIIA	JIIIA	JIIIA	1.5 IIIA	1 IIIA
Doodbook Agamagy (fro	m front nand or ov	or CDID with room	l	 tout @ 25 ±:5 %	C)	
Readback Accuracy (fro	0.07% +		15 mV	1 25 mV		80 mV
Voltage:		6 mV			40 mV	
+Current	0.15% +	18 mA	9.1 mA	5 mA	3 mA	1.3 mA
-Current	0.35% +	40 mA	20 mA	12 mA	6.8 mA	2.9 mA
I and Dan dark and dark			1 . 1			
Load Regulation (chang	e in output voitage (				1 4 37	F 37
Voltage		1 mV	2 mV	3 mV	4 mV	5 mV
Current:		1 mA	0.5 mA	0.25 mA	0.25 mA	0.25 mA
Line Regulation (change	in output voltage o	r current for any li	na changa withi	n retings		
Voltage:	in output voltage o	0.5 mV	0.5 mV	1 mV	1 mV	2 mV
Current:		1 mA	0.5 mA	0.25 mA	0.25 mA	0.25 mA
Current:		I IIIA	0.5 IIIA	0.23 IIIA	0.23 IIIA	0.23 IIIA
Transient Response Tin	o (for the output vo	Itaga to recover to	ite provious los	al (within 0.19/	of the roted vo	ltage or
20 mV, whichever is grea						ntage of
20 m v, whichever is grea	ici) ionowing any s	step change in load	current up to 3	0 /0 Of the fateur	current.	
	1			< 100 µs		
AC Input Ratings (selec	stable vie internal er	vitahing saa Amas	ndiv P)	< 100 μs		
	table via internai sv 	vitching - see Appe	ciluix b)			
Nominal line voltage				120/ +60/		
100,120,220,240 Vac:				13%, +6 %		
230 Vac:			=.	10%, +10%		
Frequency range:				47-63 Hz		
Output Terminal	Icolotion		240 Vda (mayir	mum from oboo	sis amound)	
Output Terminal	1501811011		240 vuc (maxii	num, from chas	sis ground)	
	Notes: <sup>1</sup> For 9	Supplemental Char	acteristics, see '	Table 1-1b.		
	1,0105. 101	Supplemental Char	actoristics, 500	1 4010 1 10.		

Parameter	,		Agile	nt Model Num	ber	
i didiliotoi		6641A	6642A	6643A	6644A	6645A
Output Programming Ra	ange (maximum			00.001		1 00.021
Voltage:		8.190 V	20.475 V	35.831 V	61.425 V	122.85 V
Current:		20.475 A	10.237 A	6.142 A	3.583 A	1.535 A
Overvoltage Protection	(OVP):	8.8 V	22.0 V	38.5 V	66.0 V	132.0 V
Average Resolution						
Voltage:		2  mV	5 mV	10 mV	15 mV	30 mV
Current:		6 mA	3 mA	2 mA	1.2 mA	0.5 mA
Overvoltage Protection	(OVP):	13 mV	30 mV	54 mV	93 mV	190 mV
Accuracy						
Overvoltage Protection Analog Programming (		160 mV	400 mV	700 mV	1.2 V	2.4 V
	0.36% +	6 mV	15 mV	27 mV	45 mV	90 mV
Analog Programming (						
	7.6% +	18 mA	9.2 mA			
	1.5% +			5.5 mA	3.2 mA	1.4 mA
Current Monitor (+IM):						
,	7.7% +	65 mA	32 mA			
	1.6 % +			8.1 mA	7.1 mA	1.8 mA
*Referenced to supply out						
Drift Temperature Stabi	•	30-minute war	mup, change in	output over 8 ho	urs under cons	tant line, load
and ambient temperature)				F		,
Voltage:	0.02% +	0.4 mV	1 mV	2 mV	3 mV	6 mV
<b>Current:</b>	0.02% +	16 mA	6 mA	3 mA	2 mA	1 mA
Temperature Coefficient	s (change per °C	C)				
Voltage:	60 ppm +	0.1 mV	0.2 mV	0.3 mV	0.5 mV	1.1 mV
+Current:	95 ppm +	0.82 mA	0.41 mA	0.18 mA	0.12 mA	0.04 mA
Voltage Readback:	60 ppm +	0.2 mV	0.5 mV	0.75 mV	1.3 mV	2.6 mV
+Current Readback:	95 ppm +	1.2 mA	0.62 mA	0.33 mA	0.20 mA	0.08 mA
Current Readback:	110 ppm +	1.2 mA	0.62 mA	0.33 mA	0.20 mA	0.08 mA
Overvoltage Protection	(OVP):					
	200 ppm +	1.6 mV	3.3 mV	5 mV	13 mV	24 mV
<b>Analog Programming (V</b>						
	60 ppm +	0.1  mV	0.25 mV	0.4 mV	0.7 mV	1.25 mV
<b>Analog Programming (I</b>						
	90 ppm +	0.56 mA	0.28 mA	0.17 mA	0.1 mA	0.04 mA
Current Monitor (+IM)						
	75 ppm +	0.61 mA	0.3 mA	0.06 mA	0.06 mA	0.02 mA
Maximum Input Power:	·		480 VA; 40	00 W, 60 W with	n no load	
		•	•			•

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Table 1-lb. Supplemental Characteristics for Series 664xA (continued)

Table 1-lb. Supplemental Char	acteristics				
Parameter			nt Model Nu		
	6641A	6642A	6643A	6644A	6645A
Maximum AC Line Current Ratings					
100 Vac nominal:			4.4 A rms		
120 Vac nominal:			3.8 A rms		
220 Vac nominal:			2.2 A rms		
230 Vac nominal:			2.1 A rms		
240 Vac nominal:			2.0 A rms		
Maximum Reverse Bias Current:			plied and the		
			source, the si		
			ge a current e	qual to its ou	tput
	current ratio	ng (see Table	: 1- 1a).		
Remote Sensing Capability	** 1/0				
Voltage Drop Per Lead:	Up to 1/2 o	f rated output	t voltage.		
Load Regulation:	Add 3 mV	to spec (see T	Table 1-la) for	each l-volt c	hange in
			load current of		8-
Load Voltages	C1-44	14	1 1	:C:-1	
Load Voltage:	voltage rati		load leads fro	om specified	output
Command Processing Time (Average time for output			eint of digital	data when th	ne supply
is connected directly to the GPIB Bus):	voltage to ent	inge unter ree	cipt of digital	data when the	ic suppry
to connected directly to the C112 2 do).			20 ms		
<b>Downprogrammer Current Capability</b> (± 15%):					
1 0 ,	5.8 A	2.5 A	1.5 A	0.9 A	0.75 A
Output Voltage Programming Response Time		-	4.		•
Rise/Fall Time (time for output to change from 90 %	to 10% or fro	om 10% to 90	% of its total	excursion):	
	1				
	<15 ms	<b>50</b> / . 1	1	c. 1 1 )	
Settling Time (time for output change to settle within	1 LSB (0.02	5% x rated vo	oitage) of its i	inai vaiue):	
	<60 ms				
Monotonicity:		onotonic ove	er entire rated	voltage, curi	ent, and
•	temperature			<i>Q</i> ,	,
Auto-Parallel Configuration:		Up to	3 identical m	odels	
Analog Programming (IP & VP)					
Input Signal:*			0 to -5 V		
Input Impedance:		10	$0 \text{ k}\Omega$ , nomina	a1	
*Signal source must be isolated.		1	o Auu, HOHHIIC	41	
Current Monitor Output (+IM):	0 to -5 V re	presents zero	to full-scale	current outpu	ıt
Savable States		_	(O.1 1.1		
Nonvolatile Memory Locations:			( 0 through 4		
Nonvolatile Memory Write Cycles:		4	0,000, typica	1	
Prestored State (factory default):			Location 0		
1					
<b>Notes</b> : <sup>1</sup> For Performanc	e Specification	ons, see Table	: 1-la.		

Table 1-1b. Supplemental Characteri Parameter	000 101 001		Models	<i>,</i>	
Digital Port Characteristics			Table 1-5)		
GPIB Interface Capabilities		(see T	Table 1-5)		
Serial Link Capabilities		(see ]	Table 1-5)		
Recommended Calibration Interval:		1	year		
Safety Compliance		CSA 22.2 N	J. 221 IEC	1 2 4 0	
Complies with: Designed to comply with:		CSA 22.2 N UI	No.231,1EC L 1244	. 340	
RFI Suppression (complies with):		CISPR-II, C	Group 1, Cl	ass B	
Dimensions Width: Height (including removable feet): Depth (including safety cover):		88.1 n	m (16.75 in nm (3.5 in) m (17.3 in)		
Note 1: For Performance Spe	ecifications, se	ee Table 1-la.:			
Net: Shipping:  Output Characteristic Curve:	14.2 kg (31.4 16.3 kg (36 lb	o)	vimnum Da	ted Outp	4
Vmax			kimum Ra		uા -lout
Vs CV Ope	erating Line	Agilent Model	Vout	lout	
		6641A	8 V	20 A	5.8 A
1/ 1/		6642A	20 V	10 A	2.5 A
	Ĺ	6643A	35 V	6 A	1.5 A
	Į	6644A	60 V	3.5 A	0.9 A
		6645A	120 V	1.5 A	0.75 A
-lout Is Imax	Operating Line				AG-R.GU
Notes: <sup>1</sup> For Performance Spe	ecifications, se	ee Table 1-la.			

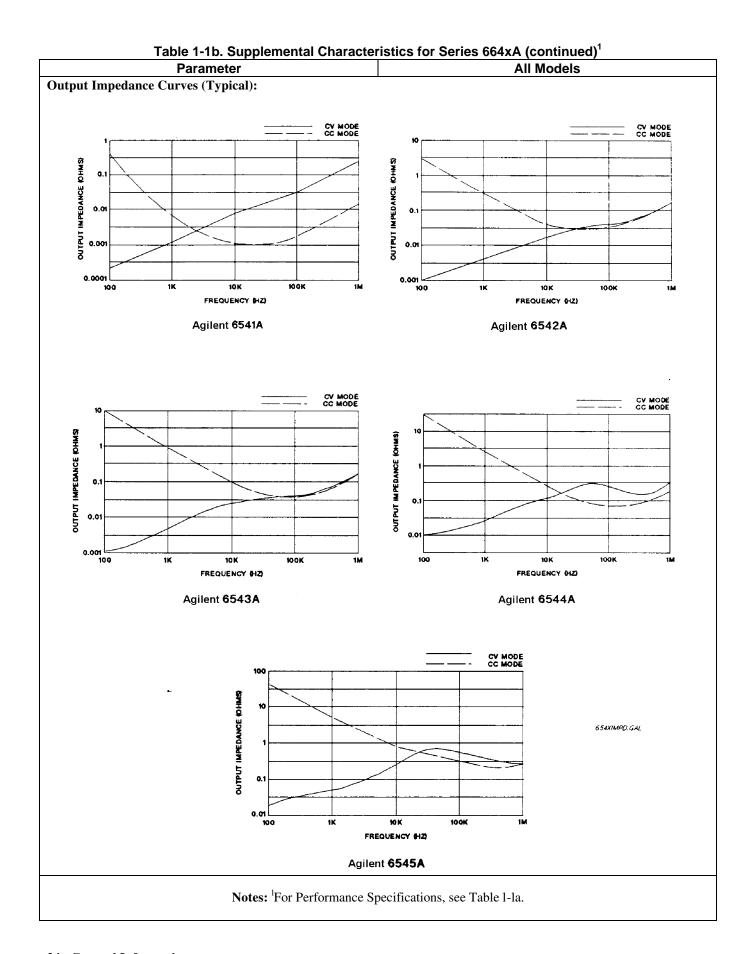


Table 1-2a. Performance Specifications for Series 665xA<sup>1</sup>

Table 1-2a. i	Performance Spec				
Parameter		Agilent	<b>Model Numb</b>	er	
	6651A	6652A	6653A	6654A	6655A
Output Ratings					
Voltage:	0 - 8 V	0 - 20 V	0- 35 V	0 - 60 V	0 - 120 V
Current:@ 40°C	0 - 50 A	0 - 25 A	0 - 15 A	0 - 9 A	0 - 4 A
Current:@ 50°C	0 - 45 A	0 - 22.5 A	0 - 13.5 A	0 - 8.1 A	0 - 3.6 A
Current:@ 55°C	0 - 42.5 A	0 - 21.3 A	0 - 12.8 A	0 - 7.7 A	0 -3.4 A
Current. w 22 C	0 .2.011	0 21.011	0 12.011	0 717 11	
<b>Programming Accuracy</b> (@ 25 ± 5 °C)					
Voltage: 0.06% +	5 mV	10 mV	15 mV	26 mV	51 mV
voitage: 0.0070	3 m v	10 111 4	15 111 4	20 111 V	31 111 4
<b>Current:</b> 0 . 15 % +	60 mA	25 mA	13 mA	8 mA	4 mA
Current. 0.13 /0 1	00 IIIA	23 11174	13 1117	o IIIA	4 111/4
Ripple & Noise (from 20 Hz to 20 MHz w	ith outputs ungroups	lad or with aith	l or output tornin	al grounded)	
		i e			700
Constant Voltage: rms	300 μV	300 μV	400 μV	500 μV	700 μV
Constant Voltage: p-p	3 mV	3 mV	4 mV	5 mV	7 mV
Constant Current: rms	25 mA	10 mA	5 mA	3 mA	2 mA
	CDTD 1.1	1	27.170	<u>a</u> ,	
Readback Accuracy (from front panel or			ř –	1	1
<b>Voltage:</b> 0.07% +	6 mV	15 mV	25 mV	40 mV	80 mV
+Current 0.15% +	67 mA	26 mA	15 mA	7 mA	3 mA
-Current 0.35% +	100 mA	44 mA	24 mA	15 mA	7 mA
		1			
Load Regulation (change in output voltage	•		1	l	1
Voltage:	1 mV	2 mV	3 mV	4 mV	5 mV
Current:	2 mA	1 mA	0.5 mA	0.5 mA	0.5 mA
Line Regulation (change in output voltage		_	_	1	1
Voltage:	0.5 mV	0.5 mV	1 mV	1 mV	2 mV
Current:	2 mA	1 mA	0.75 mA	0.5 mA	0.5 mA
Transient Response Time (for the output					ltage or
20 mV, whichever is greater) following an	y step change in load	current up to 50	0% of the rated	current.	
	1				
			< 100 µs		
AC Input Ratings (selectable via internal	switching - see Appe	endix B)			
Nominal line voltage					
100,120,220,240 Vac:			13%, +6 %		
230 Vac:			10%, +10%		
Frequency range:			47-63 Hz		
<b>Output Terminal Isolation</b>	<u>+</u>	240 Vdc (maxir	num, from chas	sis ground)	
1					
Notes: <sup>1</sup> Fo	r Supplemental Char	acteristics, see	Γable 1-2b.		

Table 1-2b. Supplemental Characteristics for Series 665xA<sup>1</sup>

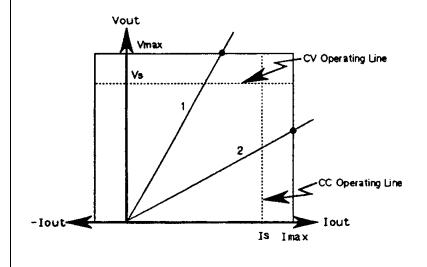
Parameter				65xA <sup>1</sup>	
		Agile	nt Model Num	ıber	
	6651A	6652A	6653A	6654A	6655A
Output Programming Range (maximu	m programmable	values)	1	1	1
Voltage:	8.190 V	20.475 V	35.831 V	61.425 V	122.85 V
Current:	51.188 A	25.594 A	15.356 A	9.214 A	4.095 A
Overvoltage Protection (OVP):	8.8 V	22.0 V	38.5 V	66.0 V	132.0 V
Average Resolution					
Voltage:	2 mV	5 mV	10 mV	15 mV	30 mV
Current:	15 mA	7 mA	4 mA	2.5 mA	1 mA
Overvoltage Protection (OVP):	13 mV	30 mV	54 mV	93 mV	190 mV
Accuracy					
Overvoltage Protection (OVP):* Analog Programming (VP):*	160 mV	400 mV	700 mV	1.2 V	2.4 V
0.36% +	6 mV	15 mV	27 mV	45 mV	90 mV
Analog Programming (IP):* 7% +	75 mA	31 mA	16 mA	8 mA	5 mA
Current Monitor (+IM):*					
7% +	730 mA	400 mA	120 mA	80 mA	75 mA
*Referenced to supply output					
Drift Temperature Stability (following	g a 30-minute war	mup, change in	output over eigh	t hours under o	constant line,
load, and ambient temperature)					
<b>Voltage:</b> 0.02% +	0.4 mV	1 mV	2 mV	3 mV	6 mV
<b>Current:</b> 0.02% +	40 mA	15 mA	8 mA	5 mA	2.5 mA
Temperature Coefficients (change per	°C)				
Voltage: 60 ppm +		0.2 mV	0.3 mV	0.5 mV	1.1 mV
<b>+Current:</b> 90 ppm +		0.7 mA	0.3 mA	0.2 mA	0.2 mA
<b>Voltage Readback:</b> 60 ppm +		0.5 mV	0.75 mV	1.3 mV	2.6 mV
<b>+Current Readback:</b> 90 ppm +		0.9 mA	0.5 mA	0.3 mA	0.2 mA
-Current Readback: 105 ppm +	1.7 mA	0.9 mA	0.5 mA	0.3 mA	0.2 mA
Overvoltage Protection (OVP):					
200 ppm +	1.6 mV	3.3 mV	5 mV	13 mV	24 mV
<b>Analog Programming (VP):</b>					
60 ppm +	0.1 mV	0.25 mV	0.4 mV	0.7 mV	1.25 mV
<b>Analog Programming (IP):</b>					
90 ppm +	1.4 mA	0.7 mA	0.3 mA	0.2 mA	0.15 mA
<b>Current Monitor (+IM):</b>					
80 ppm +	1.4 mA	0.7 mA	0.3 mA	0.2 mA	0.15 mA
		1200 374. 11	00 W, 120 W w	ith no load	
Maximum Input Power		1360 VA; 11	.00 W, 120 W W	itii iio ioau	
Maximum Input Power	 <sup>1</sup> For Performance			illi ilo ioad	

Table 1-2b. Supplemental Cha	racteristics				
Parameter	00544		nt Model Nu	•	00554
M I AGII G AD I	6651A	6652A	6653A	6654A	6655A
Maximum AC Line Current Ratings		12.4	(15 A)	T.C	
100 Vac nominal:			A rms (15 AM A rms (12 AM		
120 Vac nominal: 220 Vac nominal:			`		
230 Vac nominal:			A rms (7 AM A rms (7 AM		
240 Vac nominal:			A mis (7 AM A rms (7 AM		
Maximum Reverse Bias Current:	With AC in	nput power ap			*******
Waximum Reverse Dias Current:		n external dc	-		
		vithout dama			
		ng (see Table	-	quar to its of	приг
Remote Sensing Capability	Current rati	ing (see Table	1 2u).		
Voltage Drop Per Lead:	Up to 1/2 o	f rated output	t voltage.		
, orange 210p 101 20mm	op to 1/2 o	Trace o depart	e voluge.		
Load Regulation:	Add 3 mV	to spec (see T	Table 1-2a) for	r each l-volt	change in
		t lead due to			
	1			S	
Load Voltage:	Subtract vo	ltage drop in	load leads fro	om specified	output
	voltage rati			-	•
Command Processing Time (Average time for output	voltage to cha	ange after rec	eipt of digital	l data when t	he supply
is connected directly to the GPIB Bus):					
			20 ms		
<b>Downprogrammer Current Capability</b> (± 15%):					
	11.6 A	5 A	3 A	1.8 A	1.5 A
<b>Output Voltage Programming Response Time</b>			·		
Rise/Fall Time (time for output to change from 90 %	to 10% or fro	om 10% to 90	% of its total	excursion):	
	1				
			<15 ms		
<b>Settling Time</b> (time for output change to settle within	n 1 LSB (0.02	5% x rated vo	oltage) of its i	final value):	
	1				
37			<60 ms		
Monotonicity:	-	nonotonic ove	er entire rated	voltage, cur	rent, and
A. A. D II. I. C C	temperature		2:1	. 1.1.	
Auto-Parallel Configuration:		Up to	3 identical m	iodeis	
Analog Programming (IP & VP)					
Input Signal:*			0 to -5 V		
Input Impedance:		1,	0 kΩ, nomina	.1	
*Signal source must be isolated.		1,	O KS2, HOHIIII	11	
Current Monitor Output (+IM):	O to 5 V re	presents zero	to full scale	current outp	t
Current Monton Output (*1111).	010-5 116	presents zero	to full-scale	carrent outp	uı.
Savable States					
Nonvolatile Memory Locations:		5	(0 through 4	(-)	
Nonvolatile Memory Write Cycles:			0,000, typica		
Prestored State (factory default):		'	Location 0		
	·				
<b>Notes</b> : <sup>1</sup> For Performance	e Specification	ns, see Table	1-2a.		

Table 1-2b. Supplemental Characteristics for Series 665xA (continued)<sup>1</sup>

Parameter	All Models
Digital Port Characteristics	(see Table 1-5)
<b>GPIB Interface Capabilities</b>	(see Table 1-5)
Serial Link Capabilities	(see Table 1-5)
Recommended Calibration Interval:	1 year
Safety Compliance	
Complies with:	CSA 22.2 No.231,IEC 348
Designed to comply with:	UL 1244
RFI Suppression (complies with):	CISPR-II, Group 1, Class B
Dimensions	I
Width:	425.5 mm (16.75 in)
<b>Height</b> (including removable feet):	132.6 mm (5.22 in)
Depth (including safety cover):	497.8 mm (19.6 in)
Weight	I
Net:	25 kg (54 lb)
Shipping:	28 kg (61 lb)
0 1 10 11 0	L

# **Output Characteristic Curve:**



# **Maximum Rated Output**

Agilent Model	Vout	lout	-lout
6651A	8 V	50 A	11.6 A
6652A	20 V	25 A	5 A
6653A	35 V	15 A	3 A
6654A	60 V	9 A	1.8 A
6655A	120 V	4 A	1.5 A

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**Notes:** <sup>1</sup>For Performance Specifications, see Table 1-2a.

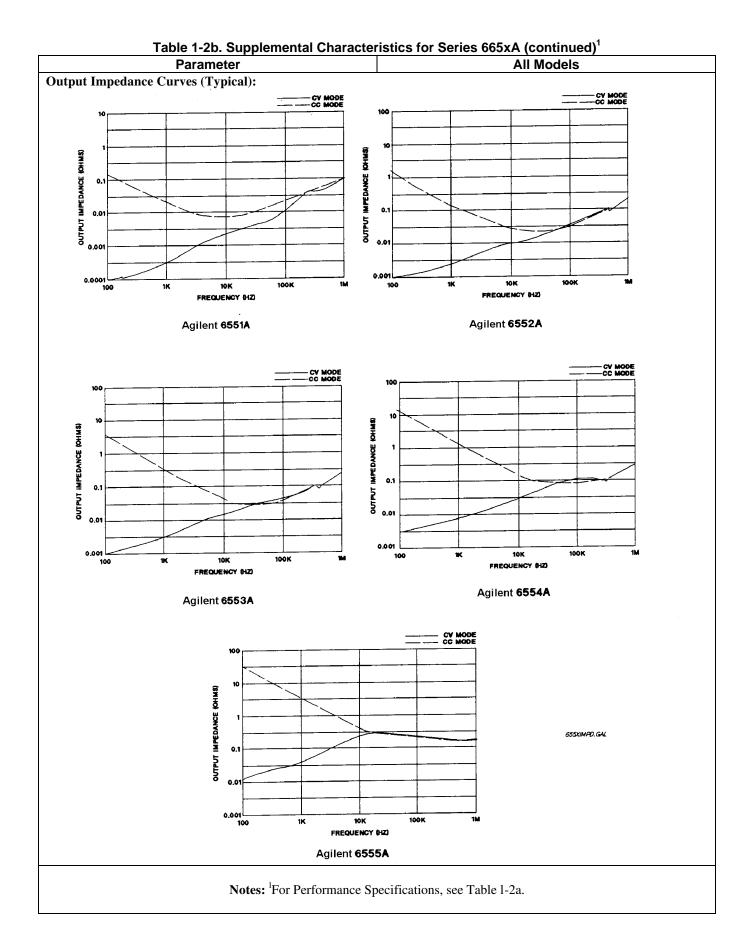


Table 1-3a. Performance Specifications for Series 667xA<sup>1</sup>

		erformance Spec				
Paramete	er			Model Numb	i .	1
		6671A	6672A	6673A	6674A	6675A
<b>Output Ratings</b>	ı		1	1	1	1
Voltage:		0 - 8 V	0 - 20 V	0- 35 V	0 - 60 V	0 - 120 V
Current:@ 0 to 55°C		0 - 220 A	0 - 100 A	0 - 60 A	0 - 35 A	0 - 18 A
<b>Programming Accuracy</b>	(@ calibration ten	nperature* ± 5 °C)				
Voltage:	0.04% +	8 mV	20 mV	35 mV	60 mV	120 mV
Current:	0.1%+	125 mA	60 mA	40 mA	25 mA	12 mA
Ripple & Noise (from 20	Hz to 20 MHz wit					
<b>Constant Voltage:</b>	rms	650 μV	750 μV	800 μV	1.25 mV	1.9 mV
<b>Constant Voltage:</b>	p-p	7 mV	9 mV	9 mV	11 mV	16 mV
<b>Constant Current:</b>	rms	200 mA	100 mA	40 mA	25 mA	12 mA
Readback Accuracy (fre	om front panel or o	ver GPIB with resp	ect to actual out	put @ calibrati	on temp <sup>1</sup> $\pm$ 5 °	<u>C</u> )
Voltage:	0.05% +	12 mV	30 mV	50 mV	90 mV	180 mV
<b>Current:</b>	0.1% +	150 mA	100 mA	60 mA	35 mA	18 mA
Load Regulation (change	e in output voltage	or current for any lo	oad change with	in ratings)		
Voltage:	0.002% +	$300 \mu\mathrm{V}$	650 μV	1.2 mV	2 mV	4 mV
<b>Current:</b>	0.005% +	10 mA	7 mA	4 mA	2 mA	1 mA
Line Regulation (change	in output voltage	or current for any lin	ne change withi	n ratings		
Voltage:	0.002% +	$300 \mu\mathrm{V}$	650 μV	1.2 mV	2 mV	4 mV
Current:	0.005% +	10 mA	7 mA	4 mA	2 mA	1 mA bisep>
Transient Response Tim	ne (for the output v	oltage to recover to	its previous lev	el (within 0.1%	of the rated vo	
20 mV, whichever is grea						
				< 900 μs		
AC Input Ratings (selec	table via internal s	witching - see Appe	ndix B)			
Nominal line voltage 200 Vac:*			1′	74-220 Vac		
*below 185 Vac, derate o	utnut voltage	7.8 V	18.0 V	31.5 V	56.5 V	108 V
linearly to:	aipui voimec	7.0 1	10.0 4	31.3 1	30.3 ¥	100 4
230 Vac:			10	91-250 Vac		I
Frequency range:				47-63 Hz		
Output Terminal	Isolation	±′.	240 Vdc (maxir	num, from chas	sis ground)	
	Notes: <sup>1</sup> For	Supplemental Char	acteristics, see	Γable 1-3b.		

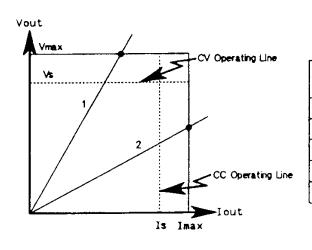
Output Programming Ra  Voltage:  Current:  Overvoltage Protection	ange (maximum	6671A	CC70 A	Agilent Model Number					
Voltage: Current:	ange (maximum	****	6672A	6673A	6674A	6675A			
Current:		programmable							
Current:	1	8.190 V	20.475 V	35.831 V	61.425 V	122.85 V			
		225.23 A	102.37 A	61.43 A	35.83 A	18.43 A			
	(OVP):	10.0 V	24.0 V	42.0 V	72.0 V	144.0 V			
Typical Resolution									
Voltage:		2 mV	5 mV	10 mV	15 mV	30 mV			
Current:		55 mA	25 mA	15 mA	8.75 mA	4.5 mA			
Overvoltage Protection	(OVP):	15 mV	35 mV	65 mV	100 mV	215 mV			
Accuracy (@ calibration	temp ±5 °C)*								
<b>Overvoltage Protection</b>	(OVP):*	200 mV	500 mV	900 mV	1.15 V	3.0 V			
<b>Analog Programming (</b>	VP):			± 0.3%					
Analog Programming (	IP):			± 7%					
Current Monitor (+IM):				±7%					
*Calibration temp = 25° C									
Drift Temperature Stabi	lity (following a	a 30-minute war	mup, change in	output over eigh	t hours under c	onstant line,			
load, and ambient tempera	iture)								
Voltage:	0.02% +	0.24 mV	0.6 mV	1 mV	1.8 mV	3.6 mV			
Current:	0.02% +	69 mA	35 mA	20 mA	10 mA	6 mA			
Temperature Coefficient	s (change per °C	C after 30-minut	e warmup)						
Voltage:	50 ppm +	0.04 mV	0.2 mV	0.7 mV	1.2 mV	2.4 mV			
Current:	75 ppm +	25 mA	12 mA	7 mA	4 mA	2 mA			
Voltage Readback:	60 ppm +	0.1 mV	0.3 mV	1 mV	1.2 mV	3 mV			
±Current Readback:	85 ppm +	30 mA	15 mA	9 mA	5 mA	2.5 mA			
Overvoltage Protection	(OVP):								
	200 ppm +	1.8 mV	5 mV	8 mV	13 mV	25 mV			
Analog Programming (V									
	60 ppm +	0.1 mV	0.3 mV	0.5 mV	0.7 mV	1.5 mV			
Analog Programming (±	· ·	26. 4	14 4	0. 4	- A	2 4			
C (36 t) (370	275 ppm +	26 mA	14 mA	9 mA	5 mA	3 mA			
Current Monitor (+IM)		2 4		4 4	0.6				
N# • T 4 T/A	50 ppm +	3 mA	2 mA	1 mA	0.6 mA	0.3 mA			
Maximum Input VA and			3800 VA; 26	00 W, 100 W w	ith no load				
Maximum AC Line Cur	0		10.4	(25.13.5.6	`				
	200 Vac		19 A	rms (25 AM fu	se)				
	nominal:		10.4	(05.43.6.6	`				
	230 Vac		19 A	rms (25 AM fu	se)				
M I D DI	nominal:	Wid AC:	1' 1	1.1 1 .	. 1: 1	1			
Maximum Reverse Bias	Current:		power applied a						
			rce, the supply v	•		nout damage			
		current equal to	its output curre	ent rating (see Ta	abie 1-3a).				
	Notes: <sup>1</sup> F	lon Donforman	Specifications,	naa Tabla 1 2-					

Parameter		Aaile	nt Model Nu	ımber	
	6671A	6672A	6673A	6674A	6675A
Remote Sensing Capability		1	•	1	
Voltage Drop Per Lead:	Up to 1/2 c	of rated outpu	t voltage.		
Load Voltage:	Subtract vo	oltage drop in	load leads fro	om specified	output
-	voltage rat	ing.		-	•
Load Regulation:					
	ΔmV (regulatio	on) = Vdrop(R)	k <sub>sense</sub> - )/k		
Degradation due to load lead drop in + output:					
$\Delta mV$ (regulation) = $V_{drop}(R_{sense} +)/k + 2V_{drop}(V_{ra})$					
where $R_{sense}$ - and $R_{sense}$ + are resistances of resp	ective sense lea	ids and k is th	e following n	nodel-depend	lent
value:	CC744 10 CC7	5 A 16 O			
6671A=1; 6672A=1.82; 6673A=4.99; 0	66/4A=10; 66/3	5A=16.2			
Command Processing Time (Average time for outp	ut voltage to ch	ange after rec	eint of digital	l data when t	he sunnly
is connected directly to the GPIB Bus):	at voltage to en	ange and rec	cipt of digital	i data wiicii t	ne suppry
			20 ms		
Output Voltage Programming Response Time**	<b>'</b>				
Rise/Fall Time (time for output to change from 90	% to 10% or fre	om 10% to 90	0% of its total	excursion):	***
	30 ms	60 ms	130 ms	130 ms	195 ms
Full-load programming speed up/down time (time	for output to se	ettle within 4	LSBs of the f	inal value):*	**
	i	Ì	1	i	
	•	190 ms			
No-load downprogrammiug discharge time (time	•	•			
<b>No-load downprogrammiug discharge time</b> (time zero volts):	for output to fall	1 to 0.5 V wh	en programm	ed from full	voltage to
zero volts):	for output to fall	•	en programm	ed from full	voltage to
zero volts):  ** All values exclude command processing time.	for output to fall	1 to 0.5 V wh	en programm	ed from full	voltage to
zero volts):   ** All values exclude command processing time.   *** With full resistive load = $V_{RATED}/I_{RATED}$ .	for output to fall	1 to 0.5 V wh 250 ms	en programm	ed from full 600 ms	voltage to 600 ms
zero volts):  ** All values exclude command processing time.	for output to fall 130 ms Output is n	to 0.5 V wh	en programm	ed from full 600 ms	voltage to 600 ms
zero volts):  ** All values exclude command processing time.  *** With full resistive load = V <sub>RATED</sub> /I <sub>RATED</sub> .  Monotonicity:	for output to fall	250 ms nonotonic over range.	en programm  350 ms  er entire rated	ed from full 600 ms	600 ms
zero volts):   ** All values exclude command processing time.   *** With full resistive load = $V_{RATED}/I_{RATED}$ .	for output to fall 130 ms Output is n	250 ms nonotonic over range.	en programm	ed from full 600 ms	voltage to 600 ms
zero volts):  ** All values exclude command processing time.  *** With full resistive load = V <sub>RATED</sub> /I <sub>RATED</sub> .  Monotonicity:  Auto-Parallel Configuration:	for output to fall 130 ms Output is n	250 ms nonotonic over range.	en programm  350 ms  er entire rated	ed from full 600 ms	voltage to 600 ms
zero volts):  ** All values exclude command processing time.  *** With full resistive load = V <sub>RATED</sub> /I <sub>RATED</sub> .  Monotonicity:  Auto-Parallel Configuration:	Output is n temperatur	250 ms monotonic over range. Up to	en programm  350 ms  er entire rated  3 identical m	ed from full 600 ms voltage, cur	600 ms
<pre>x** All values exclude command processing time. *** With full resistive load = V<sub>RATED</sub>/I<sub>RATED</sub>. Monotonicity: Auto-Parallel Configuration: Analog Programming (IP &amp; VP)</pre>	Output is n temperatur	250 ms nonotonic over range.	en programm  350 ms  er entire rated  3 identical m	ed from full 600 ms voltage, cur	600 ms
zero volts):  ** All values exclude command processing time.  *** With full resistive load = V <sub>RATED</sub> /I <sub>RATED</sub> .  Monotonicity:  Auto-Parallel Configuration:  Analog Programming (IP & VP)  Input Signal:*  VP Input Signal:**  (0 to VP Input Impedance:	Output is n temperatur  -4.72 V	1 to 0.5 V wh 250 ms  monotonic over range.  Up to	en programm  350 ms  er entire rated  3 identical m  -4.25 V  0 kΩ, nomina	ed from full 600 ms voltage, curnodels	600 ms
zero volts):  ** All values exclude command processing time.  *** With full resistive load = V <sub>RATED</sub> /I <sub>RATED</sub> .  Monotonicity:  Auto-Parallel Configuration:  Analog Programming (IP & VP)  Input Signal:*  VP Input Signal:**  (0 to	Output is n temperatur  -4.72 V	1 to 0.5 V wh 250 ms  monotonic over range.  Up to	en programm  350 ms  er entire rated  3 identical m	ed from full 600 ms voltage, curnodels	600 ms
*** All values exclude command processing time.  *** With full resistive load = V <sub>RATED</sub> /I <sub>RATED</sub> .  Monotonicity:  Auto-Parallel Configuration:  Analog Programming (IP & VP)  Input Signal:*  VP Input Signal:*  VP Input Signal:**  (0 to VP Input Impedance:  IP to -IP Differential Input Signal:  (0 to *Signal source must be isolated.	Output is n temperatur  -4.72 V	1 to 0.5 V wh 250 ms  monotonic over range.  Up to	en programm  350 ms  er entire rated  3 identical m  -4.25 V  0 kΩ, nomina	ed from full 600 ms voltage, curnodels	evoltage to 600 ms rent, and -3.97 V
*** All values exclude command processing time.  *** With full resistive load = V <sub>RATED</sub> /I <sub>RATED</sub> .  Monotonicity:  Auto-Parallel Configuration:  Analog Programming (IP & VP)  Input Signal:*  VP Input Signal:*  VP Input Signal:**  (0 to VP Input Impedance:  IP to -IP Differential Input Signal:  *Signal source must be isolated.  ** Referenced to output signal common.	Output is n temperatur  -4.72 V	1 to 0.5 V wh 250 ms  monotonic over range.  Up to	en programm  350 ms  er entire rated  3 identical m  -4.25 V  0 kΩ, nomina	ed from full 600 ms voltage, curnodels	evoltage to 600 ms rent, and -3.97 V
*** All values exclude command processing time.  *** With full resistive load = V <sub>RATED</sub> /I <sub>RATED</sub> .  Monotonicity:  Auto-Parallel Configuration:  Analog Programming (IP & VP)  Input Signal:*  VP Input Signal:**  (0 to  VP Input Impedance:  IP to -IP Differential Input Signal:  (0 to  *Signal source must be isolated.  ** Referenced to output signal common.  Current Monitor Output (+IM):	Output is n temperatur  -4.72 V +7.79 V	1 to 0.5 V wh 250 ms  monotonic over range. Up to  -4.24 V 6 +6.81 V	en programm  350 ms  er entire rated  3 identical m  -4.25 V  0 kΩ, nomina  +6.81 V	ed from full 600 ms l voltage, curnodels -4.24 V al =7.01 V	-3.97 V +6.34 V
** All values exclude command processing time.  *** With full resistive load = V <sub>RATED</sub> /I <sub>RATED</sub> .  Monotonicity:  Auto-Parallel Configuration:  Analog Programming (IP & VP)  Input Signal:*  VP Input Signal:**  (0 to  VP Input Impedance:  IP to -IP Differential Input Signal:  (0 to  *Signal source must be isolated.  ** Referenced to output signal common.  Current Monitor Output (+IM):  Output Signal:*  (-0.25 to)	Output is n temperatur  -4.72 V +7.79 V	1 to 0.5 V wh 250 ms  monotonic over range.  Up to	en programm  350 ms  er entire rated  3 identical m  -4.25 V  0 kΩ, nomina  +6.81 V  +7.70 V	ed from full 600 ms l voltage, curnodels -4.24 V al =7.01 V	-3.97 V +6.34 V
** All values exclude command processing time.  *** With full resistive load = V <sub>RATED</sub> /I <sub>RATED</sub> .  Monotonicity:  Auto-Parallel Configuration:  Analog Programming (IP & VP)  Input Signal:*  VP Input Signal:**  (0 to  VP Input Impedance:  IP to -IP Differential Input Signal:  ** Referenced to output signal common.  Current Monitor Output (+IM):  Output Signal:*  Output Impedance:	Output is n temperatur  -4.72 V +7.79 V	1 to 0.5 V wh 250 ms  monotonic over range. Up to  -4.24 V 6 +6.81 V	en programm  350 ms  er entire rated  3 identical m  -4.25 V  0 kΩ, nomina  +6.81 V	ed from full 600 ms l voltage, curnodels -4.24 V al =7.01 V	-3.97 V +6.34 V
*** All values exclude command processing time.  *** With full resistive load = V <sub>RATED</sub> /I <sub>RATED</sub> .  Monotonicity:  Auto-Parallel Configuration:  Analog Programming (IP & VP)  Input Signal:*  VP Input Signal:*  VP Input Impedance:  IP to -IP Differential Input Signal:  ** Referenced to output signal common.  Current Monitor Output (+IM):  Output Signal:*  (-0.25 to)  Output Impedance:  ** Corresponds to 0% to 100% output current.	Output is n temperatur  -4.72 V +7.79 V	1 to 0.5 V wh 250 ms  monotonic over range. Up to  -4.24 V 6 +6.81 V	en programm  350 ms  er entire rated  3 identical m  -4.25 V  0 kΩ, nomina  +6.81 V  +7.70 V	ed from full 600 ms l voltage, curnodels -4.24 V al =7.01 V	-3.97 V +6.34 V
*** All values exclude command processing time.  *** With full resistive load = V <sub>RATED</sub> /I <sub>RATED</sub> .  Monotonicity:  Auto-Parallel Configuration:  Analog Programming (IP & VP) Input Signal:*     VP Input Signal:** (0 to     VP Input Impedance:     IP to -IP Differential Input Signal: (0 to  *Signal source must be isolated.  *** Referenced to output signal common.  Current Monitor Output (+IM): Output Signal:* (-0.25 to) Output Impedance:     * Corresponds to 0% to 100% output current.  Savable States	Output is n temperatur  -4.72 V +7.79 V	250 ms   2	en programm    350 ms    er entire rated  3 identical m    -4.25 V    0 kΩ, nomina   +6.81 V      +7.70 V    490 Ω	ed from full of 600 ms and voltage, curnodels and ended with the second	-3.97 V +6.34 V
*** All values exclude command processing time.  *** With full resistive load = V <sub>RATED</sub> /I <sub>RATED</sub> .  Monotonicity:  Auto-Parallel Configuration:  Analog Programming (IP & VP) Input Signal:*     VP Input Signal:** (0 to     VP Input Impedance:     IP to -IP Differential Input Signal: (0 to  *Signal source must be isolated.  *** Referenced to output signal common.  Current Monitor Output (+IM): Output Signal:* (-0.25 to) Output Impedance:     * Corresponds to 0% to 100% output current.  Savable States Nonvolatile Memory Locations:	Output is n temperatur  -4.72 V +7.79 V	250 ms	en programmer at $350 \text{ ms}$   $350 \text{ ms}$   er entire rated a 3 identical mass   $-4.25 \text{ V}$   $0 \text{ k}\Omega$ , nominar   $+6.81 \text{ V}$   $+7.70 \text{ V}$   $490 \Omega$   $(0 \text{ through 4})$	ed from full of 600 ms of voltage, curnodels of 4.24 V of all =7.01 V of the 4.93 v of the 4.93 v of the 4.93 v	-3.97 V +6.34 V
*** All values exclude command processing time.  *** With full resistive load = V <sub>RATED</sub> /I <sub>RATED</sub> .  Monotonicity:  Auto-Parallel Configuration:  Analog Programming (IP & VP) Input Signal:*     VP Input Signal:** (0 to     VP Input Impedance:     IP to -IP Differential Input Signal: (0 to  *Signal source must be isolated.  *** Referenced to output signal common.  Current Monitor Output (+IM):     Output Signal:* (-0.25 to)  Output Impedance:     * Corresponds to 0% to 100% output current.  Savable States	Output is n temperatur  -4.72 V +7.79 V	250 ms	en programm    350 ms    er entire rated  3 identical m    -4.25 V    0 kΩ, nomina   +6.81 V      +7.70 V    490 Ω	ed from full of 600 ms of voltage, curnodels of 4.24 V of all =7.01 V of the 4.93 v of the 4.93 v of the 4.93 v	-3.97 V +6.34 V

Table 1-3b. Supplemental Characteristics for Series 667xA (continued)<sup>1</sup>

Parameter	All Models				
Digital Port Characteristics	(see Table 1-5)				
<b>GPIB Interface Capabilities</b>	(see Table 1-5)				
Serial Link Capabilities	(see Table 1-5)				
Recommended Calibration Interval:	1 year				
Safety Compliance					
Complies with:	CSA 22.2 No.231,IEC 348				
Designed to comply with:	UL 1244				
RFI Suppression (complies with):	CISPR-II, Group 1, Class B				
Dimensions					
Width:	425.5 mm (16.75 in)				
<b>Height</b> (including removable feet):	145.1 mm (5.71 in)				
<b>Depth</b> (including safety cover):	640 mm (25.2 in)				
Weight					
Net:	27.7 kg (61 lb)				
Shipping:	31.4 kg (69 lb)				

# **Output Characteristic Curve:**



# **Maximum Rated Output**

Agilent Model	Vout	lout	
6671A	8 V	220 A	
6672A	20 V	100 A	
6673A	35 V	60 A	
6674A	60 V	35 A	
6675A	120 V	18 A	

**Notes:** <sup>1</sup>For Performance Specifications, see Table 1-3a.

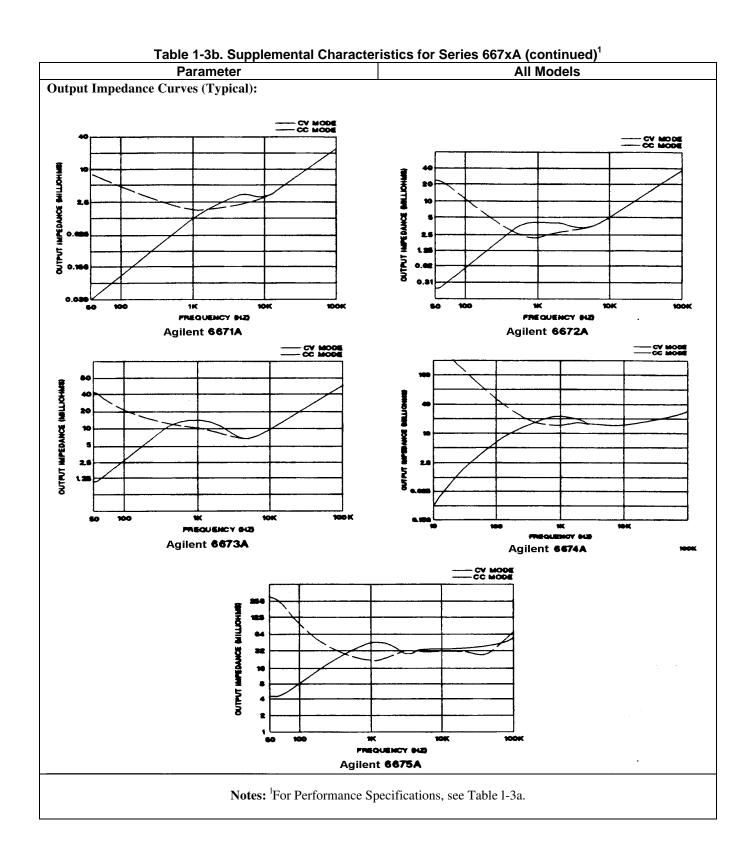


Table 1-4a. Performance Specifications for Series 668xA<sup>1</sup>

Dame		A class A Mark Mark Land Name Land					
Paramete	r	Agilent Model Number					
		6680A	6681A	6682A	6683A	6684A	
Output Ratings							
Voltage:		0 - 5 V	0 - 8 V	0- 21 V	0 - 32 V	0 - 40 V	
Current:*		0 - 875 A	0 - 580 A	0- 21 V 0 - 240 A	0 - 160 A	0 - 128 A	
*Derated linearly 1%/°C	from 40 ° C to 55	°C					
<b>Programming Accuracy</b>	$(@ 25 \pm 5 ^{\circ}C)$						
Voltage:	0.04% +	5 mV	8 mV	21 mV	32 mV	40 mV	
Current:	0.1%+	450 mA	300 mA	125 mA	85 mA	65 mA	
Ripple & Noise (from 20	Hz to 20 MHz wi	th outputs unground	ed, or with eithe	er output termin	al grounded)		
Constant Voltage:	rms	1.5 mV	1.5 mV	1.0 mV	1.0 mV	1.0 mV	
Constant Voltage:	p-p	10 mV	10 mV	10 mV	10 mV	10 mV	
Constant Current:**	rms	290 mA	190 mA	40 mA	28 mA	23 mA	
**With load inductance	> 5μH.						
Readback Accuracy (fro	m front panel or o	over GPIB with resp	ect to actual out	tput @ 25 ± 5 °C	C)		
Voltage:	0.05% +	7.5 mV	12 mV	32 mV	48 mV	60 mV	
<b>±Current</b>	0.1% +	600 mA	400 mA	165 mA	110 mA	90 mA	
Load Regulation (change	in output voltage	or current for any le	oad change with	in ratings)			
Voltage	0.002% +	190 μV	300 μV	650 μV	1.1 mV	1.5 mV	
Current:	0.005% +	65 mA	40 mA	17 mA	12 mA	9 mA	
Line Regulation (change	in output voltage	or current for any lin	ne change within	n ratings)			
Voltage:	0.002% +	190 μV	300 μV	650 μV	1.1 mV	1.5 mV	
Current:	0.005% +	65 mA	40 mA	17 mA	12 mA	9 mA	
Transient Response Time	(for the output w	altega to recover to	within 150 mV	following ony	tan ahanga fra	m 1000/ to	

Transient Response Time (for the output voltage to recover to within 150 mV following any step change from 100% to 50% or 50% to 100% of the rated output current):  $< 900 \mu s$ 

**AC Line Input** \* (selectable - see Appendix C)

Range 1

Ac input phase-to-phase voltage: 3-phase 180-235 Vac Ac input frequency: 47-63 Hz \*

Range 2

Ac input phase-to-phase voltage: 3-phase 360-440 Vac Ac input frequency: 47-63 Hz \*

Notes: <sup>1</sup>For Supplemental Characteristics, see Table 1-4b.

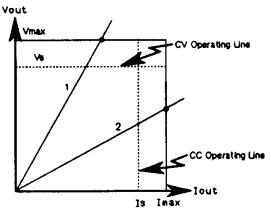
<sup>\*</sup> Power source can be DELTA or WYE.

<sup>\*</sup> For 47 to 53 on Range 1 only, derate output voltage linearly from 100% at 200 Vac to 95% at 180 Vac.

Paramete		Supplemental Characteristics for Series 668xA <sup>1</sup> Agilent Model Number						
Output Programming I	Danga (mayimum	6680A	6681A	6682A	6683A	6684A		
Output Frogramming I	Kange (maximum	programmable	values)					
Voltage:		5.125 V	8.190 V	21.50 V	32.75 V	41.0 V		
Current:		895 A	592 A	246 A	164 A	131 A		
Overvoltage Protectio	n (OVP):	6.25 V	10.0 V	25.2 V	38.4 V	48.0 V		
Typical Resolution								
Voltage:		1.35 mV	2.15 mV	5.7 mV	8.6 mV	10.8 mV		
Current:		235 mA	155 mA	64 mA	43 mA	34 mA		
Overvoltage Protection	n (OVP):	30 mV	45 mV	120 mV	180 mV	225 mV		
Accuracy ( @ 25 ±5 °C)								
Overvoltage Protectio	, ,	120 mV	180 mV	470 mV	720 V	900 V		
<b>Analog Programming</b>		10 mV	20 mV	50 mV	75 mV	100 mV		
Analog Programming	1 1	8 A	4 A	2 A	1.5 A	1 A		
<b>Current Monitor (IM):</b>		8 A	4 A	2 A	1.5 A	1 A		
<b>Analog Programming (</b>								
Input Signal (source i	must be isolated)	1						
VP Input Signal:*				0 to -5.				
+ IP Input Signal:**	*			0  to  +5.	0 V			
Input Impedance				20.1				
$V_P$ and $I_P$ Inputs:	l D	I.	** D C 1.	> 30 k				
*Referenced to common			** Referenced to -IP differential input signal					
Current Monitor (IM)			0.125 V to +5 V		. 1	1.		
<b>Drift Temperature Stal</b>		30-minute war	mup, change in o	output over eigh	t hours under co	onstant line,		
load, and ambient temper	rature)							
Voltage:	0.02% +	0.15  mV	0.24 mV	0.63 mV	0.96 mV	1.2 mV		
Current:	0.02% +	315 mA	170 mA	71 mA	47 mA	38 mA		
Temperature Coefficie	nts (change per °C	C after 30-minut	e warmup)					
Voltage:	50 ppm +	0.05 mV	0.08 mV	0.21 mV	0.32 mV	0.40 mV		
<b>Current:</b>	75 ppm +	110 mA	62 mA	26 mA	17 mA	14 mA		
Voltage Readback:	60 ppm +	0.075  mV	0.1 mV	0.25 mV	0.40  mV	0.50 mV		
±Current Readback:	85 ppm +	135 mA	90 mA	37 mA	25 mA	20 mA		
Overvoltage Protection	ı (OVP):							
	200 ppm +	1.25 mV	1.8 mV	4.7 mV	7.2 mV	9.0 mV		
Typical Common Mode	e Noise Current*		1 1	ı		i		
rms:		1.5 mA	1.5 mA	3 mA	3 mA	3 mA		
peak-to-peak:		10 mA	10 mA	20 mA	20 mA	20 mA		
* Referenced to signal gr	round binding pos	t.						
Output Float Voltage (1	maximum from ou	ıtput signal gro	and):	±60 Vdc				
	Notes: <sup>1</sup> F	D 6	Specifications,	TD 11 1 4				

Table 1-4b. Supplemental Cha	racteristi				
Parameter	Agilent Model Number			i -	
	6680A	6681A	6682A	6683A	6684A
Remote Sensing Capability Voltage Drop Per Lead:	Up to 1/2 of rated output voltage.				
Load Voltage:	Subtract voltage drop in load leads from specified output voltage rating.				
Load Regulation:	1	8.			
	v (regulat	tion) = Vdrop	(R <sub>sansa</sub> -)		
Degradation due to load lead drop in + output:	( '6'	,	sense /		
$\Delta$ mV (regulation) = V <sub>drop</sub> (R <sub>sense</sub> +) + 2V <sub>drop</sub> (V <sub>rating</sub> )/(	$V_{rating} + 10$	) V)			
where $R_{sense}$ and $R_{sense}$ are resistances of respect					
Maximum Reverse Voltage Current Sink Capability	1				
•			pplied and the		
			ce, the supply		•
			nage a current	equal to its o	utput
***	current r	atıng.			
* Current must be limited by user's external dc source.					
Typical Common Mode Noise Current **	ſ				
rms:			1.5 mA		
Peak-to-Peak	0.1.	1, 1	10 mA	• • •	
Load Voltage:			in load leads f	rom specified	output
	voltage r	ating.			
** From 20 Hz to 2 MHz, referenced to signal ground b	ı pinding po	st.			
Maximum Input Power:	7350 VA	, 6000 W, 16	0 W with no l	oad	
Maximum AC Line Current Ratings Range 1					
Rms line current:	ĺ	2	1.4 A (27.7 A)	) ***	
Line fuse:		_	30 AM	,	
Range 2	Į.		201111		
Rms line current:	1	1	0.7 A (14.4 A)	) ***	
Line fuse:			16 AM		
*** Includes 5% unbalanced voltage phase condition.	•				
Output Voltage Programming Response Time** Programming Rise/Fall Time (time for output to cha	inge from	90 % to 10%	or from 10% to	o 90% of its t	otal
excursion):***	C				
,	9 ms	12 ms	45 ms	60 ms	60 ms
Full-load programming speed up/down time (time fo	r output to	settle within	4 LSBs of the	final value):*	**
	27 ms	35 ms	140 ms	185 ms	185 ms
No-load downprogrammiug discharge time (time for	•				
zero volts):	p 10 1		programm		. 51.000
,	90 ms	100 ms	475 ms	650 ms	575 ms
** All values exclude command processing time. *** With full resistive load = $V_{RATED}/I_{RATED}$	,		, ,		
Notes: <sup>1</sup> For Performance	Specifica	tions see Tol	ale 1-4a		
rotes: For Performance	Specifica	aons, see rai	лс 1- <del>4</del> а.		

Parameter	All Models		
Command Processing Time (Average time for output	out voltage to change after receipt of digital data when the supply is		
connected directly to the GPIB Bus): 20 ms			
Monotonicity:	Output is monotonic over entire rated voltage, current, and		
•	temperature range.		
Auto-Parallel Configuration:	Up to 3 identical models		
Nonvolatile Storage			
State storage & recall locations:	4		
Prestored turn-on state:	Location 0		
Maximum memory write cycles:	40,000, typical		
Digital Port Characteristics	(see Table 1-5)		
GPIB Interface Capabilities	(see Table 1-5)		
Serial Link Capabilities (see Table 1-5)			
Recommended Calibration Interval:	1 year		
Safety Compliance			
Complies with:	CSA 22.2 No.231,		
Designed to comply with:	IEC 1010 (carries CE mark)		
	UL 1244		
RFI Suppression (complies with):	CISPR-II, Group 1, Class B		
Dimensions			
Width:	425.5 mm (16.75 in)		
Height			
including removable feet	234.2 mm (9.25 in)		
excluding removable feet	221.5 mm (8.75 in)		
<b>Depth</b> (without output safety cover):	674.7 mm (25.56 in)		
Weight			
Net:	51.3 kg (113 lb)		
Shipping:	63.6 kg (140 lb)		
Output Characteristic Curve:			
Vout Vmax	Maximum Rated Output		
CV ON	Agilent Vout lout  Model		



Agilent Model	Vout	lout
6680A	5 V	875 A
6681A	8 V	580 A
6682A	21 V	240 A
6683A	32 V	160 A
6684A	40 V	128 A

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**Notes:** <sup>1</sup>For Performance Specifications, see Table 1-4a.

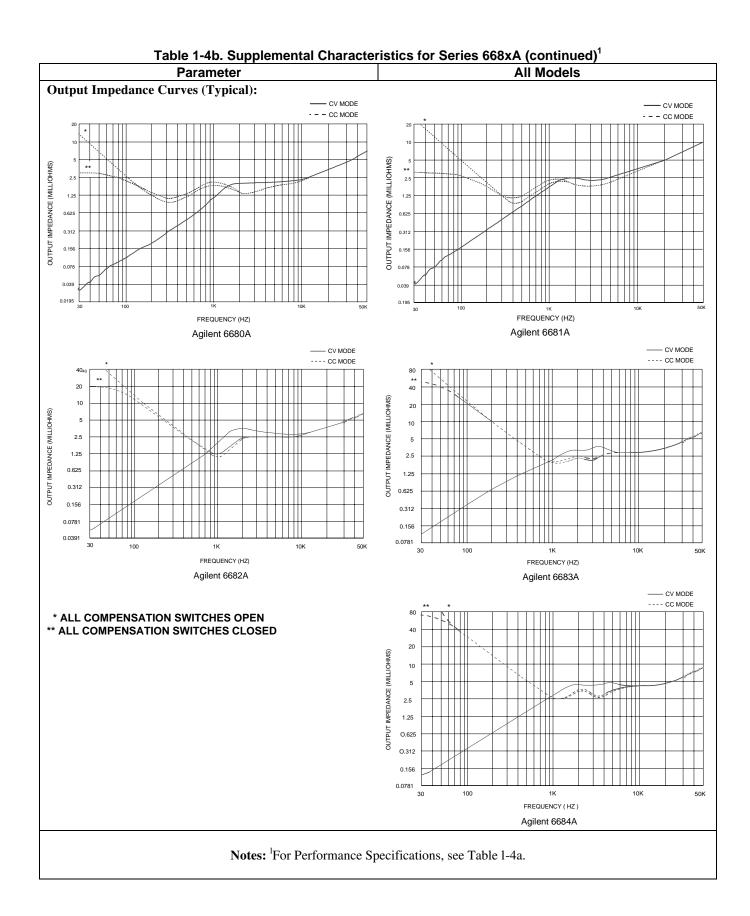


Table 1-5. Supplemental GPIB Characteristics For All Models

Table 1-5. Supplemental GPIB Characteristics For All Models		
Parameter	All Models	
Digital Port Characteristics		
Maximum ratings:	16.5 Vdc between terminals 1 & 2; 3 & 4; and from 1 or 2 to	
	chassis ground	
FLT/INH Operation		
FLT/INH Terminals 1 & 2		
I <sub>ol</sub> (low-level output current)	1.25 mA maximum	
V <sub>ol</sub> (low-level output voltage)	0.5 V maximum	
FLT/INH Terminals 3 & 4		
V <sub>il</sub> (low-level input voltage)	0.8 V maximum	
V <sub>ih</sub> (high-level input voltage)	2.0 V minimum	
I <sub>il</sub> (low-level input current)	1 mA	
tw (pulse width)	100 μs, minimum	
td (time delay)	4 ms, typical	
Digital I/O Operation		
Digital OUT Port 0,1,2 - Open Collector:		
I <sub>oh</sub> (high-level output leakage @ 16.5 V)	100 μA (ports 0,1); 12.5 mA (port 2)	
I <sub>oh</sub> (high-level output leakage @ 5.25 V)	100 μA (ports 0,1); 250 μA (port 2)	
I <sub>ol</sub> (low-level output sink current @ 0.5 V)	4 mA	
I <sub>ol</sub> (low-level output sink current @ 1 V)	250 mA	
Digital IN Port 2 - Internal 4.64 k Pullup:		
I <sub>il</sub> (low-level input current @ 0.4 V)	1.25 mA	
I <sub>ih</sub> (high-level input current @ 5.25 V)	250 μΑ	
V <sub>il</sub> (low-level input voltage)	0.8 V maximum	
V <sub>ih</sub> (high-level input voltage)	2.0 V minimum	
GPIB Interface Capabilities	SCPI (default); Compatibility	
Languages:	AH1, C0, DC1, DT1, E1, LE4, PP0, RL1, SH1,	
Interface:	SR1, TE6	
Serial Link Capabilities (multiple supplies sharing one GP		
Maximum number of supplies:	16	
Maximum number of linked supplies:	15	
Maximum total chain cable length:	30 m (100 ft)	

Table 1-6. Operator Replaceable Parts List	
Description	Agilent Part No.
(Unless otherwise specified, parts apply to all models.)	
Cable assembly, GPIB	(See "Accessories")
Cable assembly, serial link	(See "Accessories")
Collar, rotary output control	5040-1700
Cover, ac input safety	
Series 667xA, w/strain relief connector & rubber boot	5040- 1676
Series 668xA	5060-3237
Cover, dc output	
Series 664xA and 665xA	0360-2191
Series 667xA	5040- 1674
Series 668xA	5060- 1692
Flatwasher, ac input safety cover (Series 667xA and 668xA)	3050-1053
Foot, cabinet	5041-8801
Fuse, power	
Series 664xA	
100 Vac line voltage, 6 AM	2110-0056
120 Vac line voltage, 5 AM	2110-0010
220/230/240 Vac line voltage, 3 AM	2110-0003
Series 665xA	
100 Vac line voltage, 15 AM	2110-0054
120 Vac line voltage, 12 AM	2110-0249
220/230/240 Vac line voltage, 7 AM	2110-0614
Series 667xA*	
*This is an internal fuse not replaceable by the operator.	
Series 668xA	
30 AM for 180-235 Vac line (set of 3)	5060-3513
16 AM for 360-440 Vac line (set of 3)	5060-3512
Knob, rotary output control	0370-1091
Lockwasher, ac input safety cover (Series 667xA and 668xA)	2190-0484
Lockwasher, output bus bar, 1/4 spring (Series 667xA only)	3050-1690
Manual	
Agilent 59510A/11 Relay Accessories	5957-6382
Series 603xA Operating	5959-3301
Series 664xA and 665xA Service	5959-3376
Series 664xA, 665xA, 667xA and 668xA Programming Guide	5960-5597
Series 667xA Service	5959-3384
Nut, output bus bar, hex 1/4-20x1/2 (Series 667xA only)	2950-0084
Nut, power ground, hex w/lw 3/8x32	0590-0305
Nut, power input cable (Series 668xA only)	0535-0082
Plug, analog connector	1252-3698
Plug, digital connector	1252-1488
Power cord assembly	(See "Options")
Rack mount kit	(See "Options")
Resistor, calibration	(See Appendix A)
Screw, ac input safety cover, M4.0 x 60 mm long (Series 667xA and 668xA)	0515-0156
Screw, carrying strap, M5x0.8x10 mm	0515-1384
Screw, dc output cover (Series 664xA and 665xA)	0360-2191

**Table 1-6. Operator Replaceable Parts List (continued)** 

ent Part No.
085
103
073
104
Accessories")
643
681
207
)(

## Installation

## Inspection

## **Damage**

When you receive your power supply, inspect it for any obvious damage that may have occurred during shipment. If there is damage, notify the shipping carrier and the nearest Agilent Sales and Support Office immediately. Warranty information is printed in the front of this guide.

### **Packaging Material**

Until you have checked out the power supply save the shipping carton and packing materials in case the power supply has to be returned to Agilent Technologies. If you return the power supply for service, attach a tag identifying the model number and the owner. Also include a brief description of the problem.

Note	Series 668xA Only
	When you no longer need the shipping carton and packing materials, package and return them to the
	recycle center that has been provided for you. In most cases, you may do this free of any shipping charges.
	Please follow the instructions in the pack return system that was included with your power supply.

## **Items Supplied**

In addition to this manual, check that the following items in Table 2-1 are included with your power supply (see Table 1-6 for part numbers):

Table 2-1. Items Supplied

Power cord	Series 664xA and 665xA
	Your power supply was shipped with a power cord for the type of outlet specified for your location. If the appropriate cord was not included, contact your nearest Agilent Sales and Support Offices (see end of this guide) to obtain the correct cord. <b>Caution:</b> Your power supply cannot use a standard power cord. The power cords supplied by Agilent Technologies have heavier gauge wire.
	Series 667xA and 668xA Your power supply was shipped with a power cord appropriate for your location. The cord may or may not be terminated in a power plug (see "Options" in Chapter 1). If the cord is not included, contact your nearest Agilent Sales and Support Office (see end of this guide ) to obtain the correct cord. These models also include a power input safety cover with strain relief connector. It is required to secure the power cord to the power supply.
Analog connector	A 7-terminal analog plug (see Table 1-6) that connects to the back of the supply. Analog connections are described in Chapter 4.
Digital connector	A 4-terminal digital plug (see Table 1-6) that connects to the back of the supply. Digital connections are described in "Appendix D - Digital Port Functions"
Serial cable	A 2-meter cable (see "Accessories" in Chapter 1) that connects to the control bus (next to the GPIB connector). This cable is used to serially connect multiple supplies as described under "Controller Connections" in Chapter 4.

#### Table 2-1. Items Supplied (continued)

	rabio 2 in Romo Gappinoa (Goritmaga)
Output hardware	Series 667xA only Output hardware (screws with nuts and lockwashers) for securing your load wires to the output bus bars (see Table 1-6).
Pack return system	Series 668xA Only (Agilent P/N 5080-2430). Materials and instructions for properly disposing of the shipping carton and packing materials.
Guide change page	If applicable, change sheets may be included with this guide. If there are change sheets, make the indicated corrections in this guide.

## **Location and Temperature**

### **Bench Operation**

The "Supplemental Characteristics" in Chapter 1 give the dimensions of your power supply. The cabinet has plastic feet that are shaped to ensure self-alignment when stacked with other Agilent System II cabinets. The feet may be removed for rack mounting. Your power supply must be installed in a location that allows sufficient space at the sides and rear of the cabinet for adequate air circulation. Minimum clearances are 1 inch (25 mm) along the sides. Do not block the fan exhaust at the rear of the supply.

#### **Rack Mounting**



Series 668xA supplies weigh 51.3 kg (113 lb). Obtain adequate help when mounting the supply in the rack.

The power supply can be mounted in a standard 19-inch rack panel or cabinet. Rack mounting kits are available as Option 908 or 909 (with handles). Installation instructions are included with each rack mounting kit.



#### Series 667xA & 668xA

Series 667xA and 668xA supplies require instrument support rails for non-stationary installations. These are normally ordered with the cabinet and are not included with the rack mounting kits.

#### **Temperature Performance**

A variable-speed fan cools the supply by drawing air through the sides and exhausting it out the back. Using Agilent rack mount or slides will not impede the flow of air. The temperature performance is as follows:

**Series 664xA & 665xA** Operates without loss of performance within the temperature range of 0 °C to 40 °C and with derated output from 40 °C to 55 °C.

Series 667xA & 668xA Operates without loss of performance within the temperature range of 0 °C to 55 °C.

WARNING

It a Series 664xA or 665xA power supply is operated at full output current for several hours, the sheet metal immediately under the transformer (near the right front) can get very hot. Do not touch this area of the cabinet. The line cord also can become quite warm. Both of these conditions are normal.

#### INPUT POWER SOURCE

Refer to the applicable paragraphs below for information on the input power source. *Do not apply power to the power supply until directed to do so in Chapter 3.* 



Check the line **Rating** label on the rear of your supply and verify that the voltage shown there corresponds to the nominal line voltage of your power source. If it does not, see "Appendix C - Line Voltage Conversion" for instructions on changing the power supply's line voltage configuration.

## Series 664xA and 665xA Supplies

The supplied cord connects to the power receptacle on the rear panel (2, Figure 2-1).

- You can operate your supply from a nominal 100 V, 120 V, 220 V, 230 V, or 240 V single-phase ac power source as indicated on the rear panel line **Rating** label **1**.
- See "AC Input Ratings" in Table 1-la or Table 1-2a for the voltage and frequency range for each type of power source. "Maximum AC Line Current Ratings" in Table 1-lb or Table 1-2b show the maximum load current.
- The line fuse is located in a fuseholder on the rear panel 3. The rear panel label 1 shows the fuse value used in the power supply and Table 1-6 identifies the replacement fuse.

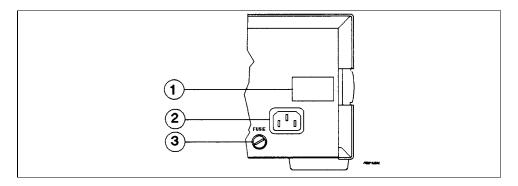


Figure 2-1. Series 664xA and 665xA Power Connection

#### Series 667xA Supplies

**Note** This product requires single-phase input voltage.

You can operate your supply from a nominal 200 V or 230 V, single-phase power source, or from the line-to-line voltage of a 208-volt, 3-phase source. The proper source is indicated on the rear **Rating** label (4, Figure 2-2). See "AC Input Ratings" in Table 1-3a for the voltage and frequency range for each type of power source.

**Note** The power source must be a dedicated line with no other devices drawing current from it.

The line fuse is located inside the power supply. Table 1-6 identifies the replacement fuse. See "In Case of Trouble" in Chapter 3 for instructions on fuse replacement.

### Installing the Power Cord

WARNING

Installation of the power cord must be done by a qualified electrician and in accordance with local electrical codes.

The power cord supplied with power supply may or may not include a power plug (see "Options" in Chapter l) at one end of the cord. Terminating connections and a ground lug are attached to the other end of the cord.

See Figure 2-2 and proceed as follows:

- 1. If they are not already in place, position the strain relief connector (11), safety cover (5), rubber boot (9), and connector nut (9) on the power cord (7).
- 2. Secure the ground wire 2 to the chassis earth ground stud.
- 3. For single-phase operation, connect the neutral wire  $\bigcirc$  to the N input terminal and the line wire  $\bigcirc$  to the L input terminal (this line is fused inside the supply).
- 4. For line-to-line operation from a three-phase source as shown in Figure 2-3, connect one phase to the N input terminal and another phase to the L input terminal (this line is fused inside the supply).

## **Note** The N terminal is not internally grounded.

5. Position the safety cover over the power input terminals and tighten the cover screws (1) and strain relief connector screws (6).

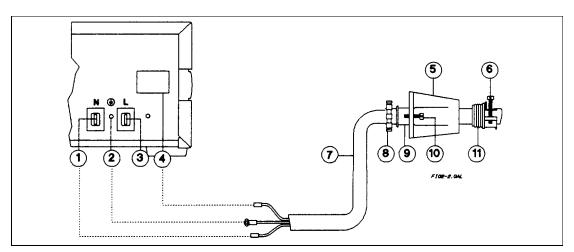


Figure 2-2. Connecting the Series 667xA Power Cord

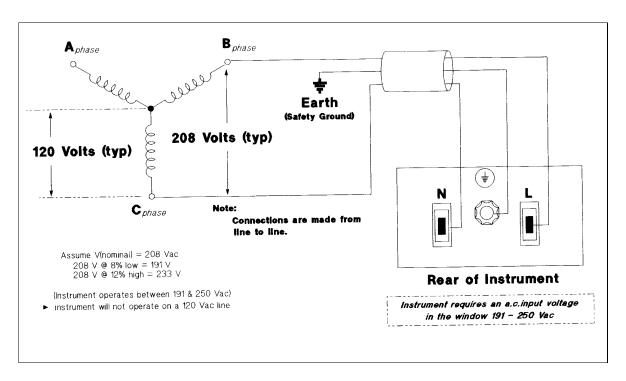


Figure 2-3. 667xA Connection to a 3-Phase Line

## Series 668xA Supplies

## **Line Wiring**

The power supply requires a 3-phase power source that provides 7350 VA (6000 W) maximum. The power supply has a delta input (no neutral connection) and will accept power from either delta (triangle) or wye (star) sources. Two voltage ranges are available (see "AC Input Ratings" in Table 1-4a). In order to maintain phase current balancing, the power source should be a dedicated line with only Agilent Technologies Series 668xA supplies drawing current from it. A disconnect box located near the power supply (see Figure 2-4) is recommended for all installations and is mandatory for direct-wired installations.

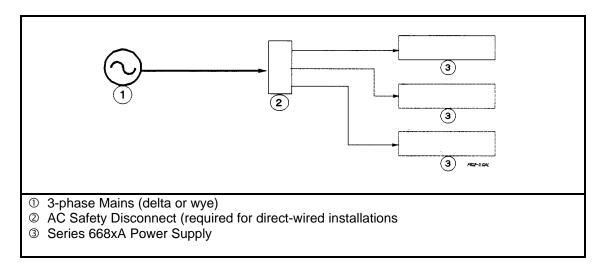


Figure 2-4. Series 668xA Overall Wiring Diagram.

### Installing the Power Cord

WARNING

Installation of the power cord must be done by a qualified electrician and in accordance with local electrical code

The power cords supplied with the power supply do not include a power plug (see "Options" in Chapter l) at one end of the cord. Terminating connectors and a ground lug are attached to the other end of the cord.

See Figure 2-5 and proceed as follows:

- 1. Check the line fuses ( 2), Figure 2-5) as follows:
  - a. Examine the **FUSES** label non the rear panel.
  - b. Unscrew the line fuse caps ( a from the rear panel and verify that all fuses are as specified on the label. Replace the fuses.
- 2. Open the line clamp 7 and insert the line cord 10 through the opening.
- 3. Position the line cord so that the clamp is near the end of the outside insulating sheath. Tighten the screws securing the clamp.
- 4. Secure the three ac lines to the ac power strip as follows: \*Phase 1<sub>3</sub> to L1. Phase 2<sub>4</sub> to L2. Phase 3<sub>6</sub> to L3.
- 5. Secure the ground wire 5 to the chassis earth ground stud.

CAUTION

Do not connect anything to the terminal marked "DO NOT USE".

- 6. Slip the safety cover (g) over the fuses and terminal strip and secure the cover with the four capscrews.
- 7. If required, wire the appropriate power plug to the other end of the power cord.

**Note** 

For user-made cable , strip back sheath 100 mm (3.9 in).

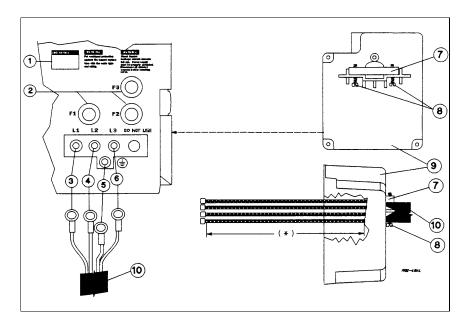


Figure 2-5. Connecting the Series 668xA Power Cord

## **Turn-On Checkout**

#### Note

This chapter provides a preliminary introduction to the power supply front panel. See "Chapter 5 - Front Panel" for more details.

#### Introduction

Successful tests in this chapter provide a high degree of confidence that the power supply is operating properly. For verification tests, see "Appendix B - Operation Verification". Complete performance tests are given in the service manual (see Table 1-5 in Chapter 1). Do not apply ac power to the power supply until told to do so.

## **Preliminary Checkout (All Models)**

- 1. Make certain that the front panel switch is off.
- 2. Examine the Line Voltage Rating or Line And Fuse Rating label (see "Chapter 2 Installation")
  - a. Verify that the line voltage rating agrees with your power source. If it does not, see "Appendix C Line Voltage Conversion".
  - b. Series 664xA/665xA Use a screwdriver to remove the line fuse from the fuseholder (3, Figure 2-1). Verify that the fuse is as specified on the label. Replace the fuse.
  - c. Series 668xA Unscrew the fuse caps from the rear panel (2, Figure 2-4). Verify that the fuse is as specified on the label. Replace the fuse.
- 3. Check the sense wiring as follows:
  - a. Series 664xA/665xA The SENSE switch (4, Figure 4-3a) is set to Local.
  - b. Series 667xA Remove the output safety cover (1, Figure 4-4a) and examine the output sense terminals (4 and
  - 5). They should be wired for local sensing as follows:
    - 1. The **+LS** sense terminal wired to the **+S** terminal of the analog connector (2).
    - 2. The **-LS** sense terminal wired to the **-S** terminal of the analog connector.
    - 3. If the power supply is not wired for local sensing, make the above connections, using small-capacity wire (#22 is sufficient).
  - c. Series 668xA Examine the output bus bars (Figure 4-5a) and make sure they are connected for local sensing as follows:
    - 1. The + bar is wired to the +S terminal of the analog connector.
    - 2. The bar is wired to the -S terminal of the analog connector.
    - 3. If the power supply is not wired for local sensing, make the above connections, using small-capacity wire (#22 is sufficient).
- 4. Make sure that there is no load connected to the output terminals or bus bars.

## **Power-On Checkout (All Models)**

- 1. Connect the power cord to the power source (for Series 668xA, turn on the safety disconnect switch).
- 2. Turn the front panel power switch to ON (1).
- 3. For **Series 668xA only**, the **Check Fuses** and **Dew** LEDs should remain off. If either light is on or is blinking, go to "In Case of Trouble" at the end of this chapter.
- 4. The power supply undergoes a self-test when you turn it on. If the test is normal, the following sequence appears on the LCD:
  - a. Series 664xA/665xA The GPIB address (factory default is 5).
  - b. **Series 667xA/668xA** The GPIB address (factory default is 5). This is then followed by **PWR ON INIT** for approximately 10 seconds.
- 5. The display then goes into the meter mode with the **Dis** annunciator on and all others off. "Meter mode" means that the **VOLTS** digits indicate the output voltage and the **AMPS** digits indicate the output current. These values will be at or near zero.
- 6. Verify that the power supply fan is on by placing your hand near the rear grill to feel the air flow. You may also be able to hear the fan operating.
- 7. Press (Output on/off) once. The Dis annunciator will go off and the CV annunciator will go on .

## **Note**

If the power supply detects an error during self-test, the display will show an error message. Go to "In Case of Trouble" at the end of this chapter.

## **Using The Keypad (All Models)**

#### **Shifted Keys**

Some of the front panel keys perform two functions, one labeled in black and the other in blue. You access the blue function by first pressing the blue **Shift** key, which is not labeled. When the **Shift** annunciator is on, you will know you have access to the key's shifted (blue) function.

#### **Backspace Key**

The key is an erase key. If you make a mistake entering a number and have not yet entered it (have not pressed **Enter**), you can delete the number by pressing . You may delete as many numbers as you wish by repeatedly pressing this key.

## **Output Checkout (All Models)**

## **Important**

When the power supply is turned on, it asserts the state stored in EEPROM memory location 0. For a new supply, this is the factory default (\*RST) state. The following procedures assume that the factory default state is still in location 0 (**Turn-On Conditions** in "Chapter 5 - Front Panel" for details).

## **Checking the Voltage Function (All Models)**

The tests in Table 3-1 check the basic voltage functions with no load connected to the power supply. The **VOLTS** display will show various readings. Ignore the AMPS display.

Table	Table 3-1. Checking the Voltage Functions (Output Terminals Open)			
Procedure	Display	Explanation		
	Output Terminals Open or Connected to a Voltmeter			
If <b>Dis</b> is on, turn it off by pressing <b>Output on/off</b>				
Press <b>Voltage</b> key	VOLT 0.000	Default voltage setting. CV annunciator should be on. (If CC annunicator		
		is on, increase the current by pressing (Current) one or more times until		
		CC turns off and CV turns on.)		
, , , , , , , , , , , , , , , , , , ,	VOLT 4	Due come automat to A coalter		
Press 4	VOLT 4	Program output to 4 volts.		
Press Enter	4.000	Enter the voltage. Meter mode displays output voltage. During these		
		tests, there may be a small (relative to full output) <b>AMPS</b> reading that		
		will be ignored.		
Press [Voltage] several		Voltage decreases several millivolts each time you press the key.*		
times		Totage decreases several minimons each time you press the key.		
Press <b>[ Voltage</b> ] the same		Voltage increases several millivolts each time you press the key.*		
number of times				
		nillivolts change is determined by the voltage programming resolution of		
Datata Waltaga aantuul finat	your power supply	(see "Supplemental Characteristics" in Chapter 1).		
Rotate <b>Voltage</b> control first counterclockwise and then		Control operates similarly to Voltage and Voltage keys. The control		
clockwise		is rate sensitive. Turning it more quickly causes a more rapid change in voltage.		
CIOCKWISC		voltage.		
Press Voltage 4 Enter	4.000	Program output to 4 volts.		
~ (31)				
Press OV		Display shows default OVP (overvoltage protection) trip voltage for your		
		supply (see "Supplemental Characteristics" in Chapter 1).		
Press 3	OV 3	Program the OVP to 3 volts, which is less than the output voltage.		
Press Enter	0.000	OVP voltage entered is less than the output voltage. This causes the OVP		
		circuit to trip. The output drops to zero, <b>CV</b> turns off, and <b>Prot</b> turns on.		
Dung (Protost)	OV	Shows that the power supply shuts down because the OVD sirewit has		
Press Protect	0 4	Shows that the power supply shuts down because the OVP circuit has tripped.		
		игрреа.		
Press 🖚		Return display to meter mode (optional step).		
Press OV 4.5 Enter	0.000	Program the OVP to 4.5 volts, which is greater than the output voltage.		
		<b>Note:</b> You cannot clear an OVP trip until you have first removed the		
		cause of the condition.		
Press <b>Prot Clear</b>	4.000	The OVP circuit is cleared, restoring the output. <b>Prot</b> turns off and <b>CV</b>		
(Shift Protect)*		turns on.		
(22)				
*Shift is the unlabeled blue key.				

## **Checking the Current Function**

# WARNING

**ENERGY HAZARD.** Some supplies (Series 668xA) can provide more than 240 VA at more than 2 V. If the output connections touch, severe arcing may occur resulting in burns, ignition or welding of parts. Do not attempt to make connections while the output is live.

The tests in Table 3-2 check the basic current functions with a short connected across the power supply output. **Do not program maximum output currents unless the shorting wire is capable of handling the current** (see "Supplemental Characteristics" and Table 4-2). The **AMPS** display will show various readings. Ignore the **VOLTS** display.

**Table 3-2. Checking the Current Functions (Output Terminals Shorted)** 

Action	Display	Explanation		
7.0	Diopiay	<u> </u>		
Turn off the power supply and connect a #14 AWG or larger wire across the output (+) and (-) terminals. If you intend to test at full-rated output current, use a wire or wires of sufficient size to carry the maximum current of the supply (see "Supplemental Characteristics" in Chapter 1 and Table 4-2 in Chapter 4).				
Turn on the supply. Set the voltage to its maximum value. This example assumes that you have an 8-volt supply (see "Performance Specifications" in Chapter 1 for the value for your specific supply).	Meter mode	Essentially zero outputs with <b>Dis</b> annunciator on.		
Press Voltage 8 Enter	VOLT 8.000	Program output to 8 volts.		
Press Current 1 Enter	AMPS 1.000	Program output to 1 ampere.		
		ain to observe this step with Series 668xA supplies. Start at ag to greater output currents.		
Press Output on/off	AMPS 1. 000	<b>Dis</b> annunciator turns off, <b>CC</b> annunciator turns on, and <b>AMPS</b> display shows the programmed current.		
Press (Current) several times		*Current decreases several milliamperes each time you press the key.:		
Press <b>Current</b> the same number of times		*Current increases several milliamperes each time you press the key.		
		iamperes is determined by the current programming resolution of e "Supplemental Characteristics" in Chapter 1).		
Rotate the <b>Current</b> control first counterclockwise and then clockwise		Control operates similarly to the <b>Current</b> and <b>Current</b> keys. The control is rate sensitive. Turning it more quickly causes a more rapid change in current.		
Press OCP		You have enabled the overcurrent protection circuit. The circuit then tripped because of the output short. The <b>CC</b> annunciator turns off and the <b>OCP</b> and <b>Prot</b> annunciators come on. The output current is near zero.		

Table 3-2. Checking the Current Functions (Output Terminals Shorted) (continued)

Action	Display	Explanation		
7 1011011	2.00			
Press Output on/off	AMPS 0.000	Dis annunciator turns on.		
Press OCP		You have disabled the overcurrent protection circuit. The <b>OCP</b> annunciator turns off.		
Press (Prot Clear) (Shift (Protect))**		You have cleared the overcurrent protection circuit. The <b>Prot</b> annunciator turns off.		
Press Output on/off	AMPS 1.000	<b>Dis</b> turns off and <b>CC</b> turns on. The output current is restored.		
<b>If you have a shorting wire of sufficient capacity,</b> you may continue testing up to the maximum rated current of the power supply (see "Performance Specifications"). When finished, go to the next step.				
Press Output on/off	AMPS 0.000	Dis turns on and output current drops to zero.		
Turn off the power supply and remove the short from the output terminals.				
**(Shift) is the unlabeled blue key.				

## **Checking The Save And Recall Functions (All Models)**

The Series 668xA supplies have four nonvolatile memory storage locations (0 through 3). The supplies of all other series have five (locations 0 through 4). Proceed as follows:

- Make certain that the output is on (**Dis** annunciator is off).
- Set the voltage output to 5 by pressing **Voltage** 5 **Enter**
- Save this value to location 1 by pressing Shift Save 1 Enter
- Return the output voltage to 0 by pressing (Recall O Enter) (This step is based on the fact that a newly shipped power supply has the \*RST parameters stored in location 0 (see "Chapter 5 - Front Panel" for more information).
- Press (Recall 1) [Enter] and notice that the output voltage returns to the value stored in location 1.

## **Determining The GPIB Address (All Models)**

When the power supply is turned on, the display shows ADDR n, where n is the power supply GPIB address. Any time you want to see the address, press (Address).

The display will indicate ADDR 5, which is the factory default. If the address has been changed, then a different number will appear (see "Setting the GPIB Address" in "Chapter 5 - Front Panel").

### In Case Of Trouble

#### Line Fuse

If the power supply appears "dead" with a blank display and the fan not running, first check your power source to be certain line voltage is being supplied to the power supply. If the power source is normal, the power supply line fuse may be defective. (On Series 668xA supplies, if the Check Fuses LED is blinking, then one or two of the line fuses are open.) If the supply has a defective fuse, replace it only once. If it fails again, investigate the reason for the failure. Proceed as follows:

#### Series 664xA and 665xA Supplies

The line fuse is located on the rear panel (3, Figure 2-1). Proceed as follows:

- 1. Turn off the front panel power switch.
- 2. Using a screwdriver, remove the fuse from the fuseholder. Replace it with one of the same type (see Table 1-5 in Chapter 1). **Do not use a time-delay** type fuse.
- 3. Turn on the power supply and check the operation.

#### Series 667xA Supplies

WARNING

Hazardous voltage can remain inside the power supply even after it has been turned off. Fuse replacement should be done only by qualified electronics personnel.



The line fuse is located inside the power supply. To change it, proceed as follows:

- 1. Turn off the front panel power switch and unplug the line cord from the power source.
- 2. Remove the power supply dustcover as follows:
  - a. Remove the four screws securing the carrying straps and dustcover.
  - b. Spread the bottom rear of the dustcover and pull it back to disengage it from the front panel.
  - c. Slide the dustcover back far enough to expose the line fuse (1, Figure 3-1).
- 3. Observe the input rail LED under the RFI shield (4, Figure C-3 in "Appendix C Line Voltage Conversion"). **If the LED is on, there is still hazardous voltage inside the supply.** Wait until the LED goes out (this may take several minutes) before proceeding.
- 4. Connect a dc voltmeter across test points TPl and TP2 (Figure C-3). It may be necessary to remove the RFI shield in order to reach these test points. (The shield is secured by four screws on each side.) When the voltmeter indicates 60 volts or less, it is safe to work inside the power supply.
- 5. Replace the fuse with one of the same type (see Table 1-5 in Chapter 1). **Do not use a time-delay** type fuse.
- 6. If you removed it in step b, be sure to replace the RFI shield.
- 7. Replace the dustcover.
- 8. Connect the line cord to the power source.
- 9. Turn on the front panel power switch and check the operation.

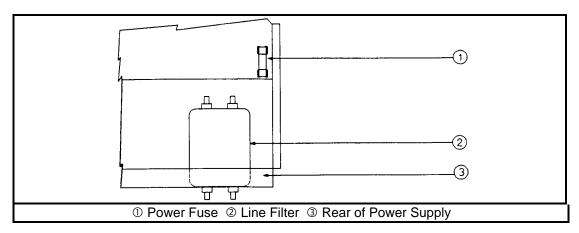


Figure 3-1. Series 667xA Line Fuse

#### Series 668xA Supplies

The line fuses are located on the rear panel (see Figure 2-4). Proceed as follows:

- 1. Turn off the front panel power switch and remove the input power (unplug the power cord or open the safety disconnect).
- 2. Remove the ac input safety cover from the rear panel.
- 3. Unscrew the fuse caps and remove the fuses.
- 4. If one or two fuses are defective, replace all three with fuses of the same type (see Table 1-5 in Chapter 1).

Note:	If all three fuses are blown, the <b>Check Fuses</b> LED will not blink and the power supply probably has a
	defect that requires service.

5. Turn on the power supply and check the operation. If it is normal, replace the ac input safety cover.

**Maintenance Note** It is recommended that new line fuses be installed every four years.

### Condensation Fault (Series 668xA Only)

If the front panel **Dew** LED is on, then there is excessive (near 100%) humidity inside the power supply. (This could occur if the supply is rapidly moved from a cold to a warm environment.) The power supply will not turn on when this LED is lit. If the LED remains on under conditions of normal humidity, the power supply has a defect and requires service. If condensation occurs after the supply is successfully turned-on, the **Dew** detector circuit will not turn off the supply.

## **Error Messages (All Models)**

Power supply failure may occur during power-on selftest or during operation. In either case, the display may show an error message that indicates the reason for the failure.

### **Selftest Errors**

When a selftest error occurs, it prevents all front panel operation. The display may show either a power-on error message or a checksum error message.

#### **Power-On Error Messages**

Power-on messages appear as:

En----

Where "n" is a number listed in Table 3-3. If this occurs, turn the power off and then back on to see if the error persists. It is possible to recover from the EE CHKSUM error (see "Checksum Errors"). If any other message persists, the power supply requires service.

Table 3-3. Power-On Selftest Errors

Error	Display	Failed Test	Error	Display	Failed Test
No.			No.		
El	FP RAM	Front Panel RAM	E8	SEC RAM	Secondary RAM
E2	FP ROM	Front Panel ROM checksum	E9	SEC ROM	Secondary ROM checksum
E3	EE	EEPROM	E10	SEC 5V	Secondary 5 V ADC
	CHKSUM				reading
E4	PRI XRAM	Primary external RAM	Ell	TEMP	Secondary ambient
E5	PRI IRAM	Primary internal RAM			thermistor reading
E6	PRI ROM	Primary ROM checksum	E12	DACS	Secondary VDAC/IDAC
E7	GPIB	GPIB R/W to serial poll			readback

#### Checksum Errors.

If the display shows **EE CHKSUM**, the power supply has detected an EEPROM checksum error. A checksum error can occur due to the following conditions:

- Excessive number of write cycles to an EEPROM (see "Nonvolatile Memory Write Cycles" in "Supplemental Characteristics" tables). This condition, which would appear only after extended use, is not recoverable and requires service.
- Loss of ac input power during a checksum calculation. This condition, which is very unlikely, is recoverable.

You may be able to recover from a checksum error by writing to the EEPROM while the power supply is in the calibration mode. To do this, proceed as follows:

- 1. Enable the calibration mode by pressing Shift Cal Enable 1 Enter
- 2. **PASWD** will appear on the display.
- 3. Press the number keys corresponding to the password, followed by **Enter**. The **Cal** annunciator will go on.

Note	On new equipment, the calibration password corresponds to the four-digit model number (such as
	<b>6651</b> ). See "Appendix A - Calibration" for more information about the calibration password.

- 4. Save any operating state (for example, press Shift Save 0 Enter).
- 5. Turn the power off and then back on.

A normal display free of error messages should appear. If not, the power supply requires service.

## **Runtime Error Messages**

Under unusual operating conditions, the **VOLT** or **AMPS** display may show **+OL** or **-OL**. This indicates that the output voltage or current is beyond the range of the meter readback circuit. Table 3-4 shows other error messages that may appear at runtime.

**Table 3-4. Runtime Errors** 

Display	Meaning
EE WRITE ERR	EEPROM status timeout
SBUB FULL	Message too long for buffer
SERIAL DOWN	Failed communication with
	front
STK OVERFLOW	Front panel stack overflow

Display	Meaning
<b>UART FRAMING</b>	UART byte framing error
UART	Overfilled UART receive buffer
OVERRUN	
UART PARITY	UART byte parity error panel

## **User Connections**

## Rear Panel Connections (All Models)

Make application load connections to the output terminals or bus bars, analog connector, and digital connector as shown on the rear-panel drawing for your model power supply. These connections are organized by series as follows:

- Series 664xA and 665xA
- Series 667xA
- Series 668xA

Make controller connections (GPIB and serial link) as shown in Figure 4-6 at the end of this chapter.

## **Load Wire Selection (All Models)**



Fire Hazard To satisfy safety requirements, load wires must be large enough not to overheat when carrying the maximum short-circuit current of the power supply. If there is more than one load, then any pair of load wires must be capable of safely carrying the full-rated current of the supply. With the larger-capacity supplies (such as Series 668xA), use of two or more load wires in parallel may be required.

Table 4-1 lists the characteristics of AWG (American Wire Gauge) copper wire.

Table 4-1. Stranded Copper Wire Capacity and Resistance

	the state of the s									
AWG No.	Ampacity <sup>l</sup>	Resistance <sup>2</sup> (Ω/m)	AWG No.	Ampacity <sup>1</sup>	Resistance² (Ω/m)					
14	25	0.0103	2	140	0.00064					
12	30	0.0065	1/0	195	0.00040					
10	40	0.0041	2/0	225	0.00032					
8	60	0.0025	3/0	260	0.00025					
6	80	0.0016	4/0	300	0.00020					
4	105	0.0010								

#### **NOTES:**

Ampacity is based on 30 °C ambient temperature with conductor rated at 60 °C. For ambient temperature other than 30 °C, multiply the above ampacities by the following constants:

Temp (°C)		Temp (°C)	
21-25	1.08	41-45	0.71
26-30	1.00	46-50	0.58
31-35	0.91	51-55	0.41
36-40	0.82		

Resistance is nominal at 75 °C wire temperature.

## **Analog Connector (All Models)**

This connector, which is on the rear panel, is for connecting remote sense leads, external current monitors, and external programming sources. The connector accepts wires sizes from AWG 22 to AWG 12.

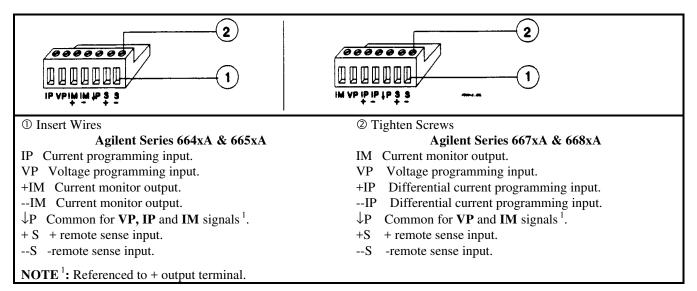


Figure 4-1. Rear Panel Analog Connector

Note	It is good engineering practice to twist and shield all signal wires to and from the analog and digital connectors.
------	---

## **Digital Connector (All Models)**

This connector, which is on the rear panel, is for connecting fault/inhibit, digital I/O, or relay link signals. The connector accepts wires sizes from AWG 22 to AWG 12.

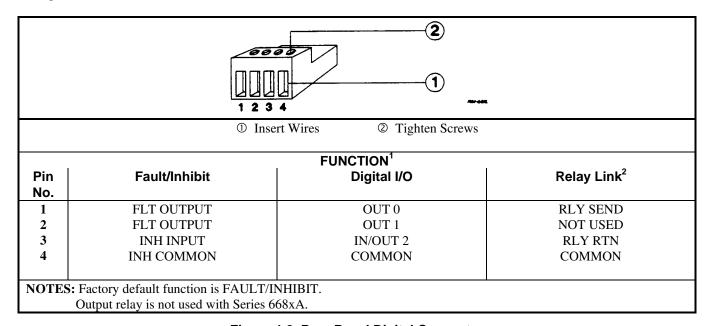


Figure 4-2. Rear Panel Digital Connector

## Connecting Series 664xA and 665xA Power Supplies To The Load

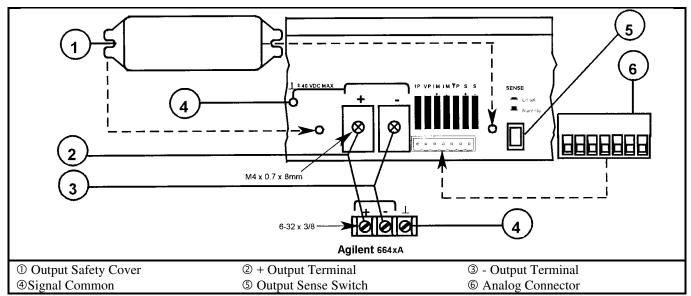


Figure 4-3a. Series 664xA and 665xA Rear Panel Output Connections

#### **Output Isolation**

The output of the power supply is isolated from earth ground. Either output terminal may be grounded, or an external voltage source may be connected between either output and ground. However, both output terminals must be kept within ± 240 Vdc of ground. An earth ground terminal is provided on the rear panel for convenience, such as grounding wire shields.



The earth ground terminal on the rear panel is a low-noise signal ground for convenience only. It is not designed to function as a safety ground.

#### **Load Considerations**

#### **Capacitive Loads**

Effect on the Output Circuit. In most cases, the power supply will continue to be stable with additional external load capacitors (see the following table for recommendations). However, large load capacitors may cause ringing in the supply's transient response. It is possible that certain combinations of load capacitance, equivalent series resistance, and load lead inductance will result in instability. If you need help in solving a stability problem, contact an Agilent service engineer through your local Sales and Support Office (see end of this guide).

Series 664xA/665xA Power Supplies, Maximum External Capacitance (μF)										
6641A	6642A	6643A	6644A	6645A	6651A	6652A	6653A	6654A	6655A	
40,000	20,000	12,000	7,000	3,000	100,000	50,000	30,000	18,000	8,000	

If the power supply output is rapidly programmed into capacitive loads, the supply may momentarily cross into CC mode. This extends the CV programming time and limits the maximum slew rate to the programmed current divided by the total internal (see the following section "Inductive Loads") and external capacitance. These momentary crossovers into CC mode will not damage the supply.

Effect on the OVP Circuit. The OVP circuit is designed to discharge fully-charged capacitances up to a specified limit for each model. These limits are as follows:

#### Series 664xA/665xA Power Supplies, Maximum OVP External Capacitance (µF)

6641A	6642A	6643A	6644A	6645A	6651A	6652A	6653A	6654A	6655A
700,000	35,000	15,000	7,000	3,000	1.6 (F)	100,000	50,000	18,000	8,000

If a load capacitance approaches the specified limit, it is recommended that you do not make it a normal practice of tripping the OVP circuit and discharging the load capacitance through that circuit. This could cause long-term fatigue in some circuit components.

CAUTION

Because of its high output voltage, the Agilent 6555A generates very high currents when discharging the load capacitor under overvoltage conditions. Excessive currents can damage the supply. The peak discharge current is limited by the sum of the external capacitor's ESR (equivalent series resistance) and the series resistance of the external circuit. For the Agilent 6555A external capacitance limit of  $8,000~\mu\text{F}$ , this total resistance must be not less than 56 milliohms. For smaller values of external capacitance, this resistance may be derated linearly.

#### **Inductive Loads**

Inductive loads provide no loop stability problems in CV mode. However, in CC mode inductive loads will form a parallel resonance network with the power supply's output capacitor. Generally, this will not affect the stability of the supply, but it may cause ringing of the current in the load. Ringing will not occur if the Q (quality factor) of the parallel resonant network is  $\leq 0.5$ . Use the following formula to determine the Q of your output.

$$Q = \frac{1}{R_{int} + R_{ext}} \sqrt{\frac{L}{C}}$$

where: C = model-dependent internal capacitance (see below); L = inductance of the load;  $R_{ext} = equivalent$  series resistance of the load;  $R_{int} = model$ -dependent internal resistance (see below):

	6641A	6642A	6643A	6644A	6645A	6651A	6652A	6653A	6654A	6655A
C =	$4,200  \mu F$	550 μF	180 μF	68 µF	$33 \mu F$	$10,000 \mu F$	$1100 \mu F$	$440  \mu F$	$120 \mu F$	50 μF
$R_{int} =$	$7~\mathrm{m}\Omega$	$30~\text{m}\Omega$	$50~\mathrm{m}\Omega$	$125~\mathrm{m}\Omega$	$300~\mathrm{m}\Omega$	$4~\mathrm{m}\Omega$	$20~\mathrm{m}\Omega$	$30~\mathrm{m}\Omega$	$80~\mathrm{m}\Omega$	$250~\mathrm{m}\Omega$

### **Battery Charging**

The power supply's OVP circuit contains a crowbar SCR that effectively shorts the output of the supply whenever OVP trips. If a battery (or other external voltage source) is connected across the output and the OVP is inadvertently triggered or the output is programmed below the battery voltage, the power supply will continuously sink a large current from the battery. This could damage the supply. To avoid this, insert a reverse blocking diode in series with the  $\oplus$  output of the supply. Connect the diode **cathode** to the + battery terminal and the diode **anode** to the supply  $\oplus$  output terminal. The diode may require a heat sink.

Note that if the OVP trips, you must remove the external current source in order to reset the internal SCR as part of clearing the OVP circuit (see Clearing the OV Condition in "Chapter 5 - Front Panel Operation").

## **Local Voltage Sensing**

Your power supply was shipped set up for local sensing. This means that the supply will sense and regulate its output at the output terminals, not at the load. Since local sensing does not compensate for voltage drops across screw terminals, bus bars, or load leads, local sensing should only be used in applications that require low output current or where load regulation is not critical.

Local sensing is obtained by placing the **SENSE switch** (see Figure 4-3a) in the **Local** position. The power supply is shipped with the switch in this position.

### **60** User Connections

#### **Note**

If the sense terminals are left unconnected, the voltage at the bus bars will increase approximately 3 to 5% over the programmed value. Since it is measured at the sense terminals, the voltage readback will not reflect this increased output.

#### **Remote Voltage Sensing**

The dashed lines in the wiring diagrams illustrate remote voltage sensing. The remote sense terminals of the power supply are connected directly to the load rather than to the output terminals. This allows the supply to automatically compensate for the voltage drop in the load leads as well as to accurately read back the voltage directly across the load.

#### **Setting Up Remote Sense Operation**

Remote sensing is obtained by placing the SENSE switch (see Figure 4-3a) in the **Remote** position. The power supply is shipped with the switch in the **Local** position.

## **Connecting The Sense Leads**

You must connect the positive side of the load to the +S analog connector pin and the negative side of the load to the -S analog connector pin (see Figure 4-1). Connect the sense leads carefully so that they do not become open-circuited. If sense leads are left open during operation, the supply will regulate at the output terminals instead of at the load. Remember to bundle or tie wrap the load leads to minimize inductance and reduce noise pickup.

## **CV** Regulation

The voltage load regulation specification in Table 1-la and Table 1-2a applies at the output terminals of the power supply. When remote sensing, this specification must be compensated. Add 3 mV to the voltage load regulation specification for each 1-volt change in the positive load lead due to a change in load current. Because the sense leads are part of the supply's feedback path, keep the resistance of the sense leads at or below  $0.5 \Omega$  to maintain the above specified performance.

#### **OVP Considerations**

The OVP circuit senses the voltage near the output terminals, not at the sense terminals. The voltage sensed by the OVP circuit can be significantly higher than the voltage being maintained at the load. When using remote sensing, you must program the OVP high enough to compensate for the expected voltage drop between the output and the load.

#### **Output Rating**

The rated output voltage and current specification in Table 1-la and Table 1-2a applies at the output terminals of the power supply. With remote sensing, any voltage dropped in the load leads causes the supply to increase the voltage at the output terminals so it can maintain the proper voltage at the load. When you attempt to operate at the full-rated output at the load, this forces the supply voltage at the output terminals to exceed the supply's rated output.

This will not damage the supply, but may trip the OVP (overvoltage protection) circuit, which senses the voltage at the output. When operated beyond its rated output, the supply's performance specifications are not guaranteed, although typical performance may be good. If the excessive demand on the supply forces it to lose regulation, the **Unr** annunciator will indicate that the output is unregulated.

#### **Output Noise**

Any noise picked up on the sense leads also appears at the output of the power supply and may adversely affect the load voltage regulation. Be sure to twist the sense leads to minimize external noise pickup and route them parallel and close to the load leads. In noisy environments, it may be necessary to shield the sense leads. Ground the shield only at the power supply. *Do not use the shield as one of the sense conductors*.

## **Stability**

Using remote sensing under unusual combinations of load-lead lengths and large load capacitances may cause your application to form a low-pass filter that becomes part of the voltage feedback loop. The extra phase shift created by this filter can degrade the supply's stability and result in poor transient response. In severe cases, this may cause output oscillations. To minimize this possibility, keep the load leads as short as possible and tie wrap them together.

In most cases, following the above guidelines will prevent problems associated with load lead inductance. This leaves load load-lead resistance and load capacitance as the major source of reduced stability. Further improvement to the stability of the supply may be obtained by keeping the load capacitance as small as possible and by decreasing the load-lead resistance by using larger diameter wires. However, if heavy gauge wire (≥ AWG 10) is used, conditions may arise where the load-lead inductance and load capacitance can form an undamped filter. This can actually reduce the damping in the system and create a destabilizing phase response.

**Note** 

If you need help in solving a stability problem with any Series 664xA or 665xA power supply contact an Agilent Service Engineer through your local Agilent Sales and Support Offices.

### **Operating Configurations**

Figure 4-3b through Figure 4-3f show the various configurations for connecting to the load. Figure 4-3g shows how to connect an external voltage source for analog programming.

#### **Connecting One Supply to the Load**

Figure 4-3b and Figure 4-3c show how to connect a single power supply to one load and to multiple loads.

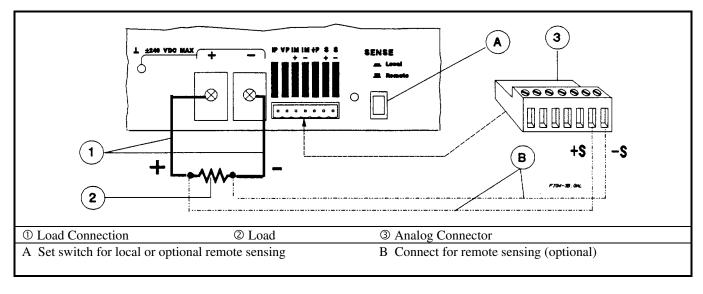


Figure 4-3b. Series 664xA and 665xA Single Load Connection

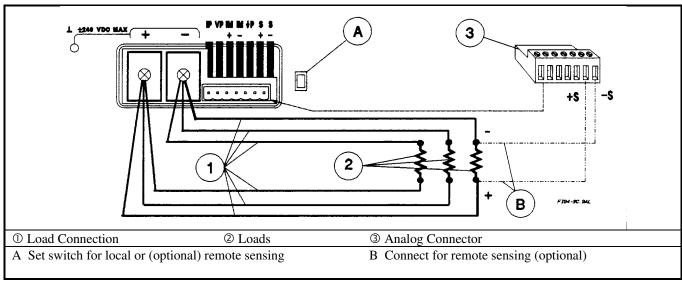


Figure 4-3c. Series 664xA and 665xA Multiple Load Connection (Remote Sensing Optional)

### **Connecting Supplies in Auto-Parallel**

**Auto-Parallel Wiring.** Figure 4-3d illustrates how power supplies can be connected in auto-parallel for increased current output. You can connect up to three supplies of the *same model*.

Use load leads of a sufficient wire size so that the absolute voltage difference between the + output terminal of the "master" supply and the + output terminal of the first "slave" supply is kept under 2 V at rated current. This also applies to the voltage difference between the + output terminals of the first and second slave supplies. If remote sensing is required, connect the load to the remote sense terminals of the master supply, as shown by the dashed lines in Figure 4-3d.

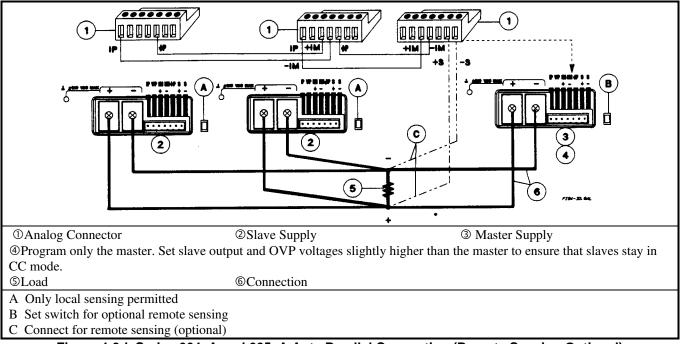


Figure 4-3d. Series 664xA and 665xA Auto-Parallel Connection (Remote Sensing Optional)

**Note** To avoid output oscillations, observe the wiring suggestions given under "External Voltage Control".

**Auto-Parallel Programming.** Program only the first ("master") supply in the series; the "slave" supplies automatically track the master's output. However, the voltage and OVP settings of the slave supplies must be set higher than the operating voltage of the master supply. This ensures that the slave supplies will operate in CC mode. Functions such as status, voltage readback, and current readback can still be read back individually for each supply.

If a "slave" supply experiences a desired shutdown condition (such as overtemperature or overcurrent), it will not automatically shut down all other supplies. You must first enable remote inhibit (RI) and discrete fault indicator (DFI) operation. See "Fault/Inhibit Operation" in Appendix D for wiring information and "Questionable Status Group" in Chapter 4 of the Programming Guide for programming information.

CAUTION

Follow the following operating precautions if you are connecting **three** of these models in auto-parallel.

You must use caution when connecting three Series 664xA or 665xA power supplies for auto-parallel operation. That is because of the OVP crowbar circuits within these supplies. If the OVP circuit of the second "slave" trips, its crowbar circuit will draw current from the other two supplies. Although some models can withstand this current, the higher-current models in each series (particularly the Agilent 6651A) may be damaged in this situation. Use any of the following operating techniques to avoid possible problems.

## 1. Program Slave 2 OVP to the Maximum Level

The following technique minimizes the chance that the slave 2 OVP circuit will trip.

- a. Program the OVP level of the master and of slave 1 to the desired protection level (below the maximum level specified in Table 1-2).
- b. Program the OV protection level of slave 2 to its maximum value.

#### 2. Enable OCP on the Master

You can do this if the combination of all three supplies is being used in the CV mode and the CC mode is only being used as a current limit. Enable OCP on the master supply. If the OVP on either slave trips it will drive the master into CC mode, thereby tripping its OCP. This will shut down all three supplies. This technique will work unless the system is programmed for very low (0.5 to 1.5) output voltages.

#### 3. Insert Protection Diodes

If you connect the slave 2 supply to the load through a series diode (see Figure 4-3e), its OVP circuit will not draw current from other supplies. Be certain to increase the programmed CV level of slave 2 by at least 0.7 V to compensate for the voltage drop in the diode.

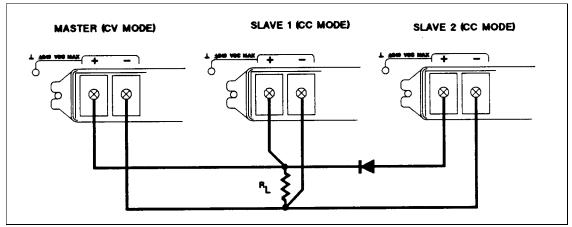


Figure 4-3e. Using Series Diodes with Series 664xA & 665xA Auto-Parallel Operation

**Note** 

Removing or disabling the power supply OVP crowbar SCR is another possibility. For further information, contact a Agilent Service Engineer through your local Agilent Sales and Support Offices.

#### **Connecting Supplies in Series**

WARNING

Floating voltages must not exceed ±240 Vdc. No output terminal may be more than 240 V from chassis ground.

Figure 4-3f shows how power supplies can be connected in series for higher voltage output.

Series connections are straightforward in this case. Program each power supply independently. If two supplies are used in the series configuration, program each supply for 50% of the total output voltage. Set the current limit of each supply to the maximum that the load can handle without damage.

CAUTION

Each power supply has a reverse voltage protection diode across its output. If a reverse voltage is applied, the supply cannot control the current conducted through this diode. To avoid damaging the supply, never connect it in such a way that a reverse voltage can force it to conduct current in excess of the supply's maximum reverse diode current (see Table 1-2).

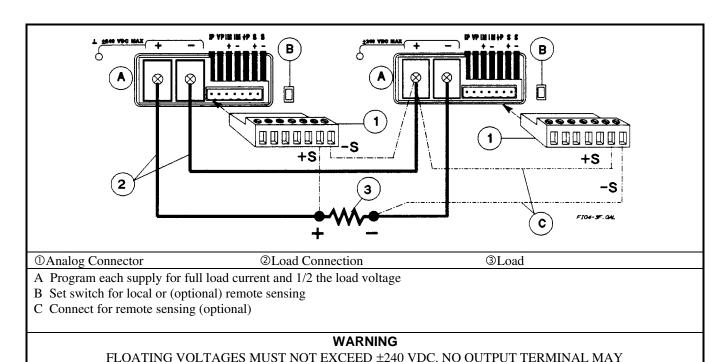


Figure 4-3f. Series 664xA and 665xA Series Connection (Remote Sensing Optional)

BE MORE THAN 240 V FROM CHASSIS GROUND

#### **External Voltage Control**

The setup shown in Figure 4-3g allows an external dc voltage to program the power supply output. A voltage applied to the voltage programming input programs the output voltage and a voltage applied to the current programming input programs the output current. See Figure 4-1 for an explanation of these programming input connections.

### Wiring Considerations

The input impedance of the analog input is  $10 \text{ k}\Omega$ . If the output impedance of your programming source is not negligible with this, programming errors will result. Larger output impedances result in proportionally greater errors.

Be careful of capacitive coupling from the programming inputs to other lines wired to the analog connector. Such coupling can cause output oscillations. You can minimize coupling by bundling the **IP**, **VP**, **and Common P** lines and keeping them separated from other wires. Twisting these three lines together is also recommended.

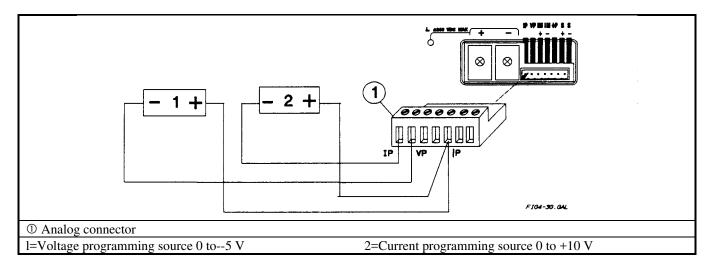


Figure 4-3g. Series 664xA and 665xA Analog Programming Connections

If you cannot avoid capacitive coupling, it may help to place capacitors from the unused programming inputs to ground. Especially with auto-parallel operation, connecting a capacitor ( $\geq$ 4,000 pF) from **VP** to **P** Common on the master supply will ensure proper operation. Also with auto-parallel operation, do not allow more than about 500 pF capacitive loading between **IM** and **Common P**.

**Programming Considerations.** When voltage programming the output, the frequency of the programming source is limited by the slew rate of the power supply. To keep the power supply from slewing its output (going into nonlinear operation), the maximum programming rate is 3750 V/s. The maximum downprogramming rate (when the power supply is sinking current) is 750 V/s. These restrictions can be expressed as the maximum programming frequency that can be applied without causing distortion at the output. The following formula can be used to determine this frequency:

 $F_{MAX} = 50$ (voltage rating of supply) p-p amplitude of desired output sine wave

At frequencies >6 kHz, voltage programming is subject to a 3 dB bandwidth limitation.

## Connecting Series 667xA Power Supplies To The Load

## **Output Isolation**

The output of the power supply is isolated from earth ground. Either output terminal may be grounded, or an external voltage source may be connected between either output and ground. However, both output terminals must be kept within  $\pm$  240 Vdc of ground. An earth ground terminal is provided on the rear panel for convenience, such as grounding wire shields.

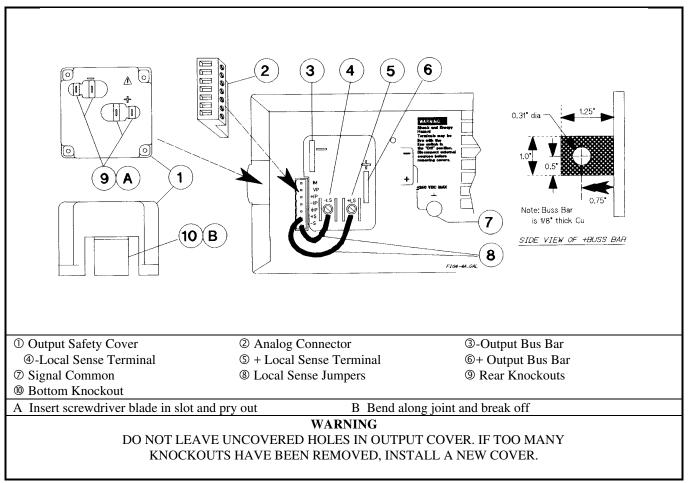


Figure 4-4a. Series 667xA Rear Panel Output Connections



The earth ground terminal on the rear panel is a low-noise signal ground for convenience only. It is not designed to function as a safety ground.

#### **Load Considerations**

### **Capacitive Loads**

In most cases, the power supply will continue to be stable with additional external load capacitors. However, large load capacitors may cause ringing in the supply's transient response. It is possible that certain combinations of load capacitance, equivalent series resistance, and load lead inductance will result in instability. If you need help in solving a stability problem, contact a service engineer through your local Sales and Support Offices (see end of this guide).

If the power supply output is rapidly programmed into capacitive loads, the supply may momentarily cross into constant current (CC) mode. This extends the CV programming time and limits the maximum slew rate to the programmed current divided by the total internal and external capacitance. These momentary crossovers into CC mode will not damage the supply.

#### **Inductive Loads**

Inductive loads provide no loop stability problems in CV mode. However, in CC mode inductive loads will form a parallel resonance network with the power supply's output capacitor. Generally, this will not affect the stability of the supply, but it may cause ringing of the current in the load. Ringing will not occur if the Q (quality factor) of the parallel resonant network is  $\leq 1.0$ . Use the following formula to determine the Q of your output.

$$Q = \frac{1}{R \text{ int} + Re \text{ xt}} \sqrt{\frac{L}{C}}$$

where: C = model-dependent internal capacitance (see below); L = inductance of the load; Rext = equivalent series resistance of the load;  $R_{int} = model$ -dependent internal resistance (see below):

	6671A	6672A	6673A	6674A	6675A
C=	$44,000 \mu F$	$44,000 \mu F$	$12,000 \mu F$	$7,000  \mu F$	$2,100 \mu F$
$R_{int} =$	$1.8~\mathrm{m}\Omega$	$2.2~\mathrm{m}\Omega$	$4~\mathrm{m}\Omega$	$14~\mathrm{m}\Omega$	$30~\mathrm{m}\Omega$

If the Q is greater than 0.5, inductive loads will ring with the output capacitance and will be damped according to the following equation:

$$\delta = \left[ e^{\left(\frac{-t}{2R}\right)} \right) \sin \omega t \sqrt{1 - \left(\frac{1}{2Q}\right)^2}$$

## **Battery Charging**

The power supply's OVP circuit has a downprogrammer FET that discharges the power supply output whenever OVP trips. If a battery (or other external voltage source) is connected across the output and the OVP is inadvertently triggered or the output is programmed below the battery voltage, the power supply will sink current from the battery. To avoid this, insert a reverse blocking diode in series with the  $\oplus$  output of the supply. Connect the diode cathode to the + battery terminal and the diode anode to the supply  $\oplus$  output terminal. The diode may require a heat sink.

## **Local Voltage Sensing**

Your power supply was shipped set up for local sensing. This means that the supply will sense and regulate its output at the output terminals, not at the load. Since local sensing does not compensate for voltage drops across screw terminals, bus bars, or load leads, local sensing should only be used in applications that require low output current or where load regulation is not critical.

Local sensing is obtained by connecting the **+LS** sense terminal to the **+S** analog connector pin and the pin and the **-LS** sense terminal to the **-S** analog connector pin. The power supply is shipped with these connections made.

If the sense terminals are left unconnected, the voltage at the bus bars will increase approximately 3 to 5% over the programmed value. Since it is measured at the sense terminals, the voltage readback will not
reflect this increased output.
(

#### **Remote Voltage Sensing**

The dashed lines in the wiring diagrams illustrate remote voltage sensing. The remote sense terminals of the power supply are connected directly to the load rather than to the output terminals. This allows the supply to automatically compensate for the voltage drop in the load leads as well as to accurately read back the voltage directly across the load.

#### **Setting Up Remote Sense Operation**

Remote sensing is obtained by removing the jumpers connecting the **+LS** sense terminal to the **+S** analog connector pin and the **-LS** sense terminal to the **-S** analog connector pin. The power supply is shipped with these jumpers connected.

#### **Connecting the Sense Leads**

You must connect the positive side of the load to the +S analog connector pin and the negative side of the load to the -S analog connector pin (see Figure 4-1). Connect the sense leads carefully so that they do not become open-circuited. If sense leads are left open during operation, the supply will regulate at the output terminals instead of at the load. Remember to bundle or tie wrap the load leads to minimize inductance and reduce noise pickup.

### **CV** Regulation

The voltage load regulation specification in Table 1-3a applies at the output terminals of the power supply. When remote sensing, this specification must be compensated. Add an increment to the voltage load regulation specification as specified by " $\Delta mV$ " in the equation given under *Load regulation* in Table 1-3b.

## **Output Rating**

The rated output voltage and current specification in Table 1-3a applies at the output terminals of the power supply. With remote sensing, any voltage dropped in the load leads causes the supply to increase the voltage at the output terminals so it can maintain the proper voltage at the load. When you attempt to operate at the full-rated output at the load, this forces the supply voltage at the output terminals to exceed the supply's rated output. This will not damage the supply, but may trip the OVP (overvoltage protection) circuit, which senses the voltage at the output bus bars. When operated beyond its rated output, the supply's performance specifications are not guaranteed, although typical performance may be good. If the excessive demand on the supply forces it to lose regulation, the **Unr** annunciator will indicate that the output is unregulated.

#### **Output Noise**

Any noise picked up on the sense leads also appears at the output of the power supply and may adversely affect the load voltage regulation. Be sure to twist the sense leads to minimize external noise pickup and route them parallel and close to the load leads. In noisy environments, it may be necessary to shield the sense leads. Ground the shield only at the power supply. *Do not use the shield as one of the sense conductors*.

**Note** 

The signal ground binding post on the rear panel is a convenient place to ground the sense shield.

#### **OVP Considerations**

The OVP circuit senses the voltage near the output terminals and not at the sense terminals. Depending on the voltage drop between the output terminals and the load, the voltage sensed by the OVP circuit can be significantly higher than actually being regulated at the load. You must program the OVP trip high enough to compensate for the expected higher voltage at the output terminals.

#### **Stability**

Using remote sensing under unusual combinations of load-lead lengths and large load capacitances may cause your application to form a low-pass filter that becomes part of the voltage feedback loop. The extra phase shift created by this filter can degrade the supply's stability and result in poor transient response. In severe cases, this may cause output oscillations. To minimize this possibility, keep the load leads as short as possible and tie wrap them together.

In most cases, following the above guidelines will prevent problems associated with load lead inductance. However, if a large bypass capacitor is required at the load and load-lead length cannot be reduced, then a sense-lead bypass network may be needed to ensure stability (see Figure 4-4b). The voltage rating of the 33  $\mu$ F capacitors should be about 50% greater than the anticipated load-lead drop. Addition of the 20- $\Omega$  resistors will cause a slight voltage rise at the remote sensing points. For utmost voltage programming accuracy, the supply should be recalibrated with the DVM at the remote sensing points (see "Appendix A - Calibration").

Note

If you need help in solving a stability problem with any Series 667xA power supply contact an Agilent Service Engineer through your local Agilent Sales and Support Offices.

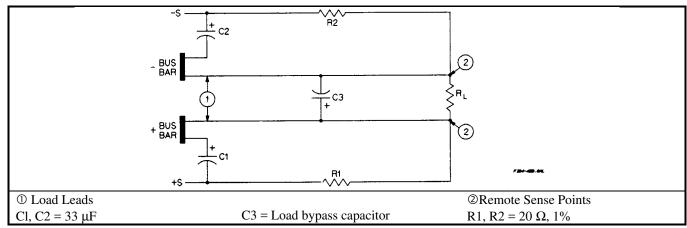


Figure 4-4b. Series 667xA Sense Lead Bypass Network

### **Operating Configuration**

Figure 4-4c through Figure 4-4f show the various configurations for connecting to the load. Figure 4-4g shows how to connect an external voltage source for analog programming.

## Connecting One Power Supply to a Single Load (Figure 4-4c)

Figure 4-4c shows how to connect a single power supply to one load. Keep output load leads close together (small loop area) to obtain a low inductance and low impedance connection to the load. If you wish to use remote sensing, connect the sense leads at the load as shown in the figures.

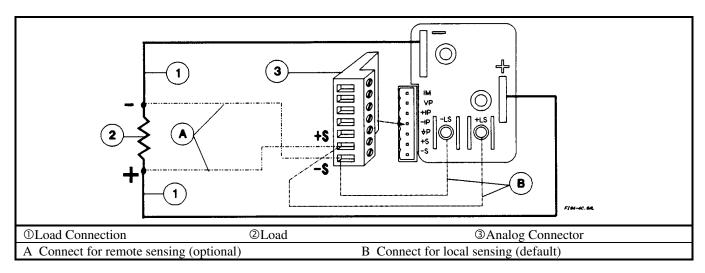


Figure 4-4c. Series 667xA Single Load Connection (Remote Sensing Optional)

## Connecting One Power Supply To Multiple Loads (Figure 4-4d)

Figure 4-4d shows how to connect a single power supply to more than one load. When connecting multiple loads to the power supply with local sensing, connect each load to the output bus bars with separate connecting wires. This minimizes mutual coupling effects and takes full advantage of the supply's low output impedance. Keep each pair of load wires as short as possible and twist or bundle them to reduce lead inductance and noise pickup.

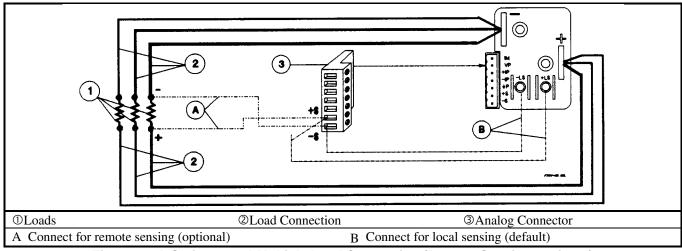


Figure 4-4d. Series 667xA Multiple Load Connection (Remote Sensing Optional)

## **Connecting Supplies in Auto-Parallel**

Auto-Parallel Wiring (Figure 4-4e). Figure 4-4e illustrates how power supplies can be connected in auto-parallel for increased current output. You can connect up to five supplies of the *same model*.

Use load leads of a sufficient wire size so that the absolute voltage difference between the + output terminal of the "master" supply and the + output terminal of the first "slave" supply is kept under 2 V at rated current. This also applies to the voltage difference between the + output terminals of the first and second slave supplies. If remote sensing is required, connect the load to the remote sense terminals of the master supply, as shown by the dashed lines in Figure 4-4e.

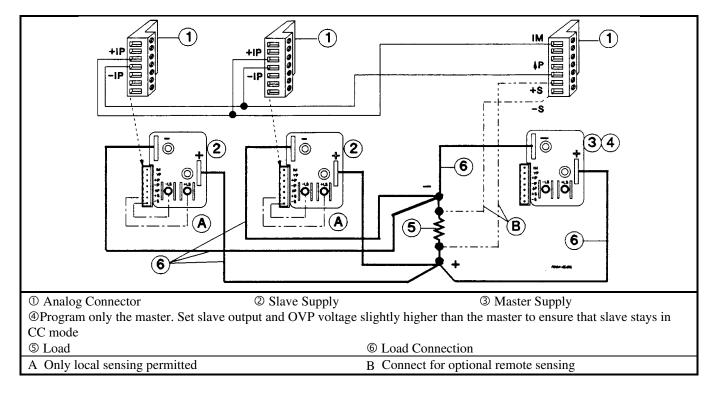


Figure 4-4e. Series 667xA Auto-Parallel Connection (Remote Sensing Optional)

**Auto-Parallel Programming.** Program only the first ("master") supply in the series; the "slave" supplies automatically track the master's output. However, the voltage and OVP settings of the slave supplies must be set higher than the operating voltage of the master supply. This ensures that the slave supplies will operate in CC mode. Functions such as status, voltage readback, and current readback can still be read back individually for each supply.

If a "slave" supply experiences a desired shutdown condition (such as overtemperature or overcurrent), it will not automatically shut down all other supplies. You must first enable remote inhibit (RI) and discrete fault indicator (DFI) operation. See "Fault/Inhibit Operation" in "Appendix D - Digital Port Functions" for wiring information and "Questionable Status Group" in Chapter 4 of the "Programming Guide" for programming information.

### **Connecting Supplies in Series**

WARNING

Floating voltages must not exceed 240 Vdc. No output terminal may be more than 240 V from chassis ground.

Figure 4-4f shows how power supplies can be connected in series for higher voltage output. Series connections are straightforward in this case.

Program each power supply independently. If two supplies are used in the series configuration, program each supply for 50% of the total output voltage. Set the current limit of each supply to the maximum that the load can handle without damage.

CAUTION

Each power supply has a reverse voltage protection diode across its output. If a reverse voltage is applied, the supply cannot control the current conducted through this diode. To avoid damaging the supply, never connect it in such a way that a reverse voltage can force it to conduct current in excess of the supply's maximum reverse diode current (see Table 1-2b).

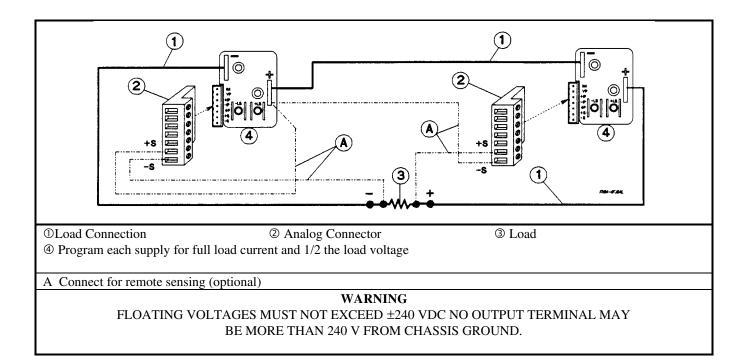


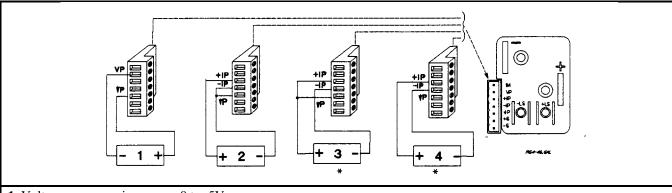
Figure 4-4f. Series 667xA Series Connection (Remote Sensing Optional)

#### **External Voltage Control**

The setup shown in Figure 4-4g allows an external dc voltage to program the power supply output. A voltage applied to the voltage programming input programs the output voltage and a voltage applied to the current programming input programs the output current. See Figure 4-1 for an explanation of these programming input connections.

#### Wiring Considerations (Figure 4-4g)

The input impedance of the analog input is over 30 k $\Omega$ . If the output impedance of your programming source is not negligible with this, programming errors will result. Larger output impedances result in proportionally greater errors.



- 1 Voltage programming source 0 to -5V
- 2 Differential current programming source 0 to +10 V
- 3 Differential current programming source 0 to -10 V
- 4 Current programming source (floating) 0 to 10 V
- \* Maximum Potential between -IP and  $\downarrow$ P is  $\pm 15$  V

Figure 4-4g. Series 667xA Analog Programming Connections

#### **Programming**

Note from Figure 4-1 that you have three options for programming the current. You can use a voltage source that is positive, negative, or floating with respect to Common P. Do not exceed ±19 V with respect to Common P.



Make certain that the common connection for your voltage programming source is isolated from the load. Failure to do this may cause damage to the power supply.

The effect of the analog programming source is always summed with the values programmed over the GPIB or from the front panel. The voltage source can act alone only if you set the other program sources to zero. Keep the total programmed setting of the supply (the analog input summed with the GPIB or front panel settings) at or under the output ratings specified in Table 1-2a. Exceeding the output ratings will not damage the supply, but it may not be able to regulate its output at the higher levels. If this happens, the **Unr** annunciator will light to warn you that the output is unregulated.

# Connecting Series 668xA Power Supplies To The Load

WARNING

**ENERGY HAZARD**. These power supplies can provide more than 240 VA at more than 2 V. If the output connections touch, severe arcing may occur resulting in burns, ignition or welding of parts. Do not attempt to make connections to live output circuits.

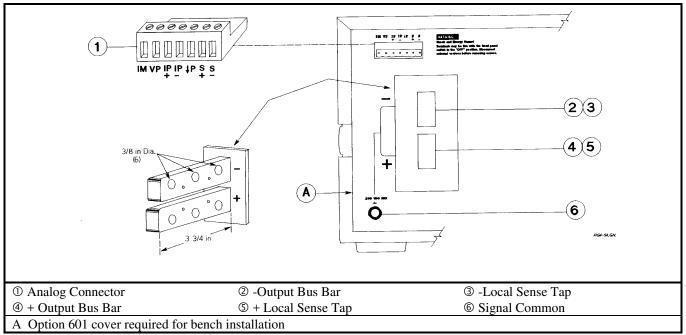


Figure 4-5a. Series 668xA Rear Panel Output Connections

#### **Output Isolation**

Except for a high value (>1  $M\Omega$ ) internal bleeder resistor, the output of the power supply is isolated from earth ground. Either output terminal may be grounded or an external dc voltage source may be connected between either output and ground. However, both output terminals must be kept within  $\pm 60$  Vdc of ground.



The earth ground terminal located near the output bus bars is a low-noise signal ground for convenience only. It is not designed to function as a safety ground.

#### **Load Considerations**

#### Capacitive Loads

In most cases, the power supply will maintain stability with external load capacitors. However, large load capacitors may cause ringing in the supply's transient response. It is possible that certain combinations of load capacitance, equivalent series resistance, and load-lead inductance will result in instability (see also "Stability" under "Remote Sensing"). If you need help solving a stability problem, contact an Agilent Service Engineer through your local Agilent Sales and Support Offices.

If the output is rapidly programmed into capacitive loads, the power supply may momentarily cross into CC operation, thereby extending the CV programming time. When it crosses into CC mode, the supply's maximum slew rate is limited by the CC loop and is a function of the loop current compensation. This may be optimized for particular compensation. These momentary crossover situations, which are communicated via the status register, may increase programming times, but will not damage the power supply.

#### **Inductive Loads**

Inductive loads present no loop stability problems in CV mode. In CC mode, inductive loads will form a parallel resonance with the power supply's output capacitor, possibly causing current ringing in the load. For a given inductance, the power supply's CC control loop can be made to stabilize the current. However, stabilizing the current for a very large load inductance creates a much slower mode crossover (CV to CC or vice versa) time. Thus, there is a tradeoff between mode crossover speed and inductive compensation. To allow an optimal solution for each load, a CC loop compensation switch is provided so the CC control loop can be optimized for a specific load inductance. See "Appendix E - Current Loop Compensation" for details.

#### **Battery Charging**

The power supply's OVP circuit has a downprogrammer FET that discharges the power supply output whenever OVP trips. If a battery (or other external voltage source) is connected across the output and the OVP is inadvertently triggered or the output is programmed below the battery voltage, the power supply will sink current from the battery. To avoid this, insert a reverse blocking diode in series with the  $\oplus$  output of the supply. Connect the diode cathode to the + battery terminal and the diode **anode** to the supply  $\oplus$  output terminal. The diode will require a heat sink.

#### **Local Voltage Sensing**

For local sensing the +S and--S analog connector pins must be connected to the + and - bus bars (see Figure 4-5b). This is the default configuration as wired at the factory. Each sense lead is connected to the small, tapped hole nearest the corresponding output lead. Since local sensing does not compensate for voltage drops in the screw connections or load leads, local sensing should only be used in applications that require low output currents or where load regulation is not critical.

Note	If the sense terminals are left open
	over the programmed value. The i

en, the voltage at the output bus bars will increase approximately 3 to 5% over the programmed value. The readback voltage will not reflect this increase because readback is measured at the sense terminals.

## **Remote Voltage Sensing**

The dashed lines in the wiring diagrams illustrate remote voltage sensing. The remote sense terminals of the power supply are connected directly to the load rather than to the output bus bars. This allows the supply to automatically increase the voltage at the output bus bars to compensate for any voltage drop in the load leads, as well as to accurately read back the voltage directly from the load.

#### **Setting Up Remote Sense Operation**

You must connect the positive side of the load to the +S analog connector pin and the negative side of the load to the -S analog connector pin (see Figure 4-1). Connect the sense leads carefully so that they do not become open-circuited. If sense leads are left open during operation, the supply will regulate at the output bus bars instead of at the load. Remember to bundle or tie wrap the load leads to minimize inductance and reduce noise pickup.

The sense leads are part of the supply's feedback path and must be kept at a low resistance in order to maintain optimal performance. Connect the sense leads carefully so that they do not become open-circuited. If the sense leads are left unconnected or become open during operation, the supply will regulate at the output bus bars, resulting in a 3 to 5% increase in output over the programmed value.

The maximum output voltage under remote sensing is reduced by the voltage drop in the load leads. See "Remote Sensing Capability" in Table 1-3b for further characteristics and a general formula for determining the extra degradation in the output due to voltage drop in the output leads.

#### **OVP Considerations**

The power supply OVP circuit senses voltage near the output bus bars, not at the load. Therefore the signal sensed by the OVP circuit can be significantly higher than the actual voltage at the load. When using remote sensing, you must program the OVP trip voltage high enough to compensate for the voltage drop between the output bus bars and the load.

#### **Output Rating**

In remote sense applications, the voltage drop in the load leads subtracts from the available load voltage. As the power supply increases its output to overcome this voltage drop, the sum of the programmed voltage and the load-lead drop may exceed the power supply's maximum voltage rating. This will not damage the supply, but may trip the OV protection circuit, which senses the voltage at the output bus bars. When the supply is operated beyond its rated output the performance specifications are not guaranteed, although typical performance may be good.

#### **Stability**

Using sensing under unusual combinations of load lead lengths and large load capacitances may cause your application to form a low-pass filter, which becomes part of the voltage feedback loop. The extra phase shift created by this filter can degrade the supply's stability, resulting in poor transient response. In severe cases, it may cause oscillation. To minimize this possibility, keep the load leads as short as possible and tie wrap them together.

In most cases, following these guidelines will eliminate problems associated with load lead inductance. However, if a large bypass capacitor is required at the load and load-lead length cannot be reduced, then a sense-lead bypass network may be needed to ensure stability (see Figure 4-5b).

The voltage rating of the 33  $\mu$ F capacitors should be about 50% greater than the anticipated load-lead drop. Addition of the 20  $\Omega$  resistors will cause a slight voltage rise at the remote sensing points. For utmost voltage programming accuracy, the supply should be recalibrated with the DVM at the remote sensing points (see "Appendix A - Calibration"). In addition, the sense protect resistors inside the power supply may have to be removed. (If you need help with a stability problem, contact an Support Engineer through your local Agilent Sales and Support offices.)

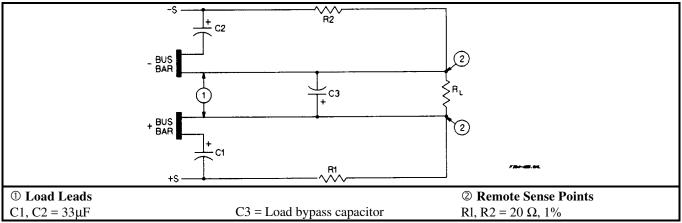


Figure 4-5b. Series 668xA Sense Lead Bypass Network

#### **Output Noise**

Any noise picked up on the sense leads may appear at the output of the supply and can adversely affect the voltage load regulation. Use shielded twisted pairs for the sense leads and route them parallel and close to the load leads. Ground the shields only at the power-supply end, utilizing the signal ground binding post. *Do not use a shield as one of the sense conductors.* Bundle or tie-wrap the load leads to minimize inductance and reduce noise pickup.

#### **Operating Configurations**

Figure 4-5c through Figure 4-5e show the various configurations for connecting to the load. Figure 4-5f shows how to connect an external voltage source for analog programming.

## 76 User Connections

#### Connecting One Power Supply to a Single Load

Figure 4-5c shows how to connect a single power supply to one load. Keep output load leads close together (small loop area) to obtain a low inductance and low impedance connection to the load. If you wish to use remote sensing, connect the sense leads at the load as shown in the figures.

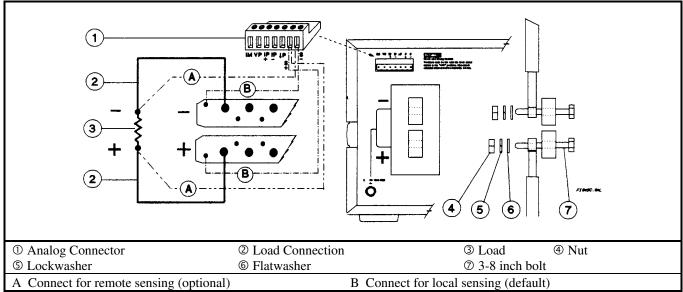


Figure 4-5c. Series 668xA Single Load Connection (Remote Sensing Optional)

**Note** 

If you are using a bench application requiring the Option 601 Output Connector Kit, be sure to consult the instructions supplied with the kit.

#### **Connecting One Power Supply to Multiple Loads**

Figure 4-5d shows how to connect a single power supply to more than one load. When connecting multiple loads to the power supply with local sensing, connect each load to the output bus bars with separate connecting wires. This minimizes mutual coupling effects and takes full advantage of the supply's low output impedance. Keep each pair of load wires as short as possible and twist or bundle them to reduce lead inductance and noise pickup.

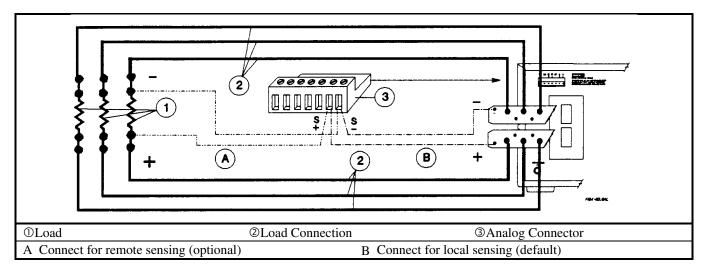


Figure 4-5d. Series 668xA Multiple Load Connection (Remote Sensing Optional)

#### **Connecting Supplies in Auto-Parallel**

**Auto-Parallel Wiring (Figure 4-5e).** Figure 4-5e shows how power supplies can be auto-paralleled for increased current output. Up to three supplies can be connected for auto-parallel operation. Use heavy enough load leads so that the absolute voltage difference between the  $\oplus$  output terminals of the "master" supply and the  $\oplus$  output terminal of the first "slave" supply is kept under 2 V at rated current. This also applies to the voltage difference between the  $\oplus$  output terminals of the first and second "slave" supplies. If remote sensing is necessary, connect the remote sense terminals of the "master" supply as shown by the dashed lines in Figure 4-5e. See "Remote Voltage Sensing" for more information.

**Auto-Parallel Programming.** Only the first supply in the series (the "master") is programmed; the supplies that are connected to the master automatically track its output. However, the voltage and OVP settings of the slave supplies must be set higher than the operating voltage of the master supply. This ensures that the slave supplies will operate in CC mode when tracking the output of the master supply. Be sure to set the output current of the slave supplies to zero, because all current programming inputs (GPIB, front panel, and external voltage) are additive. Functions such as status, voltage readback, and current readback can still be read back individually for each supply.

If a "slave" supply experiences a desired shutdown condition (such as caused by overtemperature or overcurrent), it does not automatically shut down all other supplies. You must first enable remote inhibit (RI) and discrete fault indicator (DFI) operation. It is recommended that you use the RI and DFI functions to automatically shut down all supplies whenever one supply experiences a shutdown condition. See "Fault/Inhibit Operation" in "Appendix D - Digital Port Functions" for wiring information and "Questionable Status Group" in the "Programming Guide" for programming information.

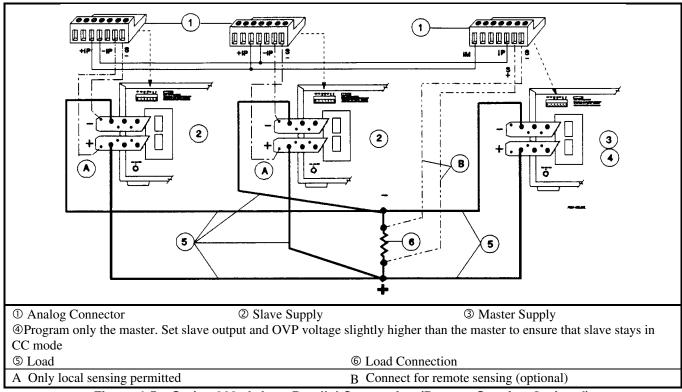


Figure 4-5e. Series 668xA Auto-Parallel Connection (Remote Sensing Optional)

#### **Connecting Supplies in Series**

Floating voltages must not exceed ± 60 Vdc. No output terminal may be more than 60 V from chassis ground.

Figure 4-5f illustrates how power supplies can be connected in series for increased voltage capability. Series connections are straightforward in this case.

#### **78** User Connections

Program each power supply as an independent supply. If two supplies are used in series operation, each supply can be programmed to deliver 50% of the total output voltage. Set the current limit of each power supply to the maximum that the load can handle without damage.

If one supply experiences a desired shutdown condition (such as caused by overtemperature or overcurrent), it does not automatically shut down the other supply. You must first enable remote inhibit (RI) and discrete fault indicator (DFI) operation. It is recommended that you use the RI and DFI functions to automatically shut down both supplies whenever one supply experiences a shutdown condition. See "Fault/Inhibit operation" in "Appendix D - Digital Port Functions" for wiring information and "Questionable Status Group" in the "Programming Guide" for programming information.

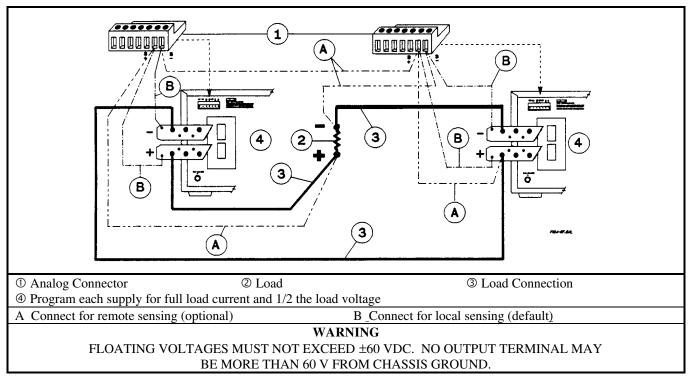


Figure 4-5f. Series 668xA Series Connection (Remote Sensing Optional)



Each power supply has a reverse voltage protection diode across its output. If the fan in one of the series power supplies shuts down for any reason (such as a fan circuit defect or loss of ac power), the supply may severely overheat due to current forced through its reverse current diode by the functioning supply. This possibility can be eliminated by use of the RI/DFI functions previously noted. Also, if a reverse voltage is applied across a functioning supply, it has no control over the current conducted through this diode. To avoid damaging the supply, never connect it in such a way that a reverse voltage can force it to conduct current in excess of the supply's maximum rated current. (see Table 1-4b)

#### **External Voltage Control**

The setup shown in Figure 4-5g allows an external dc voltage to program the power supply output. A zero-to-full scale voltage applied to the voltage programming input produces a proportional zero-to-full scale output voltage. The voltage programming source is referenced to the programming **Common P** ( $\downarrow$ P) terminal. A zero-to-full scale voltage applied to one of the current programming inputs produces a proportional zero-to-full scale output current. See Figure 4-1 for an explanation of these programming input connections.

#### Wiring Considerations (Figure 4-5g)

The input impedance of the analog input is over 30 k $\Omega$ . If the output impedance of your programming source is not negligible with this, programming errors will result. Larger output impedances result in proportionally greater errors.

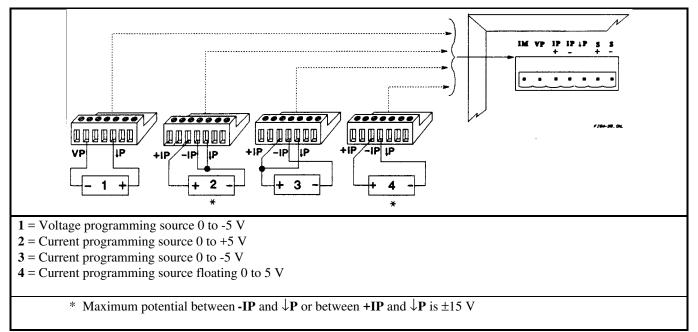


Figure 4-5g. Series 668xA Analog Programming Connections

#### **Programming**

Note from Figure 4-1 that you have three options for programming the current. You can use a voltage source that is positive, negative, or floating with respect to **Common P**. Do not exceed +15 V with respect to **Common P**.



Make certain that the common connection for your voltage programming source is isolated from the load. Failure to do this may cause damage to the power supply.

The effect of the analog programming source is always summed with the values programmed over the GPIB or from the front panel. The voltage source can act alone only if you set the other program sources to zero. Keep the total programmed setting of the supply (the analog input summed with the GPIB or front panel settings) at or under the output ratings specified in Table 1-3a. Exceeding the output ratings will not damage the supply, but it may not be able to regulate its output the higher levels. If this happens, the **Unr** annunciator will light to warn you that the output is unregulated.

#### **Controller Connections**

Figure 4-6 shows two basic ways of connecting your power supply to a controller. They are "linked" and "stand-alone configurations.

#### **Stand-Alone Connections**

See Figure 4-6A. Each stand-alone power supply has its own GPIB bus address. Stand-alone power supplies may be connected to the bus in series configuration, star configuration, or a combination of the two. You may connect from 1 to 15 stand-alone power supplies to a controller GPIB interface.

#### **Linked Connections**

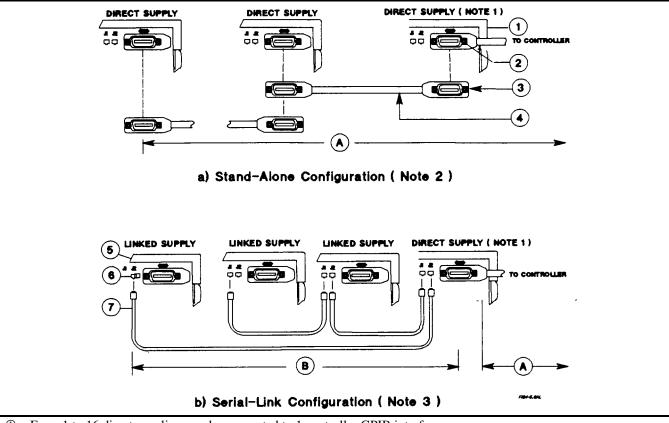
See Figure 4-6B. Up to 16 power supplies may be used at a single GPIB primary bus address by making linked connections. (You cannot use linked connections if you intend to program power supplies with the Compatibility Language - see the power supply "Programming Guide".)

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- The first power supply in a linked connection is a "direct supply" connected to the controller via a GPIB cable. The direct supply is the only supply connected directly to the bus and has a unique primary bus address.
- The remaining power supplies are "linked supplies" connected to the direct supply via a serial-link cable. Each linked supply has a unique secondary GPIB address and derives its primary address from the direct supply. You may connect from 1 to 15 linked supplies to each direct supply.

#### **Note**

The power supply is shipped from the factory with its GPIB address set to 5. The power supply primary and secondary addresses can be changed from the front panel as described in "Chapter 2 - Remote Programming" of the "Programming Guide". For power supply GPIB interface capabilities, see Table 1-5 in Chapter 1 of this guide.



- From 1 to 16 direct supplies may be connected to 1 controller GPIB interface.
- Tighten connector thumbscrews by hand. Do not use a screwdriver.
- 3 Do not stack more than 3 connectors on a GPIB receptacle.
- ④ GPIB cable (see **Accessories** in Chapter 1)
- From 1 to 15 linked supplies may be connected to 1 direct supply.
- © Either receptacle (Jl or J2) may be used as an input or an output.
- © Serial Link Cable (see **Accessories** in Chapter 1), 2 meters. 1 is supplied.
- A Maximum total length of all GPIB cables (including controller) not to exceed 20 meters. Use caution with individual lengths over 4 meters.
- B Maximum total length of all serial cables not to exceed 30 meters.

#### **NOTES:**

- 1. A direct power supply is connected to the controller interface and must have a unique primary GPIB bus address.
- 2. The stand-alone configuration uses only direct supplies connected to the controller interface.
- 3. The linked configuration uses 1 or more linked power supplies connected to each direct supply. Each linked supply has a unique secondary GPIB bus address and derives its primary address from the direct supply.

Figure 4-6. Controller Connections

# **Front Panel Operation**

#### Introduction

This chapter shows you how to operate the front panel. It is assumed that you are familiar with the turn-on checkout procedure in Chapter 3. That chapter describes how to perform basic power supply functions from the control panel. operations that you can perform are:

- Enabling or disabling the power supply output.
- Setting the output voltage and current.
- Monitoring the output voltage and current.
- Setting the overvoltage protection (OVP) trip point.
- Enabling the overcurrent protection (OCP) circuit.
- Saving operating states in nonvolatile memory.
- Recalling operating states from nonvolatile memory.
- Setting the power supply GPIB bus address.
- Displaying error codes created during remote operation.
- Enabling local (front panel) operation.

Note

You also can calibrate the power supply from the front panel (see Appendix A).

## **Getting Acquainted**

The front panel is summarized in Figure 5-1 and Table 5-1. Note that the panel is organized as follows:

- ① LCD display (including annunciators)
- ② Output VOLTAGE and CURRENT rotary (RPG) knobs
- 3 SYSTEM keypad
- FUNCTION keypad
- © ENTRY keypad
- © Power (LINE) switch
- Tuse LED (Series 668xA only)
- ® DEW LED (Series 668xA only)

Some keys have two functions. For example, the System (Recall) key (3, Figure 5-1) can be used either to recall a stored operating state or to Save (store) an operating state. The first operation is shown on the key and the second (shifted) operation is shown in blue **above** the key. In order to do a shifted operation, first press the solid blue key, which is unlabeled but shown throughout this manual as **Shift**.

For example, for a recall operation, press the recall key (Recall). For a save operation, press the save key, which is Shift (Recall). When you do this, the Shift annunciator will light to remind you that the (Recall) key is now functioning as the Save key. In this chapter, such a shifted operation may be shown simply as Save.

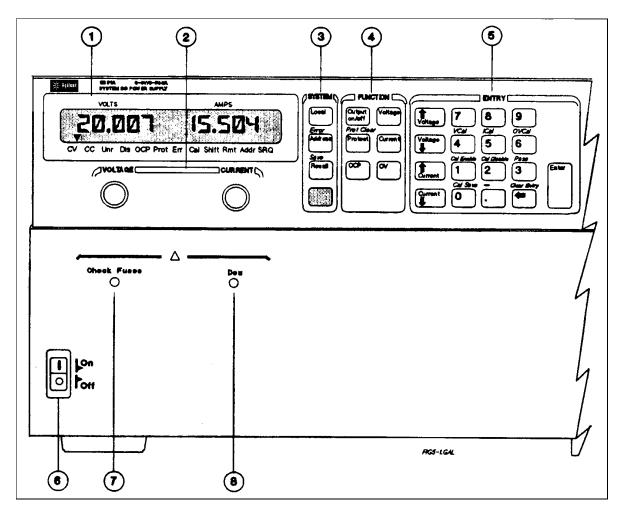


Figure 5-1. Front Panel Controls and Indicators

Table 5-1. Front Panel Controls and Indicators (see Figure 5-1)

Control or	Function or Indication			
Indicator				
	① Display			
VOLTS	Chave present output voltage of the power supply			
	Shows present output voltage of the power supply.			
AMPS	Shows present output current of the power supply.			
	Status Annunciators			
CV	The power supply is in constant-voltage mode.			
CC	The power supply is in constant-current mode.			
Unr	The power supply output is unregulated (output is neither CV or CC).			
Dis	The power supply output is disabled.			
OCP	The overcurrent protection function is enabled.			
Prot	A protection circuit has caused the power supply to shut down. (Press <b>Protect</b> to determine the reason.)			
Err	An error has been generated as a result of remote operation. (Press <b>Error</b> to display the error code).			
Cal	The power supply is in calibration mode.			
Shift	The shift key <b>Shift</b> has been pressed.			
Rmt	The power supply is in the remote mode (controlled over the GPIB).			
Addr	The power supply is addressed to listen or talk.			
SRQ	The power supply is requesting service from the controller.			

Table 5-1. Front Panel Controls and Indicators (continued)				
Valdana	© Output Rotary Controls			
Voltage	Rotate clockwise to increase output voltage or program setting. Use to rapidly set an approximate output value (see <b>Tvoltage</b> and <b>Ivoltage</b> keys).			
Current	Rotate clockwise to increase output current or program setting. Use to rapidly set an approximate current value (see <b>Current</b> and <b>Current</b> keys).			
	③ SYSTEM Keys			
Local	When the power supply is under remote control, press to enable local operation. <i>This control can be defeated by a lock-out command over the GPIB</i>			
Address  Error  Recall	Press to display the power supply's GPIB address. You can change the address with the ENTRY keys Use to display error codes generated during remote operation. (Select by pressing Shift Address.)  Use to restore a previously saved power supply state. Use ENTRY keys ① through ④ (① through ③ on the Series 668xA) to specify which location to recall. (Select by pressing Shift Recall.)  Note: Location 0 may contain the power supply turn-on state. See "Turn-on operation" in this chapter.			
Save	Use to save the power supply's present state to nonvolatile memory. (Select by pressing Shift Recall.)  Use ENTRY keys to specify the location where you want to store the state. You may use locations through 4 (0 through 3 on the Series 668xA).			
	This unlabeled blue key is the Shift key. Press to access the shifted (alternate) key functions.			
	Function Keys			
Output on/off	Press to enable or disable the power supply output. This key toggles between the two states. The disabled state programs the output to the *RST voltage and current settings (see the Programming Guide).			
(Voltage)	Press to display the output voltage setting. After pressing Voltage, you may use the ENTRY keys to change the value.			
Current	Press to display the output current setting. After pressing <b>Current</b> , you may use the ENTRY keys to change the value.			
<b>◎</b>	Press to display the OV trip voltage setting. After pressing <b>OV</b> , you may use the ENTRY keys to change the value.			
Protect	When the <b>Prot</b> annunciator is on, press <b>Protect</b> to see which protection circuit caused the power supply to shut down. Response can be OC (overcurrent), OT (overtemperature), or OV (overvoltage). If no protection circuit has tripped, the display will show dashes ().			
Prot Clear	Press this key to reset the protection circuit. If the condition that caused the circuit to trip has been removed, the <b>Prot</b> annunciator will go off.			
ОСР	Press to enable or disable the power supply OCP trip circuit. This key toggles between the two states. which are indicated by the <b>OCP</b> annunciator.			
	© ENTRY Keys			
<b>↑</b> Voltage	Press to increment the output voltage in the CV mode, or to increase the voltage setting after you have pressed the Voltage key. <sup>3</sup>			
[Voltage]	Press to decrement the output voltage in the CV mode, or to decrease the voltage setting after you have pressed the <b>Voltage</b> key. <sup>3</sup>			
(†Current)	Press to increment the output current in the CC mode, or to increase the current setting after you have pressed the <b>Current</b> key. <sup>3</sup>			
Current	Press to decrement the output current in the CC mode, or to decrease the current setting after you have pressed the <b>Current</b> key. <sup>3</sup>			

Table 5-1. Front Panel Controls and Indicators (continued)

	© ENTRY Keys (continued)		
Othru9 .	Press to select numerical values .		
Θ	Press to enter a minus sign.		
-	Press to delete the last keypad entry. Use this key to remove one or more incorrect digits before they are entered.		
	<sup>3</sup> These four entry keys operate in two modes. Press and release for a single minimal change as determined by the programming resolution (see Table 1-2 in Chapter I). Press and hold for an increasingly rapid output change.		
Clear Entry	Press to delete an entire keypad entry and return to the meter mode. Use this key to exit from a value		
Enter	before it is entered.  Press to enter a value or to accept an existing value and return the display to the meter mode.  The remaining shifted keys are for calibration (see "Appendix A - Calibration").		
	© Check Fuses LED and ⊘ Dew LED (Series 668xA only)		
<b>Check Fuses</b>	If one or more of the line fuses opens, this LED lights. (see "In Case of Trouble" in Chapter 3).		
Dew	If you turn on the power supply when its inside humidity is $\approx 100\%$ , the power will not go on and this LED will light (see "In Case of Trouble" in Chapter 3).		

## **Programming The Output**

#### Introduction

Important	These instructions show how to program a single power supply. There are special considerations when
	you have two or more supplies connected in series or in autoparallel. See "Chapter 4 - User Connections
	and Considerations".

The power supply accepts values directly in volts and amperes. Values will be rounded off to the nearest multiple of the output resolution (see "Average Resolution" in Table 1-2 of Chapter 1). If you attempt to enter a value not in a valid range, the entry will be ignored and **OUT OF RANGE** appears on the display.

Figure 5-2 shows the general response of a typical power supply. Unless directed otherwise, always keep the output voltage and current within the boundaries of its operating line for the specified mode of operation (CV or CC).

#### **Establishing Initial Conditions**

Set the power supply to its \*RST state by pressing Recall O Enter. This state was stored in location 0 at the factory. If it has since been changed, you can restore it as directed under "Turn-on Conditions", later in this chapter. \*RST results in the following operating conditions:

- Zero voltage output.
- Minimal current output.
- Output disabled (**Dis** annunciator on).
- Overcurrent protection off (**OCP** annunciator off).
- Protection circuits cleared (**Prot** annunciator off).

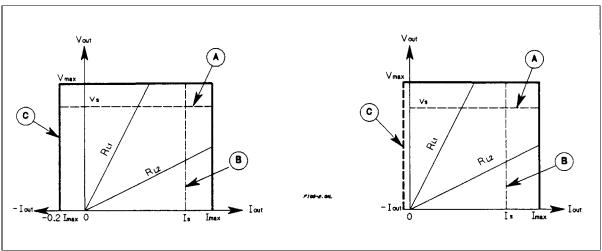


Figure 5-2. Typical Power Supply Operating Curve

#### **Programming Voltage**

To program the output for 4.5 volts, proceed as follows:

- Press **(Voltage)**. The display will change from meter mode to indicate **VOLTS**.
- Press 4 . 5 (Enter). If you discover a mistake before pressing (Enter), erase the incorrect value with the backspace
- The display will return to the meter mode and indicate 0.000 volts.
- Press Output on/off to enable the output (Dis annunciator turns off). The VOLTS display will indicate 4.500 volts.

#### **Note**

The power supply must be programmed for a minimal current in order to increase the output voltage beyond zero. Normally, there is sufficient idle current to do this. If the power supply does not respond or the CC annunciator turns on, go to "Programming Current" and set the current to a small value.

- Now raise the voltage by pressing **[Voltage]** .Note that the voltage increases by a specific increment (depending on the voltage programming resolution) each time you press the key and increases rapidly as you hold down the key. To lower the voltage, press [Voltage].
- Try raising and lowering the voltage by rotating the **Voltage** control clockwise and then counterclockwise. Note how the output responds as compared to using the Entry keys.

Try to program a voltage greater than the V<sub>MAX</sub> for your supply (see "Supplemental Characteristics" for your particular model in Chapter 1). Note that the display shows **OUT OF RANGE**.

#### **Programming Overvoltage Protection**

Overvoltage protection guards the load against voltages that reach a specified value above the programmed output voltage.

#### Setting the OVP Level

Assuming that you have programmed the power supply for 4.5 volts, you can set the OVP level to 4.8 volts as follows:

- Press **OV**. The display will change from meter mode to indicate OV, followed by the present OVP value.
- Press (4) (.) (8) (Enter).
- The display will return to the meter mode and indicate the output (4.500 volts).
- Press (OV) again. The display will now indicate 0V 4.800.
- Press **Enter** to return to the meter mode.

#### **Checking OVP Operation**

Assuming the above operating conditions (voltage programmed to 4.5 V and OVP programmed to 4.8 V), trip the OVP circuit as follows:

- Gradually increase the output voltage by pressing **TVoltage** until the OVP circuit trips. This will cause the output voltage to drop to zero and the **Prot** annunciator to go on.
- There now is no power supply output due to an overvoltage condition.
- To verify this, press **Protect** and observe that the display indicates **0V**. This shows that the protection circuit tripped due to an overvoltage condition.

## **Clearing The OVP Condition**

With the OVP tripped, return to the meter mode and try to clear the condition by pressing **Prot Clear**. Nothing will appear to happen because the OV trip voltage is still below the programmed output voltage. Thus, as soon as the circuit is cleared, it trips again. You can clear the OV condition by:

- Lowering the output voltage below 4.8 (the OV setting), or
- By raising the OV trip voltage above the output voltage setting.

Try either of these methods. Now when you press **Prot Clear**, the **Prot** annunciator will turn off and the output voltage will return to normal.

#### **Programming Current**



**ENERGY HAZARD**. Some power supplies (Series 668xA) can provide more than 240 VA at more than 2 V. If the output connections touch, severe arcing may occur resulting in burns, ignition or welding of parts.

You may program the power supply current without a load, but must have a load in order to draw output current. These tests assume you have the load connected in accordance with the information in "Chapter 4 - User Connections and Considerations". If you do not have a load on the power supply, you may connect a short across the output terminals as described in "Chapter 3 - Turn-on Checkout".

The example will program a low current. (You may later increase the output current to the levels you will expect to use.) To program the output current to 1.3 amperes, proceed as follows:

- Disable the output by pressing Output on/off). The Dis annunciator will turn on.
- Program the voltage by pressing **(Voltage) (Enter)**.
- Press Current . The display will change from meter mode to indicate AMPS.
- Press 1 . 3 Enter. If you discover a mistake before pressing Enter erase the incorrect value with the backspace key .
- The display will return to the meter mode and indicate up to 0 . 000.
- Press Output on/off to enable the output. Dis will turn off and the display will indicate VOLTS 5.000 AMPS 1.300.
- Now increase the current by pressing **Current**. Note that the current increases by a specific increment (depending on the current programming resolution) each time you press the key and increases rapidly as you hold down the key. To decrease the current, press **Current**.
- Try increasing and decreasing the current by rotating the **Current** knob clockwise and counterclockwise. Note how the output responds as compared to using the **Entry** keys.

Disable the output by pressing  $\bigcirc$  Utput on/off. The **Dis** annunciator will turn on. Now try to program a current greater than the  $I_{MAX}$  for your supply. Note that the display shows **OUT OF RANGE**.

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#### **Programming Overcurrent Protection**

When enabled, overcurrent protection removes the power supply output whenever it goes into CC operation. This prevents the supply from indefinitely supplying the full programmed current to the load.

## **Setting The OCP Protection**

To activate overcurrent protection, press **OCP**. The **OCP** annunciator will light and power supply will continue to operate normally until it is forced into CC operation. If that occurs, the OCP circuit will trip and the power supply will remove its output.

#### **Checking OCP Operation**

The easiest way to check this operation at any specified current is to increase the load current beyond the programmed current value and, if necessary, decrease the programmed voltage. This will force the power supply into the CC mode (see Figure 5-2). When OCP trips, the **Prot** annunciator will light and the power supply output will drop to zero.

There is now no power supply output due to an overcurrent condition. To verify this, press **Protect** and observe that the display indicates **OC**.

## **Clearing The OCP Condition**

With the OCP tripped, return to the meter mode and try to clear the condition by pressing (Prot Clear). Nothing will appear to happen because the reason for the condition has not been removed. Thus, as soon as the circuit is cleared, it trips again. You can clear the OC condition by:

- Increasing the load resistance to lower the output current below the programmed current value, or
- By raising the programmed current to a value above that required by the load.

Clear the fault by either of the above methods. Then clear the OCP circuit by pressing [Prot Clear]. The Prot annunciator will go off and the power supply output will be restored to normal.

If desired, you can also restore the output by disabling the OCP function (press OCP) to turn off the OCP annunciator). This restores the output but does not clear any condition that may have caused OCP to trip.

**Note** 

Under certain conditions, the OCP circuit may fail to clear because load demand occurs before the power supply has time to build up the required output current capacity. In such cases, disable the output (press Output on/off before clearing the OCP circuit). After OCP is cleared, enable the power supply output.

#### CV Mode VS. CC Mode

Once you program a voltage  $(V_S)$  and a current  $(I_S)$  in Figure 5-2, the power supply will try to maintain itself in either CV or CC mode, depending on the impedance of the load (R<sub>1</sub>). If the load demands less current than I<sub>s</sub>, operation will be in CV mode with the voltage maintained at  $V_s$ . The output current will be at some value below  $I_s$  as determined by  $V_S \div R_L$ .

If the current increases beyond  $I_S$  (see  $R_{L2}$ ), the supply will switch to CC mode by varying its output voltage to maintain a constant current value of I<sub>s</sub>. As more current is demanded, the voltage decreases to maintain the increased current level. If the load current increases to the maximum output of the power supply, the output voltage will be maintained at a near-zero level.

## **Unregulated Operation**

If the power supply goes into a mode of operation that is neither CV nor CC, the **Unr** annunciator will light. An unregulated condition limits the output current to a value that is safe for the power supply. Some unregulated states occur so briefly that they do not turn on the **Unr** annunciator, but they may set the **UNR** status bit during remote operation (see the power supply "Programming Guide"). One condition that can cause a noticeable unregulated state is low ac line voltage.

# **Saving and Recalling Operating States**

You can save programming time by storing up to 5 (up to 4 with Series 668xA supplies) operating states in nonvolatile memory. The front panel programming parameters that are saved are:

- Output voltage, Output current, OVP voltage.
- OCP state (on or off), Output state (enabled or disabled).

**Note** More power supply parameters are saved in remote operation. See the power supply "Programming Guide".

As an example, set up the following state:

- Voltage = 4 V Current = 5 A OVP voltage = 4.5 V.
- lacktriangle OCP = on (**OCP** annunciator on) Output = off (**Dis** annunciator on).

Save the above state to location 1 by pressing Save 1 Enter. Now set up the following state:

- Voltage = 4.5 V Current = 2.5 A OVP voltage = 5 V.
- lacktriangle OCP = off (OCP annunciator off) Output = on (**Dis** annunciator off).

Save the above state to location 2 by pressing Save (2) Enter.

Restore the first state by pressing Recall 1 Enter and verify the parameters. Restore the second state by pressing Recall 2 Enter. Note how the power supply is automatically programmed each time.

#### **Turn-On Conditions**

Whenever you apply power to a new power supply it automatically turns on in a safe reset state with the following parameters:

```
Output on/off off Voltage 0 Current minimum*

OV maximum OCP off
```

It is recommended that you leave the turn-on conditions as programmed. However, you may change them if you wish. To do this, proceed as follows:

- 1. Set up the power supply to the state you want when it is turned on.
- 2. Store that state to location 0.
- 3. Turn off the power supply.
- 4. Hold in the <sup>3</sup> key and turn the power supply back on. The display indicates **RCL 0 PWR-ON** to verify that the power supply has configured its turn-on state to that stored in location 0.
- 5. From now on the supply will always turn on to the state defined in location 0.

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<sup>\*</sup>Minimum is the \*RST value specified in Table 3-1 in the Programming Guide.

Whenever you wish, you can return the power supply to the original factory reset state. To do this, simply hold down the 19 key when you turn on the supply. The display indicates RST POWER-ON to verify that the power supply has configured its turn-on state to the original reset state. From now on it will continue to turn on in that state.

## **Setting The GPIB Address**

#### **Types of Power Supply GPIB Addresses**

Figure 4-6 in Chapter 4 shows the ways the power supply can be connected to the GPIB bus. You can set up the GPIB address in one of three ways:

- 1. As a stand-alone supply (the only supply at the address). It has a primary address in the range of 0 to 30. For example: 5 or 7.
- 2. As the direct supply in a serial link. It is the only supply connected directly to the GPIB bus. The primary address is unique and can be from 0 to 30. It is entered as an integer followed by a decimal separator. The secondary address always is 0, which may be added after the primary address. If the secondary address is omitted, it is assumed to be 0. For example: **5.0** or **7**.
- 3. As a linked supply in serial link. It gets its primary address from the direct supply. It has a unique secondary address that can be from 1 to 15. It is entered as an integer preceded by a decimal separator. For example: .1 or .12

When you enter a secondary address, leading zeros between the decimal separator and the first digit are ignored. For example, .1, .01, and .001 are accepted as secondary address 1 and displayed as **0.01**. Zeros following a digit are not ignored. Thus, .10 and .010 are both accepted as secondary address 10 and displayed as **0.10**.

#### **Changing the Power Supply GPIB Address**

Use the (Address) key and numerical keypad for entering addresses. The power supply is shipped with a 5 stand-alone address as the default. The general procedure for setting an address is:

Action **Display Shows** Current address Press (Address)

Press new address kevs New address replaces numbers on the display

Press (Enter) Display returns to meter mode

If you try to enter a forbidden number, **ADDR ERROR** is displayed.

The following examples show how to set addresses:

To set stand-along primary address 6, press (Address) 6 (Enter)

To set direct supply primary address 6, press (Address) 6 . Enter.

To set linked secondary address 1, press (Address) . 1 Enter.

To set linked secondary address 12, press (Address) . 1 2 Enter.

#### Note

The power supply display will reset (recall the state in location 0) whenever you change between the following types of GPIB addresses:

- a stand-alone primary address and a direct primary address.
- a direct primary address and a secondary address.

A

# Calibration

#### Introduction

The power supply may be calibrated either from the front panel or from a controller over the GPIB. The procedures given here apply to all models.

**Important** 

These instructions do not include verification procedures. If you need to perform verification as a erequisite to or as part of your calibration procedure, see "Appendix B - Verification".

# **Equipment Required**

The equipment listed in Table A-1, or equivalent, is required for calibration.

**Table A-1. Equipment Required For Calibration** 

Equipment	Characteristics	Recommended Model
Voltmeter	D-c accuracy 0.005%, 6 digits	Agilent 3456A or 3458A
Shunt resistor		
Agilent 6641A, 51A, 52A	100 A, 0.01 Ω, 0.04%, 100 W	Guildline 9230/100
Agilent 6642A, 43A, 44A, 45A,	15 A, 0.1 Ω, 0.04%, 25 W	Guildline 9230/15
6643A, 54A, 55A		
Agilent 6671A	300 A, 0.001 Ω, 0.04%,100 W	Guildline 9230/300
Agilent 6672A, 73A, 74A, 75A	300 A, 0.001 Ω, 0.04%, 100 W	Guildline 9230/300
Agilent 6680A, 81A	1000 A, 0.1 mΩ, 0.05%	Burster 1280S
Agilent 6682A, 83A, 84A	$300 \text{ A}, 0.1 \text{ m}\Omega, 0.05\%$	Guildline 9230/300
For Calibration Over the GPIB		
GPIB Controller	HP Vectra (or IBM compatible) with GPIB Interface, or HP BASIC series	

## **General Procedure**

WARNING

Because the power supply output must be enabled during calibration, voltages or currents hazardous to personnel and/or damaging to equipment can appear at the output terminals.

WARNING

**ENERGY HAZARD.** Series 668xA supplies can provide more than 240 VA at more than 2 V. If the output connections touch, severe arcing may occur resulting in burns, ignition or welding of parts. Do not attempt to make connections to live output circuits.

#### **Parameters Calibrated**

The following parameters may be calibrated:

- Output voltage.
- Output voltage readback.
- Overvoltage protection (OVP).

- Output current.
- Output current readback.
- Current monitor input I<sub>M</sub> (Series 668xA only).

You do not have to do a complete calibration each time. If appropriate, you may calibrate only the voltage or current and proceed to "Saving the Calibration Constants". However, for Series 668xA supplies, the following sequences must be followed:

- Calibrate voltage before OVP.
- Calibrate the current monitor input before current output.

## **Test Setup**

Figure A-1 shows the test setups required for voltage and current calibration for each power supply series.

## **Front Panel Calibration**

Eight shifted keys and the Entry keypad are used for calibration functions (see "Chapter 5 - Front Panel Operation" for explanations of shifted keys and the Entry keypad). The following procedures assume you understand how to operate front panel keys.

#### **Entering the Calibration Values**

Follow the steps in Table A-2 for entering calibration values.

#### **Saving the Calibration Constants**



Storing calibration constants overwrites the existing ones in nonvolatile memory. If you are not absolutely sure you want to permanently store the new constants, omit this step. The power supply calibration will then remain unchanged.

To replace any existing calibration constants with ones you have just entered, press Cal Save. CAL SAVED then appears on the display.

#### **Disabling the Calibration Mode**

To disable the calibration mode, press (Cal Disable). The display will return to meter mode with the Cal annunciator off.

## **Changing the Calibration Password**

The factory default password is the model number of your supply, such as 6671. You can change the calibration password only when the power supply is in the calibration mode (which requires you to enter the existing password). Proceed as follows:

- 1. Press (Pass).
- 2. Enter the new password from the keypad. (You can use up to six integers and an optional decimal point.) If you want **Cal Enable** to operate without requiring any password, change the password to 0 (zero).
- 3. **AGAIN** will appear on the display. Enter the password a second time.
- 4. When **OK** is displayed, the new password has been accepted.

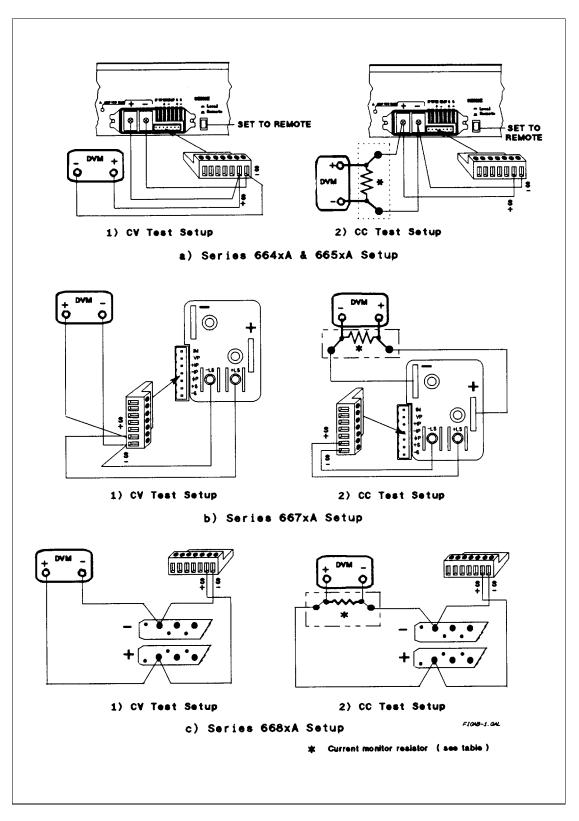


Figure A-1. Calibration Test Setup

Table A-2. Typical Front Panel Calibration Procedure Action	Display Response
Addon	Display Response
Enabling the Calibration Mode	
. Begin calibration by pressing (Cal Enable).	PASWD <sup>1</sup>
. Enter calibration password from Entry keypad.	
If password is correct the Cal annunciator will come on.	
If password is incorrect, an error occurs <sup>2</sup> .	PASSWD ERROR
<b>Note:</b> The initial (factory-default) password is the model number of the power supply,	
but it can be changed (see "Changing the Password" in Appendix A - Calibration).	
Entering Voltage Calibration Values	
Make certain the DVM is the only load on the power supply.	(Meter mode)
Select the first calibration point by pressing Vcal .	VRDG1
If the power supply is not in CV mode, an error occurs <sup>3</sup>	WRONG MODE
3. Read the DVM and use the Entry keypad to enter the first voltage value.	(Meter mode)
Select the second calibration point by pressing (Vcal) again.	VRDG2
Read the DVM and use the Entry keypad to enter the second voltage value.	(Meter mode)
<b>Note:</b> If one of the entered values is not within acceptable range, an error occurs.	
The power supply is now holding the new voltage calibration constants in RAM.	CAL ERROR
The power supply is now holding the new voltage editoration constants in 12112.	
Calibrating the OVP Trip Point	
. Make certain the voltage has been calibrated and there is no load on the power supply.	(Meter mode)
. Select OVP calibration by pressing OVCal.	OVPCAL
6. Wait for the power supply to compute the OVP calibration constant.	CAL COMPLETE
If the supply goes unregulated or into CC mode during OVP calibration, an error occurs.	NOT CV MODE
If the computed constant is out of acceptable range, an error occurs.	DOES NOT CAL
The power supply is now holding the new OVP calibration constant in RAM.	
Entering Current Calibration Values	
. Make certain appropriate shunt resistor (see Table A-1) is the only load on the power supply.	(Meter mode)
. Select the first calibration point by pressing (cal).	IRDG1
If the power supply is not in CC mode, an error occurs. <sup>4</sup>	WRONG MODE
. Wait for DVM reading to stabilize. Then read DVM and compute the first current value	(Meter mode)
(DVM reading ÷ shunt resistance).	(Meter mode)
. Use Entry keypad to enter the first current value.	IRDG2
. Select second calibration point by pressing [cal] again.	
. Wait for DVM reading to stabilize. Then read DVM and compute the second	(Meter mode)
current value (DVM reading ÷ shunt resistance).	(Meter mode)
. Use Entry keypad to enter the second current value.  Note: If the entered value is not within acceptable range, an error occurs.	CAL ERROR
Wait for the power supply to compute the new current calibration constants, which will be	CAL COMPLETE
stored in RAM.	

<sup>&</sup>lt;sup>1.</sup> If **CAL DENIED** appears, then an internal jumper has been set to prevent the calibration from being changed. (See the

<sup>&</sup>lt;sup>2</sup> If the active password is lost, the calibration function can be recovered by moving an internal jumper that defeats password protection. However, this also will change all calibration constants to their factory-default values. (For more information, see the Service Manual.)

<sup>&</sup>lt;sup>3.</sup> Program the output current to 10% of its rated output\*

<sup>4.</sup> Program the output voltage to 10% of its rated output\*

<sup>\*</sup> See applicable Output Ratings in "Chapter 1- General Information"

Table A-2. Typical Front Panel Calibration Procedure (continued)

Action	Display Response
Calibrating Current Monitor (I <sub>M</sub> ) (Series 668xA Only)	
If you perform this calibration, then you must recalibrate the current output.	
1. Make certain the appropriate shunt resistor (see Table A-1) is the only load on the power	(Meter mode)
supply.	
2. Select IMN calibration by pressing Callmon	IMON CAL
If the power supply is not in CC mode, an error occurs. <sup>4</sup>	WRONG MODE
3. Wait for DVM reading to stabilize. Then read DVM and compute the current value	(Meter mode)
(DVM reading ÷ shunt resistance).	
4. Use Entry keypad to enter the current value.	(Meter mode)
<b>Note:</b> If the entered value is not within acceptable range, an error occurs.	CAL ERROR
Wait for the power supply to compute the new current calibration constants, which will be	CAL COMPLETE
stored in RAM.	
If the constant is not within acceptable range, an error occurs.	CAL ERROR
if the constant is not within acceptable range, an error occurs.	
4. Program the output voltage to 10% of its rated output*	I
*See applicable Output Ratings in "Chapter 1- General Information"	,

## **Recovering From Calibration Problems**

You can encounter serious calibration problems if you cannot determine a calibration password that has been changed or the power supply is severely out of calibration. There are jumpers inside the power supply that permit the calibration password to be defeated and allow the original factory calibration constants to be restored. These jumpers are explained in the *Service Manual*.

## **Calibration Error Messages**

Error messages that can occur during calibration are shown in Table A-3.

**Table A-3. GPIB Calibration Error Messages** 

Error No.	Meaning	Error No.	Meaning
1	CAL jumper prevents calibration <sup>1</sup>	6	Wrong CAL command sequence
2	CAL password is incorrect	7	Incorrect state (CV/CC) for this command
3	CAL mode is not enabled		
4	Incorrect computed readback constants		
5	Incorrect computed programming constants	<sup>1</sup> This is a Service M	hardware disable. See the power supply <i>lanual</i> .

#### Calibration Over The GPIB

You can calibrate the power supply by using SCPI commands within your controller programming statements. Be sure you are familiar with calibration from the front panel before you calibrate from a controller. The SCPI calibration commands are related to the front panel calibration controls as follows:

Front Panel	Corresponding SCPI	Front Panel	Corresponding SCPI
Command	Command	Command	Command
Cal Enable	CAL:STAT {ON 1}, <password></password>	OVCal	CAL:VOLT:PROT
Cal Disable	CAL:STAT {OFF 0}	(Ical)	CAL:CURR:LEV {MIN MAX} CAL:CURR[:DATA] <nrf></nrf>
Pass	CAL:PASS <nrf></nrf>	Cal Imon	CAL:CURR:MON <newline> CAL:CURR:DATA<nrf></nrf></newline>
Vcal	CAL:VOLT:LEV {MIN MAX} CAL:VOLT[:DATA] <nrf></nrf>	(Cal Save)	CAL:SAVE

#### **Calibration Example**

A sample calibration program is given at the end of this appendix. If your system is Agilent BASIC, you can use the program with very little modification. Otherwise, use it as a guide for writing your own program.

#### **Calibration Language Dictionary**

The calibration commands are listed in alphabetical order. The format for each command follows that shown in "Chapter 3 - Language Dictionary" of the Programming Guide. Calibration error messages that can occur during GPIB calibration are shown within this guide (Table A-3 in Appendix A - Calibration).

#### **CAL:CURR**

This command is used to calibrate the output current. The command enters current value that you obtain from an external meter. (If you are entering the current value, allow time for the DVM to stabilize.) You must first select a calibration level (CAL:CURR:LEV) for the value being entered. Two successive values (one for each end of the calibration range) must be selected and entered. The power supply then computes new current calibration constants. These constants are **not** stored in nonvolatile memory until saved with the CAL:SAVE command.

Parameters (See applicable Output Ratings specification in "Chapter 1- General Information")

**Default Suffix** A

**Examples** CAL: CURR 32 . 33 A CAL: CURR: DATA 5 . 00

Query Syntax (None)

Related Commands CAL:SAVE CAL:STAT

#### CAL:CURR:LEV

This command sets the power supply to a calibration point that is then entered with CAL:CURR[:DATA]. During calibration, two points must be entered and the low-end point (MIN) must be selected and entered first.

Command Syntax CALibrate: CURRent: LEVel {MIN|MAX}

Parameters {<CRD>|MINimum|MAXimum}

**Examples CAL: CURR: LEV MIN CAL: CURR: LEV MAX** 

Query Syntax (None)

Related Commands CAL:CURR[:DATA] CAL:STAT

#### CAL:CURR:MON (Series 668xA only)

This command sets the power supply to the current monitor (I<sub>MON</sub>) calibration point that is then entered with CAL:CURR[:DATA]. The output current must be calibrated after CAL:CURR:MON is performed.

**Command Syntax CALibrate: CURRent: MONitor** 

> **Parameters** <NRf+>

**Examples CAL: CURR: MON CALibrate: CURRent: MONitor** 

Query Syntax (None)

Related Commands CAL:CURR[:DATA] CAL:STAT

#### CAL:PASS

This command enters a new calibration password. The command is active only when the power supply is already in the calibration mode. Unless it is changed subsequently to shipment, the password is the power supply's four-digit model number. If the password is set to 0, password protection is removed and CAL:STAT ON is unrestricted. A new password is automatically stored in nonvolatile memory and does not have to be stored with the CAL:SAVE command.

Command Syntax CALibrate: PASScode < NRf>

<NRf>**Parameters** 

Examples CAL:PASS 6671 CAL:PASS 09.1993

Query Syntax (None) Related Commands CAL:STAT

#### **CAL:SAVE**

This command saves any new calibration constants (after a current or voltage calibration procedure has been completed) in nonvolatile memory.

**Command Syntax:** CALibrate:SAVE

> Parameters (None) **Examples** CAL: SAVE Query Syntax (None)

Related Commands CAL:CURR CAL:VOLT CAL:STAT

#### **CAL:STAT**

This command enables and disables the calibration mode. The calibration mode must be enabled before the power supply will accept any other calibration commands. The first parameter specifies the enabled or disabled state. The second parameter is the password. It is required if the calibration mode is being enabled and the existing password is not 0. If the second parameter is not entered or is incorrect, an error is generated and the calibration mode remains disabled. The query statement returns only the state, not the password.

Whenever the calibration mode is changed from enabled to disabled, any new calibration constants are lost unless they have been stored with CAL:SAVE.

**Command Syntax:** CALibrate:STATe <bool> [,<NRf>]

**Parameters** {0 | OFF} | {1 | ON} [,<NRf>]

\*RST Value OFF

Examples CAL:STAT 1,6671 CAL:STAT OFF

**Ouerv Syntax** CALibrate:STATe?

**Returned Parameters**  $\{0 \mid 1\}$ 

Related Commands CAL:PASS CAL:SAVE

#### **CAL:VOLT**

This command is used to calibrate the output voltage. The command enters voltage value that you obtain from an external meter. (If you are entering the voltage value, allow time for the DVM to stabilize.) You must first select a calibration level (CAL:VOLT:LEV) for the value being entered. Two successive values (one for each end of the calibration range) must be selected and entered. The power supply then computes new voltage calibration constants. These constants are not stored in nonvolatile memory until saved with the CAL:SAVE command.

Command Syntax CALibrate: VOLTage[:DATA] <NRf>

**Parameters** (See applicable Output Ratings in "Chapter 1- General Information")

Default Suffix A

**Examples** CAL: VOLT 322 . 5 MV CAL: VOLT: DATA 3 . 225

Query Syntax (None)

Related Commands CAL:SAVE CAL:STAT

#### CAL:VOLT:LEV

This command sets the power supply to a calibration point that is then entered with **CAL:VOLT[:DATA].** During calibration, two points must be entered and the low-end point (MIN) must be selected and entered first.

Command Syntax CALibrate: VOLTage: DATA {MIN|MAX}

Parameters { < CRD > | MINimum | MAXimum}

**Examples** CAL: VOLT: LEV MIN CAL: VOLT: LEV MAX

Query Syntax (None)

**Related Commands** CAL:VOLT[:DATA] CAL:STAT

#### **CAL:VOLT:PROT**

This command calibrates the power supply overvoltage protection (OV) circuit. The *output voltage must be in calibration* before this procedure is performed. Also, the power supply output must be enabled and operating in the constant voltage (CV) mode. If present, the optional relay accessory must either be disconnected or set to the off (open) state. The power supply automatically performs the calibration and stores the new OV constant in nonvolatile memory. **CAL:VOLT:PROT** is a sequential command that takes several seconds to complete.

Command Syntax: CALibrate: VOLTage: PROTection

Parameters (None)

Example CAL: VOLT: PROT

**Query Syntax** (None) **Related Commands** CAL:STAT

#### Agilent BASIC Calibration Program

The following program can be run on any controller operating under Agilent BASIC. The assumed power supply address is 5 and calibration password is 6680. If required, change these parameters in the appropriate statements.

**Note** If you are calibrating models 664x, 665x, or 667x, delete or comment out lines 640 through 670 in the following calibration program. These program lines are only required when calibrating models 668x.

```
10
       ! Agilent BASIC Calibration Program
20
30
       DIM Resp$ [255],Err_msg$[255]
40
50 Volt_cal: !
                Voltage DAC calibration
60
       Err found=0
70
       PRINT TABXY(5,10), "CONNECT INSTRUMENTS AS SHOWN IN FIG. A -1(1). Then Press Continue"
80
       PAUSE
90
       CLEAR SCREEN
100
110
       ! Assign power supply GPIB address
120
130
       ASSIGN @Ps TO 705
140
150
       ! Initialize power supply
160
170
       OUTPUT @Ps;"*RST;OUTPUT ON"
180
190
       ! Password is optional - only required if set to non-zero value
200
       ! Default password is the four-digit model number
210
       ! LINE 240 PASSWORD MUST BE EDITED FOR MODEL OTHER THAN 6680
220
230
240
       OUTPUT @Ps;"CAL:STATE ON, 6680"
250
260
       OUTPUT @Ps;"CAL:VOLTAGE:LEVEL MIN"
270
       INPUT "ENTER VOLTAGE MEASUREMENT FROM EXTERNAL VOLTMETER", Volt_read
280
       OUTPUT @Ps;"CAL:VOLTAGE ";Volt_read
290
       OUTPUT @Ps;"CAL:VOLTAGE:LEVEL MAX"
300
       INPUT "ENTER VOLTAGE MEASUREMENT FROM EXTERNAL VOLTMETER", Volt read
310
       OUTPUT @Ps;"CAL:VOLTAGE ";Volt_read
320
330
       ! Calibrate overvoltage protection circuit
340
350
       OUTPUT @Ps;"CAL:VOLTAGE:PROTECTION"
360
370
       GOSUB Save cal
380
       IF Err found THEN
390
              INPUT "ERRORS have occurred, REPEAT VOLTAGE CALIBRATION ( Y 0R N )?", Resp$
400
              IF TRIM$(UPC$(Resp$[1,1]))="Y" THEN GOTO Volt_cal
410
       END IF
420
       IF Err_found THEN
              PRINT "VOLTAGE CALIBRATION NOT SAVED"
430
440
       ELSE
450
              PRINT "VOLTAGE CALIBRATION COMPLETE"
460
       END IF
470
480 Current cal: !
                    Imon DAC and Current DAC calibration
490
       Err found=0
500
       PRINT TABXY(5,10), "CONNECT INSTRUMENTS AS SHOWN IN FIG. A -1(2). Then Press Continue"
510
       PAUSE
520
       CLEAR SCREEN
```

Figure A-2. Agilent BASIC Calibration Program

```
540
       Password is optional - only required if set to non-zero value
550
       Default password is four-digit model number
560
570
       ! LINE 590 PASSWORD MUST BE EDITED FOR MODEL OTHER THAN 6680
580
590
       OUTPUT @Ps;"CAL:STATE ON, 6680"
       OUTPUT @Ps;"VOLT:LEV 2"
600
610
       ! Refer to Table A-1 for correct shunt value for model being calibrated
620
630
       INPUT "ENTER VALUE OF CURRENT SHUNT BEING USED", Shunt val
                     STEPS 640 THROUGH 670 NOT USED ON 664x, 665x and 667x
640
       OUTPUT @Ps;"CAL:CURRENT:MONITOR"
650
       INPUT "ENTER VOLTAGE MEASUREMENT FROM EXTERNAL VOLTMETER", Volt read
660
       Current=Volt read/Shunt val
670
       OUTPUT @Ps;"CAL:CURRENT ";Current
       OUTPUT @Ps;"CAL:CURRENT:LEVEL MIN"
680
690
       INPUT "ENTER VOLTAGE MEASUREMENT FROM EXTERNAL VOLTMETER", Volt read
700
       Current=Volt_read/Shunt_val
710
       OUTPUT @Ps;"CAL:CURRENT ";Current
720
       OUTPUT @Ps;"CAL:CURRENT:LEVEL MAX"
730
       INPUT "ENTER VOLTAGE MEASUREMENT FROM EXTERNAL VOLTMETER", Volt_read
740
       Current=Volt read/Shunt val
750
       OUTPUT @Ps;"CAL:CURRENT ";Current
760
       GOSUB Save cal
770
       IF Err found THEN
780
              INPUT "ERRORS have occurred, REPEAT CURRENT CALIBRATION ( Y 0R N )?", Resp$
790
              IF TRIM$(UPC$(Resp$[1,1] ))="Y" THEN GOTO Volt_cal
800
       END IF
810
       IF Err found THEN
820
              PRINT "CURRENT CALIBRATION NOT SAVED"
830
       ELSE
840
              PRINT "CURRENT CALIBRATION COMPLETE"
850
       END IF
       STOP
860
870 Save cal: ! SAVE CALIBRATION
880
       REPEAT
890
              OUTPUT @Ps;"SYSTEM:ERROR?"
900
              ENTER @Ps;Err num,Err msg$
910
              IF Err num < >0 THEN
920
                     PRINT "ERROR: ";Err_msg$
930
                     Err found=1
940
              END IF
950
       UNTIL Err_num=0
       IF NOT Err_found THEN
960
970
              INPUT "SAVE CALIBRATION CONSTANTS (Y 0R N)?", Resp$
980
              IF TRIM$(UPC$(Resp$[1,1]))="Y" THEN
990
                     OUTPUT @Ps;"CAL:SAVE"
1000
              END IF
1010
       END IF
1020
       OUTPUT @Ps;"CAL:STATE OFF"
1030
       RETURN
1040
       END
```

Figure A-2. Agilent BASIC Calibration Program (continued)

# **Operation Verification**

#### Introduction

This appendix provides operation verification test procedures. The tests do not check all the operating parameters, but verify that the power supply is performing properly. The required test equipment and acceptable test results are specified in tables at the end of this appendix.

**Note** 

Performance Tests, which check all the specifications of the power supply, are given in the applicable power supply Service Manual.

# **Test Equipment Required**

## **List of Equipment**

The following equipment is required to perform the tests:

**Table B-1. Equipment Required for Verification Tests** 

Equipment	Characteristics	Recommended Model
Digital Voltmeter	Resolution: 10 nV @ 1 V Readout: 8 1/2 digits Accuracy: 20 ppm	Agilent 3458A
<b>Current Monitor Resistor</b>		
Agilent 6641A, 51A, 52A	100 A, 0.01 Ω, 0.04%, 100 W	Guildline 9230/100
Agilent 6642A, 43A, 44A, 45A, 53A, 54A, 55A	15 A, 0.1 Ω, 0.04%, 25 W	Guildline 9230/15
Agilent 6671A	300 A, 0.001 Ω, 0.04%, 100 W	Guildline 9230/300
Agilent 6672A, 73A, 74A, 75A	100 A, 0.001 Ω, 0.04%, 100 W	Guildline 9230/100
Agilent 6680A, 81A	1000 A, 0.1 mΩ, 0.05%	Burster 1280S
Agilent 6682A, 83A, 84A	300 A, 0.1 mΩ, 0.05%	Guildline 9230/300

#### **Current Monitoring Resistor**

The 4-terminal current-monitoring resistor listed in Table B-1 is required to eliminate output current measurement error caused by voltage drops in leads and connections. The specified resistors have special current-monitoring terminals inside the load connection terminals. Connect the current monitor directly to these current-monitoring terminals.

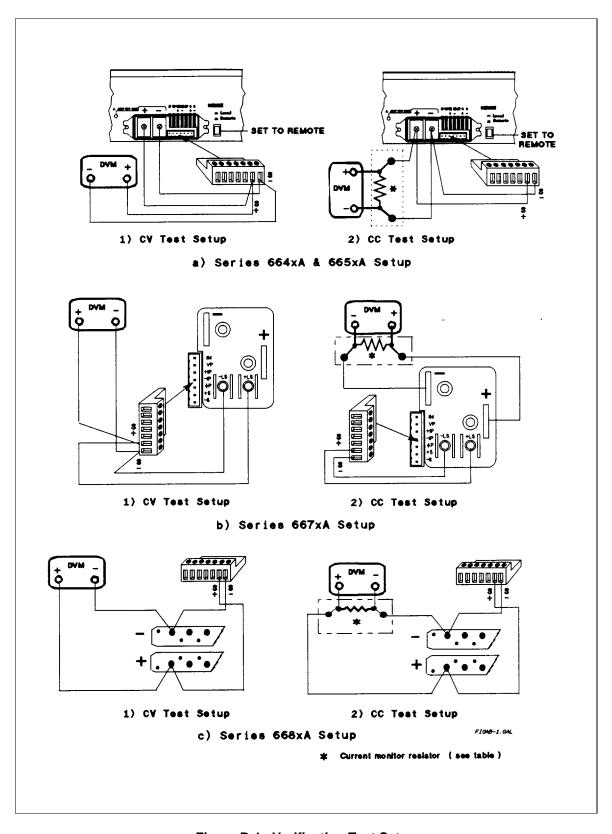


Figure B-1. Verification Test Setup

## **Performing The Tests**

#### **General Measurement Techniques**

Figure B-1 shows the setup for the tests. Be certain to use load leads of sufficient wire gauge to carry the output current (see Table 4-1). To avoid noise pickup, use coaxial cable or shielded pairs for the test leads.

#### **Programming the Power Supply**

Table 1-1b, Table 1-2b, Table 1-3b and Table 1-4b in Chapter 1 list the programming voltage and current ranges for each model. Enter the appropriate values from the front panel. The programming procedures assume you know how to operate the power supply from the front panel (see "Chapter 5 - Front Panel Operation").

#### **Order of Tests**

Perform the following tests for operation verification. Test 1 must be done first, followed by Tests 2 and 3 in any order.

- 1 Turn-on Checkout
- 2 Voltage Programming and Readback Accuracy
- 3 Current Programming and Readback Accuracy

#### **Turn-on Checkout**

Perform the Turn-on Checkout as directed in "Chapter 3 - Turn-on Checkout".

Note

The power supply must pass turn-on selftest before you can proceed with these tests.

#### **Voltage Programming and Readback Accuracy**

This test verifies that the voltage programming, GPIB readback, and front panel display functions are within specifications. Figure B-1 shows the setup for the tests. Measure the dc output voltage directly at the sense connections of the output terminals or bus bars. Connect the output as shown.

Table B-2. Voltage Programming and Readback Accuracy Tests

	Action	Normal Result
1	Turn off the power supply and connect a DVM across the sense terminals (see Figure B-1(1)).	
2	Turn on the power supply with no load and program the output for 0 volts and maximum programmable current.	CV annunciator on. Output current near 0.
3	Record voltage readings at DVM and on front panel display. (Subtract or add the specified readback limit to the actual output values).	Readings within Low Voltage limits (see applicable test table).
4	Program voltage to full scale.	
5	Record voltage readings of DVM and on front panel display. (Subtract or add the specified readback limit to the actual output values)	Readings within High Voltage limits (see applicable test table).

## **Current Programming and Readback Accuracy**

This test verifies that the current programming and readback are within specification. Connect the appropriate current monitoring resistor (see Table B-1) as shown in Figure B-1(2). The accuracy of the resistor must be as specified in the table.

Table B-3. Current Programming and Readback Accuracy Test

	Action	Normal Result
1	Turn off the power supply and connect the current monitoring resistor as shown in Figure B-1(2). Be certain to use wire of sufficient size to carry the maximum rated current of the supply (see Table 4-1 in Chapter 4).	
2	Connect a DVM across the resistor.	
3	Turn on the power supply and program the output for 5 volts and 0 amperes.	
4	Disable the output ( Output Off )	
	WARNING ENERGY HAZARD for Series 668xA. The power supply can output connections touch, severe arcing may occur resulting in be make connections to live output circuits.	
5	Enable the output On or OUTP ON).	
6	Observe the DVM voltage reading. Divide this by the resistance of the current monitor resistor. Record the result as the Low Current value in applicable test table.	Value within Low Current limits (see applicable test table).
7	Record the front panel display readback	Value within specified readback limits (see applicable test table).
8	Program output current to full scale.	
9	Repeat Steps 6 and 7.	Both current readings within specified High Current and readback limits (see applicable test table).
10	Disable the output ( Output Off ).	
11	Remove the short from across the load.	

	4. Operation Verificati			
Test Description	Minimum Spec	Results *	Maximum Spec	Measurement Uncertainty
MODEL Agilent 6641A				•
_	Voltage Programmi	ng and Readback		
Low Voltage (0 V) V <sub>out</sub>	-5 mV	mV	+ 5 mV	$2.0 \mu V$
Front Panel Display Readback		mV	Vout +6.0 mV	2.0 μV
High Voltage (8 V) V <sub>out</sub>		V	8.010 V	88 μV
Front Panel Display Readback	Vout -11.6 mV	mV	Vout +11.6 mV	88 μV
	Current Programmi	ng and Readback		•
Low Current (0 A) I <sub>out</sub>	• • •	mA	+26 mA	153 μΑ
Front Panel Display Readback		mA	Iout +18 mA	153 µA
High Current (20 Å) I <sub>out</sub>		A	+20.056 A	2.7 mA
Front Panel Display Readback		mA	Iout +48 mA	2.7 mA
MODEL Agilent 6642A				
WIODEL right 0042/1	Voltage Programmi	ng and Readhack		
Low Voltage (0 V) V <sub>out</sub>		mV	+ 10 mV	$2.0~\mu V$
Front Panel Display Readback		mV	Vout +15 mV	2.0 μV
High Voltage (20 V) V <sub>out</sub>		V	20.022 V	•
Front Panel Display Readback		mV	Vout +29 mV	335 μV
Profit Failer Display Readback	Current Programmi		V Out +29 III V	335 μV
Low Current (0 A) I <sub>out</sub>	_	_	+13 mA	20 4
Front Panel Display Readback		mA		20 μΑ
* ·		mA	Iout +9.1 mA	20 μΑ
High Current (10 A) I <sub>out</sub>		A	+10.028 A	3.1 mA
Front Panel Display Readback	Iout -24.1 mA	mA	Iout +24.1 mA	3.1 mA
MODEL Agilent 6643A				
	Voltage Programmi		4.77	
Low Voltage (0 V) V <sub>out</sub>		mV	+ 15 mV	2.0 μV
Front Panel Display Readback		mV	Vout +25 mV	2.0 μV
High Voltage (35 V) V <sub>out</sub>		V	35.036 V	525 μV
Front Panel Display Readback	Vout -50 mV	mV	Vout +50 mV	525 μV
	Current Programmi	ng and Readback		
Low Current (0 A) I <sub>out</sub>	-6.7 mA	mA	+6.7 mA	16 µA
Front Panel Display Readback	Iout -5 mA	mA	Iout +5 mA	16 µA
High Current (6 A) I <sub>out</sub>	5.985 A	A	6.015 A	1.1 mA
Front Panel Display Readback	Iout -14 mA	mA	Iout +14 mA	1.1 mA
MODEL Agilent 6644A				
5	Voltage Programmi	ng and Readback		
Low Voltage (0 V) V <sub>out</sub>	26 11	mV	+ 26 mV	2.0 μV
Front Panel Display Readback	Vout -40 mV	mV	Vout +40 mV	2.0 μV
High Voltage ( 60 V) V <sub>out</sub>	59.938 V	V	60.062 V	845 μV
Front Panel Display Readback	Vout -82 mV	mV	Vout +82 mV	845 μV
	Current Programmi		. 555 . 52 111 ,	015 μ τ
Low Current (0 A) I <sub>out</sub>	Ü	mA	+4.1 mA	16 μΑ
Front Panel Display Readback		mA	Iout +3 mA	16 μA
High Current (3.5 A) I <sub>out</sub>	3.491 A	A	+3.509 A	10 μA 500 μA
Front Panel Display Readback	Iout -8.3 mA		F3.309 A Iout +8.3 mA	•
From Faner Display Readback	10ut -0.3 IIIA	mA	10uι το.3 IIIA	500 μΑ
	* Enter your test	results in this column		

Table B-4. Operation Verification Test Parameters for Series 664xA (continued)

Test Description	Minimum Spec	Results *	Maximum	Measurement		
			Spec	Uncertainty		
MODEL Agilent 6645A						
Voltage Programming and Readback						
Low Voltage (0 V) V <sub>out</sub>	-51 mV	mV	+ 51 mV	$2.0 \mu V$		
Front Panel Display Readback	Vout -80 mV	$\_\_\_$ mV	Vout +80 mV	$2.0 \mu V$		
High Voltage (120 V) V <sub>out</sub>	119.877 V	V	120.123 V	1.7 mV		
Front Panel Display Readback	Vout -164 mV	$\underline{\hspace{1cm}}$ mV	Vout +164 mV	1.7 mV		
	Current Programm	ing and Readback				
Low Current (0 A) I <sub>out</sub>	-1.7 mA	mA	+1.7 mA	16 μΑ		
Front Panel Display Readback	Iout -1.3 mA	mA	Iout $+1.3 \text{ mA}$	16 μΑ		
High Current (1.5 A) I <sub>out</sub>	1.496 A	A	+1.504 A	188 μΑ		
Front Panel Display Readback	Iout -3.5 mA	mA	Iout +3.5 mA	188 µA		
	* Enter your test	results in this column.		·		

	5. Operation Verificat			
Test Description	Minimum Spec	Results *	Maximum Spec	Measurement Uncertainty
MODEL Agilent 6651A				
	Voltage Programmi	ng and Readback		
Low Voltage (0 V) V <sub>out</sub>	-5 mV	mV	+ 5 mV	$2.0~\mu V$
Front Panel Display Readback		mV	Vout +6.0 mV	2.0 μV
High Voltage (8 V) V <sub>out</sub>		V	8.010 V	88 μV
Front Panel Display Readback	Vout -11.6 mV	mV	Vout +11.6 mV	88 μV
	Current Programmi	ing and Readback		•
Low Current (0 A) I <sub>out</sub>		mA	+60 mA	150 μΑ
Front Panel Display Readback		mA	Iout +67 mA	150 µA
High Current (50 A) I <sub>out</sub>		A	+50.135 A	10.7 mA
Front Panel Display Readback		mA	Iout +142 mA	10.7 mA
MODEL Agilent 6652A				
WODEL Agnetit 0032A	Voltage Programmi	ng and Readback		
Low Voltage (0 V) V <sub>out</sub>		mV	+ 10 mV	2.0 μV
Front Panel Display Readback		mV	Vout +15 mV	2.0 μV 2.0 μV
High Voltage (20 V) V <sub>out</sub>		V	20.022 V	•
Front Panel Display Readback		mV	Vout +29 mV	335 μV
From Famer Display Readback			Vout +29 III V	335 μV
I are Comment (0, A) I	Current Programmi	~	125 A	152 4
Low Current (0 A) I <sub>out</sub>		mA	+25 mA	153 μA
Front Panel Display Readback		mA	Iout +26 mA	153 μΑ
High Current (25 A) I <sub>out</sub>	24.937 A	A	+25.063 A	3.5 mA
Front Panel Display Readback	Iout -63.5 mA	mA	Iout +63.5 mA	3.5 mA
MODEL Agilent 6653A				
	Voltage Programmi			
Low Voltage (0 V) V <sub>out</sub>		mV	+ 15 mV	$2.0 \mu V$
Front Panel Display Readback	Vout -25 mV	mV	Vout +25 mV	$2.0 \mu V$
High Voltage (35 V) V <sub>out</sub>	34.964 V	V	35.036 V	525 μV
Front Panel Display Readback	Vout -50 mV	mV	Vout +50 mV	525 μV
	Current Programmi	ing and Readback		
Low Current (0 A) I <sub>out</sub>	-13 mA	mA	+13 mA	17 μΑ
Front Panel Display Readback	Iout -15 mA	mA	Iout +15 mA	17 μA
High Current (15 A) I <sub>out</sub>		A	15.036 A	6.2 mA
Front Panel Display Readback	Iout -37.5 mA	mA	Iout +37.5 mA	6.2 mA
MODEL Agilent 6654A				
	Voltage Programmi	ng and Readback		
Low Voltage (0 V) V <sub>out</sub>	-26 mV	mV	+ 25 mV	2.0 μV
Front Panel Display Readback	Vout -40 mV	mV	Vout +40 mV	2.0 μV
High Voltage ( 60 V) Vout	59.938 V	V	60.062 V	2.0 μV 845 μV
Front Panel Display Readback	Vout -82 mV	mV	Vout +82 mV	845 μV
Tom I and Display Readback	Current Programmi		1 Out 1 02 III 1	0+3 μν
Low Current (0 A) I <sub>out</sub>	_	mA	+8 mA	16 μΑ
Front Panel Display Readback	Iout -7 mA		Iout +7 mA	•
- ·	8.978 A	mA		16 μA 2.5 mA
High Current (9 A) I <sub>out</sub> Front Panel Display Readback	8.978 A Iout -20.5 mA	A mA	+9.022 A Iout +20.5 mA	2.5 mA 2.5 mA
	10111 <b>-</b> /U <b>7</b> MA	mA	IOIII ±7U 7 MA	2) mA

Table B-5. Operation Verification Test Parameters for Series 665xA (continued)

Test Description	Minimum Spec	Results *	Maximum	Measurement		
			Spec	Uncertainty		
MODEL Agilent 6655A						
Voltage Programming and Readback						
Low Voltage (0 V) V <sub>out</sub>	-51 mV	mV	+ 51 mV	$2.0 \mu V$		
Front Panel Display Readback	Vout -80 mV	mV	Vout +80 mV	$2.0 \mu V$		
High Voltage (120 V) V <sub>out</sub>	119.877 V	V	120.123 V	1.7 mV		
Front Panel Display Readback	Vout -164 mV	mV	Vout +164 mV	1.7 mV		
	Current Programm	ing and Readback				
Low Current (0 A) I <sub>out</sub>	-4 mA	mA	+4 mA	15 μΑ		
Front Panel Display Readback	Iout -3 mA	mA	Iout +3 mA	15 μΑ		
High Current (4 A) I <sub>out</sub>	3.990A	A	+4.010 A	586 μΑ		
Front Panel Display Readback	Iout -9 mA	mA	Iout +9 mA	586 μA		
	* Enter your test	results in this column.		·		

Table B-6. Operation Verification Test Parameters for Series 667xA

	6. Operation Verificati			
Test Description	Minimum Spec	Results *	Maximum Spec	Measurement Uncertainty
MODEL Agilent 6671A				-
_	Voltage Programmi	ng and Readback		
Low Voltage (0 V) V <sub>out</sub>	-8 mV	mV	+ 8 mV	1.6 μV
Front Panel Display Readback		mV	Vout +12 mV	1.6 μV
High Voltage (8 V) V <sub>out</sub>		V	8.0012 V	100 μV
Front Panel Display Readback		mV	Vout +16 mV	100 µV
	Current Programmi	ing and Readback		•
Low Current (0 A) I <sub>out</sub>	-125 mA	mA	+125 mA	50 µA
Front Panel Display Readback		mA	Iout +150 mA	50 μA
High Current (220 A) I <sub>out</sub>		A	220.345 A	92 mA
Front Panel Display Readback	T 4 270 A	mA	Iout +370 mA	92 mA
MODEL Agilent 6672A				
S	Voltage Programmi	ng and Readback		
Low Voltage (0 V) V <sub>out</sub>		mV	+ 20 mV	2.0 μV
Front Panel Display Readback		mV	Vout +30 mV	2.0 μV
High Voltage (20 V) V <sub>out</sub>		V	20.028 V	335 μV
Front Panel Display Readback		mV	Vout +40 mV	335 μV
1 2	Current Programmi	ng and Readback		<b>,</b>
Low Current (0 A) I <sub>out</sub>	_	mA	+60 mA	40 μΑ
Front Panel Display Readback		mA	Iout +100 mA	40 μA
High Current (100 A) I <sub>out</sub>		A	+100.16 A	41 mA
Front Panel Display Readback		mA	Iout +200 mA	41 mA
MODEL Agilent 6673A				
Wieber ignent outer	Voltage Programmi	ng and Readback		
Low Voltage (0 V) V <sub>out</sub>		mV	+ 35 mV	2.0 μV
Front Panel Display Readback		mV	Vout +50 mV	2.0 μV
High Voltage (35 V) V <sub>out</sub>		V	35.049 V	526 μV
Front Panel Display Readback	Vout -68 mV		Vout +68 mV	526 μV
remeration and applies reduced the	Current Programmi		, 640 - 66 111 ,	020 pt 1
Low Current (0 A) I <sub>out</sub>	_	mA	+40 mA	31 μΑ
Front Panel Display Readback	T	mA	Iout +60 mA	31 µA
High Current ( 60 A) I <sub>out</sub>	50.0 A	A	60.1 A	25 mA
Front Panel Display Readback	Iout -120 mA	mA	Iout +120 mA	25 mA
MODEL Agilent 6674A				
WODEL Agnesit 0074A	Voltage Programmi	ng and Readback		
Low Voltage (0 V) V <sub>out</sub>	-60 mV	mV	+ 60 mV	2.2 μV
Front Panel Display Readback	Vout -90 mV	mV	Vout +90 mV	2.2 μV 2.2 μV
High Voltage (60 V) V <sub>out</sub>	59.916 V	N	60.084 V	2.2 μV 1 mV
Front Panel Display Readback	Vout -132 mV	v mV	Vout +132 mV	1 mV
	Current Programmi		, 000 102 m	- 111 '
Low Current (0 A) I <sub>out</sub>	_	mA	+25 mA	21 μΑ
Front Panel Display Readback	Iout -35 mA	mA	Iout +35 mA	21 μA 21 μA
High Current (35 A) I <sub>out</sub>		MA	35.06 A	21 μA 15 mA
		mA	Iout +70 mA	15 mA
Front Panel Display Readback	10111 = /11 m A			

Table B-6. Operation Verification Test Parameters for Series 667xA (continued)

Test Description	Minimum Spec	Results *	Maximum	Measurement	
		<u> </u>	Spec	Uncertainty	
MODEL Agilent 6675A					
-	Voltage Programm	ing and Readback			
Low Voltage (0 V) V <sub>out</sub>	-120 mV	mV	+ 120 mV	$3.0 \mu\text{V}$	
Front Panel Display Readback	Vout -180 mV	mV	Vout +180 mV	3.0 μV	
High Voltage (120 V) V <sub>out</sub>	119.832 V	V	120.168 V	1.7 mV	
Front Panel Display Readback	Vout -240 mV	mV	Vout +240 mV	1.7 mV	
I	Current Programm	ning and Readback			
Low Current (0 A) I <sub>out</sub>	-12 mA	mA	+12 mA	20 μΑ	
Front Panel Display Readback	Iout -18 mA	mA	Iout +18 mA	20 μΑ	
High Current (18 A) I <sub>out</sub>	17.97 A	A	+18.03 A	7.5 mA	
Front Panel Display Readback	Iout -36 mA	mA	Iout +36 mA	7.5 mA	
-  -	* Enter your test	t results in this column.			
1					

Table B-7. Operation Verification Test Parameters for Series 668xA

	7. Operation Verificat				
Test Description	Minimum Spec	Results *	Maximum Spec	Measurement Uncertainty	
MODEL Agilent 6680A					
	Voltage Programmi	ing and Readback			
Low Voltage (0 V) V <sub>out</sub>	-0.005 V	V	+ 0.005 V	$1.0 \mu V$	
Front Panel Display Readback	Vout -7.5 mV	$\_\_\_$ mV	Vout +7.5 mV	1.0 µV	
High Voltage (5 V) V <sub>out</sub>	4.9943 V	V	5.0057 V	56 μV	
Front Panel Display Readback	Vout -10 mV	mV	Vout +10 V	56 μV	
	Current Programm	ing and Readback		•	
Low Current (0 A) I <sub>out</sub>	_	A	+0.450 A	15 mA	
Front Panel Display Readback		mA	Iout +600 mA	15 mA	
High Current (875 A) I <sub>out</sub>		A	+876.325 A	461 mA	
Front Panel Display Readback		A	Iout +1.475 A	461 mA	
MODEL Agilent 6681A					
	Voltage Programmi	ing and Readback			
Low Voltage (0 V) V <sub>out</sub>		V	+ 0.008 V	1.0 μV	
Front Panel Display Readback	Vout -12 mV	mV	Vout +12 mV	1.0 μV	
High Voltage (8 V) V <sub>out</sub>		V	8.0112 V	88 μV	
Front Panel Display Readback	Vout -16 mV	mV	Vout +16 mV	88 μV	
Tone Faner Display Readouck	Current Programm		vout 10 mv	σο μν	
Low Current (0 A) I <sub>out</sub>	_	A	+0.300 A	15 mA	
Front Panel Display Readback		mA	Iout +400 mA	15 mA	
High Current (580 A) I <sub>out</sub>	579.12 A	A	+580.88 A	311 mA	
Front Panel Display Readback	Iout -980 mA	mA	Iout +980 mA	311 mA	
MODEL Agilent 6682A	1001 700 1111	III 1	1041 1900 1111 1	311 11111	
WODEL Agnetit 0002A	Voltage Programmi	ing and Daadhaak			
Low Voltage (0 V) V <sub>out</sub>		mV	+ 21 mV	1 7 uV	
Front Panel Display Readback		mV	Vout +32 mV	1.7 μV	
High Voltage (21 V) V <sub>out</sub>				1.7 μV	
Front Panel Display Readback	Vout -42 mV	V	348 μV Vout +42 mV	240	
From Panel Display Readback		mV	vout +42 mv	348 μV	
I - C (O A) I	Current Programm		. 105 A	1 5 A	
Low Current (0 A) I <sub>out</sub>		mA	+125 mA	1.5 mA	
Front Panel Display Readback		mA	Iout +165 mA	1.5 mA	
High Current (240 A) I <sub>out</sub>		A	240.365 A Iout +405 mA	83 mA	
Front Panel Display Readback	Iout -405 mA	mA	10ut +405 mA	83 mA	
MODEL Agilent 6683A					
	Voltage Programmi	· ·	22 **		
Low Voltage (0 V) V <sub>out</sub>	-32 mV	mV	+ 32 mV	1.9 μV	
Front Panel Display Readback	Vout -48 mV	mV	Vout +48 mV	1.9 µV	
High Voltage (32 V) V <sub>out</sub>	31.955 V	V	32.044 V	$488 \mu V$	
Front Panel Display Readback	Vout -?? mV	mV	Vout +?? mV	$488  \mu V$	
	Current Programm	ing and Readback			
Low Current (0 A) I <sub>out</sub>	-85 mA	mA	+85 mA	1.5 μΑ	
Front Panel Display Readback	Iout -60 mA	mA	Iout +60 mA	1.5 μΑ	
High Current (160 A) I <sub>out</sub>	159.755 A	A	160.245 A	35.6 mA	
Front Panel Display Readback	Iout -270 mA	mA	Iout +270 mA	35.6 mA	
	** **	results in this column.			

Table B-7. Operation Verification Test Parameters for Series 668xA (continued)

Test Description	Minimum Spec	Results *	Maximum	Measurement	
			Spec	Uncertainty	
MODEL Agilent 6684A					
	Voltage Programn	ning and Readback			
Low Voltage (0 V) V <sub>out</sub>	-40 mV	mV	+40  mV	2.0 μV	
Front Panel Display Readback	Vout -60 mV	mV	Vout +60 mV	2.0 μV	
High Voltage (40 V) V <sub>out</sub>	39.944 V	V	40.056 V	590 μV	
Front Panel Display Readback	Vout -80 mV	mV	Vout +80 mV	590 μV	
	Current Programn	ning and Readback		·	
Low Current (0 A) I <sub>out</sub>	-65 mA	mA	+65 mA	1.5 mA	
Front Panel Display Readback	Iout -90 mA	mA	Iout +90 mA	1.5 mA	
High Current (128 A) I <sub>out</sub>	127.807 A	A	128.193 A	24.1 mA	
Front Panel Display Readback	Iout -218 mA	mA	Iout +218 mA	24.1 mA	
	* Enter your tes	t results in this column.			

## **Line Voltage Conversion**

### Series 664xA and 665xA Power Supplies

WARNING

**SHOCK HAZARD**. Hazardous voltage can remain inside the power supply even after it has been turned off. This procedure should only be done by qualified electronics service personnel.

Line voltage conversion is accomplished by:

- Series 664xA setting line voltage select switches.
- Series 665xA changing wire and jumper positions on the ac input of the main power transformer.

#### Proceed as follows:

- 1. Turn off the ac power to the supply and disconnect the power cord from the power source.
- 2. Remove the four screws that secure the two carrying straps and outer cover.
- 3. Slightly spread the bottom rear of the cover and pull it back to disengage it from the front panel.
- 4. Slide the dustcover back far enough to expose the select switches (see Figure C-1) or the line select jumpers (see Figure C-2).
- 5. On the Series 664xA supply, move the line voltage select switches to the positions corresponding to the desired line voltage.
- 6. **On the Series 665xA supply,** move the line voltage select jumpers to the positions corresponding to the desired line voltage. To disconnect it from the transformer tab, pull the wire straight up. Moving the wire from side-to-side can damage the tab.
- 7. Replace the top cover and secure the carrying straps.
- 8. Change the line fuse (on the rear panel) to the proper value for the new line voltage (see Table 1-6 in Chapter 1).

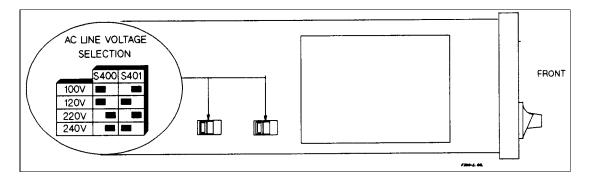


Figure C-1. Series 664xA Line Select Switches

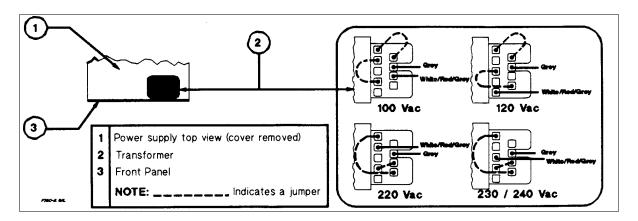


Figure C-2. Series 665xA Line Select Jumpers

### **Series 667xA Power Supplies**



**SHOCK HAZARD**. Hazardous voltage can remain inside the power supply even after it has been turned off. This procedure should only be done by qualified electronics service personnel.

Line voltage conversion is accomplished by setting a line voltage select switch. Proceed as follows:

- 1. Turn off the ac power and disconnect the power cord from the power source.
- 2. Remove the four screws securing the carrying straps and dustcover.
- 3. Spread the bottom rear of the dustcover and pull it back to disengage it from the front panel.
- 4. Slide the dustcover back far enough to expose the line select switch (see Figure C-3).
- 5. Observe the input rail LED under the RFI shield. **If the LED is on, there is still hazardous voltage inside the supply.** Wait until the LED goes out (this may take several minutes) before proceeding.
- 6. Connect a dc voltmeter across test points TP1 and TP2. (It may be necessary to remove the RFI shield in order to reach these test points. The shield is secured by four screws on each side.) When the voltmeter indicates 60 volts or less, it is safe to work inside the power supply.
- 7. Locate the line selector switch and slide it to the desired position.
- 8. If you removed it in step 6, be sure to replace the RFI shield.
- 9. Replace the dustcover.

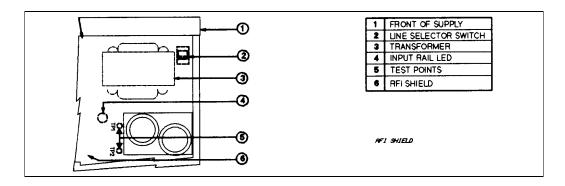


Figure C-3. Series 667xA Line Select Switch

### **Series 668xA Power Supplies**

# WARNING

**SHOCK HAZARD**. Hazardous voltage can remain inside the power supply even after it has been turned off. This procedure should only be done by qualified electronics service personnel.

Line voltage conversion is accomplished by changing jumper cable positions on the ac input of the main power transformer. Proceed as follows:

- 1. Turn off the power switch and disconnect the power cord from the power source or turn off the power disconnect switch.
- 2. Remove the four screws that secure the two carrying straps and outer cover.
- 3. Slightly spread the bottom rear of the cover and pull it back to disengage it from the front panel.
- 4. Remove the outer cover by sliding it back towards the rear of the supply.
- 5. Observe the input rail LEDs under the inner cover (see Figure C-4). **If the LEDs are on, there is still hazardous voltage inside the supply.** Wait until they both go out (this may take several minutes) before proceeding. (If one LED remains on while the other goes out, the power supply probably has a defect that requires service.)

# WARNING

If you cannot see the LEDs through the hole in the inner cover, then wait until power has been removed for at least 15 minutes before proceeding to the next step.

- 6. Remove the screws securing the inner cover (see Figure C-4).
- 7. Remove the inner cover.
- 8. Locate the three line conversion cables (A,B,C in Figure C-5). All three cables will be connected to the jacks that correspond to one of the voltage ranges (1 or 2, Figure C-5).
- 9. Unplug the cables from their present jacks and plug them into the jacks for the other range.
- 10. Replace the inner cover.

### **Note**

Be sure to replace all of the screws removed in Step 6. All the screws are not needed for mechanical security, but they are required to ensure proper magnetic shielding.

- 11. Replace the outer cover.
- 12. Remove the three fuses from the rear panel. If required, first remove the ac safety cover (see Figure 2-4).
- 13. Replace the fuses with the proper ones for the new range (see Table 1-6 in Chapter 1).
- 14. If required, replace the ac safety cover.

Reconnect the power and turn on the power supply.

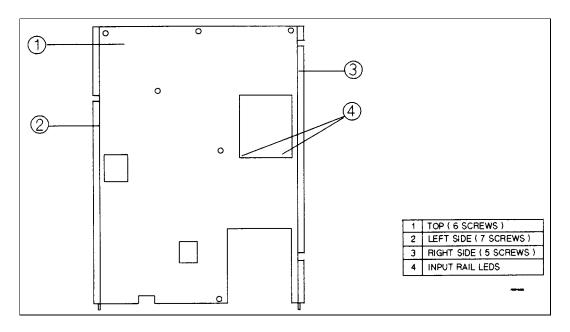


Figure C-4. Removing the Series 668xA Inner Cover

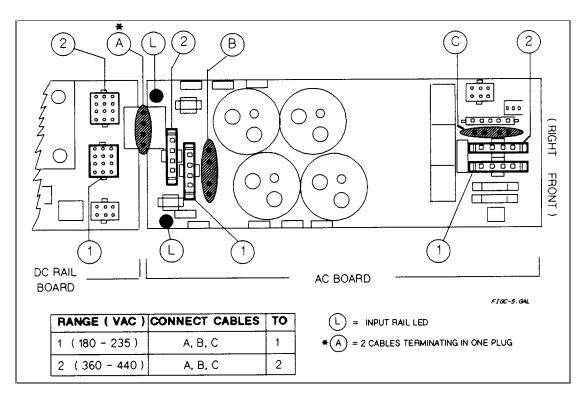


Figure C-5. Series 668xA Line Conversion Jumpers

D

# **Digital Port Functions**

### **Digital Connector**

A 4-pin connector and a quick-disconnect mating plug are provided for digital input and output signals (see Figure D-l for wiring connections, and Table 1-5 in Chapter 1 for electrical characteristics). This digital port can be configured to provide either Fault/Inhibit or Digital I/O functions.

**Note** Consistent with good engineering practice, twist and shield all signal wires to and from the digital connector.

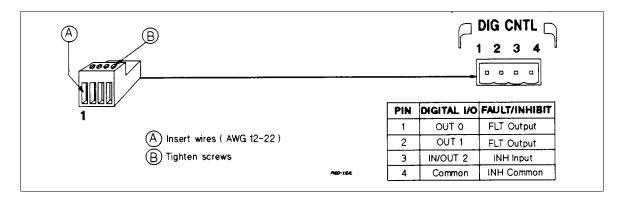


Figure D-1. Digital Port Connector

### Fault/Inhibit Operation

As shipped from the factory, the digital port is configured to provide a fault indicator (FLT) output and a remote (INH) input. Unplug the mating plug to make the connections. After you have finished making all connections, plug the wired plug back into the connector.

FLT Output	Used to indicate that a fault has occurred in power supply. Pins 1 and 2 are the open collector
(pins 1 and 2)	output of an optocoupler, with pin 1 the collector and pin 2 the emitter. When a fault has occurred,
	pin 1 is driven low with respect to pin 2 (negative-true).
******	

**INH Input** (pin 3) Used to shut down the power supply output. Pin 3 is a high impedance input. The supply shuts down when this input is driven low (negative-true). This can be done by shorting pin 3 to pin 4.

**INH Common** Provides the common connection for the INH input. (pin 4)

Three examples are provided to show how to use the FLT/INH circuits of your power supply. Use twisted wire connections to reduce or prevent EM in all cases. If shielded wire is used, connect only one end of the shield to the chassis signal ground binding post to prevent ground loops.

In Figure D-2, the INH input is connected to a switch that shorts pin 3 to pin 4 whenever it is necessary to externally disable the output of the supply. This will activate the remote inhibit (RI) fault protection circuit, causing the front panel **Prot** annunciator to come on. It also sets the RI event bit in the supply's Questionable Status Event register (see "Chapter 4-Status Reporting" in the Programming Guide). To re-enable the supply after it has been disabled by the INH input, first open the connection between pins 3 and 4. Then clear the protection circuit either from the front panel (see "Chapter 5 - Front Panel Operation" in this guide) or over the GPIB (see the Programming Guide).

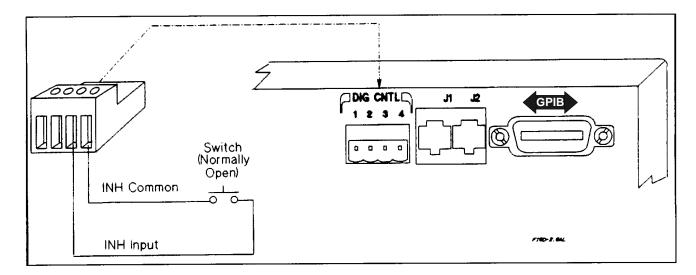


Figure D-2. Example of Inhibit Input

In Figure D-3A, the FLT output is connected to a relay driver circuit that energizes a relay whenever a fault condition occurs in the power supply. The relay can be used to physically disconnect the output of the power supply from the load. The FLT output is generated by the logical ORing of the power supply's Operation, Questionable, and Event status summary bits (see "Chapter 4 - Status Reporting" in the Programming Guide). You can cause one or more events to activate the FLT output by enabling the appropriate events in these status registers. The fault condition is cleared by first removing the cause of the fault and then reading the appropriate status event register(s).

In Figure D-3B, the FLT output of one supply is connected to the INH input of another supply. Although only two supplies are shown, it is possible to chain other supplies with this arrangement. A fault condition in any one of the power supplies will disable all of them without intervention either by the controller or external circuitry. The controller can be made aware of the fault via a service request (SRQ) generated by the Questionable Status summary bit (see "Chapter 4 - Status Reporting" in the Programming Guide).

Note

The INH input cannot be used to disable outputs set from the external voltage programming port.

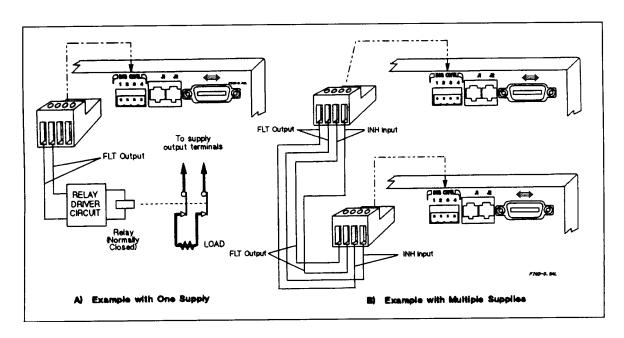


Figure D-3. Examples of FLT Outputs

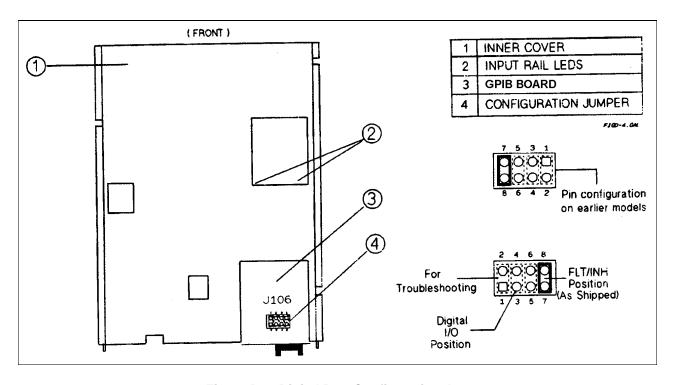


Figure D-4. Digital Port Configuration Jumper

### **Changing The Port Configuration**

As shipped from the factory, the digital port is configured for FLT/INH operation. You can change the configuration of the port to operate as a general-purpose digital input/output port to control your custom circuitry as shown in Figure D-4. To change the port configuration, you must move a jumper on the GPIB board.

WARNING

**Shock Hazard**. Hazardous voltage can remain inside the power supply even after it has been turned off. This procedure should only be done by qualified electronics service personnel.

#### Proceed as follows:

- 1. Turn off the power supply and disconnect the power cord from the power source or turn off the power disconnect switch (Series 668xA).
- 2. Remove the four screws that secure the two carrying straps and outer cover.
- 3. Spread the bottom rear of the cover and pull it back to disengage it from the front panel.
- 4. Slide the outer cover back to expose the top of the GPIB board.
- 5. Refer to Figure D-4 and use needle-nose pliers to move the jumper to the Digital I/O position.
- 6. Replace the outer cover, and secure the carrying straps.
- 7. Make the necessary wire connections to the digital connector.

### **Digital I/O Operation**

The digital port can be configured (see Figure D-4) to provide a digital input/output to be used with custom digital interface circuits or relay circuits. Some examples are shown Figure D-5. See Figure D-1 for the pin assignments of the mating plug and Table 1-5 for the electrical characteristics of the port. See **DIG:DATA[:VAL]** in "Chapter 3 - Language Dictionary" of the Programming Guide for information on programming the port. The digital port pins are as follows:

**OUT 0** (pin 1) This port can only be used as an open-collector output. It is assigned a bit weight of 1.

OUT 1 (pin 2) This port can only be used as an open-collector output. It is assigned a bit weight of 2.

**IN/OUT 2** (pin 3) This port can be programmed to be either a high impedance input or an open-collector output.

**Common** (pin 4) This pin is the common connection for the Digital I/O ports.

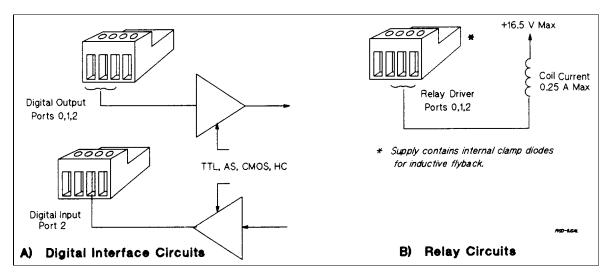


Figure D-5. Digital I/O Port Applications

### **Relay Link Operation**

The digital port can be configured to provide relay control outputs for the Agilent 59510A or 59511A Relay Accessory. Refer to Figure D-1 for the pin assignments of the mating plug.

CAUTION

Not used with units that output more than 50 amps.

**RLY SEND** Provides the serial data to control the relays in the Relay Accessory.

(pin 1)

(pin 2) (Not used)

**RLY RTN** Receives the data readback that indicates the status of the relays in the Relay Accessory.

(pin 3)

Common connection for the RLY SEND and RLY RTN lines. Common

(pin 4)

Figure D-6 shows how to connect your power supply to an Agilent 59510A or 59511A Relay Accessory when the digital port is configured for relay link operation. An error will be generated if you attempt to program the relay box without first configuring the digital port for relay link operation. For more information about programming the relay, refer to **OUTP:REL[:STAT]** in Chapter 3 of the Programming Guide. For more information about the Relay Accessory, refer to its manual (see Table 1-6).

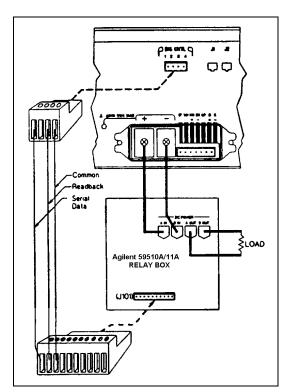


Figure D-6. Relay Link Connections

# **Current Loop Compensation (Series 668xA Only)**

This section describes how you may use current loop compensation to optimize for inductive loads or for fast CV/CC mode crossover. A 7-position compensation switch for this purpose is located under the cover on the rear of the power supply.

### **Function Of Loop Compensation**

Figure E-1 shows the switch settings for specific combinations of load inductance and resistance. Two sets of curves show the small-signal response for each model. The dashed curves represent programming performance of no more than 10% current overshoot. The solid curves represent operating conditions with 25% overshoot. The curve obtained with all switches open gives the fastest CC mode crossover response time. However, as shown by these curves, the loop will not tolerate larger inductances unless the load resistance is increased. The curve described when all switch positions are closed shows the as-shipped performance curve. This position provides 10% overshoot and fast CV/CC crossover performance for load inductances that are specific for each model. (For Models 6680A and 6681A, this curve ranges from 100 µohms at 15 µhenries to about 100 milliohms at 40 millihenries.). You can select a different compensation curve by opening a specific switch or combination of switches.

Table E-1 shows some specific  $L \div R$  ratios and the switch positions required for these ratios. Table E-1 is valid only for Models 6680A and 6681A - you must use the curves for the remaining models. The corresponding 10% overshoot curves are shown in Figure E-1. As operation moves along the curves from left to right, the switch positions must be changed as shown along the X-axis.

Table E-1. Settings For CC Loop Compensation Switch (Models 6680A and 6681A Only)

Load Characteristic (L/R)			<sup>1</sup> Sw	itch S	etting	<u> </u>	
	7	6	5	4	3	2	1
1 μH/3 mΩ	0	0	0	0	0	0	0
$^{2}15  \mu H/100  \mu \Omega$	1	1	1	1	1	1	1
$30  \mu H/100  \mu \Omega$	0	0	0	0	0	0	1
$100  \mu \text{H} / 100  \mu \Omega$	1	1	1	1	1	1	0
$150  \mu H/100  \mu \Omega$	0	0	0	0	0	1	0
$600  \mu \text{H}/100  \mu \Omega$	1	1	1	1	1	0	0
$1.2~\mathrm{mH/100~\mu\Omega}$	0	0	0	0	1	0	0
$4~\mathrm{mH/100~\mu\Omega}$	1	1	1	1	0	0	0
$10~\mathrm{mH}/100~\mathrm{\mu\Omega}$	0	0	0	1	0	0	0
$40 \text{ mH}/100 \mu\Omega$	1	1	1	0	0	0	0
$100 \text{ mH}/100 \mu\Omega$	0	0	1	0	0	0	0
$380 \text{ mH}/100 \mu\Omega$	1	1	0	0	0	0	0
650 mH/100 μΩ	0	1	0	0	0	0	0
7 H/100 μΩ	1	0	0	0	0	0	0

For example, examine Figure E-l for the Model 6680A/6681A. The chart shows that a load comprised of about

1 millihenry inductance and 100 micro ohms resistance (see point (a)) requires switch setting 9 (only switch 3 closed) to obtain 10% overshoot. If the load resistance is increased to 1 milliohm, then the operating position will be to the left of the existing compensation curve (see point (b)). This will result in a stable condition with less overshoot, but greater CV/CC crossover time than if the curve defined by switch setting 8 were used. If the load resistance remains at 1 milliohm but the load inductance increases to 10 millihenries, then the operating position will be far to the right of the compensation curve (see point (c)). This results in a less stable condition with more overshoot. To obtain better operation at point (c) use the compensation curve defined by switch setting 13 (Model 6680A) or 12 (Model 6681A).

Most operating conditions will not fall directly on a curve and you will have to interpolate between curves. Generally, moving to the left of a given curve increases stability. However, at large values of inductance the curves become almost vertical because the load resistance has no effect on dampening the system. For Models 6680A and 6681A, the most stable points are on the solid curves shown in Figure E-l. Points to the right or left of a curve will have more overshoot. Note the two dashed vertical lines at switch setting 25 for Models 6682A, 6683A, and 6684A. Operation between these lines will result in somewhat increased stability.

**Note** 

The best procedure is to test your settings under real operating conditions. For help in tailoring a specific CC compensation, contact your Agilent Sales and Support Offices.

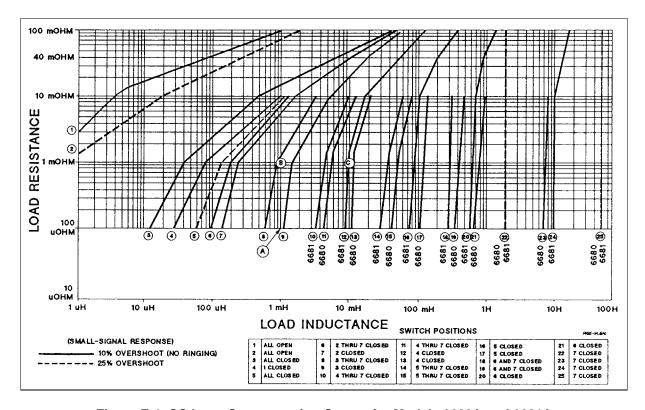


Figure E-1. CC Loop Compensation Curves for Models 6680A and 6681A

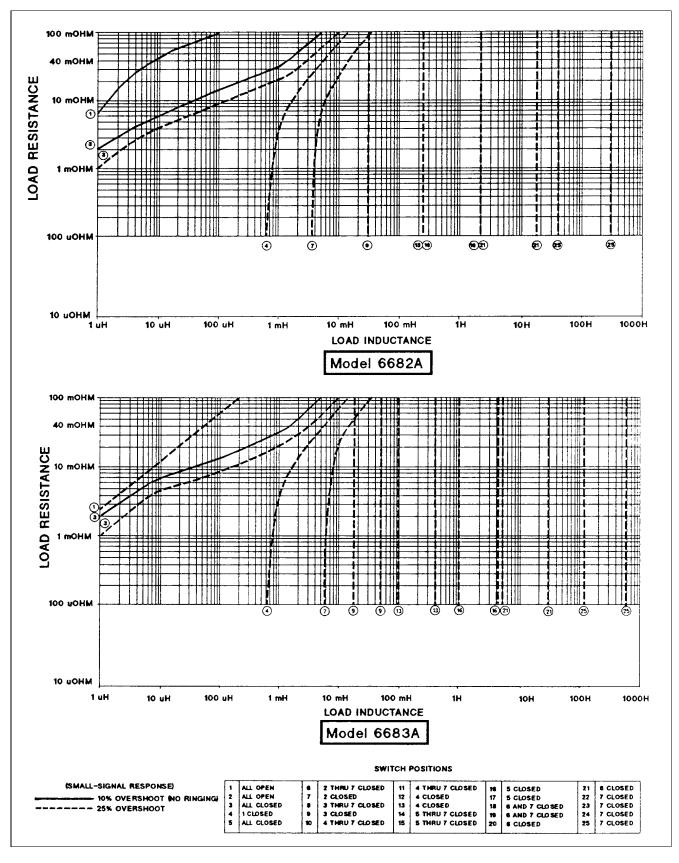


Figure E-1. CC Loop Compensation Curves For Models 6682A and 6683A

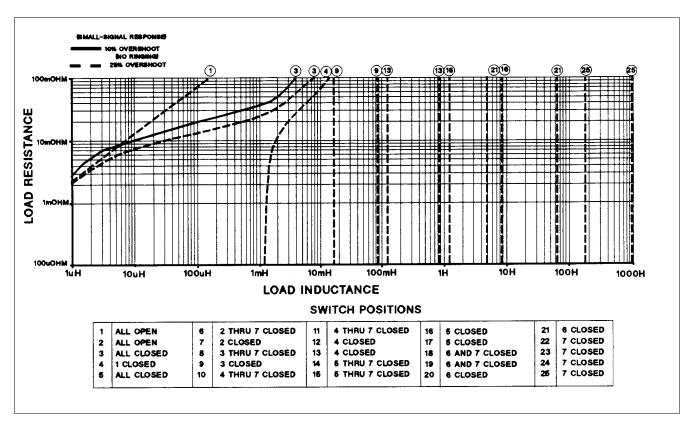


Figure E-1. CC Loop Compensation Curves For Model 6684A

### **Setting The Loop Compensation Switch**



**SHOCK/ENERGY HAZARD**. This procedure involves removing the outside cover and should only be done by qualified electronics service personnel.

- 1. Turn off the power switch and disconnect the power cord from the power source. If this is not possible, remove the three line fuses from the rear panel (see Figure 2-4).
- 2. Remove the four screws that secure the two carrying straps and outside cover.
- 3. Spread the bottom rear of the cover and pull it back to disengage it from the front panel.
- 4. Remove the cover by sliding it back towards the rear of the supply.
- 5. Locate the compensation switch (see Figure E-2).
- 6. Move the switches to the desired position.
- 7. Replace the outside cover.

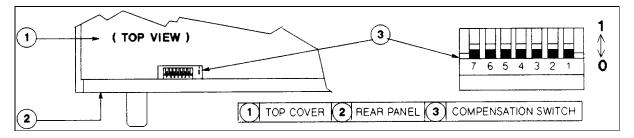


Figure E-2. CC Loop Compensation Switch

# Using Agilent 668xA Series Power Supplies in Autoparallel

This information is supplementary to the information on page 80.

A maximum of three Agilent 668xA series power supplies having the **same** model number, may be configured for autoparallel operation. The Agilent 668xA power supplies were designed with an external programming offset so that the master unit will output current before the slave units do. Therefore, slave supplies will always sink current when low output current values are desired.

### **Autoparallel Procedure**

- 1. Connect the Agilent 668xA power supplies with the **Im** terminal from the master connected to the **+Ip** terminal of each slave. Connect the **▶P** terminal of the master to the **-Ip** terminal of each slave (see Figure 4-5e on page 81).
- 2. Each load lead should be of the same wire gauge and length.
- 3. Turn on all power supplies.
- 4. Program each slave supply for zero (0) output current either by pressing [CURRENT] [0] [ENTER] from the front panel keypad or sending the command "CURR:LEV 0" via the GPIB (see notes 2 and 3 on the following page).
- 5. Program each slave's output voltage at least 2 volts higher than the output voltage that the master supply will be programmed to.
- 6. Program the master supply's output current for a value slightly greater than one-half of the total desired output current if there is one slave supply, or one-third of the total desired output current if there are two slave supplies.
- 7. Enable all power supplies by pressing the [Output On/Off] key.
- 8. Increase the master supply's output voltage. At low output currents, the master unit will be supplying all of the load current and the slave supplies will be sinking current, which is normal. At maximum output current each supply will be delivering an equal amount of output current. When operating at less than maximum current, it is normal to have unequal current sharing between the master and slave supplies. Current sharing among the supplies only becomes equal at maximum output current (see Figure F-1).
- 9. For remote sensing, connect only the master supply's +S and-S lines. Slave supplies should be connected for local sensing at the rear of their respective output terminals.

**Note 1** The current division between the master and slaves can be determined as follows: Iout=Im [1 + Ns (1 + 0.127V/5V)] - Ns Ifs (0.127V/5V)

The amount of current the master unit must output before the slave units will output current can be determined as follows:

Ns \* Ifs (0.127V/5V) where Im = master current Ns = number of slaves Ifs = full scale current

Example: 1 master unit, 2 slave units, Agilent Models 6680A (5V, 875A) Iout = Im ( 3.0508 ) - 44.4A The master current limit must be set above 44.4A / 3.0508 = 14.55A to obtain any output current. For a no-load condition:

Master current = 14.55AEach slave current = -14.55A/2 = -7.28AIout = 0A

All Agilent 668xA power supplies have an output current programmed at power-on. The default current value programmed at power-on can be found in Table 3-1 of the Programming Guide (p/n 5960-5597). See \*RST and \*SAV in the Programming Guide to change the power-on current value.

A current programmed via the rear panel +Ip or -Ip inputs will be summed with the current programmed via the front panel keypad or over the GPIB. When programming slave supplies via the rear panel +Ip or -Ip inputs, all slave current programming values must be zero (0).

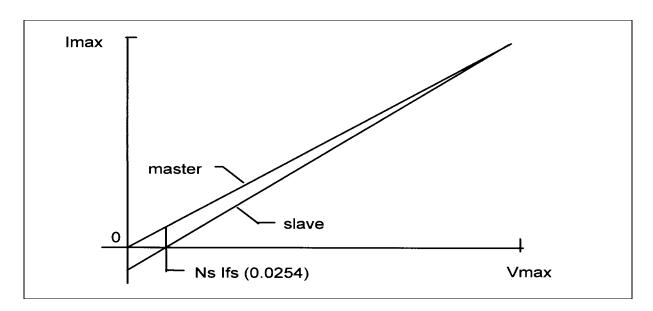


Figure F-1 Master/Slave Current Division

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# **Manual Updates**

The following updates have been made to this manual since the print revision indicated on the title page.

4/01/00

All references to HP have been changed to Agilent. All references to HP-IB have been changed to GPIB.